

# CSE 373: Data Structures and Algorithms

## Lecture 22: Graphs IV

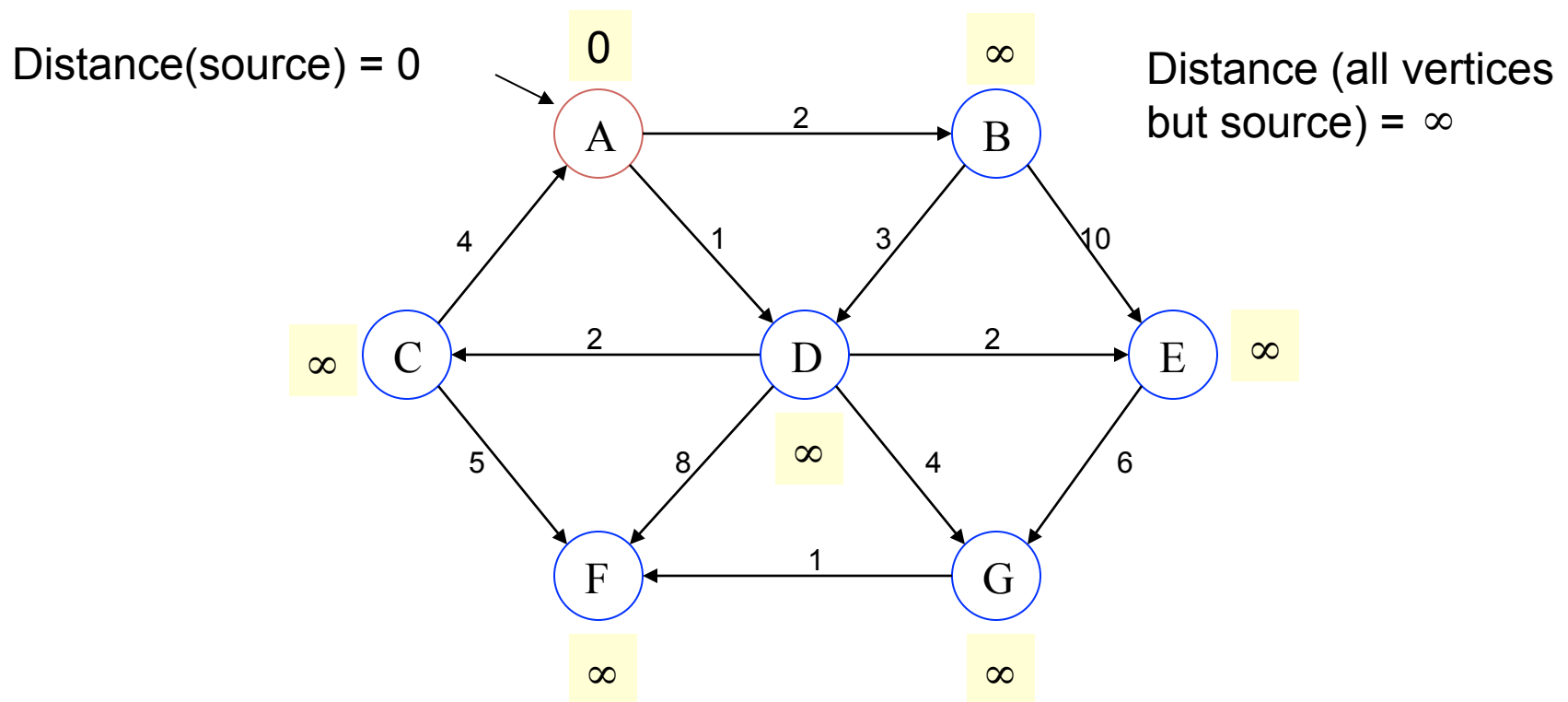
# Dijkstra's algorithm

- **Dijkstra's algorithm:** finds shortest (minimum weight) path between a particular pair of vertices in a *weighted* directed graph with nonnegative edge weights
  - solves the "one vertex, shortest path" problem
  - basic algorithm concept: create a table of information about the currently known best way to reach each vertex (distance, previous vertex) and improve it until it reaches the best solution
- in a graph where:
  - vertices represent cities,
  - edge weights represent driving distances between pairs of cities connected by a direct road,  
Dijkstra's algorithm can be used to find the shortest route between one city and any other

