



# CSE373: Data Structures & Algorithms

## Lecture 28: Final review and class wrap-up

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# *Final Exam*

As also indicated on the web page:

- Bring your student ID
- Next **Tuesday**, 2:30-4:20 in this room
- Cumulative but topics post-midterm about 2/3 of the questions
- See information on course web-page
- Not unlike the midterms in style, structure, etc.

# *Terminology*

- **Abstract Data Type (ADT)**
  - Mathematical description of a “thing” with set of operations
  - Not concerned with implementation details
- **Algorithm**
  - A high level, language-independent description of a step-by-step process
- **Data structure**
  - A specific organization of data and family of algorithms for implementing an ADT
- **Implementation** of a data structure
  - A specific implementation in a specific language

# *Asymptotic and Algorithm Analysis*

1. Add up time for all parts of the algorithm  
e.g. number of iterations =  $(n^2 + n)/2$
2. Eliminate low-order terms i.e. eliminate  $n$ :  $(n^2)/2$
3. Eliminate coefficients i.e. eliminate  $1/2$ :  $(n^2)$

Examples:

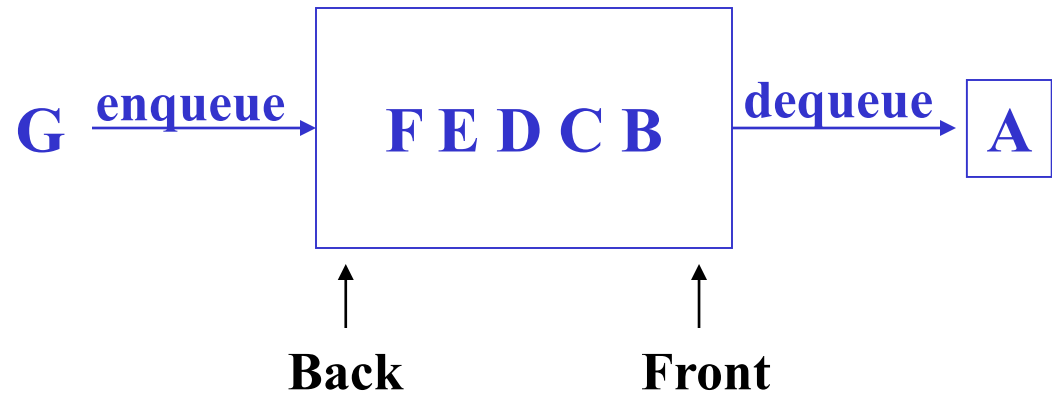
- $4n + 5$  =  $O(n)$
- $0.5n \log n + 2n + 7$  =  $O(n \log n)$
- $n^3 + 2^n + 3n$  =  $O(2^n)$
- $n \log(10n^2)$ 
  - $2n \log(10n)$  =  $O(n \log n)$

# *Amortized Analysis*

- In amortized analysis, the time required to perform a **sequence** of data structure operations is **averaged** over all the operations performed.
- Typically used to show that the **average** cost of an operation is small for a **sequence** of operations, even though a **single operation** can cost a lot

# The Queue ADT

- Operations  
`create`  
`destroy`  
`enqueue`  
`dequeue`  
`is_empty`



# The Stack ADT

Operations:

