



# CSE373: Data Structures & Algorithms

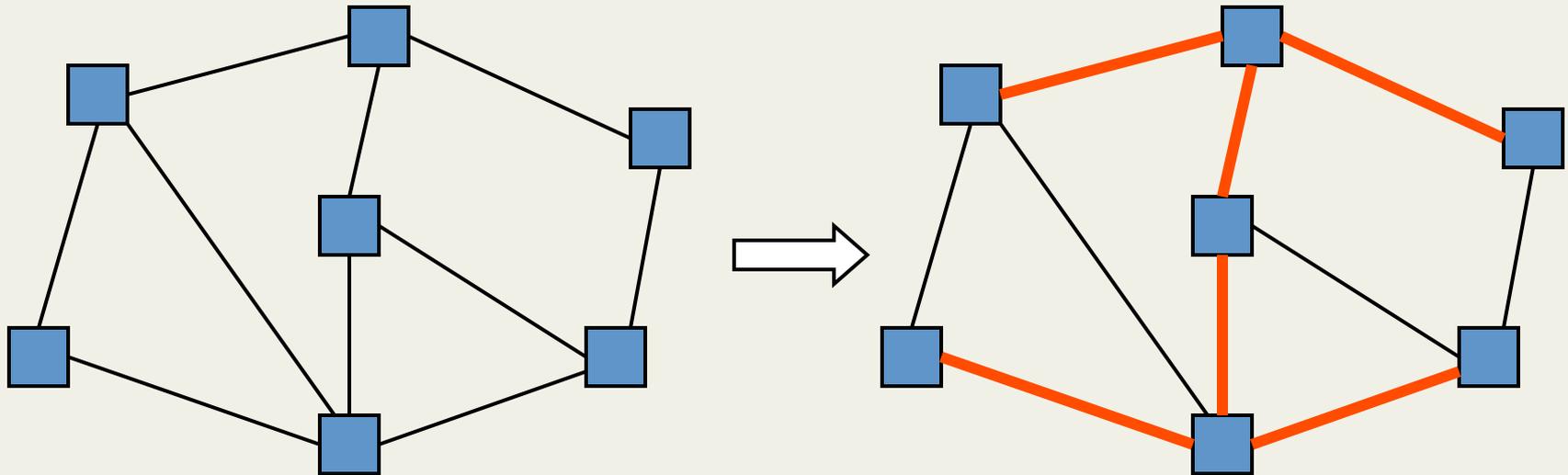
## Lecture 17: Minimum Spanning Trees

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# Spanning Trees

- A simple problem: Given a *connected* undirected graph  $\mathbf{G}=(\mathbf{V},\mathbf{E})$ , find a minimal subset of edges such that  $\mathbf{G}$  is still connected
  - A graph  $\mathbf{G2}=(\mathbf{V},\mathbf{E2})$  such that  $\mathbf{G2}$  is connected and removing any edge from  $\mathbf{E2}$  makes  $\mathbf{G2}$  disconnected



# Observations

1. Any solution to this problem is a tree
  - Recall a tree does not need a root; just means acyclic
  - For any cycle, could remove an edge and still be connected
2. Solution not unique unless original graph was already a tree
3. Problem ill-defined if original graph not connected
  - So  $|E| \geq |V|-1$
4. A tree with  $|V|$  nodes has  $|V|-1$  edges
  - So every solution to the spanning tree problem has  $|V|-1$  edges

# Motivation

A **spanning tree** connects all the nodes with as few edges as possible

- Example: A “phone tree” so everybody gets the message and no unnecessary calls get made
  - Bad example since would prefer a balanced tree

In most compelling uses, we have a *weighted* undirected graph and we want a tree of least total cost

- Example: Electrical wiring for a house or clock wires on a chip
- Example: A road network if you cared about asphalt cost rather than travel time

This is the **minimum spanning tree** problem

- Will do that next, after intuition from the simpler case

# *Two Approaches*

Different algorithmic approaches to the spanning-tree problem:

1. Do a graph traversal (e.g., depth-first search, but any traversal will do), keeping track of edges that form a tree
2. Iterate through edges; add to output any edge that does not create a cycle

# Spanning tree via DFS

```
spanning_tree(Graph G) {
    for each node i: i.marked = false
    for some node i: f(i)
}

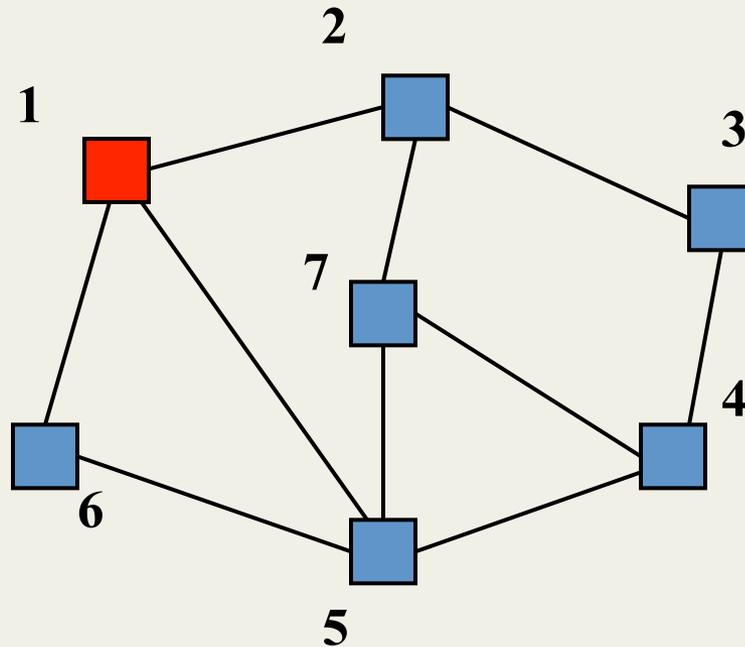
f(Node i) {
    i.marked = true
    for each j adjacent to i:
        if(!j.marked) {
            add(i,j) to output
            f(j) // DFS
        }
}
```

Correctness: DFS reaches each node. We add one edge to connect it to the already visited nodes. Order affects result, not correctness.

Time:  $O(|E|)$

# Example

Stack  
f(1)



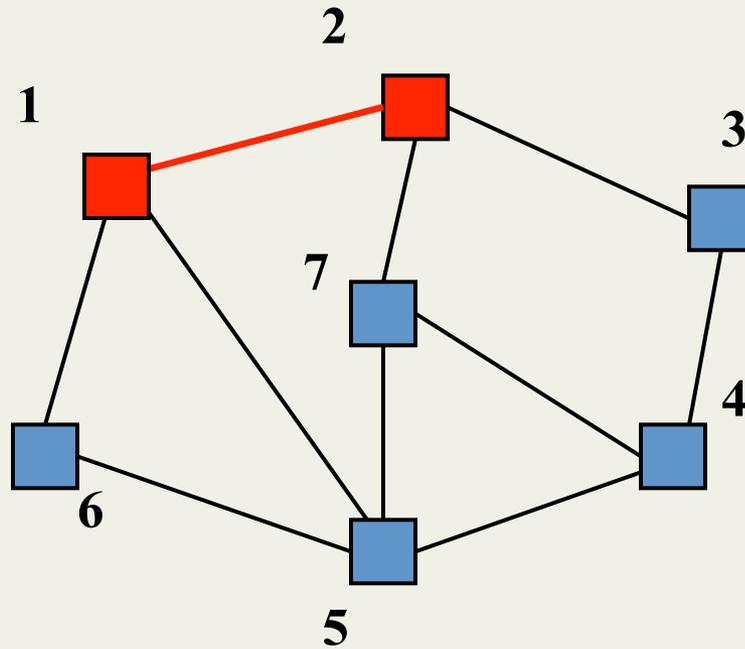
Output:

# Example

Stack (bottom)

f(1)

f(2)



Output: (1,2)

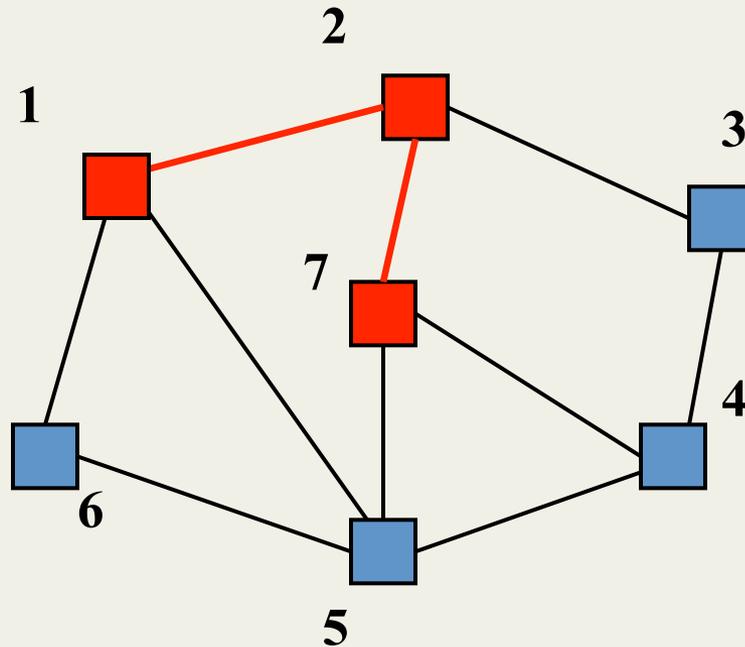
# Example

Stack (bottom)

f(1)

f(2)

f(7)



