

Design of Digital Circuits and Systems

Memory I

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Relevant Course Information

- ❖ hw1 can still be submitted tonight (1 late day)
 - Solution outline will be posted tomorrow (UW login)
- ❖ hw2 released today, due next Wednesday (4/16)
- ❖ Lab 1 reports due Friday (4/11), demos 4/14-18
- ❖ Lab 2 released today, due next Friday (4/18)
- ❖ Quiz 1 is Thursday, 4/10 in last 25 min of lecture
 - FSM design – state diagram, explain design decisions
 - 23sp, 24sp Quiz 1 available for practice on course website

Review Question

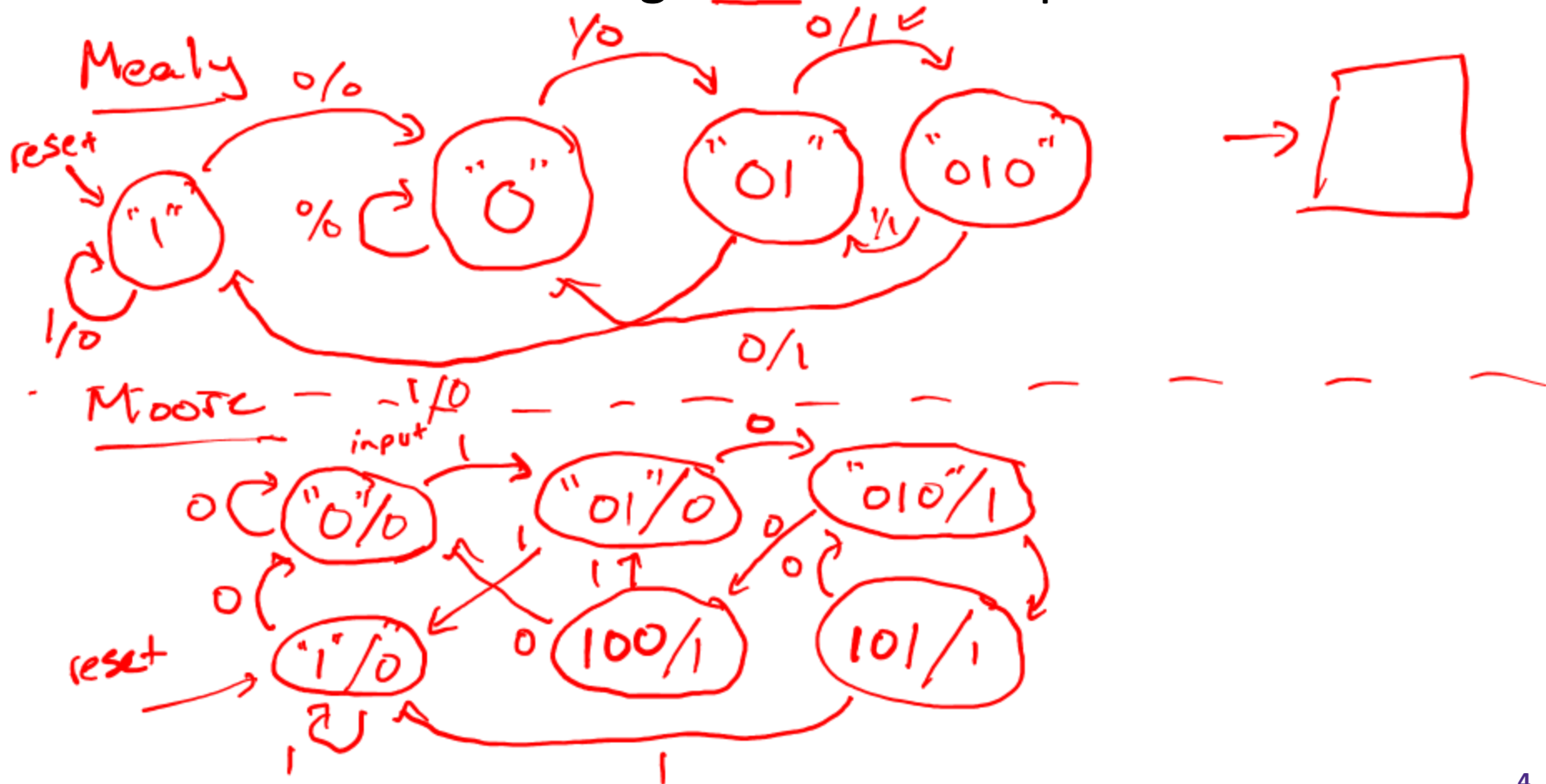
- ❖ Design a FSM that will output two consecutive 1's any time it sees the string "010" and outputs 0 otherwise
 - 1 input bit and 1 output bit
 - How many state bits do we need?
 - Which state should be your initial/reset state?
- ❖ If you have time, design both a **Moore** machine and **Mealy** machine "from scratch" (*i.e.*, don't convert between the two)
 - Which seems easier to implement? Can you name specific ways that the SystemVerilog implementation will be "easier"?