`create`

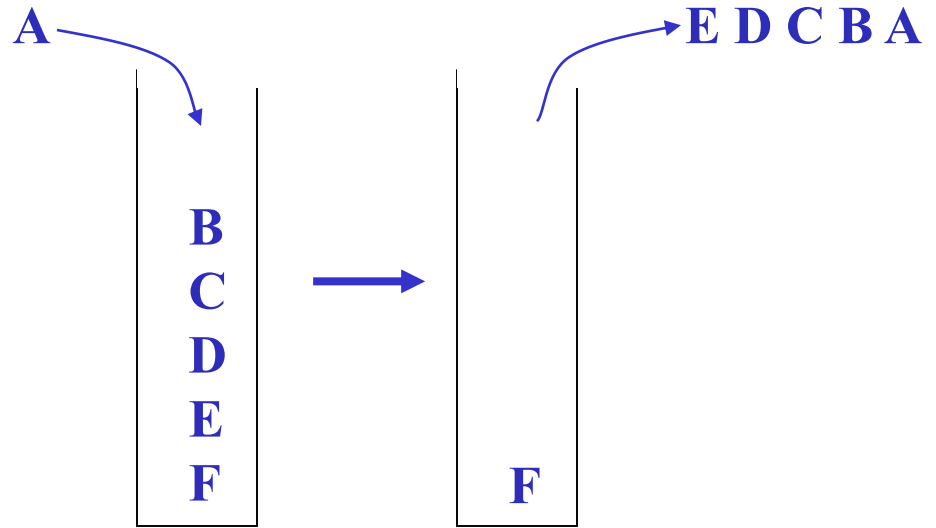
`destroy`

`push`

`pop`

`top`

`is_empty`



# The Dictionary (a.k.a. Map) ADT

- Data:
  - set of (key, value) pairs
  - keys must be comparable

- Operations:
  - `insert(key, value)`
  - `find(key)`
  - `delete(key)`
  - ...

`insert(catie, ...)` →

← `find(rama)`  
Rama Gokhale, ...

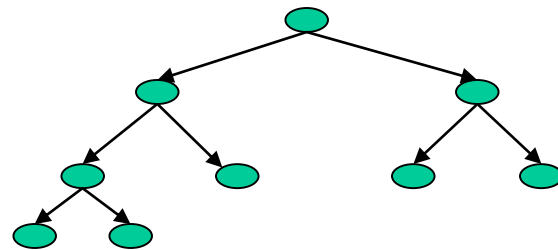
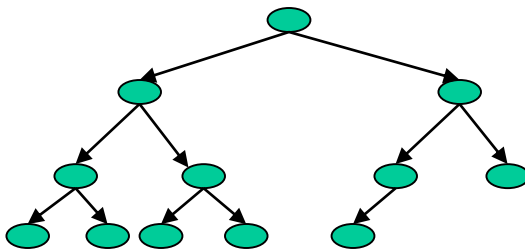
- **catie**  
Catie Baker  
OH: Wed 11.00-12.00  
...
- **rama**  
Rama Gokhale  
OH: Fri 3.30-4.30  
...
- **conrad**  
Conrad Nied  
OH: Wed 4:00-5:00  
...

*Will tend to emphasize the **keys**;  
don't forget about the stored values*



# Trees

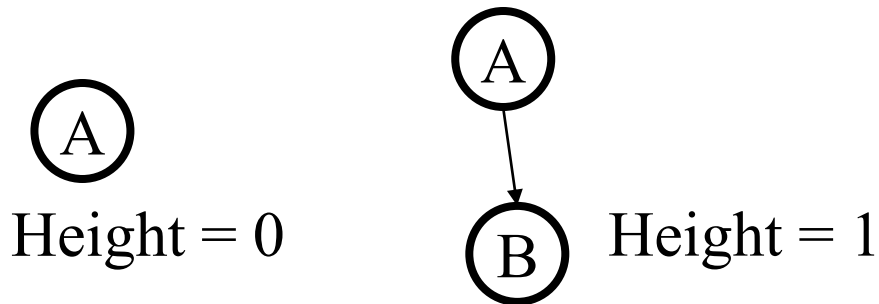
- **Binary tree:** Each node has at most 2 children (branching factor 2)
- **$n$ -ary tree:** Each node has at most  $n$  children (branching factor  $n$ )
- **Perfect tree:** Each row completely full
- **Complete tree:** Each row completely full except maybe the bottom row, which is filled from left to right



# Tree Calculations

Recall: **Height** of a tree is the **maximum** number of edges from the **root** to a **leaf**.

What is the **height** of this tree?

