



# CSE373: Data Structure & Algorithms

## Lecture 19: Comparison Sorting

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Summer 2015

# *Admin*

- Homework 5 due next Wednesday
- START SOON!!
- Homework 6 assigned next Wednesday (due the week after)
- Final will be last day in class (Friday 8/21)
- Pick up any midterms after class today or in office hours

# *Introduction to Sorting*

- Stacks, queues, priority queues, and dictionaries all focused on providing one element at a time
- But often we know we want “all the things” in some order
  - Humans can sort, but computers can sort fast
  - Very common to need data sorted somehow
    - Alphabetical list of people
    - List of countries ordered by population
    - Search engine results by relevance
    - ...
- Algorithms have different asymptotic and constant-factor trade-offs
  - No single “best” sort for all scenarios
  - Knowing one way to sort just isn’t enough

# *More Reasons to Sort*

General technique in computing:

*Preprocess data to make subsequent operations faster*

Example: Sort the data so that you can

- Find the  $k^{\text{th}}$  largest in constant time for any  $k$
- Perform binary search to find elements in logarithmic time

Whether the performance of the preprocessing matters depends on

- How often the data will change (and how much it will change)
- How much data there is

# *Why Study Sorting in this Class?*

- Unlikely you will ever need to reimplement a sorting algorithm yourself
  - Standard libraries will generally implement one or more (Java implements 2)
- You will almost certainly use sorting algorithms
  - Important to understand relative merits and expected performance
- Excellent set of algorithms for practicing analysis and comparing design techniques

# *The main problem, stated carefully*

For now, assume we have  $n$  comparable elements in an array and we want to rearrange them to be in increasing order

Input:

- An array  $\mathbf{A}$  of data records
- A key value in each data record
- A comparison function

Effect:

- Reorganize the elements of  $\mathbf{A}$  such that for any  $i$  and  $j$ , if  $i < j$  then  $\mathbf{A}[i] \leq \mathbf{A}[j]$
- (Also,  $\mathbf{A}$  must have exactly the same data it started with)
- Could also sort in reverse order, of course

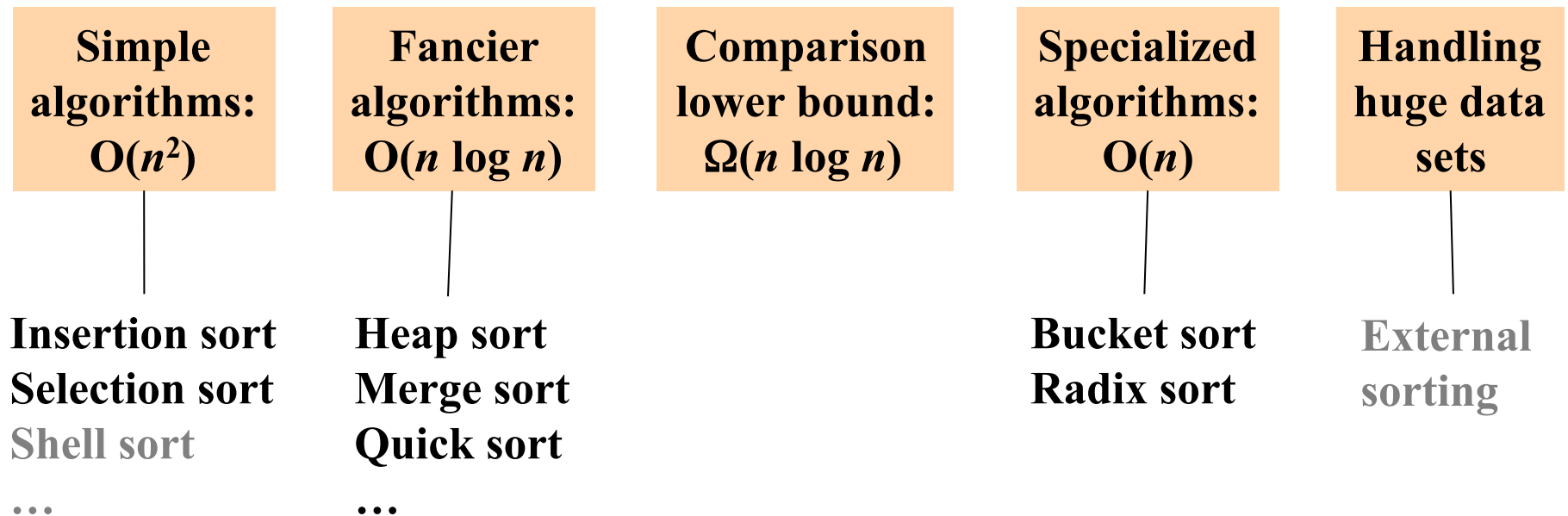
An algorithm doing this is a **comparison sort**

# *Variations on the Basic Problem*

1. Maybe elements are in a linked list (could convert to array and back in linear time, but some algorithms needn't do so)
2. Maybe ties need to be resolved by “original array position”
  - Sorts that do this naturally are called **stable sorts**
3. Maybe we must not use more than  $O(1)$  “auxiliary space”
  - Sorts meeting this requirement are called **in-place sorts**
4. Maybe we can do more with elements than just compare
  - Sometimes leads to faster algorithms
5. Maybe we have too much data to fit in memory
  - Use an “**external sorting**” algorithm

