## Lists

## CSE 373 - Data Structures

April 5, 2002

## Readings and References

- Reading
> Sections 3.1-3.2.8, Data Structures and Algorithm Analysis in C, Weiss
- Other References


## Review: Pointers and Memory

- Recall that memory is a one-dimensional array of bytes, each with an address
- Pointer variables contain an address

```
int y, *aP, *bP; // pointer vars use * in declaration
y = 3;
aP = &y;
*aP = 17;
printf("aP: %p\n",aP);
printf("*aP = %d\n",y); // prints out what?
printf("bP: %p\n",bP); // what happens? (hint: DOOM)
```


## Example result

\#include <stdio.h>
int main(int argc, char *argv[]) \{
int $y$, *aP, *bP; // pointer vars use * in declaration
$\mathrm{y}=3$;
$a \mathrm{aP}=8 \mathrm{y}$;
*aP = 17;
printf("aP: \%p\n",aP); $\}$
printf("*aP $=\% d \backslash n ", y) ;\} / /$ prints out what?
printf("bP: \%p\n",bP);
*bP = 1; // what happens? (hint: DOOM)
return 0;
\}
aP: Oxbffffa5 $* a P=17$
Segmentation fault (core dumped)

## Review: Memory Management

- Use "malloc" to allocate a specified number of bytes for new variables
$a \mathrm{a}=$ (int *) malloc (sizeof(int));
, Use the sizeof operator to compute the number of bytes needed for the data type
> malloc does not initialize the memory
- To deallocate memory, use "free" and pass a pointer to an object allocated with malloc free (aP);


## List Implementations

- Two types of implementation:
> Array-Based
> Pointer-Based


## List ADT

- What is a List?
, Ordered sequence of elements $\mathrm{A}_{1}, \mathrm{~A}_{2}, \ldots, \mathrm{~A}_{\mathrm{N}}$
- Elements may be of arbitrary type, but all are the same type
- Common List operations are
> Insert, Find, Delete, IsEmpty, IsLast, FindPrevious, First, Kth, Last

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## List: Array Implementation

- Basic Idea:
> Pre-allocate a big array of size MAX_SIZE
> Keep track of current size using a variable count
> Shift elements when you have to insert or delete

| 0 | 1 | 2 | 3 | $\cdots$ | count-1 |  | MAX_SIZE-1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :--- | :---: |
| $\mathrm{A}_{1}$ | $\mathrm{~A}_{2}$ | $\mathrm{~A}_{3}$ | $\mathrm{~A}_{4}$ | $\cdots$ | $\mathrm{~A}_{\mathrm{N}}$ |  |  |

## List: Array Implementation

```
typedef struct _ListInfo (
    ElementType *theArray; //= malloc(MAX_SIZE*sizeof(ElementType))
    int count; // = 0
    int maxsize; //=MAX_SIZE
}
typedef ListInfo *List;
typedef int Position;
//Empty list has allocated array and count = 0
Need to define: void Insert(List L, ElementType E, Position P)
// Example: Insert E at position P = 2
\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline 0 & 1 & 2 & 3 & \(\ldots\) & count-1 & MAX_SIZE-1 \\
\hline \(\mathrm{A}_{1}\) & \(\mathrm{~A}_{2}\) & \(\mathrm{~A}_{3}\) & \(\mathrm{~A}_{4}\) & \(\ldots\) & \(\mathrm{~A}_{\mathrm{N}}\) & & \\
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\hline
\end{tabular}
```


## Array List Insert Operation

- Basic Idea: Insert new item and shift old items to the right.

```
void Insert(List L, ElementType e, Position p) {
    Position current;
    if (p > L->count || L->count == MAX_SIZE) exit(1);
    current = L->count;
    while (current != p) {
        L->a[current] = L->a[current-1];
        current--;
    }
    L->a[current] = e;
    L->count++;
}
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\section*{Array List Insert Running Time}
- Running time for N elements?
- On average, must move half the elements to make room
- Worst case is insert at position 0. Must move all N items down one position before the insert
- This is \(\mathrm{O}(\mathrm{N})\) running time.

\section*{List: Pointer Implementation}
- Basic Idea:
> Allocate little blocks of memory (nodes) as elements are added to the list
> Keep track of list by linking the nodes together
> Change links when you want to insert or delete


\section*{List: A Pointer Implementation}

\section*{Pointer-Based Linked List}
```