# Dijkstra pseudocode

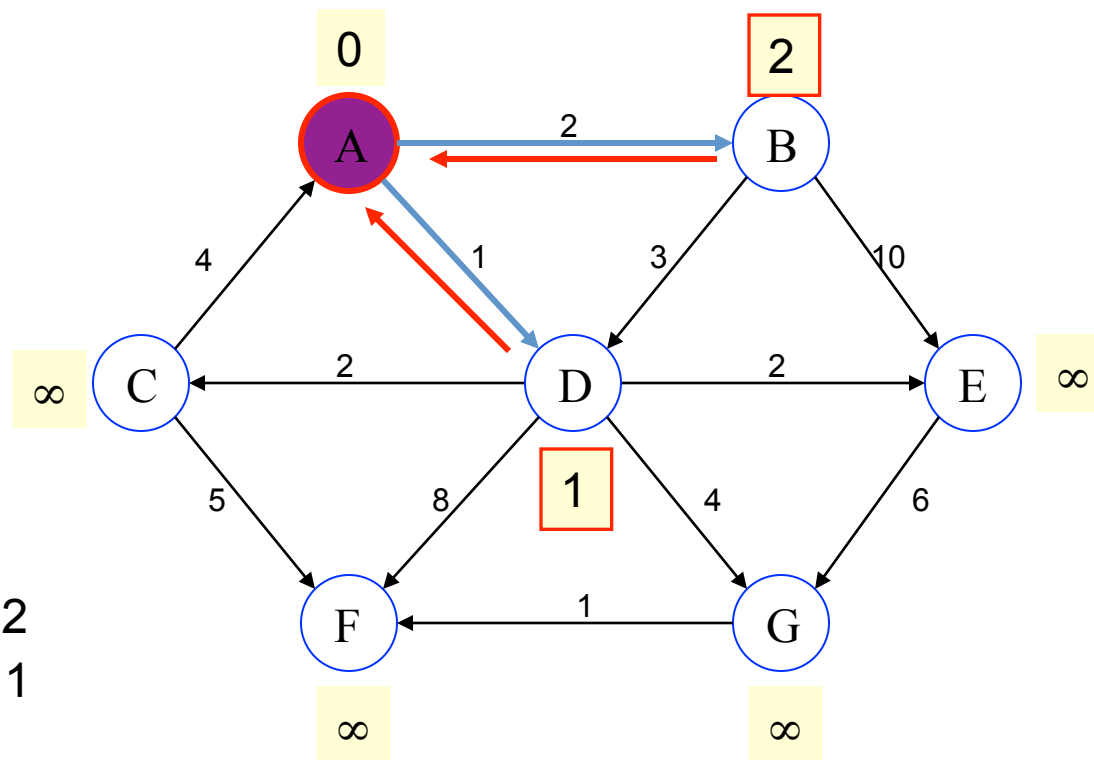
```
Dijkstra(v1, v2):  
  for each vertex v:                                // Initialization  
    v's distance := infinity.  
    v's previous := none.  
  v1's distance := 0.  
  List := {all vertices}.  
  
  while List is not empty:  
    v := remove List vertex with minimum distance.  
    mark v as known.  
    for each unknown neighbor n of v:  
      dist := v's distance + edge (v, n)'s weight.  
  
      if dist is smaller than n's distance:  
        n's distance := dist.  
        n's previous := v.  
  
  reconstruct path from v2 back to v1,  
  following previous pointers.
```