Output: (1,2), (2,7)

# Example

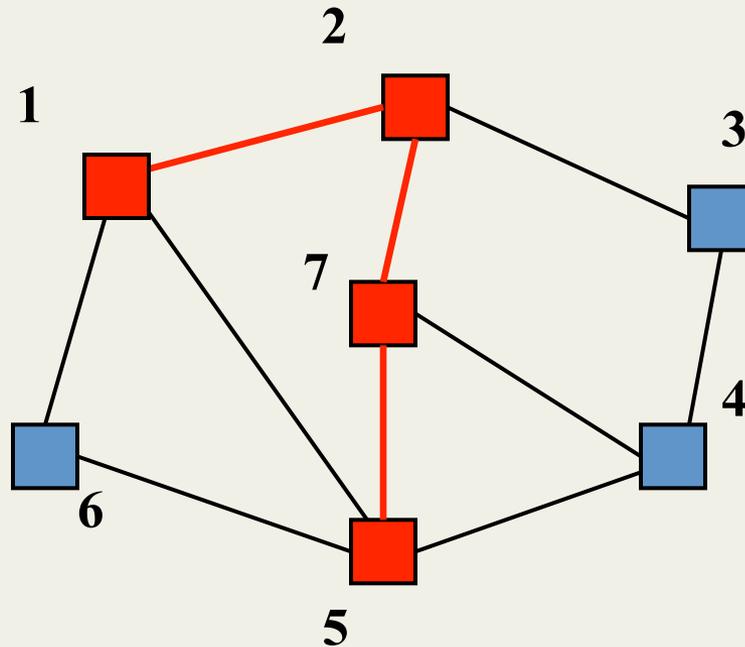
Stack (bottom)

f(1)

f(2)

f(7)

f(5)



Output: (1,2), (2,7), (7,5)

# Example

Stack (bottom)

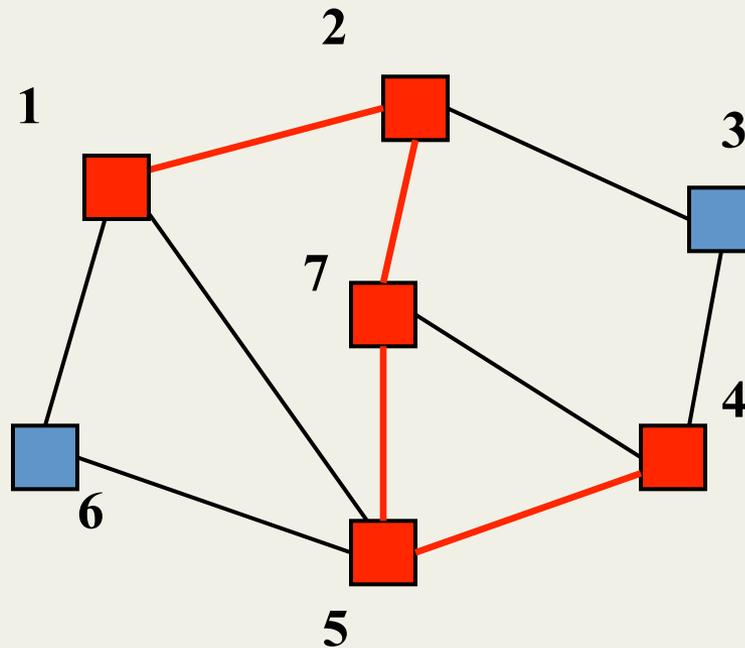
f(1)

f(2)

f(7)

f(5)

f(4)



Output: (1,2), (2,7), (7,5), (5,4)

# Example

Stack (bottom)

f(1)

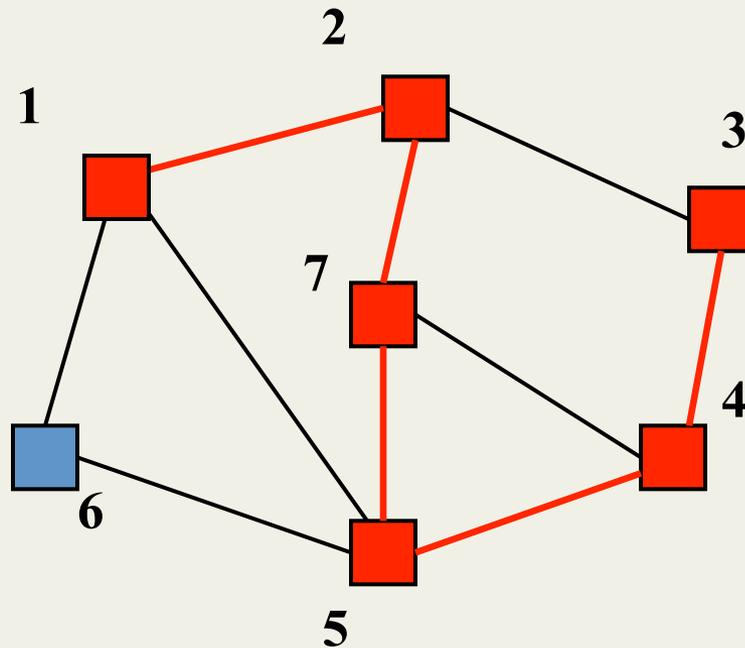
f(2)

f(7)

f(5)

f(4)

f(3)



Output: (1,2), (2,7), (7,5), (5,4),(4,3)

# Example

Stack (bottom)

f(1)

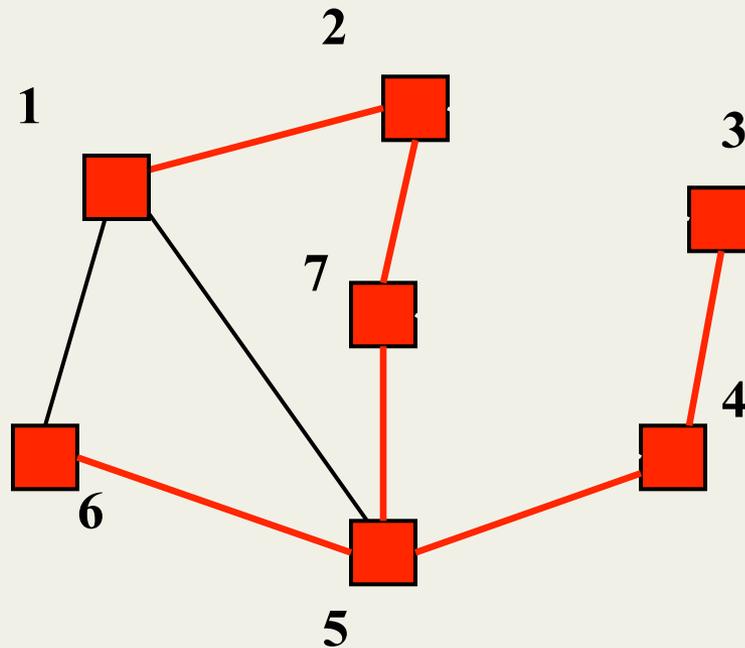
f(2)

f(7)

f(5)

f(4) f(6)

f(3)



Output: (1,2), (2,7), (7,5), (5,4), (4,3), (5,6)

# Example

Stack (bottom)

f(1)

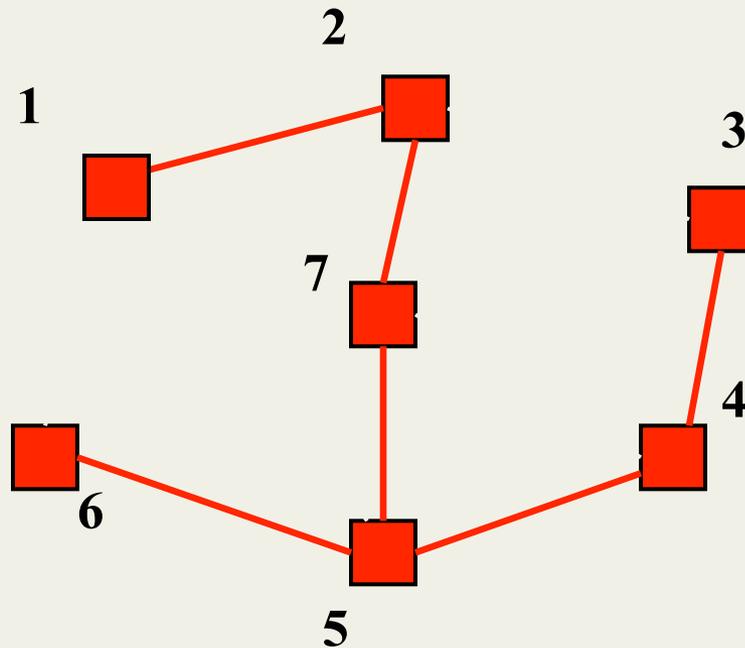
f(2)

f(7)

f(5)

f(4) f(6)

f(3)



