

# Sorting Summary

CSE 373 - Data Structures  
May 15, 2002

# Readings and References

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- Reading
  - › Sections 7.8-7.11, *Data Structures and Algorithm Analysis in C*, Weiss
- Other References

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# How fast can we sort?

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- Heapsort, Mergesort, and Quicksort all run in  $O(N \log N)$  best case running time
- Can we do any better?
- Can we believe LaMoC, Inc, which claims to have discovered an  $O(N \log(\log N))$  general purpose sorting algorithm?
  - › The US patent office probably believes it, do you?

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# No! (if using comparisons only)

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- Recall our basic assumption: we can only compare two elements at a time
  - › we can only reduce the possible solution space by half each time we make a comparison
- Suppose you are given  $N$  elements
  - › Assume no duplicates
- How many possible orderings can you get?
  - › Example: a, b, c ( $N = 3$ )

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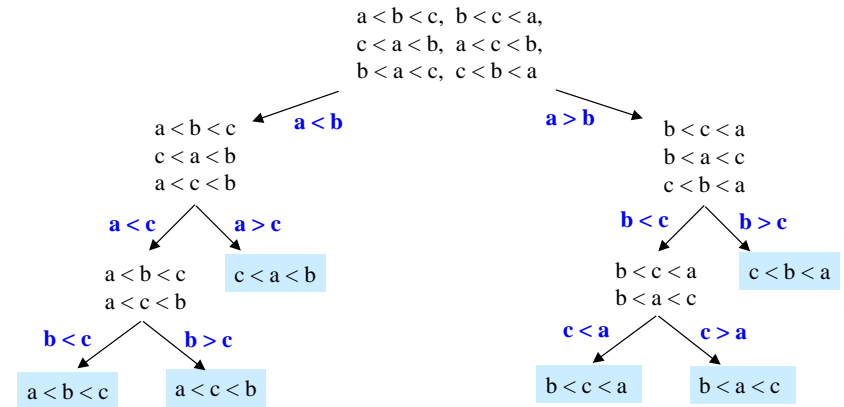
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# Permutations

- How many possible orderings can you get?
  - › Example: a, b, c (N = 3)
  - › (a b c), (a c b), (b a c), (b c a), (c a b), (c b a)
  - › 6 orderings =  $3 \cdot 2 \cdot 1 = 3!$  (ie, “3 factorial”)
  - › All the possible permutations of a set of 3 elements
- For N elements
  - › N choices for the first position, (N-1) choices for the second position, ..., (2) choices, 1 choice
  - ›  $N(N-1)(N-2) \cdots (2)(1) = N!$  possible orderings

# Decision Tree



The leaves contain all the possible orderings of a, b, c

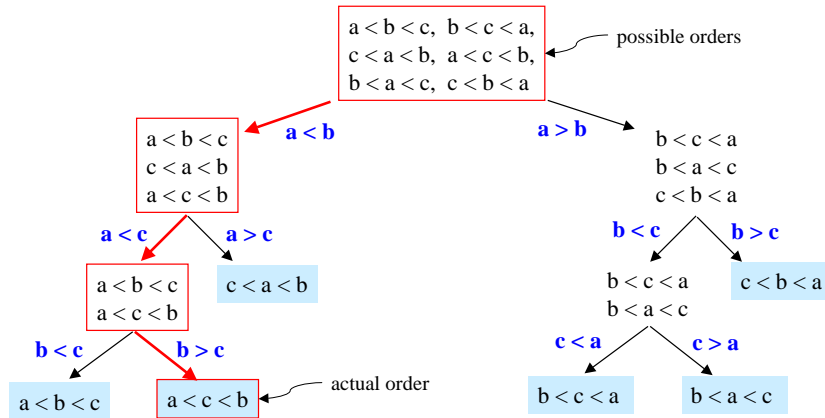
# Decision Trees

- A Decision Tree is a Binary Tree such that:
  - › Each node = a set of orderings
    - ie, the remaining solution space
  - › Each edge = 1 comparison
  - › Each leaf = 1 unique ordering
  - › How many leaves for N distinct elements?
    - $N!$ , ie, a leaf for each possible ordering
- Only 1 leaf has the ordering that is the desired correctly sorted arrangement

# Decision Trees and Sorting

- Every sorting algorithm corresponds to a decision tree
  - › Finds correct leaf by choosing edges to follow
    - ie, by making comparisons
  - › Each decision reduces the possible solution space by one half
- Run time is  $\geq$  maximum no. of comparisons
  - › maximum number of comparisons is the length of the longest path in the decision tree
    - the length of the longest path is the depth of the tree

# Decision Tree Depth Example



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# How many leaves on a tree?

- Suppose you have a binary tree of depth d. How many leaves can the tree have?
  - ›  $d = 1 \rightarrow$  at most 2 leaves,
  - ›  $d = 2 \rightarrow$  at most 4 leaves, etc.



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# How deep is it, Jim?

