

CSE 373: Sorting II

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<http://www.cs.washington.edu/education/courses/cse373/00sp>

Analyzing Mergesort

- Recall: mergesort splits array in half and recursively calls itself on the halves
- Work done per step is $O(N)$ for the merge
- Each recursive call has half as much work to do
- We write a *recurrence relation* for the time T as a function of N :
 - $T(1) = O(1)$
 - $T(N) = 2 * T(N/2) + O(N)$

Recurrences

- One way to see the value of this recurrence is to keep expanding the terms
 - $T(N) = 2 * T(N/2) + N$
 - $T(N) = 2 * [2 * T(N/4) + N/2] + N$
 - $= 4 * T(N/4) + 2 * N$ $or, 2^2 * T(N/2^2) + 2 * N$
 - $T(N) = 4 * [2 * T(N/8) + N/4] + 2 * N$
 - $= 8 * T(N/8) + 3 * N$ $or, 2^3 * T(N/2^3) + 3 * N$
 - ...
 - $T(N) = 2^{\log N} * T(1) + (\log N) * N$ $or, 2^{\log N} * T(N/2^{\log N}) + \log N * N$
 - $= N * O(1) + N \log N$
 - $= O(N \log N)$

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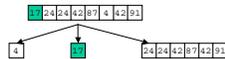
Quicksort

- Mergesort operated by arbitrarily splitting the array in half, sorting the halves, and merging
 - Splitting was easy
 - Merging took $O(N)$ work
- Quicksort is slightly different
 - Partition array into halves
 - Elements in left half all smaller than elements in right half
 - Recurse on halves
 - Concatenate halves – $O(1)$ work

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Partitioning

- Choose a value p (the *pivot*) from the list
- Move all elements $\leq p$ into left half, elements $\geq p$ into right half
 - Note ambiguity for elements that equal p



- How long does this take?
- Can partition array in place by swapping elements in the wrong half

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Partitioning In-place

- Important not to use an extra array
- Algorithm:
 - Swap pivot with last element, leaving $N-1$
 - Set pointers i, j at beginning, end
 - Move i up array until hit an element $> p$
 - Move j down array until hit an element $< p$
 - Swap elements pointed at by i and j
 - Repeat until i and j meet
 - Swap pivot with element at meeting point
- Keys equal to p are annoying—see book

This inner loop is very simple—just repeated compare and increment. This is why quicksort is so fast.

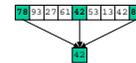
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Choosing Pivot

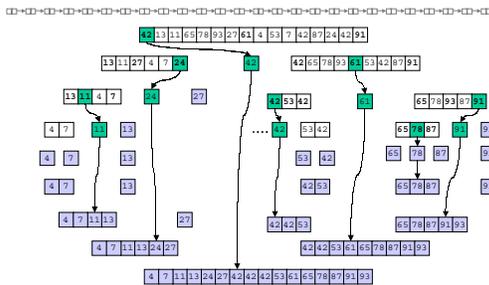
- BAD!**
- Naive: pick first element
 - [17|24|24|42|97|4|42|93]
 - What if it's the smallest or largest? → [1|24|24|42|97|17|42|93]
 - What happens if array was sorted? → [4|17|24|24|42|42|97|93]
 - Optimal: pick the median
 - [17|24|24|42|97|4|42|93]
 - Randomize: pick a random element
 - Makes naive problem very unlikely
 - Requires random number generator
 - Standard trick is *median-of-three*...