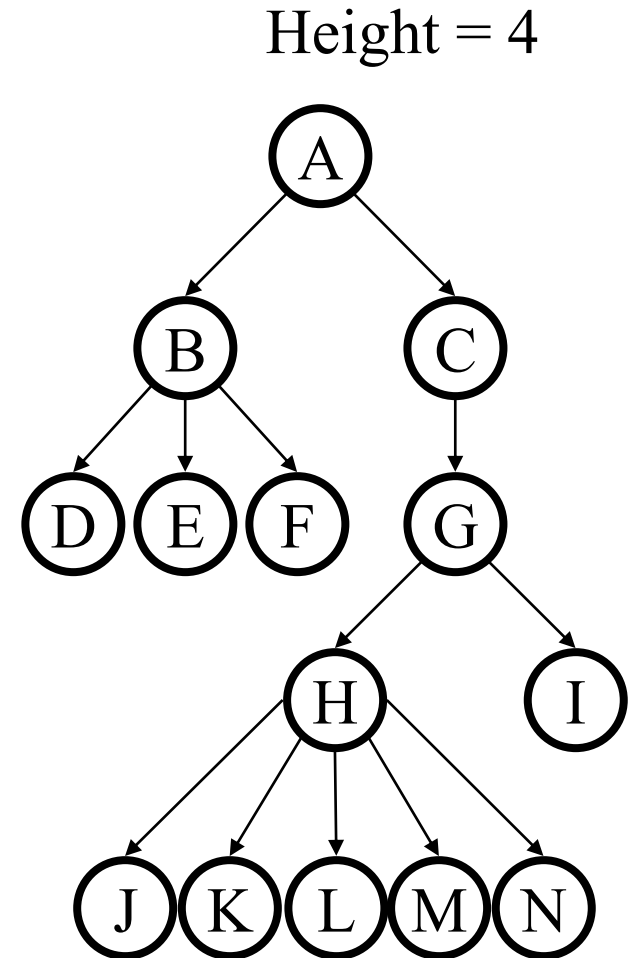


What is the **depth** of node G?

Depth = 2

What is the **depth** of node L?

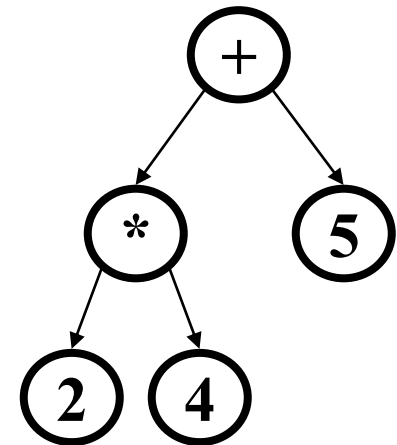
Depth = 4



# Tree Traversals

A *traversal* is an order for visiting all the nodes of a tree

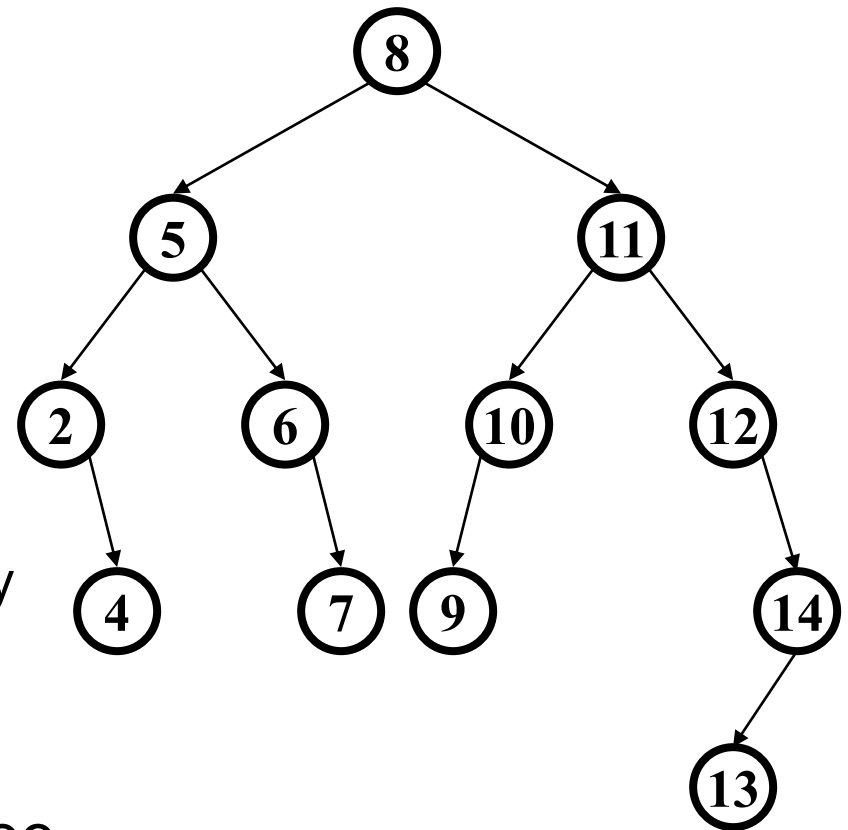
- *Pre-order*: root, left subtree, right subtree  
+ \* 2 4 5
- *In-order*: left subtree, root, right subtree  
2 \* 4 + 5
- *Post-order*: left subtree, right subtree, root  
2 4 \* 5 +