Review Solution

0100
01

000
111

- ❖ Design a FSM that will output two consecutive 1's any time it sees the string "010" and outputs 0 otherwise



Aside: Powers of 2 and Prefixes

- ❖ Here focusing on large numbers (*i.e.*, exponents > 0)
- ❖ SI prefixes are *ambiguous* if base 10 or 2
 - Note that $10^3 \approx 2^{10}$
- ❖ IEC prefixes are *unambiguously* base 2

SIZE PREFIXES (10^x for Disk, Communication; 2^x for Memory)

SI Size	Prefix	Symbol	IEC Size	Prefix	Symbol
10^3	Kilo-	K	2^{10}	Kibi-	Ki
10^6	Mega-	M	2^{20}	Mebi-	Mi
10^9	Giga-	G	2^{30}	Gibi-	Gi
10^{12}	Tera-	T	2^{40}	Tebi-	Ti
10^{15}	Peta-	P	2^{50}	Pebi-	Pi
10^{18}	Exa-	E	2^{60}	Exbi-	Ei
10^{21}	Zetta-	Z	2^{70}	Zebi-	Zi
10^{24}	Yotta-	Y	2^{80}	Yobi-	Yi

$2^0 = 1$
$2^1 = 2$
$2^2 = 4$
$2^3 = 8$
$2^4 = 16$
$2^5 = 32$
$2^6 = 64$
$2^7 = 128$
$2^8 = 256$
$2^9 = 512$
$2^{10} = 1024$

Large Powers of 2 and Units

- ❖ Because IEC prefixes are powers of 2^{10} , we can convert any large power of 2 as follows:
 - Note that we are only changing the *quantity* and the *units* remain the same

$$2^{XY} \text{ "things"} = \left[\begin{array}{l} Y=0 \rightarrow 1 \\ Y=1 \rightarrow 2 \\ Y=2 \rightarrow 4 \\ Y=3 \rightarrow 8 \\ Y=4 \rightarrow 16 \\ Y=5 \rightarrow 32 \\ Y=6 \rightarrow 64 \\ Y=7 \rightarrow 128 \\ Y=8 \rightarrow 256 \\ Y=9 \rightarrow 512 \end{array} \right] + \left[\begin{array}{l} X=0 \rightarrow \\ X=1 \rightarrow \text{Kibi-} \\ X=2 \rightarrow \text{Mebi-} \\ X=3 \rightarrow \text{Gibi-} \\ X=4 \rightarrow \text{Tebi-} \\ X=5 \rightarrow \text{Pebi-} \\ X=6 \rightarrow \text{Exbi-} \\ X=7 \rightarrow \text{Zebi-} \\ X=8 \rightarrow \text{Yobi-} \end{array} \right] + \text{"things"}$$

❖ Examples:

- 2 GiB of memory?
- 2^{47} things into IEC:

$$2^1 \times 2^{30} = 2^{31} \text{ bytes}$$

$$2^7 \times 2^{40} = 128 \text{ TiB}$$

Memory

- ❖ Several forms of memory are available, which include:
 - ~~Secondary memory (e.g., hard disk, flash drive)~~
 - Read-only memory (ROM)
 - Random-access memory (RAM)
 - Register files
 - Small, fast, fixed-sized memory that hold CPU data state
 - First in, first out (FIFO) buffers