# Example: Initialization



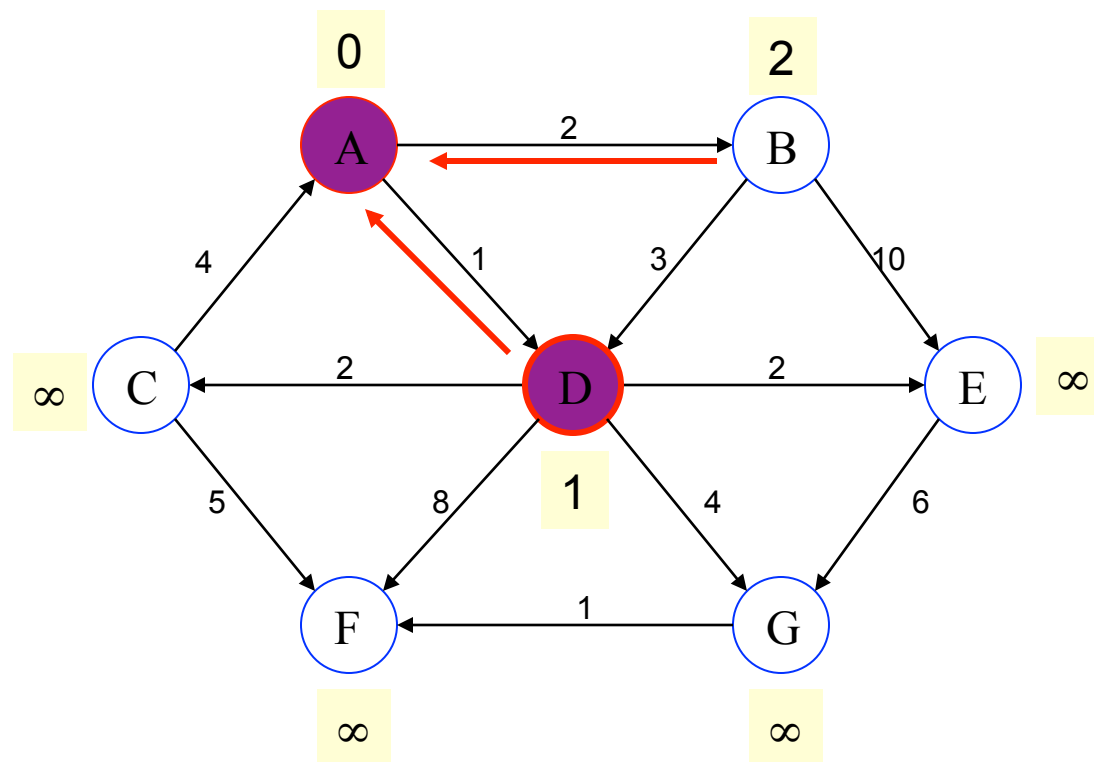
Pick vertex in List with minimum distance.