Output: (1,2), (2,7), (7,5), (5,4), (4,3), (5,6)

## *Second Approach*

Iterate through edges; output any edge that does not create a cycle

Correctness (hand-wavy):

- Goal is to build an acyclic connected graph
- When we add an edge, it adds a vertex to the tree
  - Else it would have created a cycle
- The graph is connected, so we reach all vertices

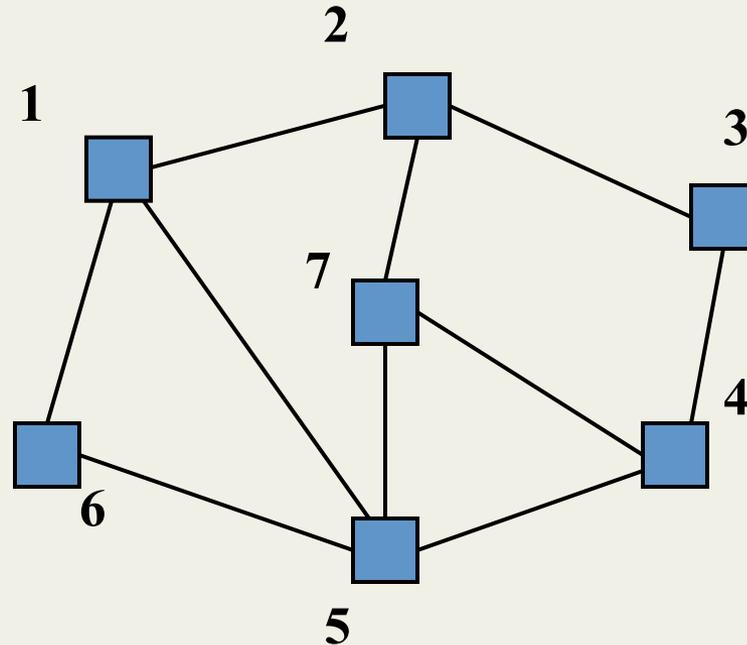
Efficiency:

- Depends on how quickly you can detect cycles
- Reconsider after the example

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

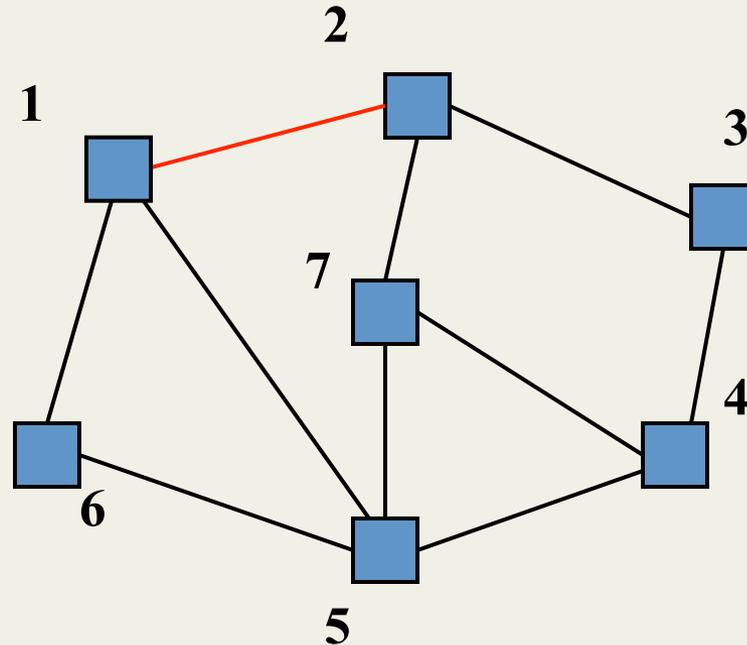


Output:

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

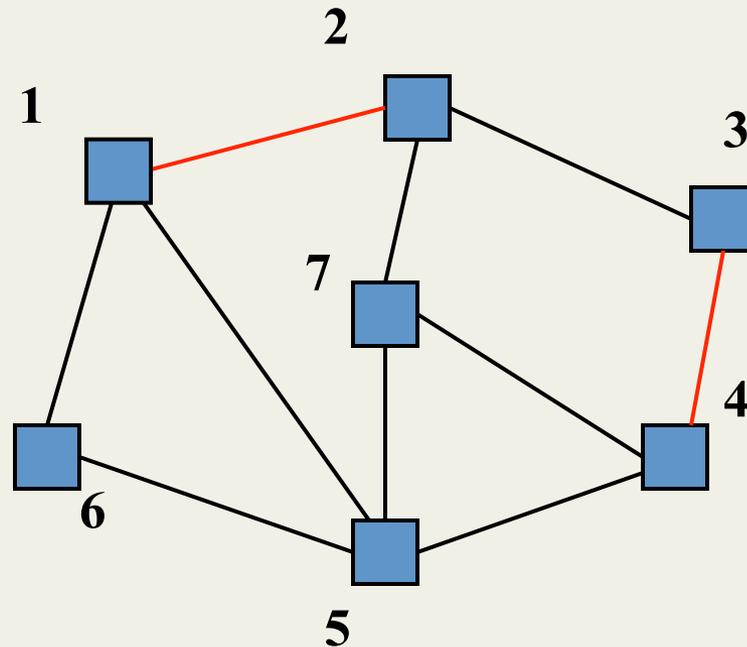


Output: (1,2)

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

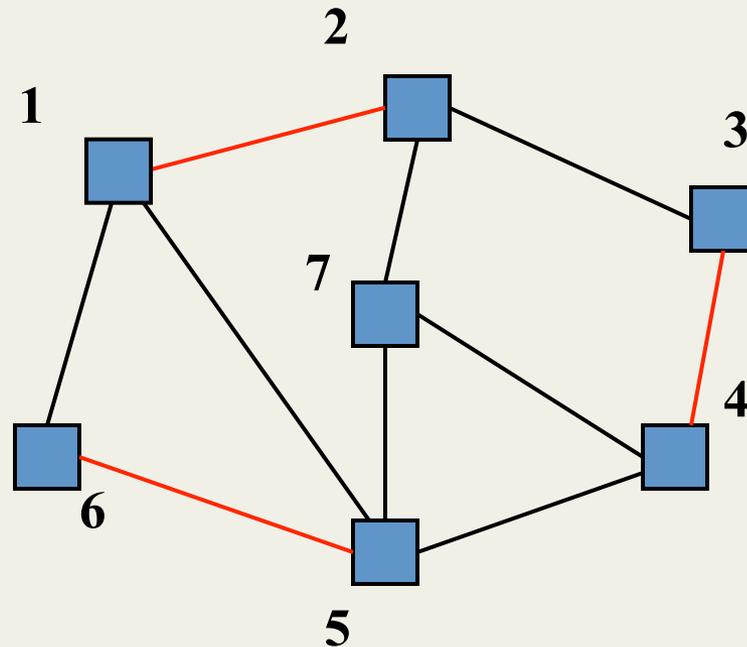


Output: (1,2), (3,4)