Embedded FPGA Memory

- ❖ An FPGA contains prefabricated memory modules
 - Intended for small or intermediate-sized storage
 - Contents of memory blocks can be configured via memory initialization files (*.mif*)
- ❖ The DE1-SoC's Cyclone V FPGA (Cyclone V SE A5) has:
 - 31k Adaptive Logic Modules (ALMs)
 - 4.45 Mbits of memory organized as 397 memory blocks, each with 10 kbits of storage (M10K)
 - Flexible, configurable memory storage available to the designer
 - Each M10K can act as single-port memory, dual-port RAM, shift register, ROM, or a FIFO buffer
 - More info on website: DE1-SoC → Cyclone V Handbook

DE1-SoC Memory

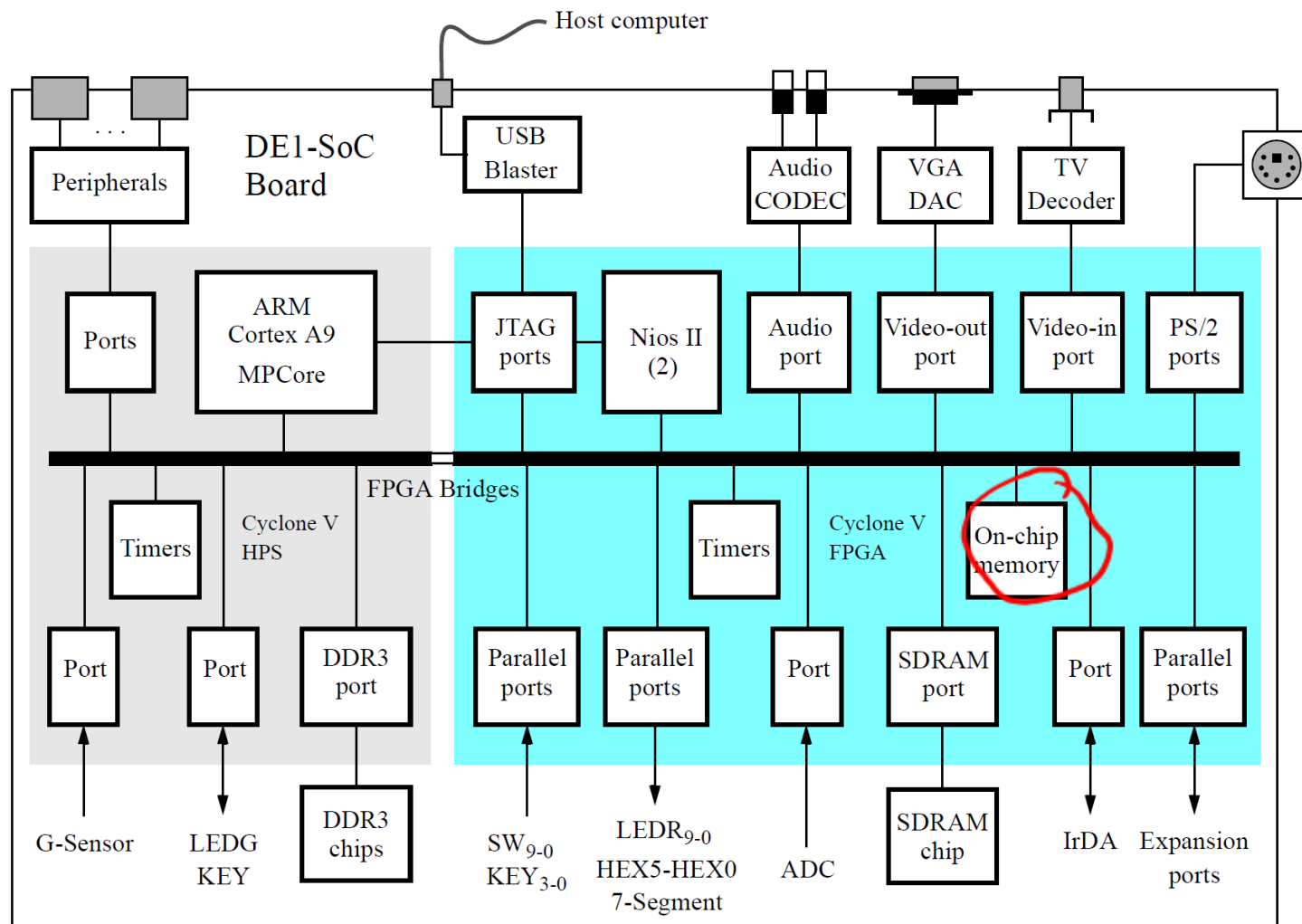
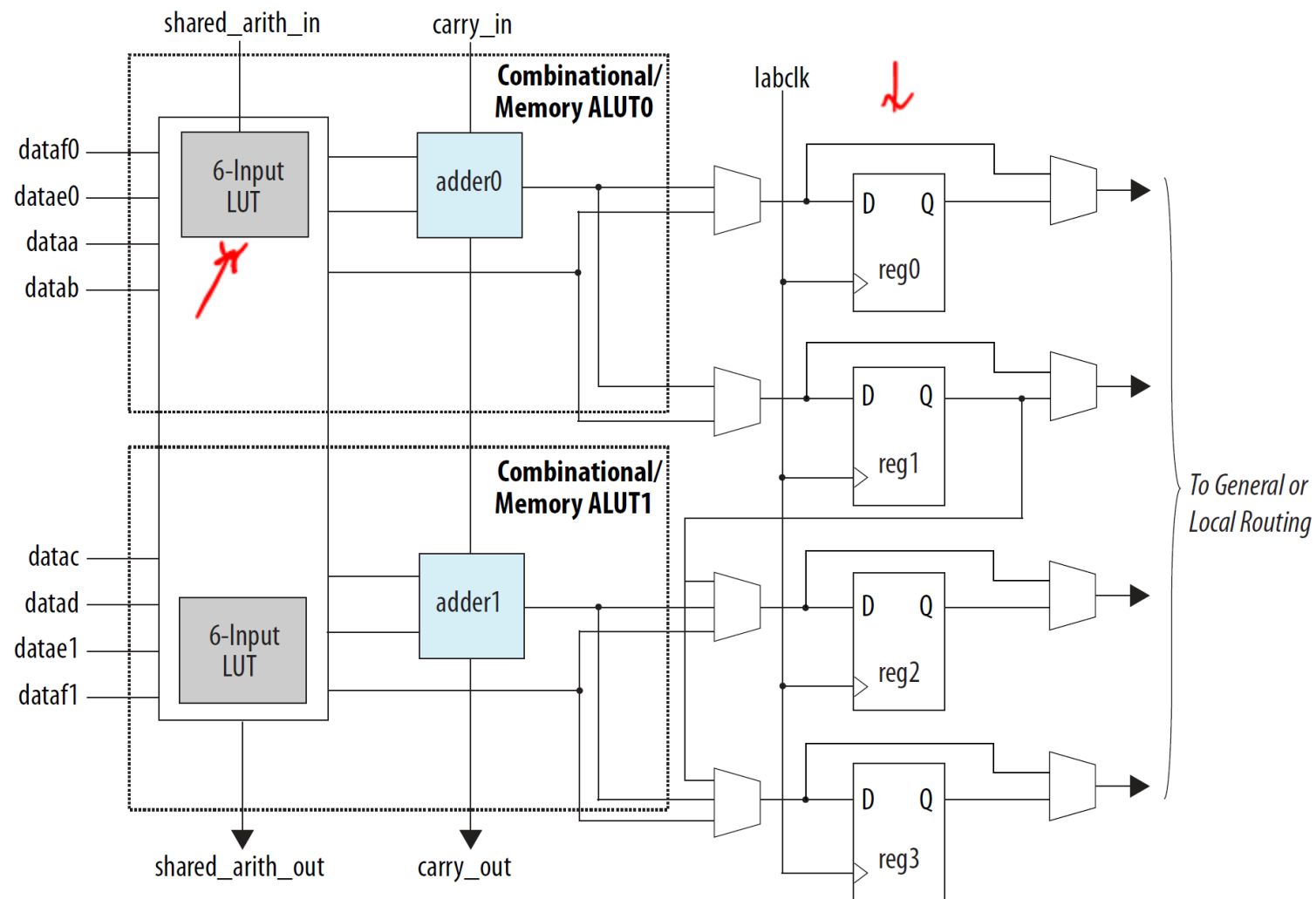


Figure 1. Block diagram of the DE1-SoC Computer.

