CSE373: Data Structures \& Algorithms Lecture 14: Hash Collisions

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## Announcements

- Friday: Review List and go over answers to Practice Problems


## Hash Tables: Review

- Aim for constant-time (i.e., O(1)) find, insert, and delete
- "On average" under some reasonable assumptions
- A hash table is an array of some fixed size
- But growable as we'll see


TableSize -1


## Collision resolution

Collision:
When two keys map to the same location in the hash table

We try to avoid it, but number-of-keys exceeds table size

So hash tables should support collision resolution

- Ideas?


## Separate Chaining

| 0 | 1 |
| :---: | :---: |
| 1 | / |
| 2 | 1 |
| 3 | / |
| 4 | / |
| 5 | / |
| 6 | 1 |
| 7 | 1 |
| 8 | 1 |
| 9 | 1 |

Chaining:
All keys that map to the same table location are kept in a list (a.k.a. a "chain" or "bucket")

As easy as it sounds

## Example:

insert 10, 22, 107, 12, 42 with mod hashing and TableSize $=10$

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## Separate Chaining



Chaining:
All keys that map to the same table location are kept in a list (a.k.a. a "chain" or "bucket")

As easy as it sounds

Example:
insert 10, 22, 107, 12, 42
with mod hashing and TableSize = 10

## Thoughts on chaining

- Worst-case time for find?
- Linear
- But only with really bad luck or bad hash function
- So not worth avoiding (e.g., with balanced trees at each bucket)
- Beyond asymptotic complexity, some "data-structure engineering" may be warranted
- Linked list vs. array vs. tree
- Move-to-front upon access
- Maybe leave room for 1 element (or 2?) in the table itself, to optimize constant factors for the common case
- A time-space trade-off...


## Time vs. space (constant factors only here)



## More rigorous chaining analysis

Definition: The load factor, $\lambda$, of a hash table is

$$
\lambda=\frac{\mathrm{N}}{\text { TableSize }} \leftarrow \text { number of elements }
$$

Under chaining, the average number of elements per bucket is $\qquad$

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So if some inserts are followed by random finds, then on average:

- Each unsuccessful find compares against $\lambda$ items
- Each successful find compares against $\qquad$ items


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Under chaining, the average number of elements per bucket is $\lambda$ ie. The average list has length $\lambda$

So if some inserts are followed by random finds, then on average:

- Each unsuccessful find compares against $\lambda$ items
- Each successful find compares against $\lambda / 2$ items

So we like to keep $\lambda$ fairly low (e.g., 1 or 1.5 or 2 ) for chaining

## Alternative: No lists; Use empty space in the table

- Another simple idea: If $\mathbf{h}$ (key) is already full,
- try (h(key) + 1) \% TableSize. If full,
- try (h(key) + 2) \% TableSize. If full,
- try (h(key) + 3) \% TableSize. If full...
- Example: insert 38, 19, 8, 109, 10

| 0 | 1 |
| :---: | :---: |
| 1 | 1 |
| 2 | 1 |
| 3 | 1 |
| 4 | 1 |
| 5 | 1 |
| 6 | 1 |
| 7 | 1 |
| 8 | 38 |
| 9 | / |

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| 6 | / |
| 7 | / |
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| 9 | 19 |

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| 0 | 8 |
| :---: | :---: |
| 1 | / |
| 2 | / |
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| 4 | / |
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| 7 | / |
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| 8 | 38 |
| 9 | 19 |

## Probing hash tables

Trying the next spot is called probing (also called open addressing)

- We just did linear probing
- $\mathbf{i}^{\text {th }}$ probe was (h(key) + i) \% TableSize
- In general have some probe function $f$ and use h(key) + f(i) \% TableSize

Open addressing does poorly with high load factor $\lambda$

- So want larger tables
- Too many probes means no more $O(1)$


## Other operations

insert finds an open table position using a probe function

What about find?

- Must use same probe function to "retrace the trail" for the data
- Unsuccessful search when reach empty position

What about delete?

- Must use "lazy" deletion. Why?
- Marker indicates "no data here, but don't stop probing"
- Note: delete with chaining is plain-old list-remove


## (Primary) Clustering

It turns out linear probing is a bad idea, even though the probe function is quick to compute (which is a good thing)

Tends to produce clusters, which lead to long probing sequences

- Called primary clustering
- Saw this starting in our example



## Analysis of Linear Probing

- Trivial fact: For any $\lambda<1$, linear probing will find an empty slot
- It is "safe" in this sense: no infinite loop unless table is full
- Non-trivial facts we won't prove:

Average \# of probes given $\lambda$ (in the limit as TableSize $\rightarrow \infty$ )

- Unsuccessful search:

$$
\frac{1}{2}\left(1+\frac{1}{(1-\lambda)^{2}}\right)
$$

- Successful search:

$$
\frac{1}{2}\left(1+\frac{1}{(1-\lambda)}\right)
$$

- This is pretty bad: need to leave sufficient empty space in the table to get decent performance (see chart)