# Example: Update neighbors' distance



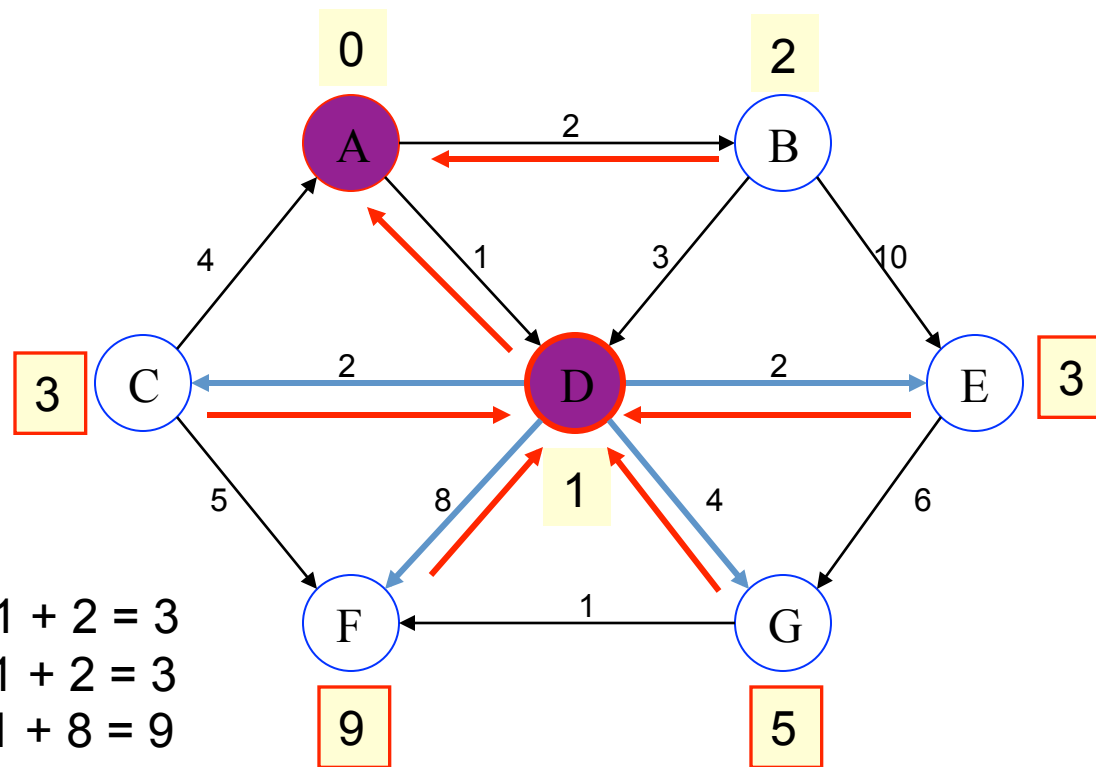
Distance(B) = 2  
Distance(D) = 1

# Example: Remove vertex with minimum distance



Pick vertex in List with minimum distance, i.e., D

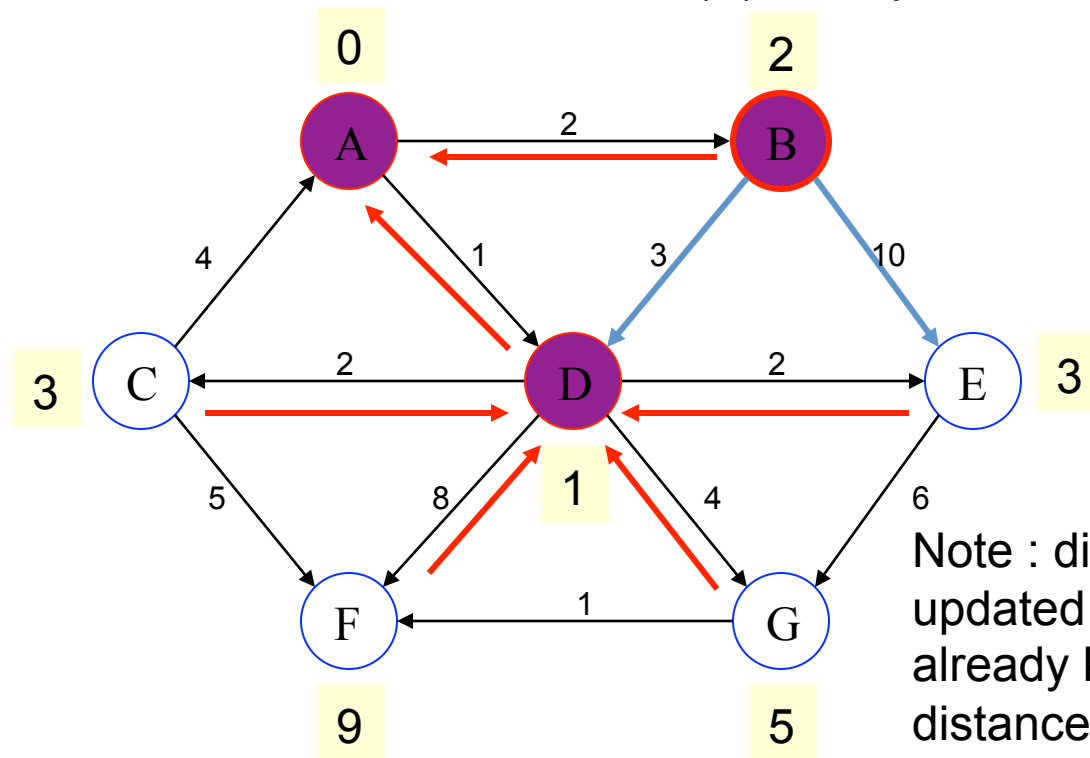
# Example: Update neighbors



Distance(C) = 1 + 2 = 3  
Distance(E) = 1 + 2 = 3  
Distance(F) = 1 + 8 = 9  
Distance(G) = 1 + 4 = 5