typedef struct Node {
ElementType Value;
struct Node *next;
};
typedef struct Node *List;
typedef struct Node *Position;
// Pointer to an empty list = NULL
void Insert(List *pL, ElementType E, Position P)

```


\section*{Pointer-based Insert Operation}


\section*{Using a Header Node}
- If the List pointer points to first item, then > any change in first item changes List itself
> need special checks if List pointer is NULL > L->next is invalid (L is not a Node struct)
- Solution: Use "header node" at beginning of all lists (see text)
, List pointer always points to header node, which points to first actual list item
, Simplifies the code, but you need to remember that there is an "empty" node at the start of the list

Linked List with Header Node


\section*{Pointer Implementation Issues}
- Whenever you break a list, your code should fix the list up as soon as possible
, Draw pictures of the list to visualize what needs to be done
- Pay special attention to boundary conditions:
> Empty list
> Single item - same item is both first and last
, Two items - first, last, but no middle items
> Three or more items - first, last, and middle items

\section*{Pointer List Insert Running Time}
- Running time for N elements?
- Insert takes constant time (O(1))
- Does not depend on input size
- Compare to array bases list which is \(\mathrm{O}(\mathrm{N})\)

\section*{Pointer-Based Linked List Delete}


\section*{Doubly Linked Lists}
- FindPrev (and hence Delete) is slow because we cannot go directly to previous node
- Solution: Keep a "previous" pointer at each node


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\section*{Double Link Pros and Cons}
- Advantage
, Delete and FindPrev are fast like Insert is
- Disadvantages:
> More space used up (double the number of pointers at each node)
> More book-keeping for updating the two pointers at each node

\section*{Circularly Linked Lists}
- Set the pointer of the last node to first node instead of NULL
- Useful when you want to iterate through whole list starting from any node
, No need to write special code to wrap around at the end
- Circular doubly linked lists speed up both the Delete and Last operations

\section*{Polynomial ADT}
- Store and manipulate single variable polynomials with non-negative exponents
, \(10 x^{3}+4 x^{2}+7\left(=10 x^{3}+4 x^{2}+0 x^{1}+7 x^{0}\right)\)
, Store coefficients \(\mathrm{C}_{\mathrm{i}}\) and exponents i
- ADT operations
> Addition: C[i] = A[i] + B[i];
> Multiplication: \(\mathrm{C}[i+j]=\mathrm{C}[i+j]+\) A[i]*B[j];

\section*{Polynomial Implementation}
- Array Implementation: \(\mathrm{C}[\mathrm{i}]=\mathrm{C}_{\mathrm{i}}\)
> E.g. C[3] \(=10, C[2]=4, C[1]=0, C[0]=7\)
- Problem with Array implementation
, High-order sparse polynomials require large sparse arrays
, E.g. \(10 X^{3000}+4 \mathrm{X}^{2}+7 \rightarrow\) Waste of space and time ( \(\mathrm{C}_{\mathrm{i}}\) are mostly 0 s )
- Instead, use singly linked lists, sorted in decreasing order of exponents
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\section*{Bucket Sort: Sorting integers}
- Bucket sort: N integers in the range 0 to \(\mathrm{B}-1\)
> Array Count has B elements ("buckets"), initialized to 0
> Given input integer i , Count[i]++
> After reading all N numbers go through the B buckets and read out the resulting sorted list
> N operations to read and record the numbers plus B operations to recover the sorted numbers

\section*{Radix Sort: Sorting integers}
- Radix sort = multi-pass bucket sort of integers in the range 0 to \(\mathrm{B}^{\mathrm{P}}-1\)
, Bucket-sort from least significant to most significant "digit" (base B)
, Use linked list to store numbers that are in same bucket
> Requires \(\mathrm{P}^{*}(\mathrm{~B}+\mathrm{N})\) operations where P is the number of passes (the number of base B digits in the largest possible input number)```