**(an expression tree)**

# Binary Search Tree (BST) Data Structure

- Structure property (binary tree)
  - Each node has  $\leq 2$  children
  - Result: keeps operations simple
- Order property
  - All keys in left subtree smaller than node's key
  - All keys in right subtree larger than node's key
  - Result: easy to find any given key
- Operations
  - Find, insert, delete, BuildTree



# The *AVL Tree* Data Structure

An AVL tree is a **self-balancing** binary search tree.

## *Structural properties*

1. **Binary tree** property (same as BST)
2. **Order** property (same as for BST)
3. **Balance** property:  
balance of every node is between -1 and 1

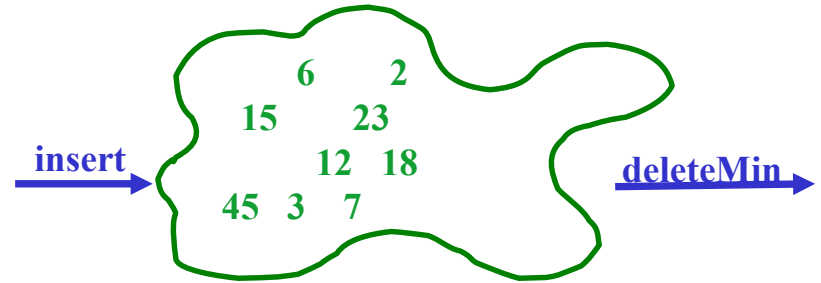
Result: **Worst-case** depth is  $O(\log n)$

- **Operations**

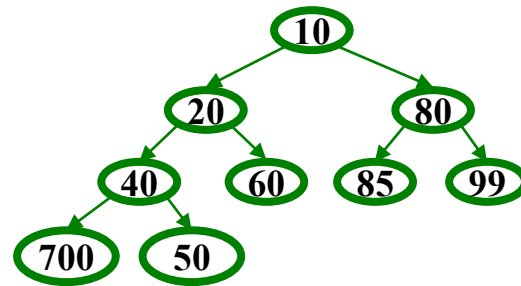
- **find**
- **insert**: First BST **insert**, *then* check balance and potentially “fix” the AVL tree (4 cases).

# Priority Queues and Binary Heaps

- Priority Queue ADT:
  - **insert** comparable object,
  - **deleteMin**



- Binary heap data structure:
  - Complete binary tree
  - Each node has less important priority value than its parent



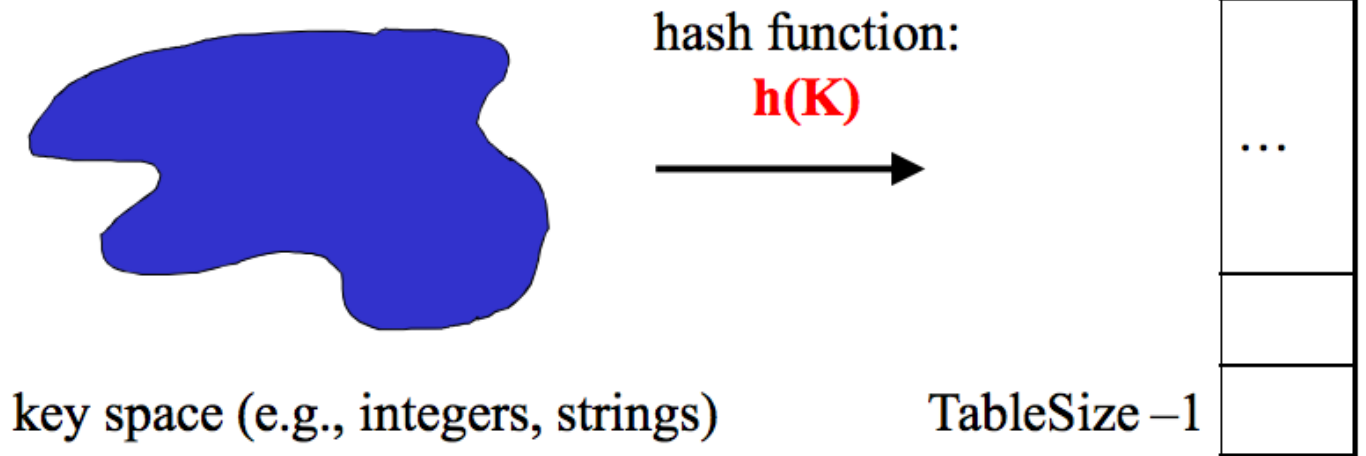
- **insert** and **deleteMin** operations =  $O(\text{height-of-tree}) = O(\log n)$ 
  - **insert**: put at new last position in tree and percolate-up
  - **deleteMin**: remove root, put last element at root and percolate-down