# Example: Continued...

Pick vertex in List with minimum distance (B) and update neighbors

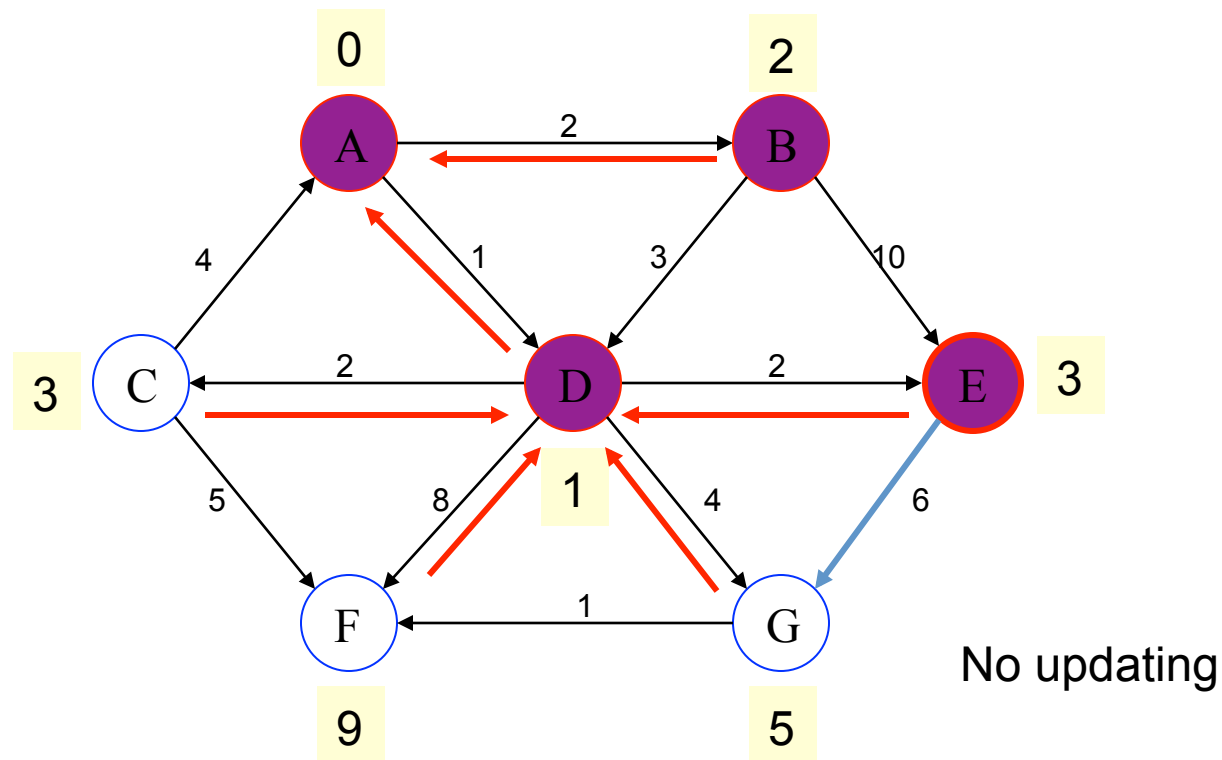


Note : distance(D) not updated since D is already known and distance(E) not updated since it is larger than previously computed