# Sorting: The Big Picture

Surprising amount of neat stuff to say about sorting:





# Insertion Sort

- Idea: At step  $k$ , put the  $k^{\text{th}}$  element in the correct position among the first  $k$  elements
- Alternate way of saying this:
  - Sort first two elements
  - Now insert 3<sup>rd</sup> element in order
  - Now insert 4<sup>th</sup> element in order
  - ...
- “Loop invariant”: when loop index is  $i$ , first  $i$  elements are sorted
- Let's see a visualization (<http://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html>)
- Time?  
Best-case \_\_\_\_\_ Worst-case \_\_\_\_\_ “Average” case \_\_\_\_\_

# Insertion Sort

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- Time?

Best-case	$O(n)$	Worst-case	$O(n^2)$	“Average” case	$O(n^2)$
start sorted		start reverse sorted		(see text)	

# Selection sort

- Idea: At step  $k$ , find the smallest element among the not-yet-sorted elements and put it at position  $k$
- Alternate way of saying this:
  - Find smallest element, put it 1<sup>st</sup>
  - Find next smallest element, put it 2<sup>nd</sup>
  - Find next smallest element, put it 3<sup>rd</sup> ...
- “Loop invariant”: when loop index is  $i$ , first  $i$  elements are the  $i$  smallest elements in sorted order
- Let's see a visualization (<http://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html>)
- Time?  
Best-case \_\_\_\_\_ Worst-case \_\_\_\_\_ “Average” case \_\_\_\_\_

# Selection sort

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- “Loop invariant”: when loop index is  $i$ , first  $i$  elements are the  $i$  smallest elements in sorted order
- Let's see a visualization (<http://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html>)
- Time?
  - Best-case  $O(n^2)$  Worst-case  $O(n^2)$  “Average” case  $O(n^2)$
  - Always*  $T(1) = 1$  and  $T(n) = n + T(n-1)$

# *Insertion Sort vs. Selection Sort*

- Different algorithms
- Solve the same problem
- Have the same worst-case and average-case asymptotic complexity
  - Insertion-sort has better best-case complexity; preferable when input is “mostly sorted”
- Other algorithms are more efficient *for **large** arrays that are **not** already almost sorted*
  - Insertion sort may do well on small arrays

# *The Big Picture*

Surprising amount of juicy computer science: 2-3 lectures...

**Simple  
algorithms:  
 $O(n^2)$**

**Insertion sort**  
**Selection sort**  
**Shell sort**  
...

**Fancier  
algorithms:  
 $O(n \log n)$**

**Heap sort**  
**Merge sort**  
**Quick sort (avg)**  
...

**Comparison  
lower bound:  
 $\Omega(n \log n)$**

**Specialized  
algorithms:  
 $O(n)$**

**Bucket sort**  
**Radix sort**

**Handling  
huge data  
sets**

**External  
sorting**

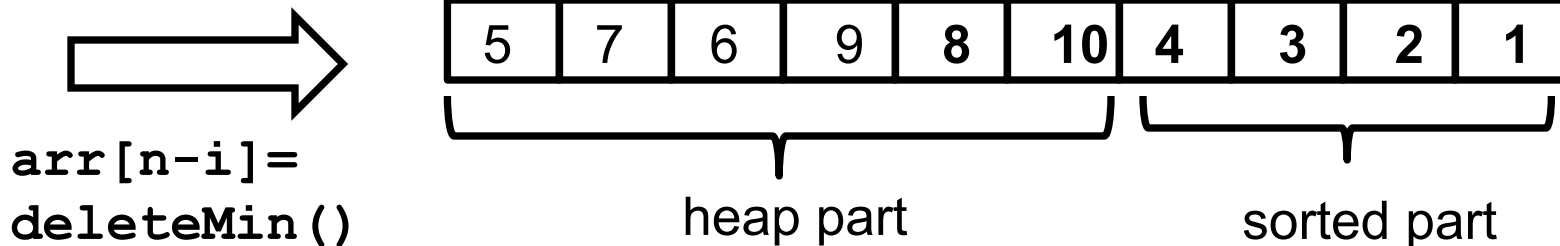
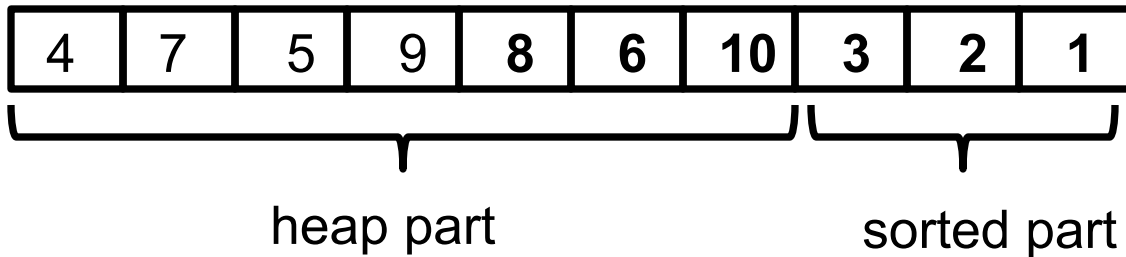
# Heap sort

- Sorting with a heap is easy:
  - `insert` each `arr[i]`, or better yet use `buildHeap`
  - `for(i=0; i < arr.length; i++)`  
    `arr[i] = deleteMin();`
- Worst-case running time:  $O(n \log n)$
- We have the array-to-sort and the heap
  - So this is not an in-place sort
  - There's a trick to make it in-place...