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

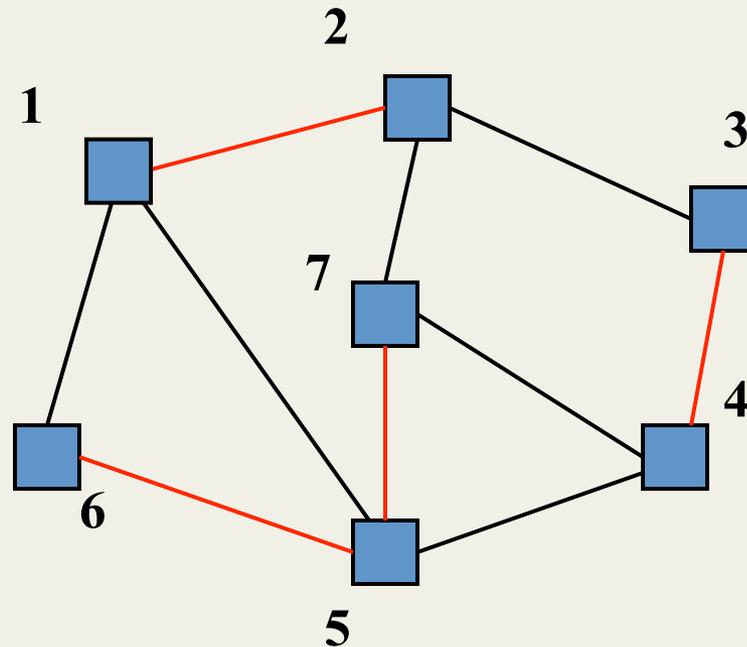


Output: (1,2), (3,4), (5,6),

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

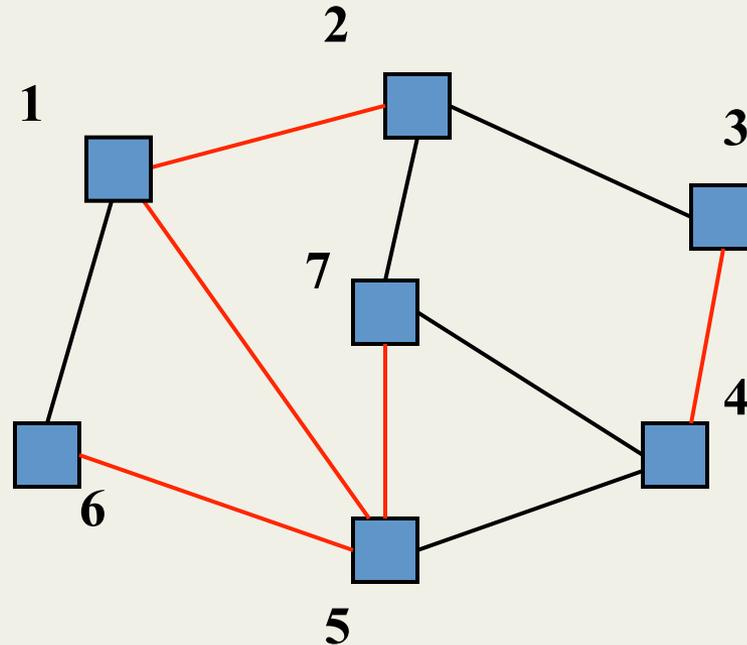


Output: (1,2), (3,4), (5,6), (5,7)

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

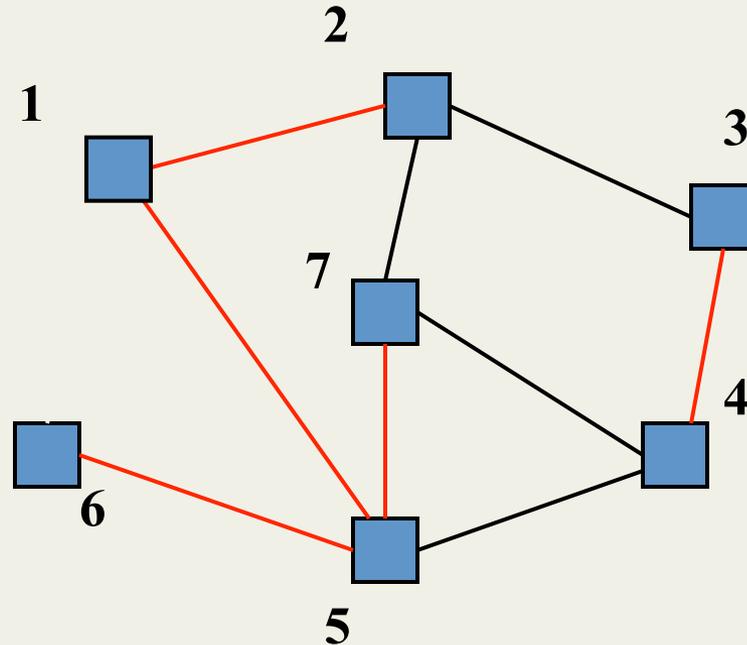


Output: (1,2), (3,4), (5,6), (5,7), (1,5)

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

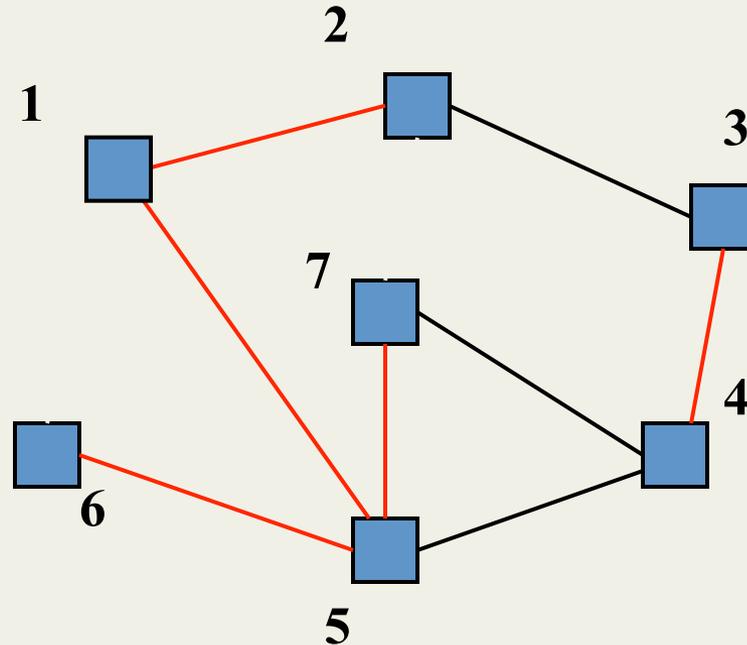


Output: (1,2), (3,4), (5,6), (5,7), (1,5)

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)

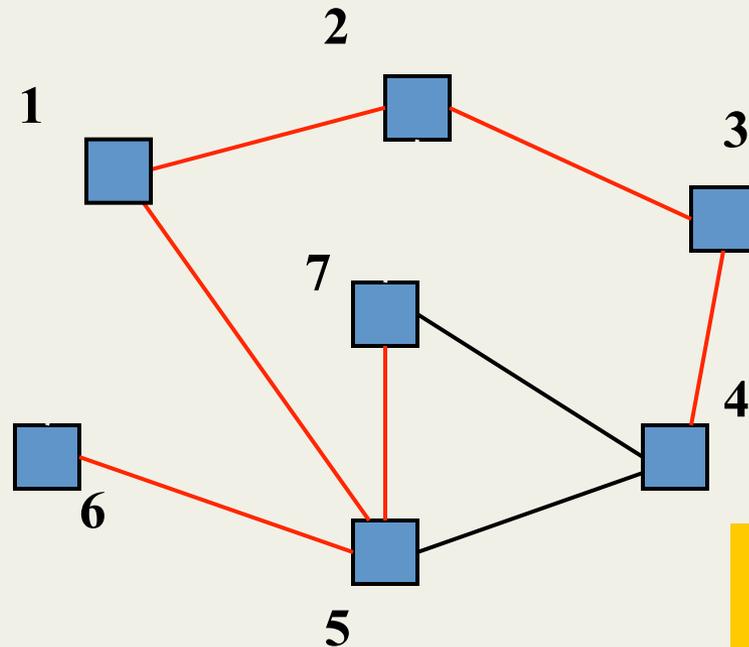


Output: (1,2), (3,4), (5,6), (5,7), (1,5)

# Example

Edges in some arbitrary order:

(1,2), (3,4), (5,6), (5,7), (1,5), (1,6), (2,7), (2,3), (4,5), (4,7)



Can stop once we have  $|V|-1$  edges

Output: (1,2), (3,4), (5,6), (5,7), (1,5), (2,3)

# *Cycle Detection*

- To decide if an edge could form a cycle is  $O(|V|)$  because we may need to traverse all edges already in the output
- So overall algorithm would be  $O(|V||E|)$
- But there is a faster way we know: use union-find!
  - Initially, each item is in its own 1-element set
  - Union sets when we add an edge that connects them
  - Stop when we have one set

# Using Disjoint-Set

Can use a disjoint-set implementation in our spanning-tree algorithm to detect cycles:

Invariant:  $u$  and  $v$  are connected in output-so-far  
iff  
 $u$  and  $v$  in the same set

- Initially, each node is in its own set
- When processing edge  $(u, v)$ :
  - If  $\text{find}(u)$  equals  $\text{find}(v)$ , then do not add the edge
  - Else add the edge and  $\text{union}(\text{find}(u), \text{find}(v))$
  - $O(|E|)$  operations that are almost  $O(1)$  amortized

# Summary So Far

## The **spanning-tree problem**

- Add nodes to partial tree approach is  $O(|E|)$
- Add acyclic edges approach is *almost*  $O(|E|)$ 
  - Using union-find “as a black box”

## But really want to solve the **minimum-spanning-tree problem**

- Given a weighted undirected graph, give a spanning tree of minimum weight
- Same two approaches will work with minor modifications
- Both will be  $O(|E| \log |V|)$

# Getting to the Point

## Algorithm #1

Shortest-path is to Dijkstra's Algorithm  
as

Minimum Spanning Tree is to [Prim's Algorithm](#)

(Both based on expanding cloud of known vertices, basically using  
a priority queue instead of a DFS stack)