Cyclone V Adaptive Logic Modules

https://www.altera.com/content/dam/altera-www/global/en_US/pdfs/literature/hb/cyclone-v/cv_5v2.pdf

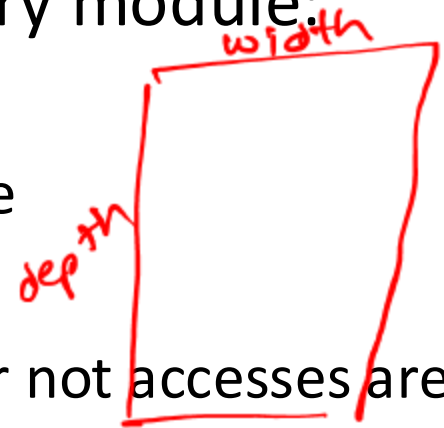
Figure 1-5: ALM High-Level Block Diagram for Cyclone V Devices



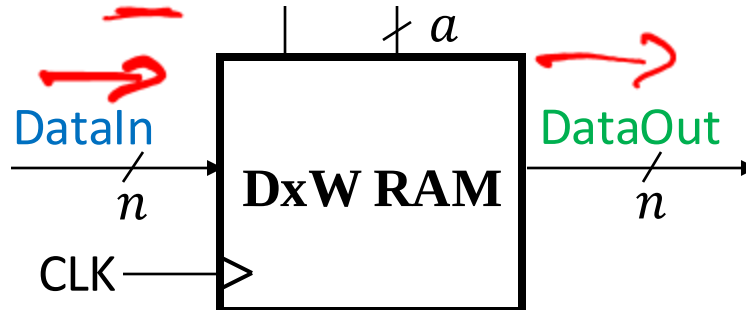
Memory Modules

❖ Key characteristics of a simple memory module:

- Width – the number of bits in a word
- Depth – the number words in the module
- Number of ports
- Synchronicity of port access – whether or not accesses are controlled by a clock signal
- Simultaneous address access – can the same address be used for both read and write operations



❖ Example: WriteEnable Address



Memory Characteristics

❖ Memory units are specified as depth × width.

❖ For the following memory units, answer:

1) Memory capacity (in bits and bytes using IEC prefixes)

2) Width of address bus (a)

3) Width of data output bus (n)

❖ Memory 1: 8Ki × 32

2^3 2^{10} 2^5

① $2^{18} = 256 \text{ Ki bits} = 32 \text{ Ki B}$

② 13 bits

③ 32 bits

❖ Memory 2: 2Gi × 8

2^1 2^{30} 2^3

① $2^{34} = 16 \text{ Gi bits} = 2 \text{ Gi bytes}$

② 31 bits

③ 8 bits

of addresses
↓

size of word
↙



Technology Break

Memory Type #1: ROM

❖ Read-Only Memory

- A purely *combinational* circuit (no internal state)
- Output is determined solely by address input

❖ In an FPGA:

- No actual embedded ROM, but can be emulated by a combinational circuit or a RAM with the write operation disabled
- Only practical for small tables

❖ In SystemVerilog:

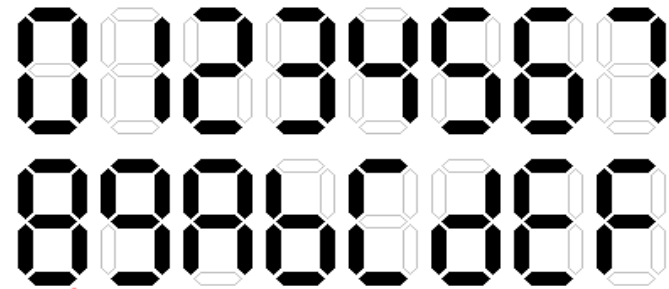
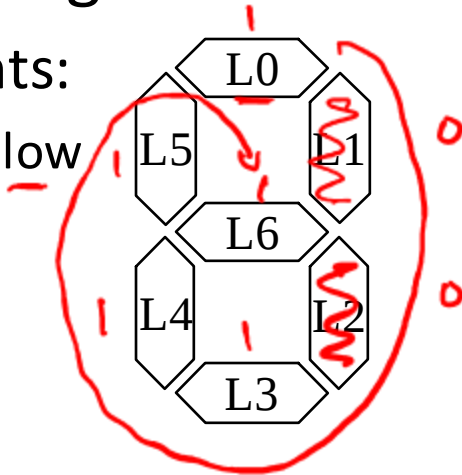
- Define the ROM content as a 2-dimensional constant
- Oftentimes a selected assignment or case statement

Example ROM

❖ Hex-to-7seg LED decoder:

■ Segments:

- Active low



❖ ROM size?