# *In-place heap sort*

But this reverse sorts –  
how would you fix that?

- Treat the initial array as a heap (via **buildHeap**)
- When you delete the  $i^{\text{th}}$  element, put it at **arr[n-i]**
  - That array location isn't needed for the heap anymore!





## “AVL sort”

- We can also use a balanced tree to:
  - **insert** each element: total time  $O(n \log n)$
  - Repeatedly **deleteMin**: total time  $O(n \log n)$ 
    - Better: in-order traversal  $O(n)$ , but still  $O(n \log n)$  overall
- Compared to heap sort
  - both are  $O(n \log n)$  in worst, best, and average case
  - neither parallelizes well
  - heap sort is can be done in-place, has better constant factors

## *“Hash sort”???*

- Nope!
- Finding min item in a hashtable is  $O(n)$ , so this would be a slower, more complicated selection sort
- And selection sort is terrible!

# *Divide and conquer*

Very important technique in algorithm design

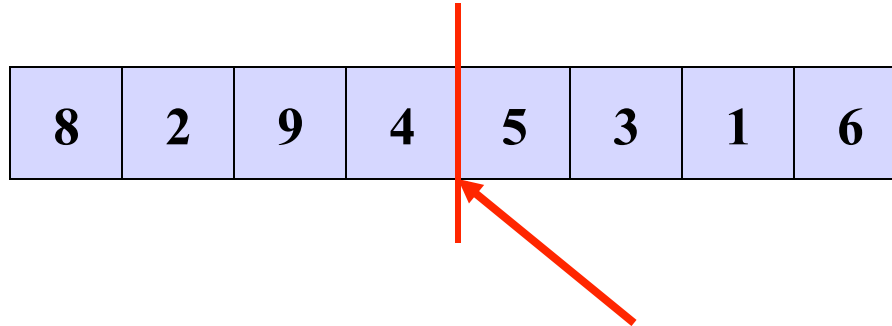
1. Divide problem into smaller parts
2. Independently solve the simpler parts
  - Think recursion
  - Or parallelism
3. Combine solution of parts to produce overall solution

# *Divide-and-Conquer Sorting*

Two great sorting methods are fundamentally divide-and-conquer

1. Mergesort:
  - Sort the left half of the elements (recursively)
  - Sort the right half of the elements (recursively)
  - Merge the two sorted halves into a sorted whole
2. Quicksort:
  - Pick a “pivot” element
  - Divide elements into less-than pivot
    - and greater-than pivot
  - Sort the two divisions (recursively on each)
  - Answer is
    - sorted-less-than then pivot then sorted-greater-than

# Merge sort



- To sort array from position **lo** to position **hi**:
  - If range is 1 element long, it is already sorted! (Base case)
  - Else:
    - Sort from **lo** to  $(\mathbf{hi} + \mathbf{lo}) / 2$
    - Sort from  $(\mathbf{hi} + \mathbf{lo}) / 2$  to **hi**
    - Merge the two halves together
- Merging takes two sorted parts and sorts everything
  - $O(n)$  but requires auxiliary space...

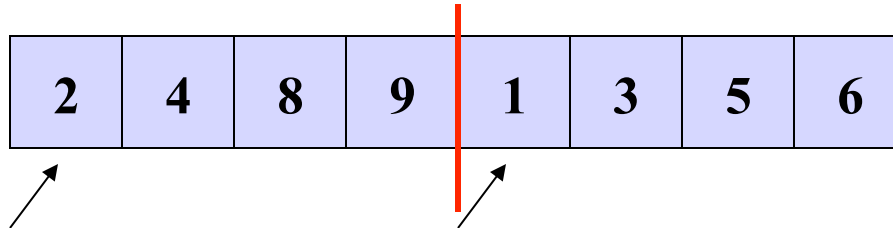
## *Example, focus on merging*

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)

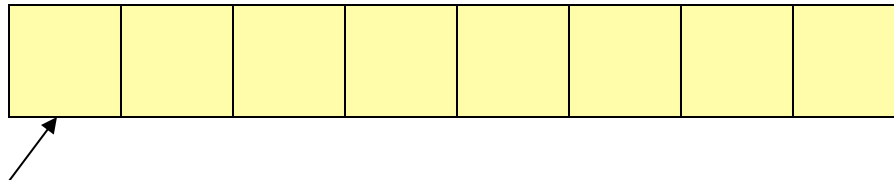
2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