## Algorithm #2

[Kruskal's Algorithm](#) for Minimum Spanning Tree  
is

Exactly our 2<sup>nd</sup> approach to spanning tree  
but process edges in cost order

# Prim's Algorithm Idea

Idea: Grow a tree by adding an edge from the “known” vertices to the “unknown” vertices. *Pick the edge with the smallest weight that connects “known” to “unknown.”*

Recall Dijkstra “picked edge with closest known distance to source”

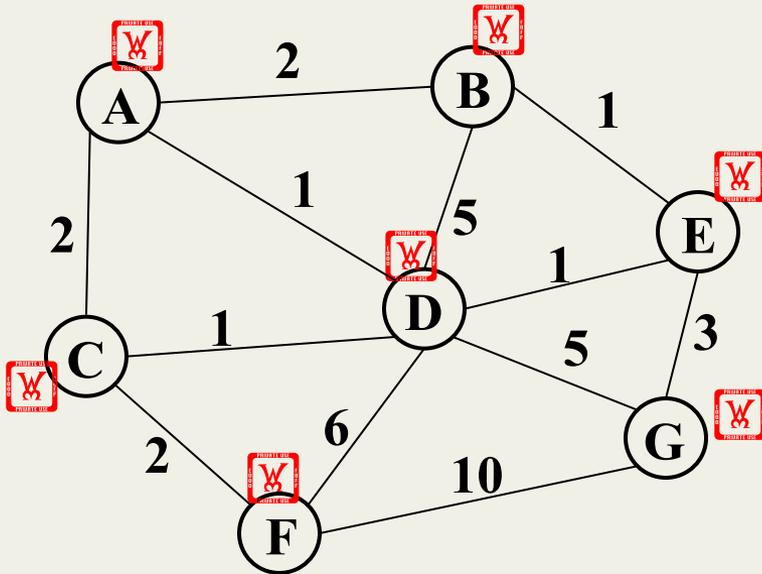
- That is not what we want here
- Otherwise identical (!)

# The Algorithm

1. For each node  $v$ , set  $v.cost = \infty$  and  $v.known = false$
2. Choose any node  $v$ 
  - a) Mark  $v$  as known
  - b) For each edge  $(v, u)$  with weight  $w$ , set  $u.cost = w$  and  $u.prev = v$
3. While there are unknown nodes in the graph
  - a) Select the unknown node  $v$  with lowest cost
  - b) Mark  $v$  as known and add  $(v, v.prev)$  to output
  - c) For each edge  $(v, u)$  with weight  $w$ ,

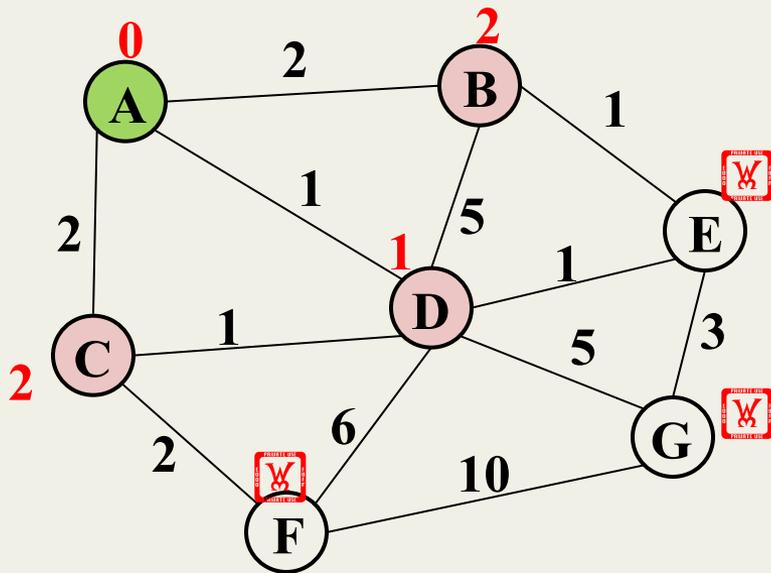
```
        if(w < u.cost) {
            u.cost = w;
            u.prev = v;
        }
```

# Example



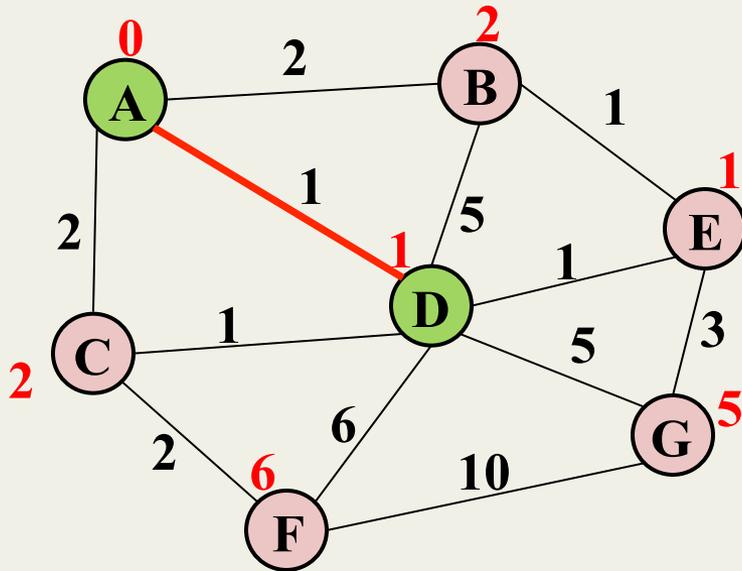
vertex	known?	cost	prev
A		??	
B		??	
C		??	
D		??	
E		??	
F		??	
G		??	

# Example



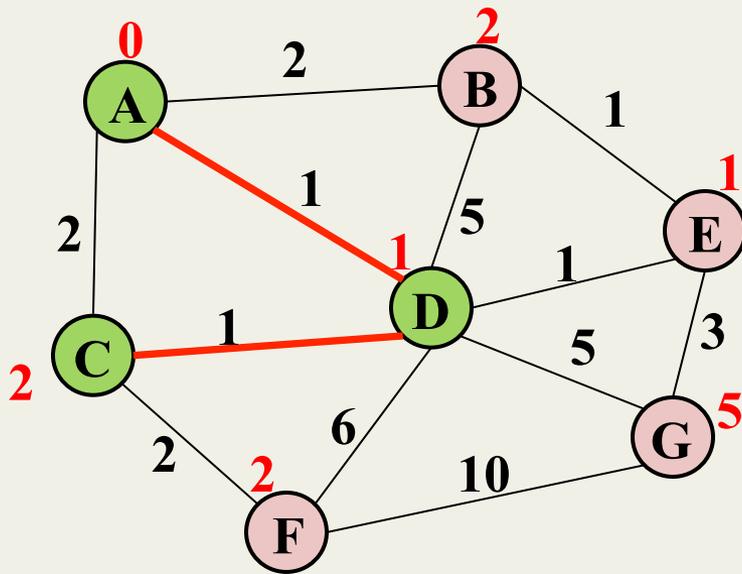
vertex	known?	cost	prev
A	Y	0	
B		2	A
C		2	A
D		1	A
E		??	
F		??	
G		??	

# Example



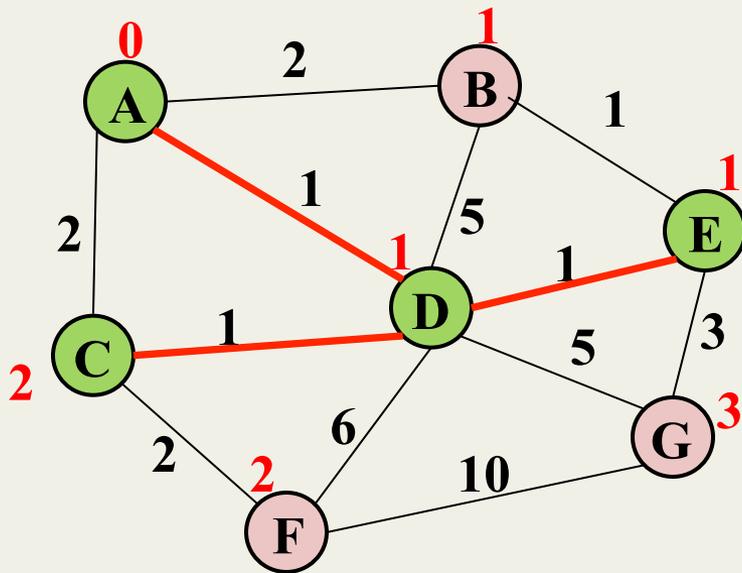
vertex	known?	cost	prev
A	Y	0	
B		2	A
C		1	D
D	Y	1	A
E		1	D
F		6	D
G		5	D

