Minimum Spanning Trees

CSE 373
Data Structures
Winter 2007

Reading

- Chapter 9
 - > Section 9.5

MSTs

Spanning Tree

- Given (connected) G(V,E) a spanning tree T(V',E'):
 - > Spans the graph (V' = V)
 - Forms a tree (no cycles); E' has |V| -1 edges

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Minimum Spanning Tree

- Edges are weighted: find minimum cost spanning tree
- Applications
 - › Find cheapest way to wire your house
 - Find minimum cost to send a message on the Internet

MSTs 4

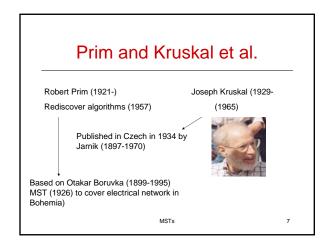
Basic Strategy

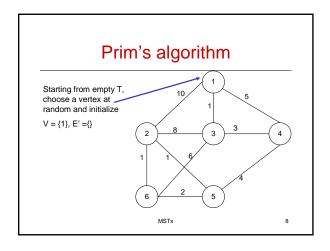
- · Strategy:
 - Add an edge of minimum cost that does not create a cycle (greedy algorithm)
 - Repeat |V| -1 times
 - Correct since if we could replace an edge with one of lower cost, the algorithm would have picked it up

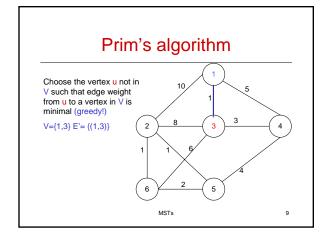
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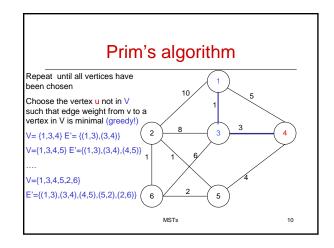
Two Algorithms

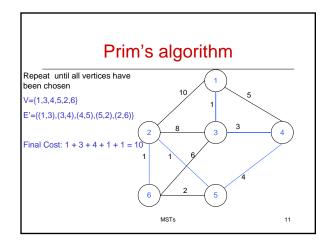
- Prim: (build tree incrementally)
 - Pick lower cost edge connected to known (incomplete) spanning tree that does not create a cycle and expand to include it in the tree
- Kruskal: (build forest that will finish as a tree)
 - Pick lower cost edge not yet in a tree that does not create a cycle and expand to include it somewhere in the forest











Prim's Algorithm Implementation

· Assume adjacency list representation

Initialize connection cost of each node to "inf" and "unmark" them Choose one node, say v and set cost[v] = 0 and prev[v] = 0 While they are unmarked nodes

Select the unmarked node u with minimum cost; mark it For each unmarked node w adjacent to u $if \ cost(u,w) < cost(w) \ then \ cost(w) := cost \ (u,w) \\ prev[w] = u$

· Looks a lot like Dijkstra's algorithm!

Prim's algorithm Analysis

- · Like Dijkstra's algorithm
- If the "Select the unmarked node u with minimum cost" is done with binary heap then $O((n+m)\log n)$

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Kruskal's Algorithm

- Select edges in order of increasing cost
- · Accept an edge to expand tree or forest only if it does not cause a cycle
- · Implementation using adjacency list, priority queues and disjoint sets

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Kruskal's Algorithm

Initialize a forest of trees, each tree being a single node Build a priority queue of edges with priority being lowest cost Repeat until |V| -1 edges have been accepted { Deletemin edge from priority queue

If it forms a cycle then discard it

else accept the edge - It will join 2 existing trees yielding a larger tree and reducing the forest by one tree

The accepted edges form the minimum spanning tree

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Detecting Cycles

- If the edge to be added (u,v) is such that vertices u and v belong to the same tree, then by adding (u,v) you would form a cycle
 - Therefore to check, Find(u) and Find(v). If they are the same discard (u,v)
 - If they are different Union(Find(u),Find(v))

MSTs

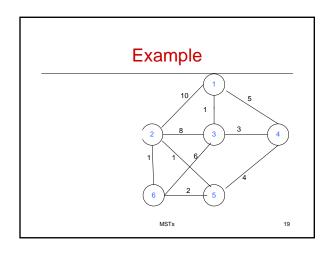
Properties of trees in K's algorithm

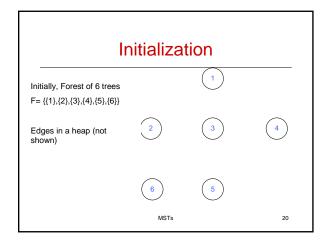
- Vertices in different trees are disjoint
 - True at initialization and Union won't modify the fact for remaining trees
- Trees form equivalent classes under the relation "is connected to"
 - u connected to u (reflexivity)
 - > u connected to v implies v connected to u (symmetry)
 - > u connected to v and v connected to w implies a path from u to w so u connected to w (transitivity)

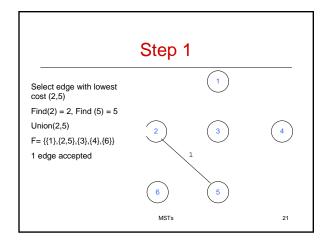
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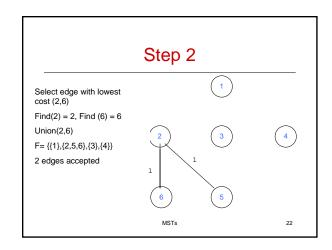
K's Algorithm Data Structures

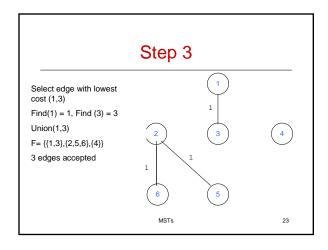
- · Adjacency list for the graph
 - > To perform the initialization of the data structures below
- · Disjoint Set ADT's for the trees (recall Up tree implementation of Union-Find)
- · Binary heap for edges

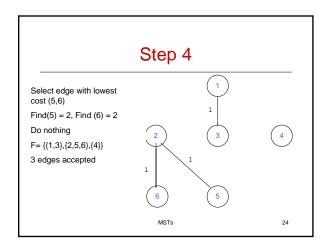


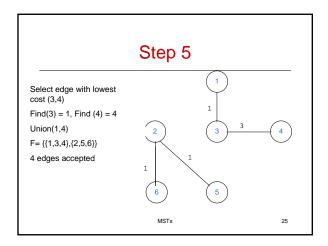


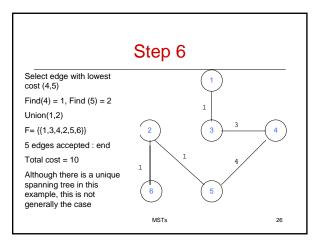












Kruskal's Algorithm Analysis

- Initialize forest O(n)
- Initialize heap O(m), m = |E|
- · Loop performed m times
 - > In the loop one Deletemin O(logm)
 - > Two Find, each O(logn)
 - One Union (at most) O(1)
- So worst case O(mlogm) = O(mlogn)

MSTs

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Time Complexity Summary

- Recall that $m = |E| = O(V^2) = O(n^2)$
- Prim's runs in O((n+m) log n)
- Kruskal's runs in O(mlogm) = O(mlogn)
- In practice, Kruskal has a tendency to run faster since graphs might not be dense and not all edges need to be looked at in the Deletemin operations