--	--	--	--	--	--	--	--



(After merge,  
copy back to  
original array)

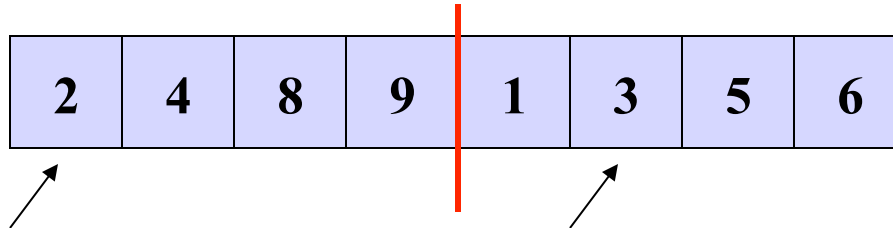
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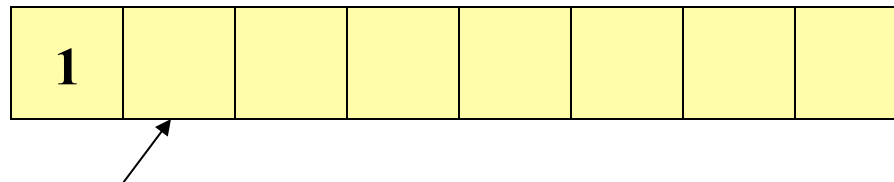
2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1							
---	--	--	--	--	--	--	--



(After merge,  
copy back to  
original array)

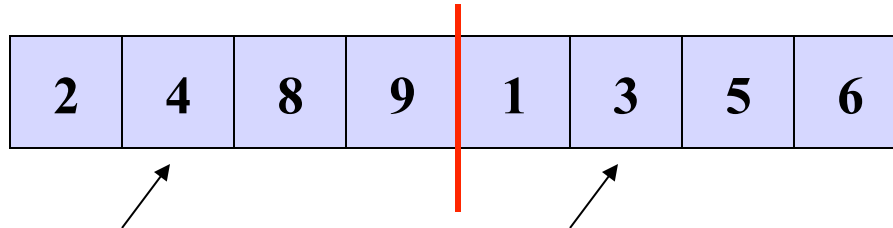
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Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)

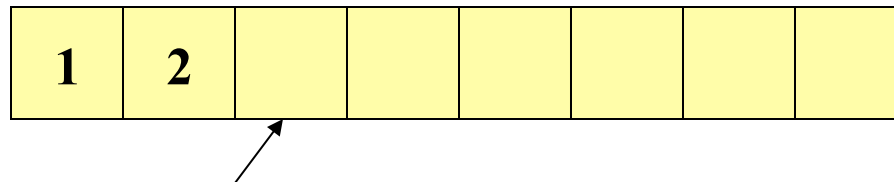
2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1	2						
---	---	--	--	--	--	--	--



(After merge,  
copy back to  
original array)



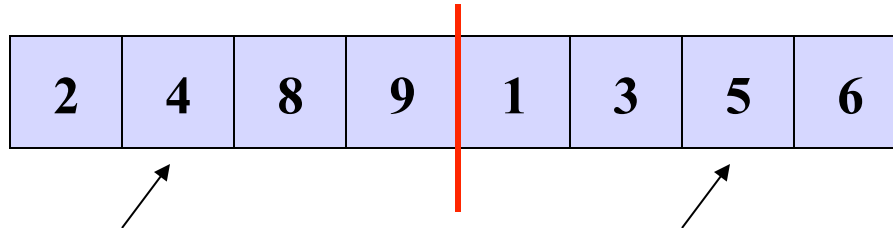
## *Example, focus on merging*

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)

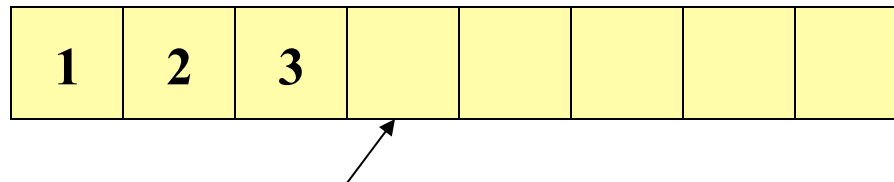
2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1	2	3					
---	---	---	--	--	--	--	--



(After merge,  
copy back to  
original array)

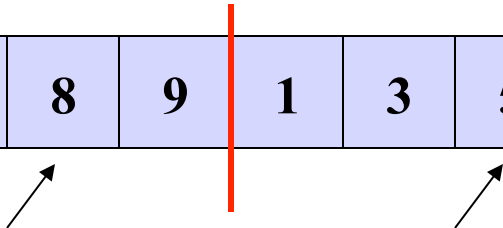
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Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)


2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1	2	3	4				
---	---	---	---	--	--	--	--



(After merge,  
copy back to  
original array)