Median-of-three pivot selection

- Instead of finding median of whole list, find median of first, middle, and last elements
- Constant time
- Reduces chance of poor behavior compared to just looking at one element, and doesn't have troubles with sorted inputs



Quicksort example



Quicksort Analysis

- Best case: we choose the ideal pivot every time, and split the list evenly
 - $T(0) = T(1) = O(1)$
 - $T(N) = 2 * T(N/2) + O(N)$
 - same as mergesort discussion: $O(N \log N)$
- Worse case: we choose the worst pivot, leaving one of the halves empty
 - $T(0) = T(1) = O(1)$
 - $T(N) = T(N-1) + O(N)$
 - $T(N) = [T(N-2) + O(N-1)] + O(N)$
 - ...
 - $= O(N^2)$

Sorting Choices

- $O(N^2)$
 - Bubble
 - Selection
 - Insertion: may be easiest to remember
- $O(N \log N)$
 - Heapsort
 - Mergesort: simple, easy to remember
 - Quicksort: fastest in practice, danger of $O(N^2)$
- For small N (e.g. < 20), the $N \log N$ sorts are slower due to extra complexity
 - Test N and use simpler sort if small

Quickselect

- Recall that to select the k th smallest item in a list, we have a few choices:
 - k linear scans, removing smallest each time: $O(kN)$
 - make a heap, do k DeleteMin's: $O(N + k \log N)$
- For the median, $k = N/2$, these are $O(N^2)$, $O(N \log N)$
- Quickselect uses a similar divide-and-conquer strategy to quicksort, and runs in $O(N)$ average time, but $O(N^2)$ worst case

Quickselect algorithm

- If array is size 1, we're done
- Otherwise, partition array as with quicksort
 - Left half size L, right half size N - L - 1
 - If k <= L, the kth smallest is in the left half
 - if k = L + 1, the pivot is the kth smallest, stop!
 - if k > L + 1, the kth smallest is in the right half
- Recurse on the side chosen above
- Only one recursive call, unlike quicksort
- $T(N) = T(N/2) + O(N)$
 - = [$T(N/4) + O(N/2)$] + $O(N)$
 - = [$T(N/8) + O(N/4)$] + $O(N/2) + O(N)$
 - ... = $O(N)$

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Sorting large structures

- Sorting involves a lot of swapping, as you've seen
- What if each item is a big data record, e.g. 2000 bytes of info about a student?
 - Don't want to repeatedly copy that much data
- Instead, sort *pointers* to each record
 - Obviously, you don't sort the pointer values themselves—they're just addresses
 - When you want to compare two items, dereference the pointers to get at the sort key in the record

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Bucket sort

- What if set of values have a relatively small range of values? (e.g. 1 to 10,000)
- Allocate array `count [10000]`
- Scan list, for an element `p`, increment `count [p]`
- When done, go through `count` array and output value `v` as many times as `count [v]`
- $O(N)$...doesn't this violate our lower bound proof?
- No. We are no longer limited to comparing one element to another. When we jump directly to the right element of the count array, we are effectively comparing against all N-1 other elements.

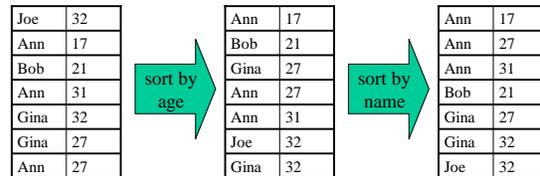
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Stable Sorting

- A stable sort is one that does not change the order of items with the same sort key
- Matters if there was some other ordering already present



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Radix sort

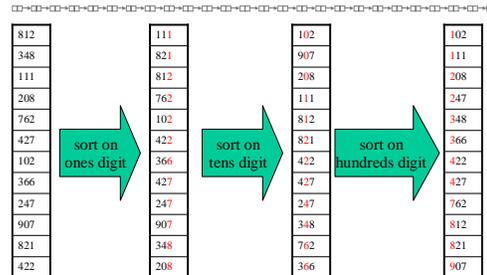
- Bucket sort + stable sorting
- Sometimes bucket sort is unusable because there are too many buckets
- But, if you can divide sort key into "slices", you can bucket sort on each slice
 - e.g. digits in a number, characters in a string
- Trick is to sort on *least* significant slice first, not most significant

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Radix sort example



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