# Example



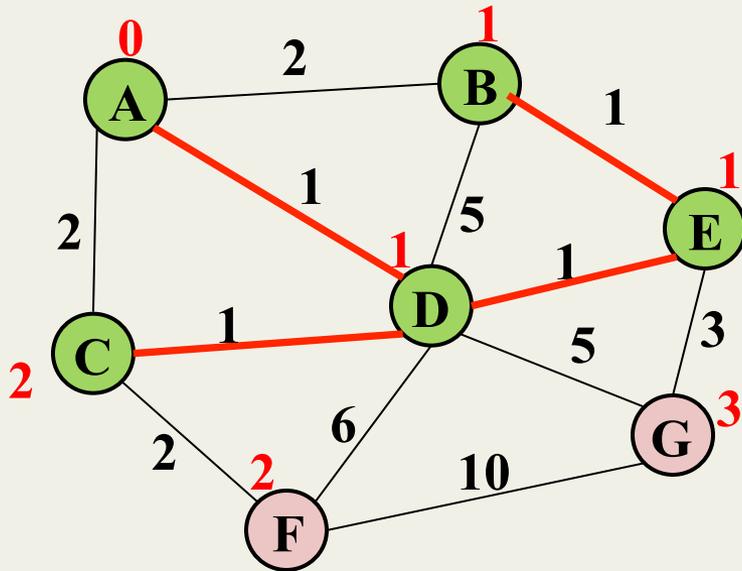
vertex	known?	cost	prev
A	Y	0	
B		2	A
C	Y	1	D
D	Y	1	A
E		1	D
F		2	C
G		5	D

# Example



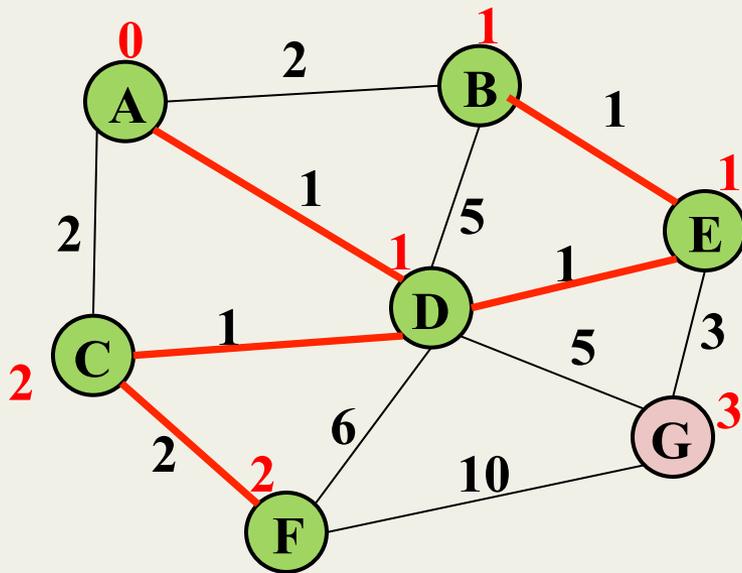
vertex	known?	cost	prev
A	Y	0	
B		1	E
C	Y	1	D
D	Y	1	A
E	Y	1	D
F		2	C
G		3	E

# Example



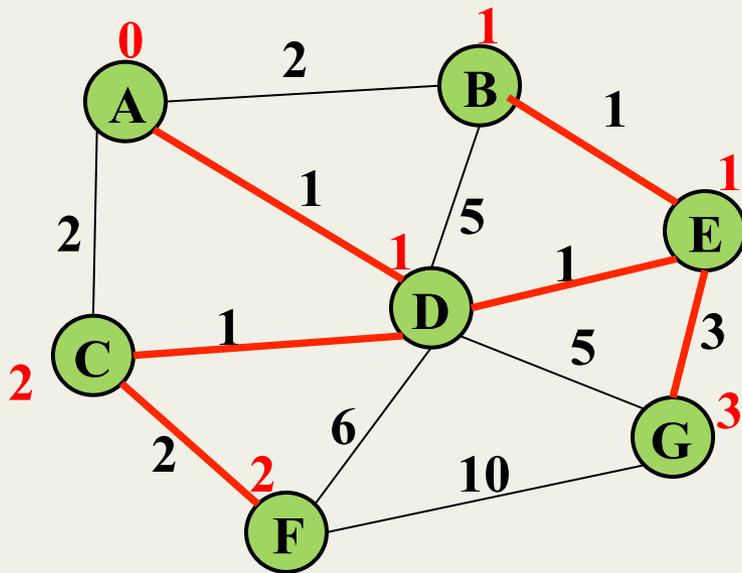
vertex	known?	cost	prev
A	Y	0	
B	Y	1	E
C	Y	1	D
D	Y	1	A
E	Y	1	D
F		2	C
G		3	E

# Example



vertex	known?	cost	prev
A	Y	0	
B	Y	1	E
C	Y	1	D
D	Y	1	A
E	Y	1	D
F	Y	2	C
G		3	E

# Example



vertex	known?	cost	prev
A	Y	0	
B	Y	1	E
C	Y	1	D
D	Y	1	A
E	Y	1	D
F	Y	2	C
G	Y	3	E

# Analysis

- Correctness ??
  - A bit tricky
  - Intuitively similar to Dijkstra
  
- Run-time
  - Same as Dijkstra
  - $O(|E| \log |V|)$  using a priority queue
    - Costs/priorities are just edge-costs, not path-costs

# Kruskal's Algorithm

Idea: Grow a forest out of edges that do not grow a cycle, just like for the spanning tree problem.

- But now consider the edges in order by weight

So:

- Sort edges:  $O(|E| \log |E|)$  (next course topic)
- Iterate through edges using union-find for cycle detection almost  $O(|E|)$

Somewhat better:

- Floyd's algorithm to build min-heap with edges  $O(|E|)$
- Iterate through edges using union-find for cycle detection and **deleteMin** to get next edge  $O(|E| \log |E|)$
- Not better *worst-case* asymptotically, but often stop long before considering all edges

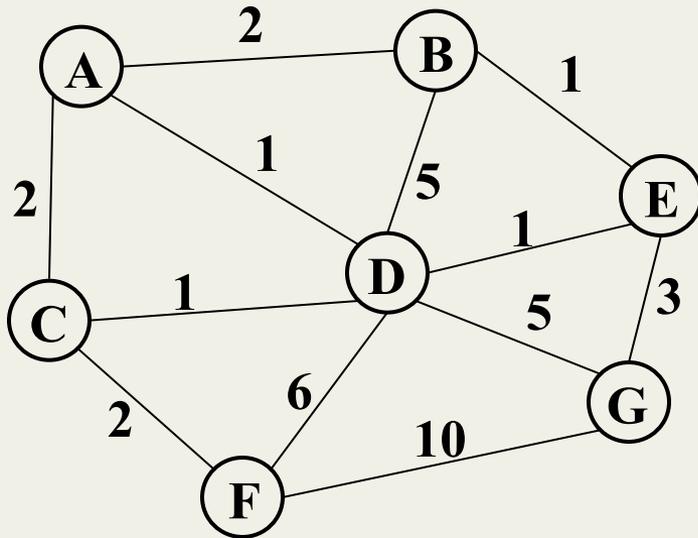
# *Pseudocode*

1. Sort edges by weight (better: put in min-heap)
2. Each node in its own set
3. While output size  $< |V|-1$ 
  - Consider next smallest edge  $(u, v)$
  - if `find(u, v)` indicates  $u$  and  $v$  are in different sets
    - output  $(u, v)$
    - `union(find(u), find(v))`

Recall invariant:

$u$  and  $v$  in same set if and only if connected in output-so-far

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

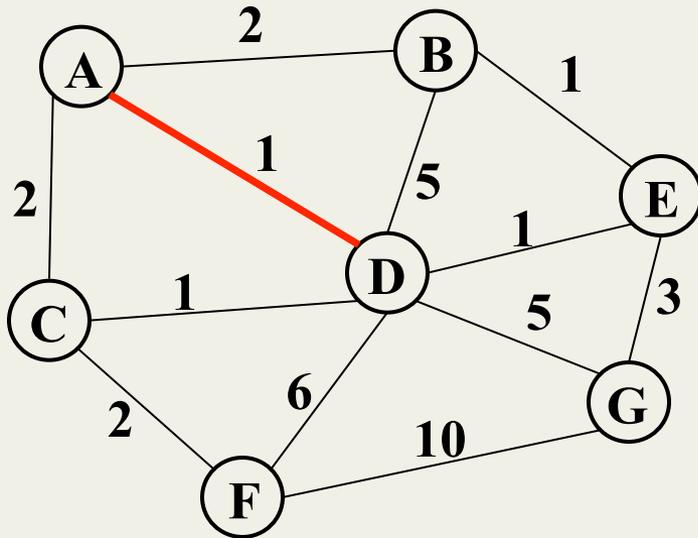
6: (D,F)

10: (F,G)

Output:

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

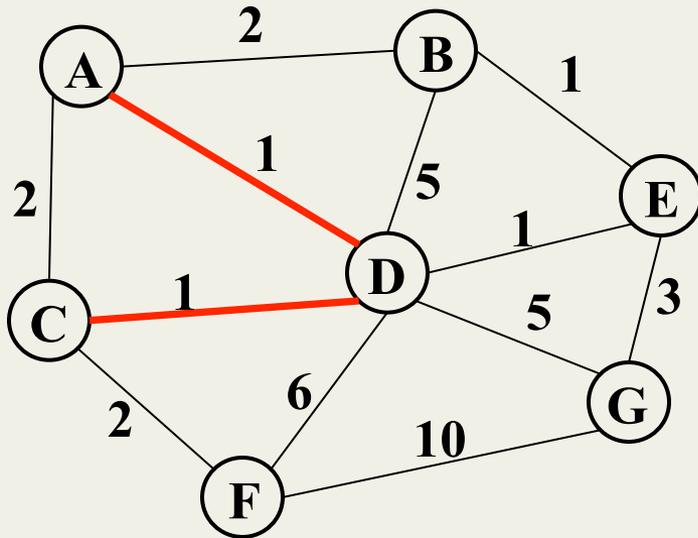
6: (D,F)

10: (F,G)

Output: (A,D)

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

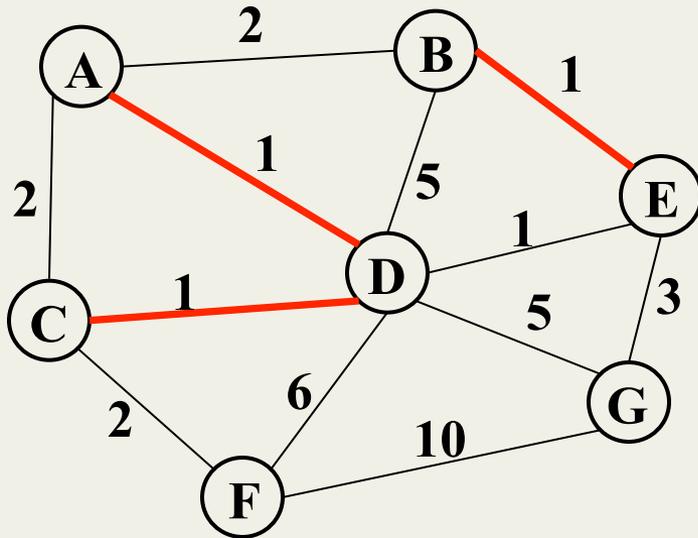
6: (D,F)

10: (F,G)

Output: (A,D), (C,D)

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

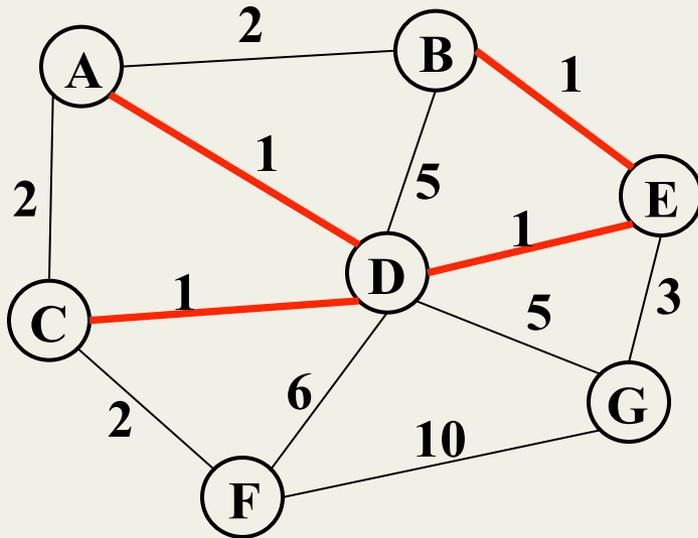
6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E)

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

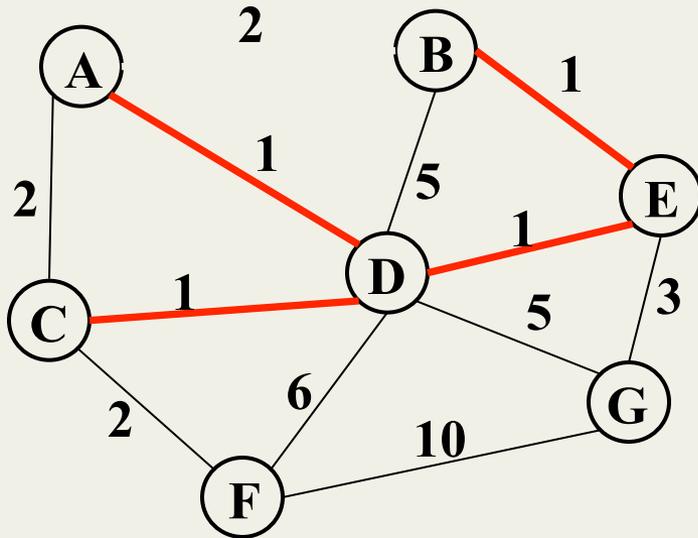
6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E)

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

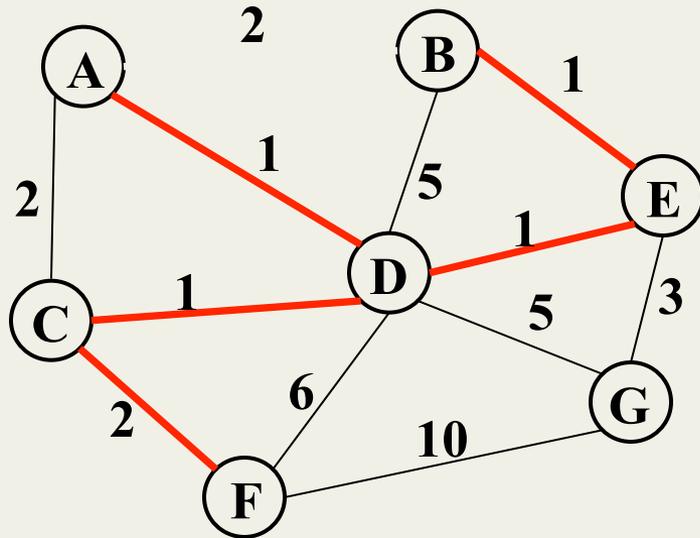
6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E)

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

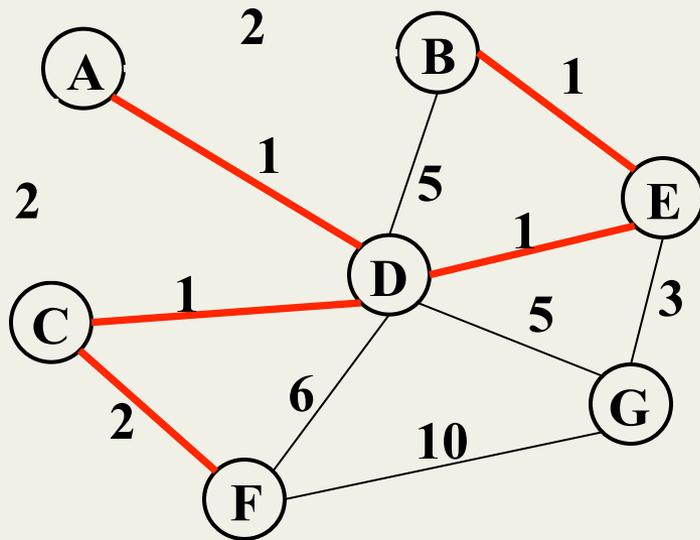
6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F)

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

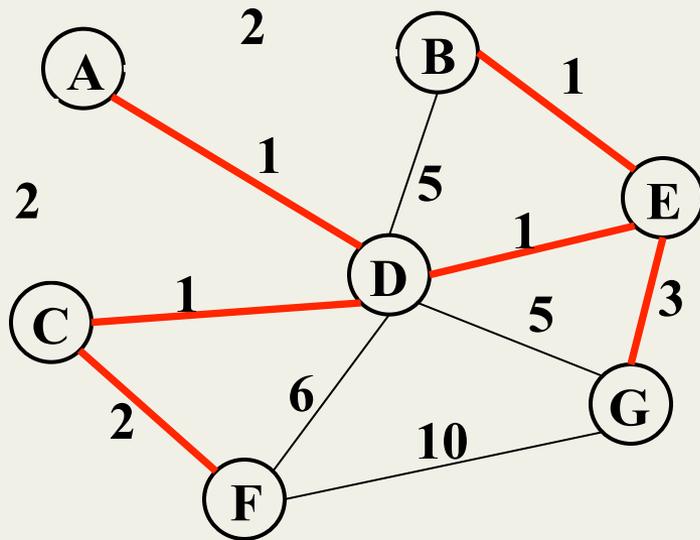
6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F)

Note: At each step, the union/find sets are the trees in the forest

## Example



Edges in sorted order:

1: (A,D), (C,D), (B,E), (D,E)

2: (A,B), (C,F), (A,C)

3: (E,G)

5: (D,G), (B,D)

6: (D,F)

10: (F,G)

Output: (A,D), (C,D), (B,E), (D,E), (C,F), (E,G)

Note: At each step, the union/find sets are the trees in the forest

# Correctness

Kruskal's algorithm is clever, simple, and efficient

- But does it generate a minimum spanning tree?
- How can we prove it?

