

DS.P.1

Priority Queues

Chapter 6 Overview

- The Concept
- Possible Implementations
- Binary Heaps
- Applications

We will NOT cover

- d-Heaps
- Leftist Heaps
- Skew Heaps
- Binomial Queues

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A **priority queue** is a 'queue' where the first element out is the one with the **minimum key value**, which we will take to mean the **highest priority**.

Operations:

Possible Implementations: complexity?

- **linked list**
Insert adds to the end.
DeleteMin has to search.
- **binary search tree**
Use normal Insert and FindMin.

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Binary Heaps

A **heap** is a binary tree that is full except for the bottom level, which is filled from left to right.

We use an **array implementation** of a binary tree, which saves memory and can be very efficient for this purpose.

A[0] is not used.
A[1] is the root of the tree.
A[i] has children at A[2i] and A[2i+1].
A[i] has parent at A[⌊i/2⌋].

13

21

16

24

31

19

1 2 3 4 5 6 What tree is this?

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Operations for Array Implementation

- Initialize (which also allocates)
- Destroy (which ought to delete)
- MakeEmpty
- Insert
- FindMin
- DeleteMin
- IsEmpty
- IsFull

How do we make the heap an **efficient** structure for priority queue operations?

Keep it in order according to the **heap order property**.

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Heap Order Property

for every node X of the tree:

key(parent(X)) ≤ key(X)

This implies that

- the **minimum value is at the root**
- this is true of any subtree as well

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Inserting in a Binary Heap

```

Insert(X) /* pseudo-code */
- let hole be the next unfilled node in the tree
- while ( X is not yet placed )
  if parent(hole) ≤ X, put X in hole
  else
    1. move the parent's data into hole
    2. let hole be the parent's node

```

We say that X **percolates up** the tree.

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Insertion Example

insert 13

Can I put 13 in the hole?

Will the order property still hold if I move the 20 into the hole?

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Insertion Example

Now can I put the 13 in the hole?

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Insertion Example

Now can I put the 13 in the hole?

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The implementation of Insert is very concise, using only simple array operations and with worst case complexity $O(\log n)$.

...	6	15	10	25	20	12	96	29	40	30	hole	
	0	1	2	3	4	5	6	7	8	9	10	11

...	6	15	10	25	hole	12	96	29	40	30	20	
	0	1	2	3	4	5	6	7	8	9	10	11

...	6	13	10	25	15	12	96	29	40	30	20	
	0	1	2	3	4	5	6	7	8	9	10	11

```
for (i = ++H->Size; H->Elements[i/2] > X; i /= 2)
  H->Elements[i] = H->Elements[i/2];
H->Elements[i] = X;
```

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DeleteMin

```
deleteMin
- Find the minimum value at the root
- Deleting it leaves a hole at the root.
- This hole must percolate down till we can place the last element in it.
- So swap it with its smaller child.
- Continue this process till the last element can be placed in the hole.
```

Try this: first draw it as a tree, then try the process.

6	15	10	25	20	12	96	29	40	30
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Building a Heap from Unordered Data

The idea:

- Put the data in an array.
- Start with the last internal node L.
- Percolate it down to its proper place.
- Continue this process for each internal node.

The code:

```
for (i = N / 2; i > 0; i--)
  PercolateDown(i);
```

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Example

16	7	9	12	5
1	2	3	4	5

$N = 5; N/5 = 2$

1. PercolateDown(2)

2. PercolateDown(1)

Which is Node 1?
Try it!

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Complexity

- Insert ???
- DeleteMin ???
- BuildHeap

Th. The running time of BuildHeap is $O(N)$.

- PercolateDown is called **potentially** for every **nonleaf** node.
- Each time, it can go all the way down, swapping the smallest child with its parent, if needed.
- This is approximately the **sum of the heights** of the nodes in the tree.

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Th. 6.1 For perfect binary tree of height h with $2^{h+1} - 1$ nodes, the sum of the heights is

$$2^{h+1} - 1 - (h+1)$$

4. Therefore, for 2^{h+1} nodes, the sum is $O(2^{h+1})$,
and for N nodes, the sum is $O(N)$.

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Applications of Heaps

- job and process queues
- event queues in simulation

random event generator → event queue → server

Simulation clock starts at time 0. Instead of checking what events happen at every tick, we just find the **next event** (the one with minimum starting time) and change the clock to that time.

Clock: 0, 5, 14, 23, 28, ...

- sorting

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Heapsort (from Chapter 7)

How can we use a heap to achieve sorting an array into ascending order?

- Build a **max heap** (instead of a min heap) in the array.
- Use DeleteMax (which is just like DeleteMin) to **remove the largest element**.
- Put that largest element **at the end** of the array, which will have become an empty spot through operation of DeleteMax.

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Heapsort Example

50	25	30	1	3	15	28
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What does the array look like after the max element is deleted?

Then what does it look like after the max element is put at the end?

Heapsort Complexity

For n elements

It takes $2n$ comparisons to build the heap.

After that there are n sorting steps

with $2\log_2 i$ comparisons at the i th step.

$$2n + 2 \sum_{i=1}^n \log_2 i \quad \text{This term dominates.}$$

$$= O(n \log_2 n)$$