16×7 bits

depth

address

B3	B2	B1	B0	L0	L1	L2	L3	L4	L5	L6
0	0	0	0	0	0	0	0	0	0	1
0	0	0	1	1	<u>0</u>	<u>0</u>	1	1	1	1
0	0	1	0	0	0	1	0	0	1	0
		:					:			
1	1	0	1	1	0	0	0	0	1	0
1	1	1	0	0	1	1	0	0	0	0
1	1	1	1	0	1	1	1	0	0	0

width

Example ROM (SystemVerilog)

```
module ROM_case(addr, data);
```

```
endmodule
```

Example ROM (SystemVerilog)

```
module ROM_case(addr, data);  
    input  logic [3:0] addr;  
    output logic [6:0] data;  
    always_comb  
        case (addr)  
            //                               L6543210  
            4'h0: data = 7'b1000000;  
            4'h1: data = 7'b1111001;  
            4'h2: data = 7'b0100100;  
            // ...  
            4'hD: data = 7'b0100001;  
            4'hE: data = 7'b0000110;  
            4'hF: data = 7'b0001110;  
        endcase  
    endmodule
```



Reading Data from a File

- ❖ Hard-coded values in your SV files can be tedious to format, debug, and swap out!
- ❖ Verilog provides *system tasks* to read data from a text file into an array: `$readmemb()` and `$readmemh()`
 - Basic usage: `$readmemb("file.txt", my_array);`
 - Reads in numerals (in **binary** or **hex**) from file separated by *whitespace* (*i.e.*, spaces, tabs, newlines)
 - Can avoid some recompilation
 - File can have any extension
 - Be very careful with dimensions of array and ordering of data in file!

Example ROM (SystemVerilog)

```
module ROM_file(addr, data);  
    input  logic [3:0] addr;  
    output logic [6:0] data;  
  
    logic [6:0] ROM [0:15]; // (!) unpacked dimension  
  
    initial  
        // reads binary values from file into array  
        $readmemb("seg7decode.txt", ROM);  
  
    assign data = ROM[addr];  
endmodule
```

seg7decode.txt:

10000000	11111001	0100100	0110000
0011001	0010010	0000010	1111000
0000000	0010000	0001000	0000011
1000110	0100001	0000110	0001110

Example ROM (SystemVerilog)

```

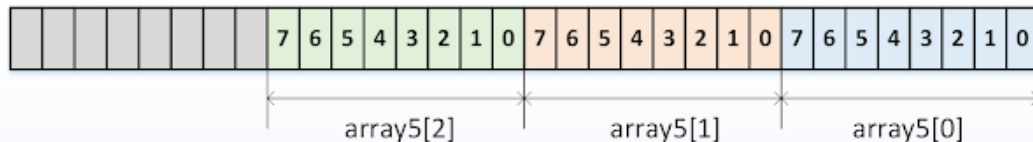
module ROM_file(addr, data);

    input  logic [3:0] addr;
    output logic [6:0] data;

    logic [6:0] ROM [0:15]; // (!) unpacked dimension

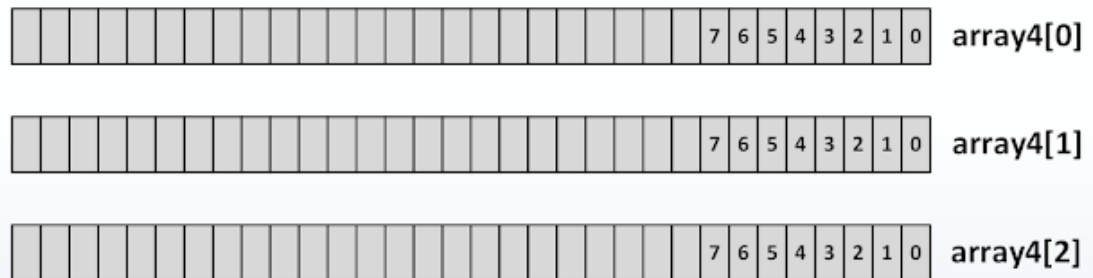
```