- A binary tree of depth  $d$  has at most  $2^d$  leaves
  - › depth  $d = 1 \rightarrow 2$  leaves,  $d = 2 \rightarrow 4$  leaves, etc.
  - › Can prove by induction
- The decision tree has  $L = N!$  leaves
- Depth  $d$  must be deep enough such that  $2^d \geq L$ 
  - › and  $2^d \geq L \rightarrow d \geq \log L$
- So the decision tree depth is  $d \geq \log(N!)$

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# $\log(N!)$ is $\Omega(N \log N)$

$$\begin{aligned}
 \log(N!) &= \log(N \cdot (N-1) \cdot (N-2) \cdots (2) \cdot (1)) \\
 &= \log N + \log(N-1) + \log(N-2) + \cdots + \log 2 + \log 1 \\
 &\geq \log N + \log(N-1) + \log(N-2) + \cdots + \log \frac{N}{2} \\
 &\geq \frac{N}{2} \log \frac{N}{2} \\
 &\geq \frac{N}{2} (\log N - \log 2) = \frac{N}{2} \log N - \frac{N}{2} \\
 &= \Omega(N \log N)
 \end{aligned}$$

select just the first  $N/2$  terms

each of the selected terms is  $\geq \log N/2$

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## $\Omega(N \log N)$

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- Run time of any comparison-based sorting algorithm is  $\Omega(N \log N)$ 
  - › Any sorting algorithm based on comparisons between elements requires  $\Omega(N \log N)$  comparisons
- Can never find an  $O(N \log \log N)$  general purpose sorting algorithm
  - › sorry, LaMoC, Inc!
  - › get a clue, patent office

## What about bucket sort?

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- You may be saying to yourself
  - “But on slide 27 of the List lecture on April 5th, he showed that the bucket sort only takes  $O(N+B)$  operations, what's up with that?”
- And I say to you: Advance knowledge of the data lets you do all sorts of magic
  - › perfect hash
  - › bucket sort, radix sort

## Bucket Sort: Sorting integers

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- Bucket sort:  $N$  integers in the range 0 to  $B-1$ 
  - › Array Count has  $B$  elements (“buckets”), initialized to 0
  - › Given input integer  $i$ ,  $\text{Count}[i]++$
  - › After reading all  $N$  numbers go through the  $B$  buckets and read out the resulting sorted list
  - ›  $N$  operations to read and record the numbers plus  $B$  operations to recover the sorted numbers

## Bucket Sort Run Time?

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- What is the running time for sorting  $N$  integers?
  - › Running Time:  $O(B+N)$ 
    - $B$  to zero/scan the array and  $N$  to read the input
  - › If  $B$  is  $\Theta(N)$ , running time for Bucket sort =  $O(N)$
- Doesn't this violate the  $O(N \log N)$  lower bound result??
- No – When we do  $\text{Count}[i]++$ , we are comparing one element with all  $B$  elements, not just two elements

# Radix Sort: Sorting integers

- Radix sort = multi-pass bucket sort of integers in the range 0 to  $B^P - 1$ 
  - › Bucket-sort from least significant to most significant “digit” (base B)
  - › Use linked list to store numbers that are in same bucket
  - › Requires  $P \cdot (B + N)$  operations where P is the number of passes (the number of base B digits in the largest possible input number)
  - › Do P passes instead of using  $B^P$  space

# Radix Sort Example

data									
478	721		3			537	478	9	
537			123			67	38		
9									
721									
3									
38									
123									
67									

Bucket sort by 1's digit

0	1	2	3	4	5	6	7	8	9
		721	3				537	478	9
			123				67	38	

Bucket sort by 10's digit

0	1	2	3	4	5	6	7	8	9
03		721	537			67	478		
09		123	38						

Bucket sort by 100's digit

0	1	2	3	4	5	6	7	8	9
003	123			478	537		721		
009									
038									
067									

This example uses B=10 and base 10 digits for simplicity of demonstration. Larger bucket counts should be used in an actual implementation.

# Internal versus External Sorting

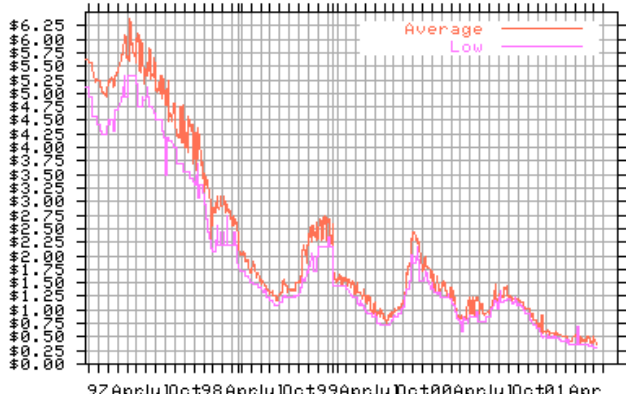
- So far assumed that accessing  $A[i]$  is fast – Array A is stored in internal memory (RAM)
  - › Algorithms so far are good for [internal sorting](#)
- What if A is so large that it doesn't fit in internal memory?
  - › Data on disk or tape
  - › Delay in accessing  $A[i]$  – e.g. need to spin disk and move head

# Internal versus External Sorting

- Need sorting algorithms that minimize disk/tape access time
  - › [External sorting](#) – Basic Idea:
    - Load chunk of data into RAM, sort, store this “run” on disk/tape
    - Use the Merge routine from Mergesort to merge runs
    - Repeat until you have only one run (one sorted chunk)
    - Text gives some examples
- But ... how important is external sorting?