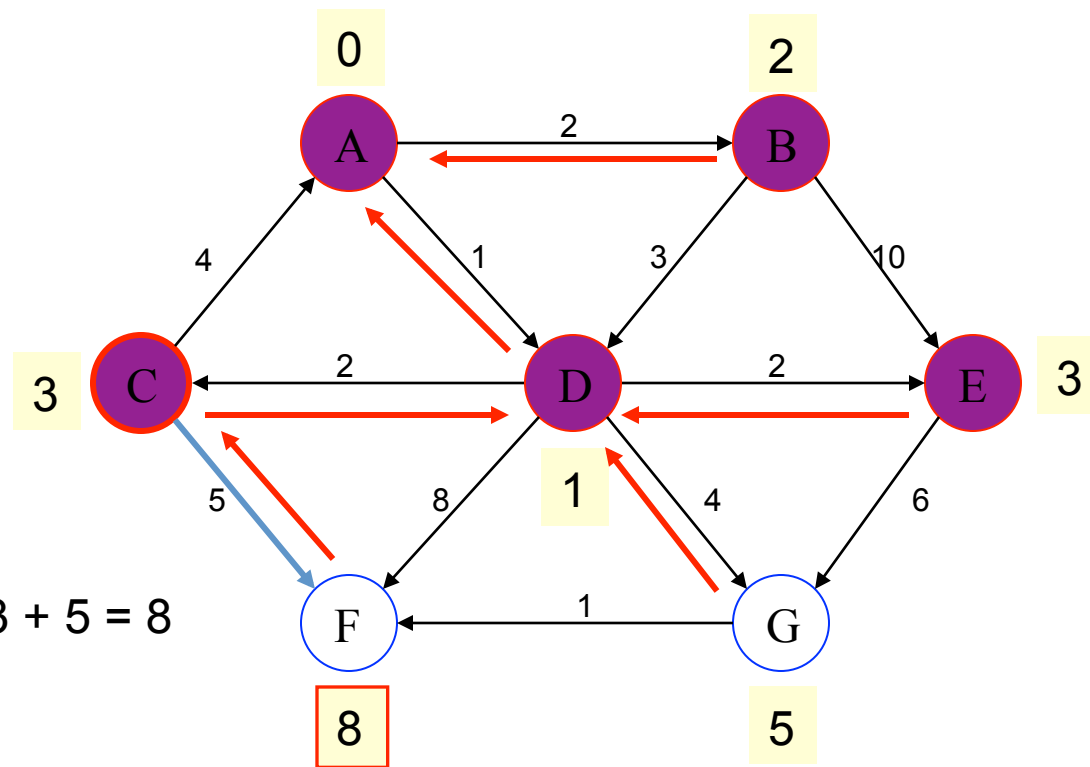
# Example: Continued...

Pick vertex List with minimum distance (E) and update neighbors



# Example: Continued...

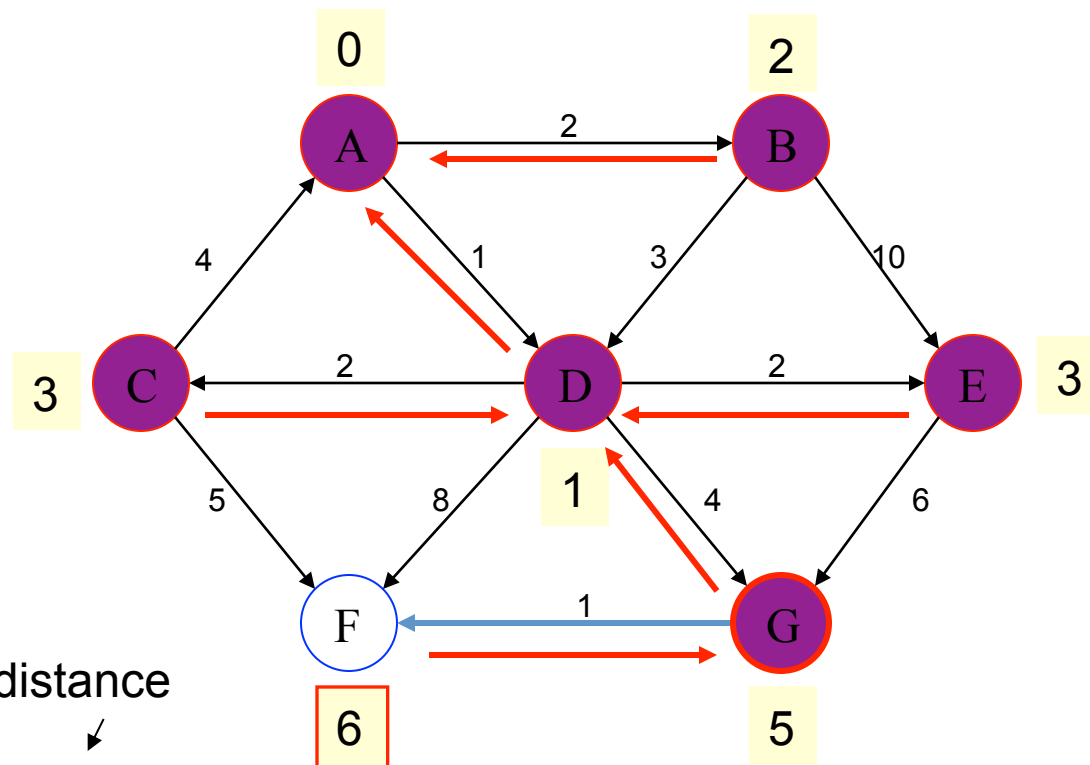
Pick vertex List with minimum distance (C) and update neighbors