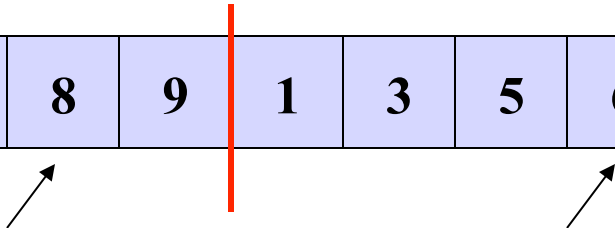
## *Example, focus on merging*

Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)


2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1	2	3	4	5			
---	---	---	---	---	--	--	--



(After merge,  
copy back to  
original array)

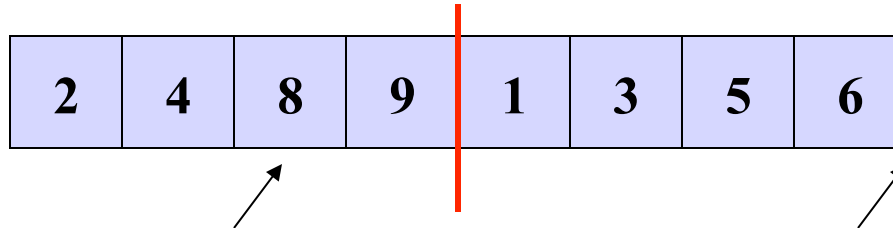
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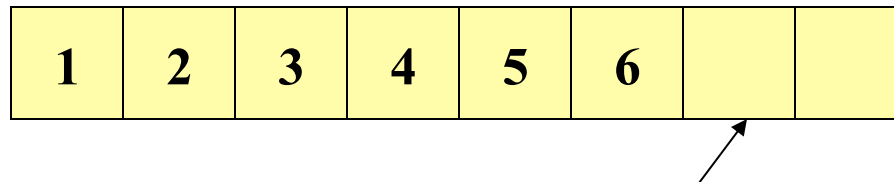
2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1	2	3	4	5	6		
---	---	---	---	---	---	--	--



(After merge,  
copy back to  
original array)

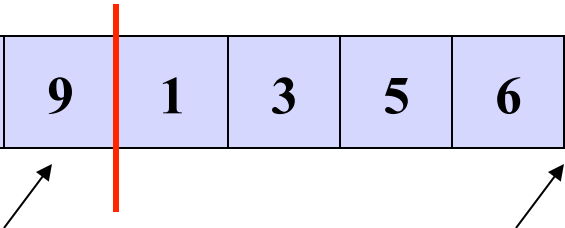
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Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)


2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1	2	3	4	5	6	8	
---	---	---	---	---	---	---	--



(After merge,  
copy back to  
original array)

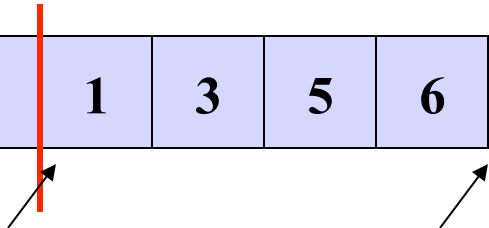
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---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)


2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

1	2	3	4	5	6	8	9
---	---	---	---	---	---	---	---



(After merge,  
copy back to  
original array)

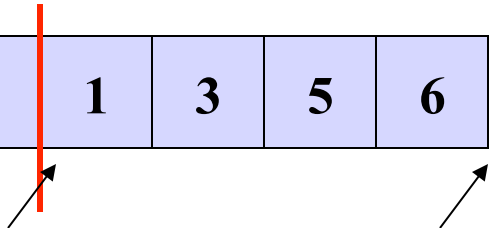
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Start with:

8	2	9	4	5	3	1	6
---	---	---	---	---	---	---	---

After recursion:  
(not magic 😊)


2	4	8	9	1	3	5	6
---	---	---	---	---	---	---	---



Merge:

Use 3 “fingers”  
and 1 more array

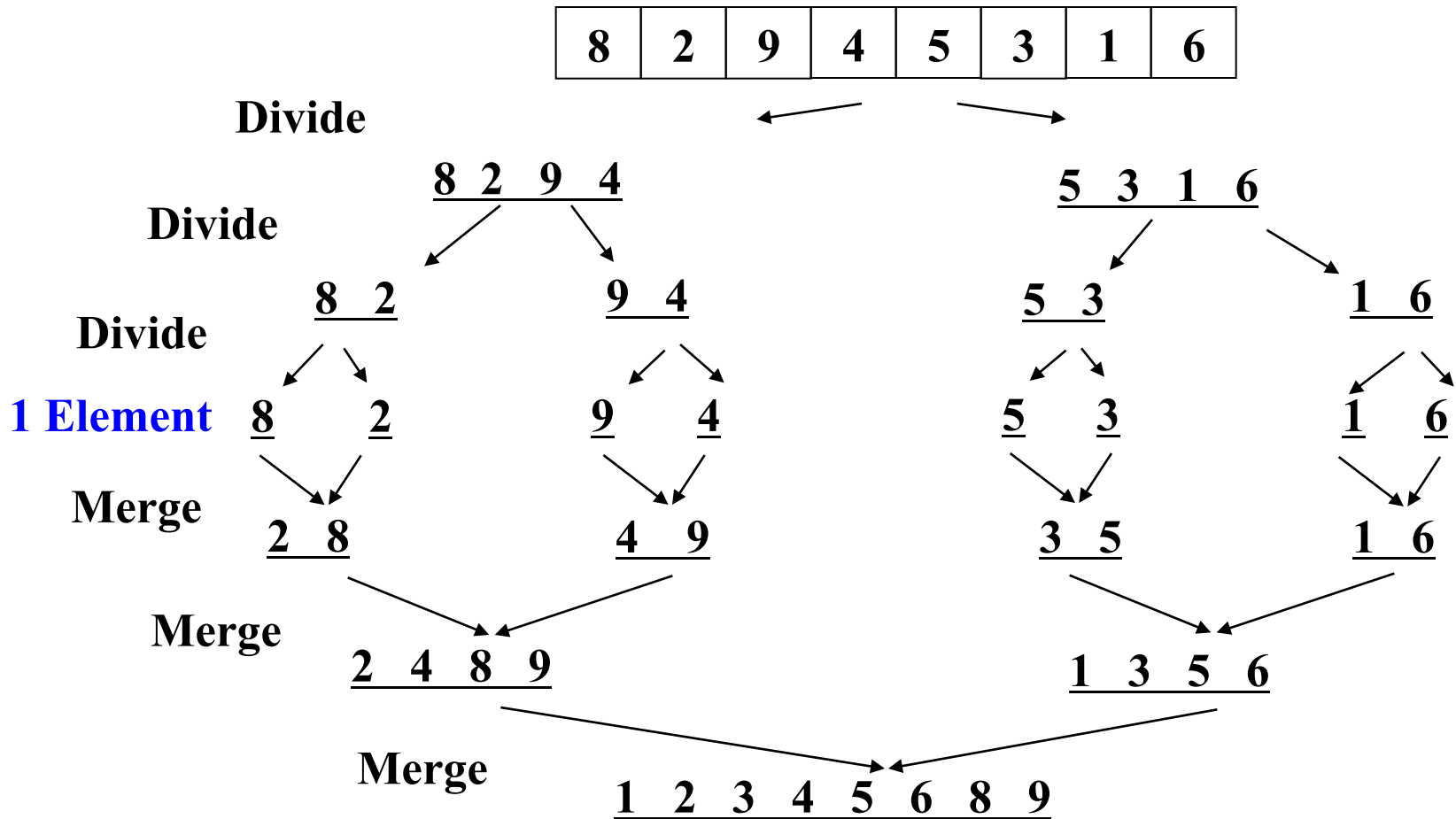
1	2	3	4	5	6	8	9
---	---	---	---	---	---	---	---



(After merge,  
copy back to  
original array)