// packed array declaration
`bit [2:0] [7:0] array5;`



*m file into array
 , ROM);*

// unpacked array declaration
`bit [7:0] array4[2:0];`



seg7decode.txt:

1
0
0
1

Example ROM (SystemVerilog)

```

module ROM_file(addr, data);
    input  logic [3:0] addr;
    output logic [6:0] data;
    logic [6:0] ROM [0:15]; // (!) unpacked dimension
    initial
        // reads binary values from file into array
        $readmemb("seg7decode.txt", ROM);
    → assign data = ROM[addr];
endmodule

```

Handwritten annotations:

- width* (under [6:0] of ROM)
- depth* (under [0:15] of ROM)
- ROM[0]* (with arrow pointing to the first row of the data table)
- ROM[15]* (with arrow pointing to the last row of the data table)

seg7decode.txt: →

10000000	1111001	0100100	0110000
0011001	0010010	0000010	1111000
0000000	0010000	0001000	0000011
1000110	0100001	0000110	0001110

Dynamic Array Indexing Operation

- ❖ A signal can be used as an index to access an element in the array:

```
assign data = ROM[addr];
```

equivalent to

```
always_comb
  case (addr)
    4'h0: data = ROM[0];
    4'h1: data = ROM[1];
    // ...
    4'hE: data = ROM[14];
    4'hF: data = ROM[15];
  endcase
```

Synchronicity Revisited



- ❖ To synchronize either the address input or ROM output, we can add a register as appropriate
 - Sometimes called “registering” the input or output to make your module “synchronous”
 - In SystemVerilog, can be done inside or outside of the module:

```
initial
    $readmemb("seg7decode.txt", ROM);

// internally-registered ROM module
→ always_ff @(posedge clk)
    data <= ROM[addr];
```

Memory Type #2: RAM

❖ Random-Access Memory

- Can read and write to any address instead of having to read in sequence (*e.g.*, a magnetic disk)

❖ Can be implemented using different semiconductor technologies:

- Static RAM (SRAM): uses flip-flops to store data
- Dynamic RAM (DRAM): uses capacitors and transistors to store data that need to be periodically refreshed
- SRAM is faster but more expensive than DRAM

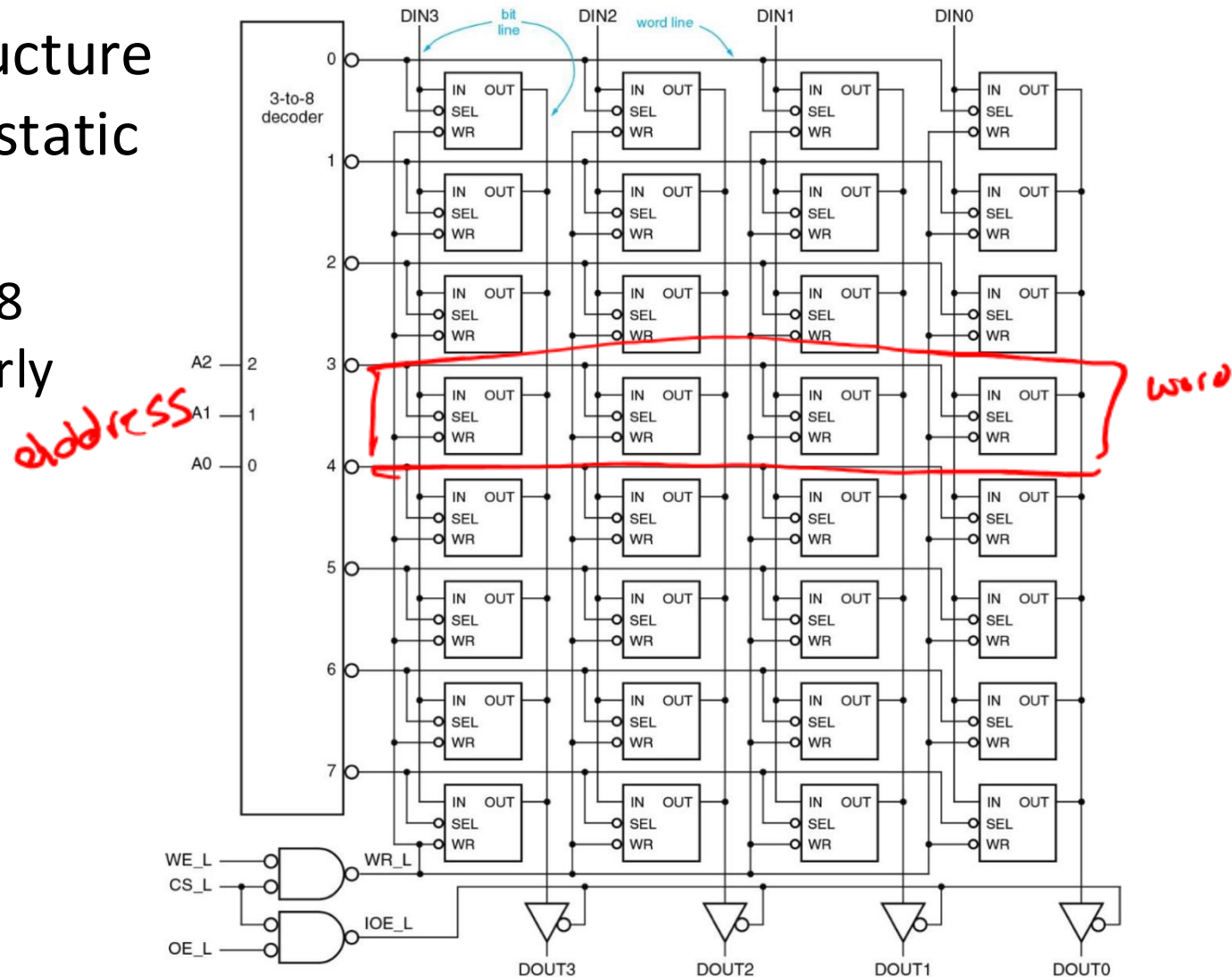
❖ In a typical home computer:

- CPU registers and caches are SRAM
- “Memory” is *synchronous* DRAM (SDRAM)

Example RAM Hardware

- ❖ Internal structure of an 8×4 static RAM:

- Figure 15.18 from Wakerly



RAM Variants

❖ Note that not all of the terminology used here is standardized:

1) Synchronicity

- Are the operations controlled by the clock?
- Can be applied to reading and writing independently

2) Number of ports

- Not in the same sense as number of SV module ports
- Can roughly think of as “channels” (set of addr in, data in, write enable, and data out ports) – how many reads and writes can occur simultaneously?

3) Address independence

- Are the port's read and write operation based on the same or independent addr in buses?

Synchronous Single-Port RAM

❖ Synchronous Inputs:

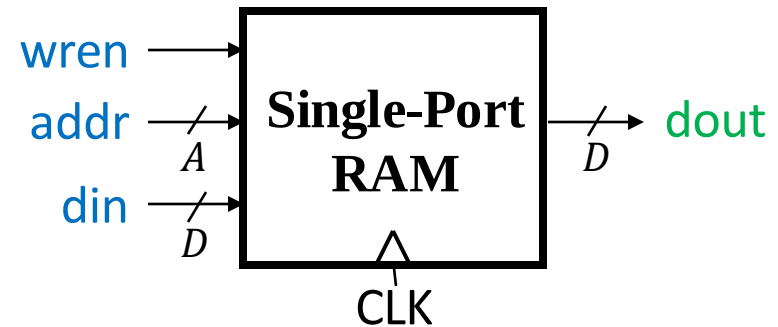
- wren (1 = write, 0 = read)
- addr (A -bit address)
- din (D -bit data)

❖ Synchronous Output:

- dout (D -bit data)

❖ Implementation hints:

- Will need an internal RAM array of what size?
- To synchronize, should update on clock triggers
- What should dout do when wren = 1?



Synchronous Single-Port RAM (SV)

```
module RAM_single #(parameter A, D)
    (clk, wren, addr, din, dout);
```

```
endmodule
```

Synchronous Single-Port RAM (SV)

```
module RAM_single #(parameter A, D)
    (clk, wren, addr, din, dout);

    input  logic clk, wren;
    input  logic [A-1:0] addr;
    input  logic [D-1:0] din;
    output logic [D-1:0] dout;

    logic [D-1:0] RAM [0:2**A-1];

    always_ff @(posedge clk) begin
        if (wren) begin
            RAM[addr] <= din;
            dout <= din;
        end
        else
            dout <= RAM[addr];
    end // always_ff
endmodule
```