# Union-Find ADT

- Given an unchanging set  $S$ , **create** an initial partition of a set
  - Typically each item in its own subset:  $\{a\}$ ,  $\{b\}$ ,  $\{c\}$ , ...
  - Give each subset a “name” by choosing a *representative element*
- Operations
  - **find** takes an element of  $S$  and returns the representative element of the subset it is in
  - **union** takes two subsets and (permanently) makes one larger subset
- Up-tree data structure
  - With path compression and union by size

# Hash Tables

- Constant time accesses!
- A **hash table** is an array of some fixed size, usually a prime number.
- General idea:



- Collision: when two keys map to the same location in the hash table.
- Two ways to resolve collision:
  - Separate chaining
  - Open Addressing (linear probing, quadratic probing, double hashing.)



# *Memory Locality*

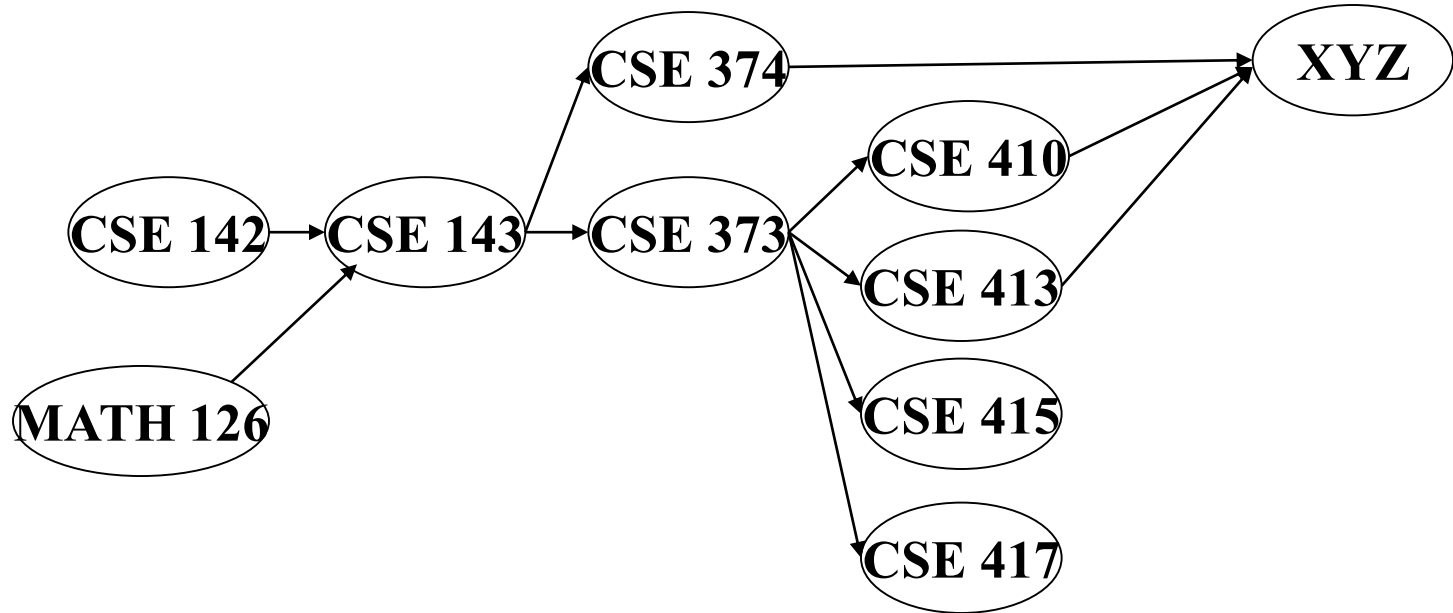
- **Temporal Locality** (locality in time)
  - If an item (a location in memory) is referenced, **that same location** will tend to be referenced again soon.
- **Spatial Locality** (locality in space)
  - If an item is referenced, items **whose addresses are close by** tend to be referenced soon.