1	2	3	4	5	6	8	9
---	---	---	---	---	---	---	---

# Example, Showing Recursion



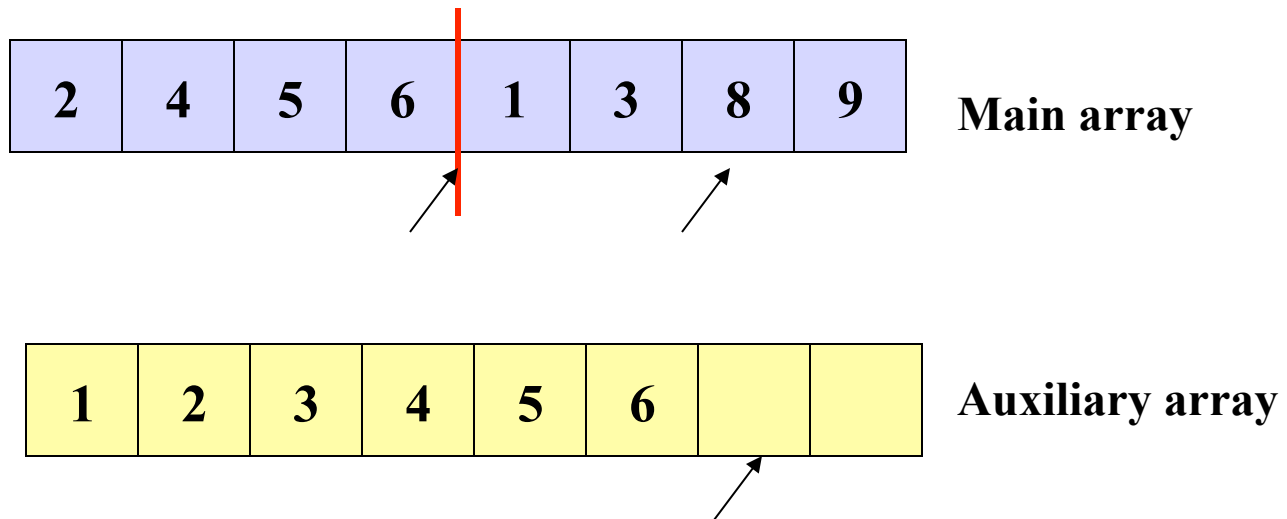


# *Merge sort visualization*

- <http://www.cs.usfca.edu/~galles/visualization/ComparisonSort.html>

## *Some details: saving a little time*

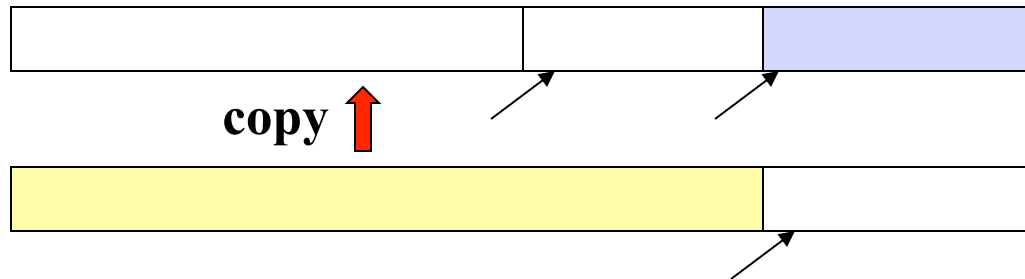
- What if the final steps of our merge looked like this:



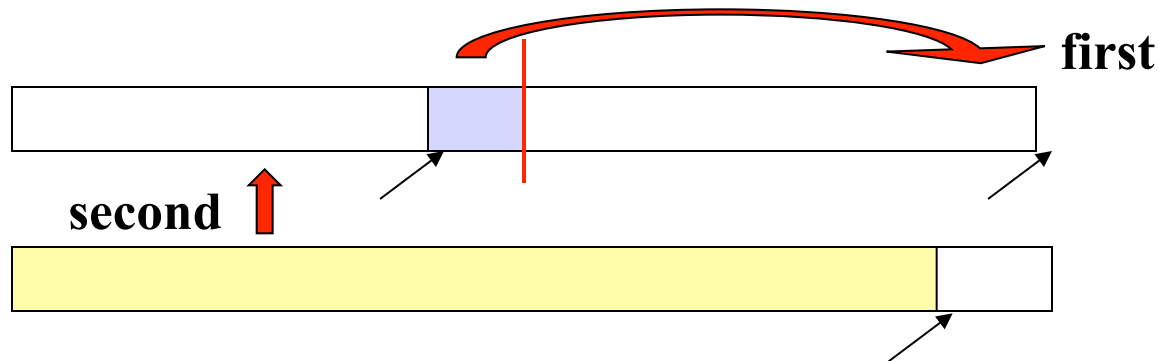
- Wasteful to copy to the auxiliary array just to copy back...

## *Some details: saving a little time*

- If left-side finishes first, just stop the merge and copy back:



- If right-side finishes first, copy drags into right then copy back



## *Some details: Saving Space and Copying*

Simplest / Worst:

Use a new auxiliary array of size  $(h_i - l_o)$  for every merge

Better:

Use a new auxiliary array of size  $n$  for every merging stage

Better:

Reuse same auxiliary array of size  $n$  for every merging stage

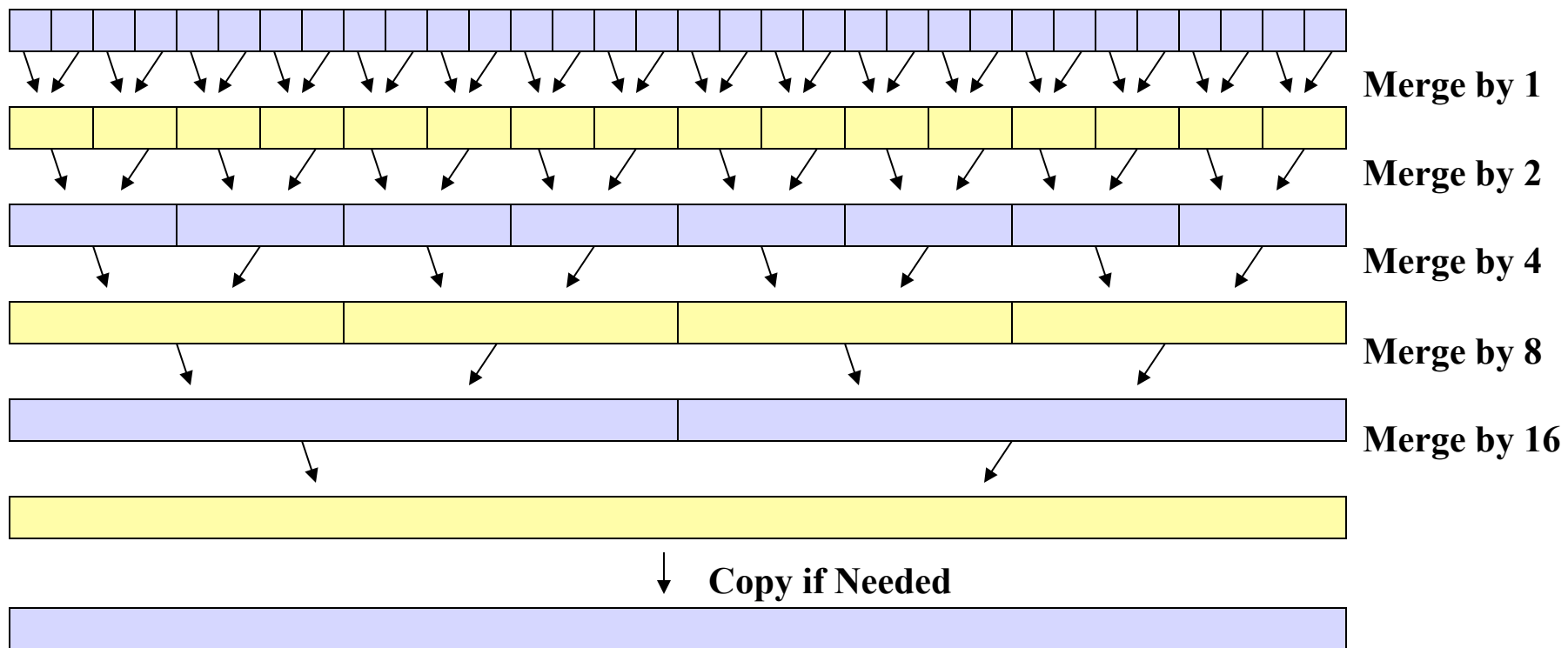
Best (but a little tricky):