$$\text{Distance}(F) = 3 + 5 = 8$$

# Example: Continued...

Pick vertex List with minimum distance (G) and update neighbors

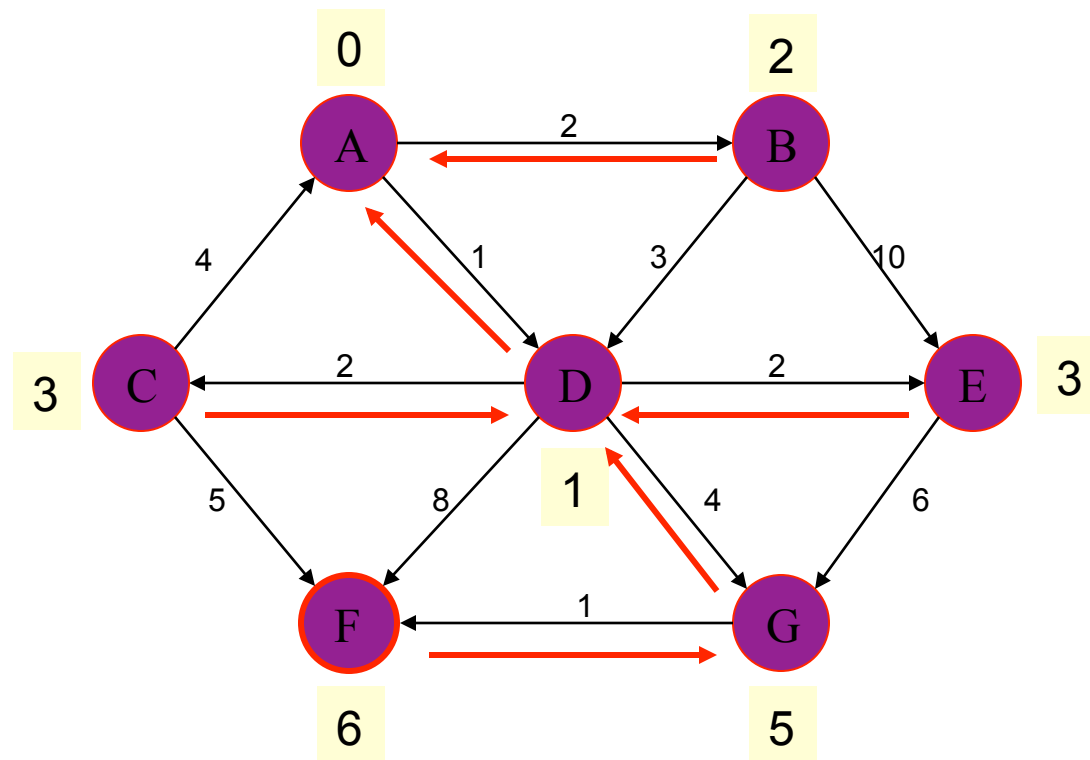


Previous distance



$$\text{Distance}(F) = \min(8, 5+1) = 6$$

# Example (end)

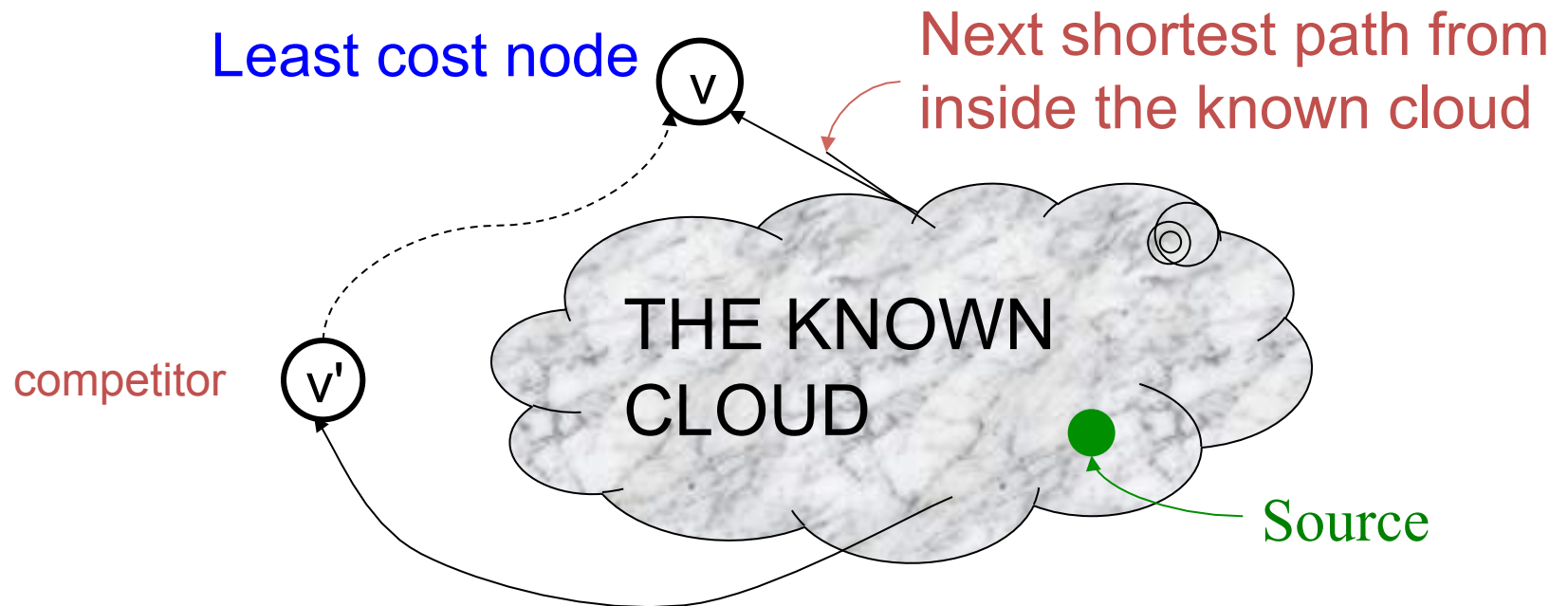


Pick vertex not in S with lowest cost (F) and update neighbors

# Correctness

- Dijkstra's algorithm is a greedy algorithm
  - make choices that currently seem the best
  - locally optimal does not always mean globally optimal
- Correct because maintains following two properties:
  - for every known vertex, recorded distance is shortest distance to that vertex from source vertex
  - for every unknown vertex  $v$ , its recorded distance is shortest path distance to  $v$  from source vertex, considering only currently known vertices and  $v$

# “Cloudy” Proof: The Idea



- If the path to  $v$  is the next shortest path, the path to  $v'$  must be at least as long. Therefore, any path through  $v'$  to  $v$  cannot be shorter!