# Internal Memory is getting cheap...

Price (in US\$) for 1 MB of RAM

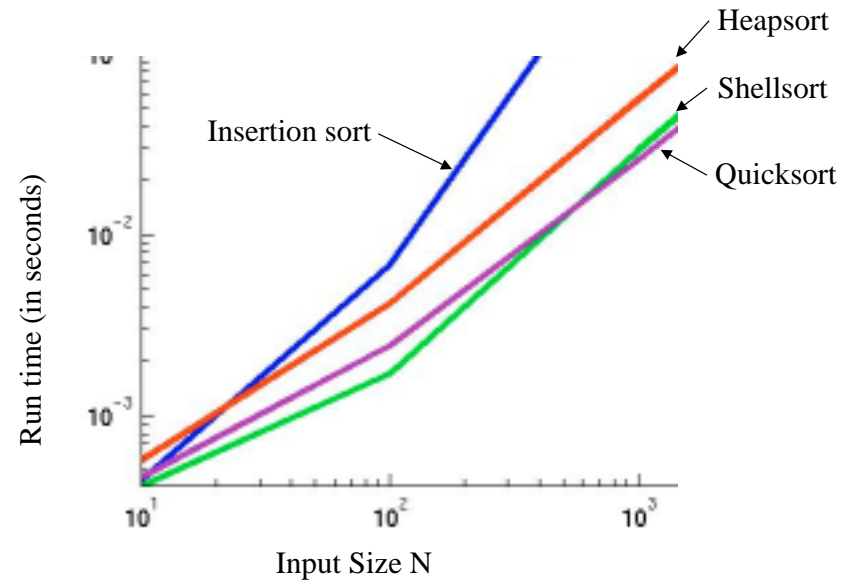
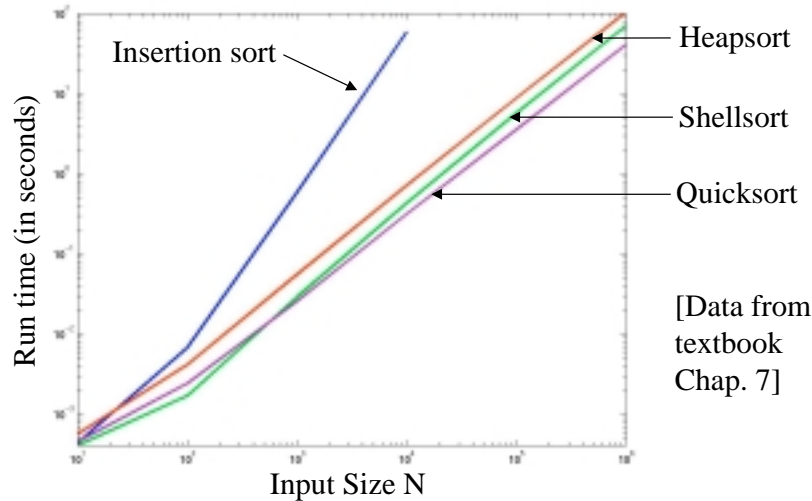


From: <http://www.macresource.com/mrp/ramwatch/trend.shtml>  
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# External Sorting

- For most data sets, internal sorting in a large memory space is possible and intricate external sorts are not required
  - › Tapes seldom used these days – random access disks are faster and getting cheaper with greater capacity
  - › Operating systems provide very, very large virtual memory address spaces so it looks like an internal sort, even though you are using the disk
    - be careful though, you can end up doing a lot of disk I/O if you're not careful

# Okay...so let's talk about performance in practice



## Summary of Sorting

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- Sorting choices:
  - ›  $O(N^2)$  – Bubblesort, Selection Sort, Insertion Sort
  - ›  $O(N^x)$  – Shellsort ( $x = 3/2, 4/3, 7/6, 2$ , etc. depending on increment sequence)
  - ›  $O(N \log N)$  average case running time:
    - [Heapsort](#): uses 2 comparisons to move data (between children and between child and parent) – may not be fast in practice (see graph)
    - [Mergesort](#): easy to code but uses  $O(N)$  extra space
    - [Quicksort](#): fastest in practice but trickier to code,  $O(N^2)$  worst case

## Practical Sorting

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- When  $N$  is large, use Quicksort with median3 pivot
- For small  $N$  ( $< 20$ ), the  $N \log N$  sorts are slower due to extra overhead (larger constants in big-Oh notation)
  - › For  $N < 20$ , use Insertion sort
  - › In Quicksort, do insertion sort when sub-array size  $< 20$  (instead of partitioning)
- When you need a sorter
  - › remember the various candidate algorithms
  - › think about the type and quantity of your data
  - › look up an appropriate reference implementation and adapt it to your requirements (ElementType, comparator, etc)