# *Graphs*

- Vertex, node, edge
- Directed, undirected
- Weighted, unweighted
- Connected, disconnected, strongly/weakly connected
- Paths, cycles
- DAGs
  
- Adjacency lists and matrices

# Topological Sort

Problem: Given a DAG  $G = (V, E)$ , output all vertices in an order such that no vertex appears before another vertex that has an edge to it



One example output:

126, 142, 143, 374, 373, 417, 410, 413, XYZ, 415

# Graph Traversals

For an arbitrary graph and a starting node  $v$ , find all nodes *reachable* from  $v$  (i.e., there exists a path from  $v$ )

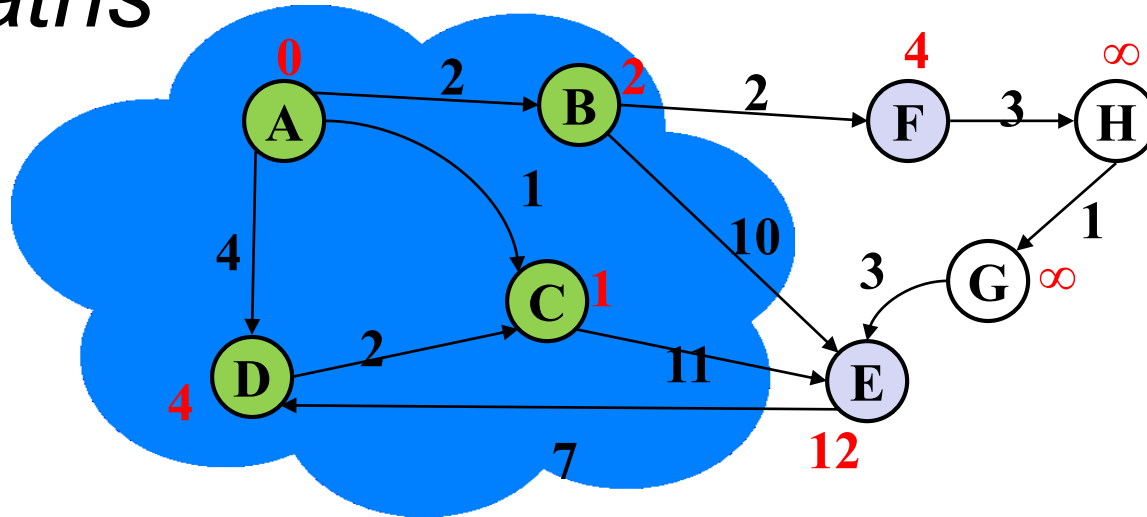
Basic idea:

- Keep following nodes
- But “mark” nodes after visiting them, so the traversal terminates and processes each reachable node exactly once

Important Graph traversal algorithms:

- “Depth-first search” “DFS”: recursively explore one part before going back to the other parts not yet explored
- “Breadth-first search” “BFS”: explore areas closer to the start node first

# Dijkstra's Algorithm: Lowest cost paths



- Initially, start node has cost 0 and all other nodes have cost  $\infty$
- At each step:
  - Pick closest unknown vertex  $v$
  - Add it to the “cloud” of known vertices
  - Update distances for nodes with edges from  $v$
- That's it!