First: it generates a spanning tree

- Intuition: Graph started connected and we added every edge that did not create a cycle
- Proof by contradiction: Suppose  $u$  and  $v$  are disconnected in Kruskal's result. Then there's a path from  $u$  to  $v$  in the initial graph with an edge we could add without creating a cycle. But Kruskal would have added that edge. Contradiction.

Second: There is no spanning tree with lower total cost...

## *The inductive proof set-up*

Let  $\mathbf{F}$  (stands for “forest”) be the set of edges Kruskal has added at some point during its execution.

Claim:  $\mathbf{F}$  is a subset of *one or more* MSTs for the graph  
– Therefore, once  $|\mathbf{F}|=|\mathbf{V}|-1$ , we have an MST

Proof: By induction on  $|\mathbf{F}|$

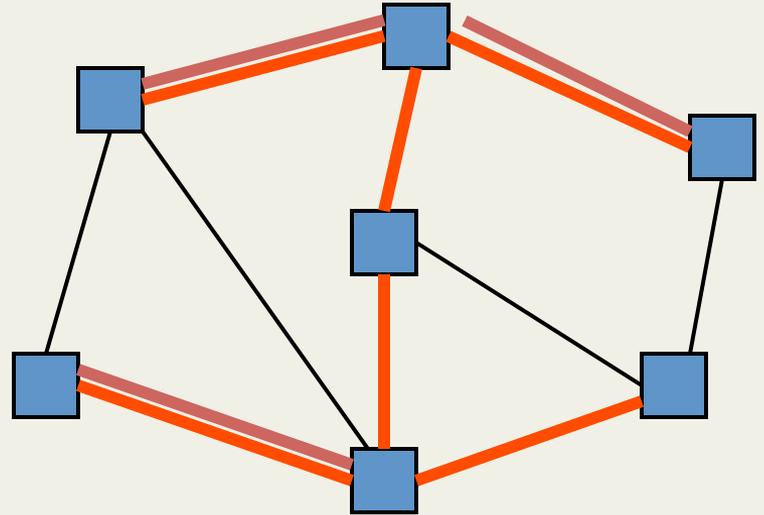
Base case:  $|\mathbf{F}|=0$ : The empty set is a subset of all MSTs

Inductive case:  $|\mathbf{F}|=k+1$ : By induction, before adding the  $(k+1)^{\text{th}}$  edge (call it  $\mathbf{e}$ ), there was some MST  $\mathbf{T}$  such that  $\mathbf{F}-\{\mathbf{e}\} \subseteq \mathbf{T} \dots$

# Staying a subset of some MST

Claim:  $F$  is a subset of *one or more* MSTs for the graph

So far:  $F - \{e\} \subseteq T$ :



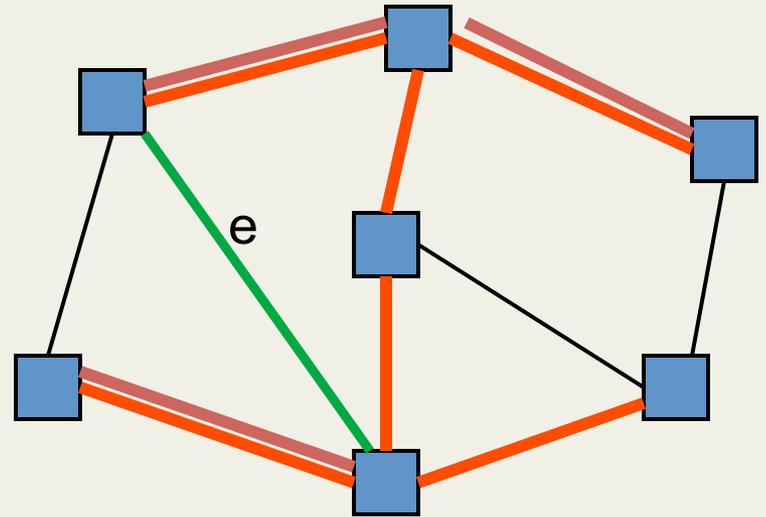
Two disjoint cases:

- If  $\{e\} \subseteq T$ : Then  $F \subseteq T$  and we're done
- Else  $e$  forms a cycle with some simple path (call it  $p$ ) in  $T$ 
  - Must be since  $T$  is a spanning tree

## Staying a subset of some MST

Claim:  $F$  is a subset of *one or more* MSTs for the graph

So far:  $F - \{e\} \subseteq T$  and  
 $e$  forms a cycle with  $p \subseteq T$



- There must be an edge  $e_2$  on  $p$  such that  $e_2$  is not in  $F$ 
  - Else Kruskal would not have added  $e$
- Claim:  $e_2.\text{weight} == e.\text{weight}$

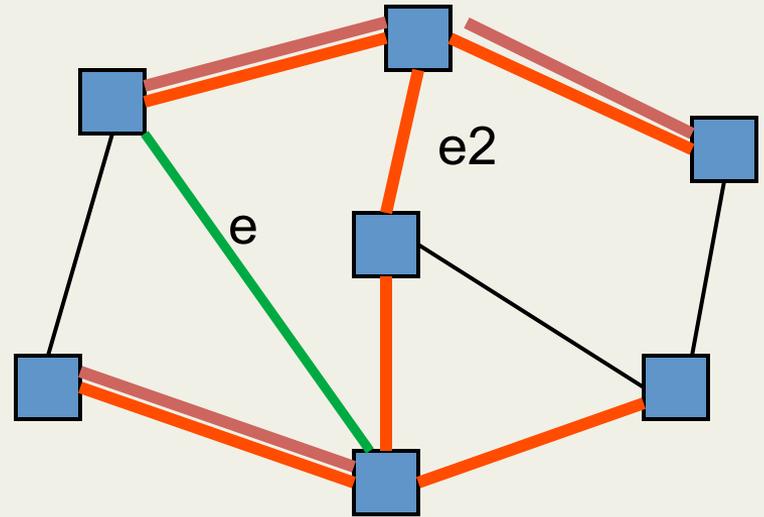
## Staying a subset of some MST

Claim:  $F$  is a subset of *one or more* MSTs for the graph

So far:  $F - \{e\} \subseteq T$

$e$  forms a cycle with  $p \subseteq T$

$e2$  on  $p$  is not in  $F$



- Claim:  $e2.weight == e.weight$ 
  - If  $e2.weight > e.weight$ , then  $T$  is not an MST because  $T - \{e2\} + \{e\}$  is a spanning tree with lower cost: contradiction
  - If  $e2.weight < e.weight$ , then Kruskal would have already considered  $e2$ . It would have added it since  $T$  has no cycles and  $F - \{e\} \subseteq T$ . But  $e2$  is not in  $F$ : contradiction

# Staying a subset of **some** MST

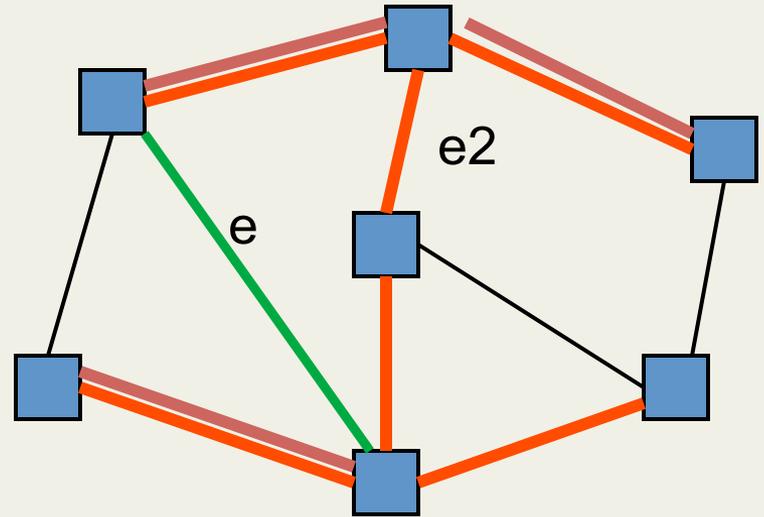
Claim: **F** is a subset of *one or more* MSTs for the graph

So far: **F** - {**e**}  $\subseteq$  **T**

**e** forms a cycle with **p**  $\subseteq$  **T**

**e2** on **p** is not in **F**

**e2.weight** == **e.weight**



- Claim: **T** - {**e2**} + {**e**} is an MST
  - It is a spanning tree because **p** - {**e2**} + {**e**} connects the same nodes as **p**
  - It is minimal because its cost equals cost of **T**, an MST
- Since **F**  $\subseteq$  **T** - {**e2**} + {**e**}, **F** is a subset of one or more MSTs

Done