Don't copy back – at 2<sup>nd</sup>, 4<sup>th</sup>, 6<sup>th</sup>, ... merging stages, use the original array as the auxiliary array and vice-versa

– Need one copy at end if number of stages is odd

# Swapping Original / Auxiliary Array (“best”)

- First recurse down to lists of size 1
- As we return from the recursion, swap between arrays



(Arguably easier to code up without recursion at all)

# *Linked lists and big data*

We defined sorting over an array, but sometimes you want to sort linked lists

One approach:

- Convert to array:  $O(n)$
- Sort:  $O(n \log n)$
- Convert back to list:  $O(n)$

Or merge sort works very nicely on linked lists directly

- Heapsort and quicksort do not
- Insertion sort and selection sort do but they're slower

Merge sort is also the sort of choice for external sorting

- Linear merges minimize disk accesses
- And can leverage multiple disks to get streaming accesses

# *Analysis*

Having defined an algorithm and argued it is correct, we should analyze its running time and space:

To sort  $n$  elements, we:

- Return immediately if  $n=1$
- Else do 2 subproblems of size  $n/2$  and then an  $O(n)$  merge

Recurrence relation:

$$T(1) = c_1$$

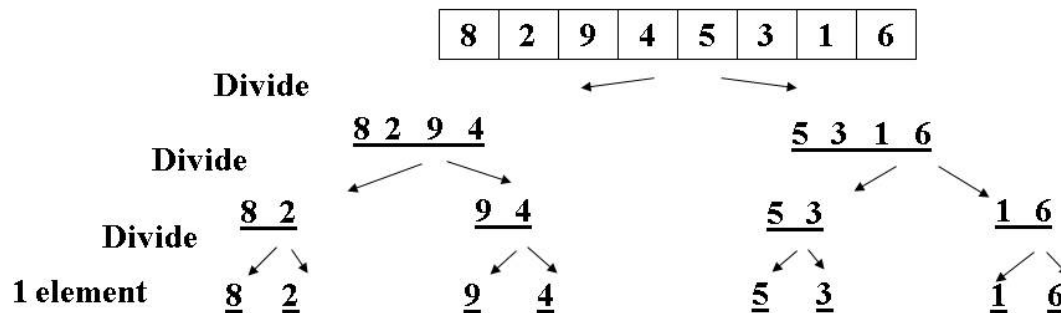
$$T(n) = 2T(n/2) + c_2n$$

# Analysis intuitively

This recurrence is common, you just “know” it’s  $O(n \log n)$

Merge sort is relatively easy to intuit (best, worst, and average):

- The recursion “tree” will have  $\log n$  height
- At each level we do a *total* amount of merging equal to  $n$





# *Analysis more formally*

*(One of the recurrence classics)*

For simplicity, ignore constants (let constants be )

$$T(1) = 1$$

$$T(n) = 2T(n/2) + n$$

$$= 2(2T(n/4) + n/2) + n$$

$$= 4T(n/4) + 2n$$

$$= 4(2T(n/8) + n/4) + 2n$$

$$= 8T(n/8) + 3n$$

....

$$= 2^k T(n/2^k) + kn$$

# *Analysis more formally*

*(One of the recurrence classics)*

For simplicity, ignore constants (let constants be )

$$T(1) = 1$$

$$T(n) = 2T(n/2) + n$$

$$= 2(2T(n/4) + n/2) + n$$

$$= 4T(n/4) + 2n$$

$$= 4(2T(n/8) + n/4) + 2n$$

$$= 8T(n/8) + 3n$$

....

$$= 2^k T(n/2^k) + kn$$

We will continue to recurse until we reach the base case, i.e.  $T(1)$   
for  $T(1)$ ,  $n/2^k = 1$ , i.e.,  $\log n = k$

So the total amount of work will be

$$= 2^k T(n/2^k) + kn = 2^{\log n} T(1) + n \log n = n + n \log n = O(n \log n)$$

## *Next lecture*

- Quick sort 😊