# Minimum Spanning Trees

The **minimum-spanning-tree problem**

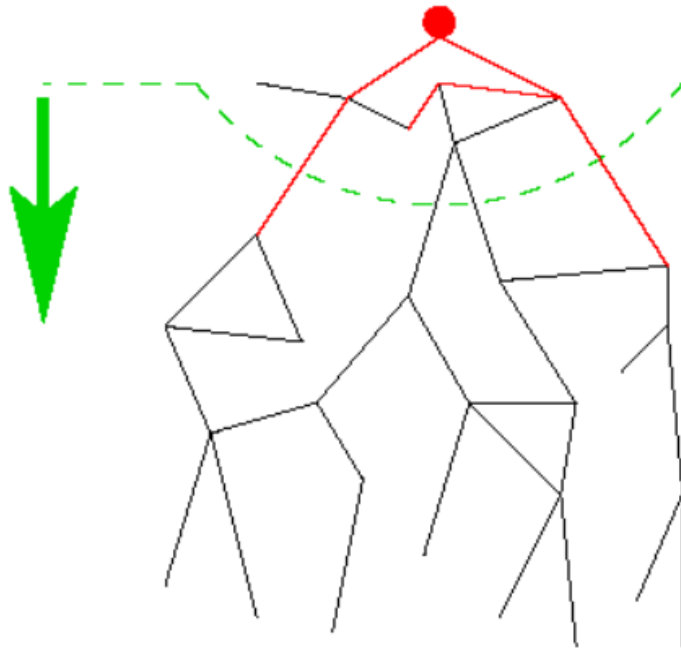
- Given a weighted undirected graph, compute a spanning tree of minimum weight

Given an undirected graph  $G=(V, E)$ , find a graph  $G'=(V, E')$  such that:

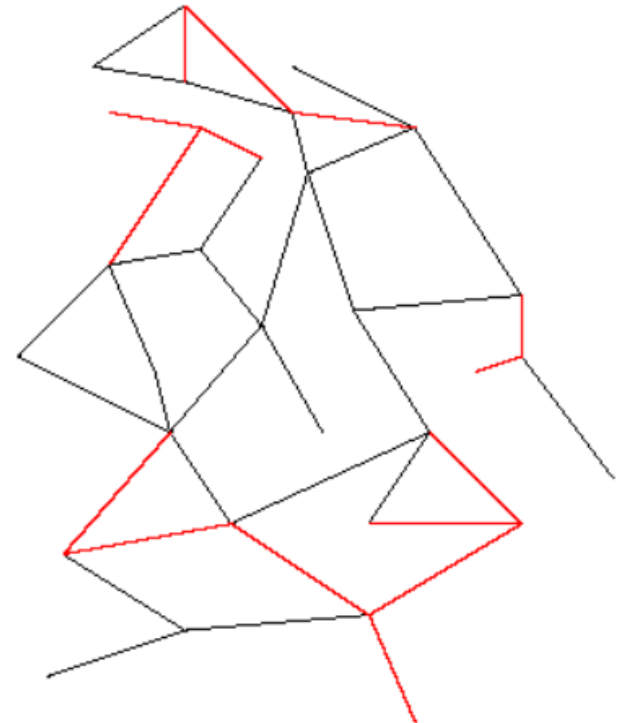
- $E'$  is a subset of  $E$
- $|E'| = |V| - 1$
- $G'$  is connected