## In a chart

- Linear-probing performance degrades rapidly as table gets full
- (Formula assumes "large table" but point remains)

Linear Probing


## Linear Probing



- By comparison, chaining performance is linear in $\lambda$ and has no trouble with $\lambda>1$


## Quadratic probing

- We can avoid primary clustering by changing the probe function (h(key) + f(i)) \% TableSize
- A common technique is quadratic probing:

$$
f(i)=i^{2}
$$

- So probe sequence is:
- $0^{\text {th }}$ probe: $\mathrm{h}($ key ) \% TableSize
- $1^{\text {st }}$ probe: $(\mathrm{h}($ key $)+1) \%$ TableSize
- $2^{\text {nd }}$ probe: $(\mathrm{h}($ key $)+4) \%$ TableSize
- $3^{\text {rd }}$ probe: (h(key) + 9) \% TableSize
- ...
- ith probe: (h(key) + i²) \% TableSize
- Intuition: Probes quickly "leave the neighborhood"


## Quadratic Probing Example



## TableSize=10 <br> Insert: <br> 89 <br> 18 <br> 49 <br> 58 <br> 79

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## TableSize=10 <br> Insert: <br> 89 <br> 18 <br> 49 <br> 58 <br> 79

## Another Quadratic Probing Example



TableSize $=7$
Insert:

| 76 | $(76 \% 7=6)$ |
| :--- | :--- |
| 40 | $(40 \% 7=5)$ |
| 48 | $(48 \% 7=6)$ |
| 5 | $(5 \% 7=5)$ |
| 55 | $(55 \% 7=6)$ |
| 47 | $(47 \% 7=5)$ |

## Another Quadratic Probing Example



TableSize $=7$
Insert:

| 76 | $(76 \% 7=6)$ |
| :--- | :--- |
| 40 | $(40 \% 7=5)$ |
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Doh!: For all $n,\left(\left(\mathbf{n}^{*} \mathbf{n}\right)+5\right) \% 7$ is $0,2,5$, or 6

- No where to put the 47 !


## From Bad News to Good News

- Bad news:
- Quadratic probing can cycle through the same full indices, never terminating despite table not being full
- Good news:
- If TableSize is prime and $\lambda<1 / 2$, then quadratic probing will find an empty slot in at most TableSize/2 probes
- So: If you keep $\lambda<1 / 2$ and TableSize is prime, no need to detect cycles



## Clustering reconsidered

- Quadratic probing does not suffer from primary clustering: no problem with keys initially hashing to the same neighborhood
- But it's no help if keys initially hash to the same index
- Called secondary clustering
- Can avoid secondary clustering with a probe function that depends on the key: double hashing...


## Double hashing

Idea:

- Given two good hash functions $h$ and $g$, it is very unlikely that for some key, $\mathbf{h}$ (key) $==\mathbf{g}$ (key)
- So make the probe function $\mathbf{f ( i )}=\mathbf{i * g}($ key $)$

Probe sequence:

- $0^{\text {th }}$ probe: $\mathrm{h}($ key $) \%$ TableSize
- $1^{\text {st }}$ probe: $(\mathrm{h}($ key $)+\mathrm{g}($ key ) ) \% TableSize
- 2nd probe: (h(key) + 2*g(key)) \% TableSize
- $3^{\text {rd }}$ probe: (h(key) + 3*g(key)) \% TableSize
- ith probe: (h(key) + i*g(key)) \% TableSize

Detail: Make sure $\mathbf{g}$ (key) cannot be $\mathbf{0}$

## Double-hashing analysis

- Intuition: Because each probe is "jumping" by $\mathbf{g}$ (key) each time, we "leave the neighborhood" and "go different places from other initial collisions"
- But we could still have a problem like in quadratic probing where we are not "safe" (infinite loop despite room in table)
- It is known that this cannot happen in at least one case:
- h(key) = key \% p
- g(key) = q - (key \% q)
- $2<q<p$
- $\mathbf{p}$ and $\mathbf{q}$ are prime


## Rehashing

- As with array-based stacks/queues/lists, if table gets too full, create a bigger table and copy everything
- With chaining, we get to decide what "too full" means
- Keep load factor reasonable (e.g., < 1)?
- Consider average or max size of non-empty chains?
- For probing, half-full is a good rule of thumb
- New table size
- Twice-as-big is a good idea, except that won't be prime!
- So go about twice-as-big
- Can have a list of prime numbers in your code since you won't grow more than 20-30 times


## Summary

- Hashing gives us approximately O(1) behavior for both insert and find.
- Collisions are what ruin it.
- There are several different collision strategies.

- Chaining just uses linked lists pointed to by the hash table bins.
- Probing uses various methods for computing the next index to try if the first one is full.
- Rehashing makes a new, bigger table.
- If the table is kept reasonably empty (small load factor), and the hash function works well, we will get the kind of behavior we want.