**$G'$  is a minimum spanning tree.**

# Two different approaches



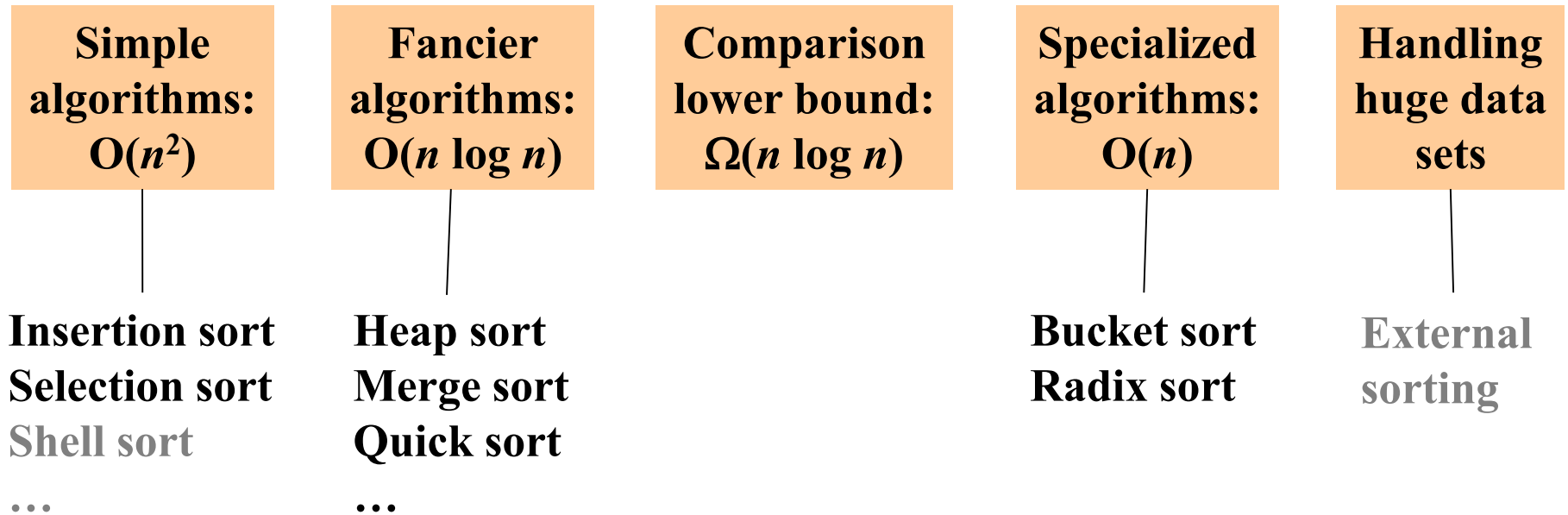
**Prim's Algorithm**  
**Almost identical to Dijkstra's**



**Kruskals's Algorithm**  
**Completely different!**

# Sorting: The Big Picture

Surprising amount of neat stuff to say about sorting:





# *Preserving Abstractions*

- Need to deep-copy data passed into abstractions to avoid pain and suffering
- Need to deep-copy data passed out of abstractions to avoid pain and suffering (unless data is “new” or no longer used in abstraction)
- If objects are immutable (no way to update fields or things they refer to), then copying unnecessary

# *Algorithm Design Techniques*

- Greedy (Shortest path, minimum spanning tree, ...)
- Divide and Conquer
  - Divide the problem into smaller subproblems, solve them, and combine into the overall solution
  - Often done recursively
  - Quick sort, merge sort are great examples
- Dynamic Programming
  - Brute force through all possible solutions, storing solutions to subproblems to avoid repeat computation
- Backtracking (A clever form of exhaustive search)
- P vs. NP (Know what it means for an algorithm to be in NP, in P.)
- Parallelism
  - Use threads to split work among many processors.

*Phew! That's it.*

- Good luck 😊

# *Victory Lap*

A victory lap is an extra trip  
around the track

- By the exhausted victors  
(that's us) 😊

Review course goals

- Slides from Lecture 1
- What makes CSE 373 special

# *Thank you!*

Big thank-you to your TAs

- Amazingly cohesive “big team”
- Prompt grading and question-answering
- Optional TA sessions weren’t optional for them!



**Conrad Nied**



**Yunyi Song**



**Andy Li**



**Rama Gokhale**



**Luyi Lu**



**Cyndi Ai**



**Johnson Goh**

# *Thank you!*

And huge thank you to all of **you**

- Great attitude
- Showed up to class (most of the time)
- Occasionally laughed at stuff 😊

Now a few slides from Lecture 1

- Hopefully they make more sense now
- Hopefully we succeeded

# *Data Structures*

- Introduction to Algorithm Analysis
- Lists, Stacks, Queues
- Trees, Hashing, Dictionaries
- Heaps, Priority Queues
- Sorting
- Disjoint Sets
- Graph Algorithms
- Introduction to Parallelism and Concurrency



# Goals

- Be able to **make good design choices** as a developer, project manager, etc.
  - Reason in terms of the general abstractions that come up in all non-trivial software (and many non-software) systems
- Be able to **justify** and **communicate** your design decisions

*You will learn the key abstractions used almost every day in just about anything related to computing and software.*

- This is not a course about Java! We use Java as a tool, but the data structures you learn about can be implemented in any language.

# *Last slide*

I had a lot of fun and learned a great deal this quarter.

You have learned the key ideas for organizing data, a skill that far transcends computer science.