Sequential logic examples

- Basic design approach: a 4-step design process
- Hardware description languages and finite state machines
- Implementation examples and case studies
 - finite-string pattern recognizer
 - complex counter
 - traffic light controller
 - door combination lock

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General FSM design procedure

- (1) Determine inputs and outputs
- (2) Determine possible states of machine
 - state minimization
- (3) Encode states and outputs into a binary code
 - state assignment or state encoding
 - output encoding
 - possibly input encoding (if under our control)
- (4) Realize logic to implement functions for states and outputs
 - combinational logic implementation and optimization
 - □ choices in steps 2 and 3 can have large effect on resulting logic

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Finite string pattern recognizer (step 1)

- Finite string pattern recognizer
 - one input (X) and one output (Z)
 - output is asserted whenever the input sequence ...010... has been

observed, as long as the sequence ...100... has never been seen

- Step 1: understanding the problem statement
 - sample input/output behavior:

X: 00101010010...

Z: 00010101000...

X: 11011010010... Z: 00000001000...

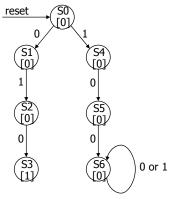
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Finite string pattern recognizer (step 2)

- Step 2: draw state diagram
 - for the strings that must be recognized, i.e., 010 and 100
 - a Moore implementation



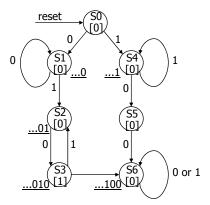
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Finite string pattern recognizer (step 2, cont'd)

- Exit conditions from state S3: have recognized ...010
 - □ if next input is 0 then have ...0100 = ...100 (state S6)
 - □ if next input is 1 then have ...0101 = ...01 (state S2)
- Exit conditions from S1: recognizes strings of form ...0 (no 1 seen)
 - loop back to S1 if input is 0
- Exit conditions from S4: recognizes strings of form ...1 (no 0 seen)
 - loop back to S4 if input is 1

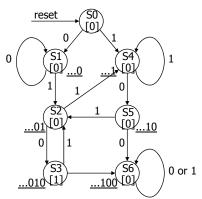


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Finite string pattern recognizer (step 2, cont'd)

- S2 and S5 still have incomplete transitions
 - S2 = ...01; If next input is 1, then string could be prefix of (01)1(00)
 S4 handles just this case
 - S5 = ...10; If next input is 1, then string could be prefix of (10)1(0)
 S2 handles just this case
- Reuse states as much as possible
 - look for same meaning
 - state minimization leads to smaller number of bits to represent states
- Once all states have a complete set of transitions we have a final state diagram



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Finite string pattern recognizer (step 3)

Verilog description including state assignment (or state encoding)

```
always @(posedge clk) begin
module string (clk, X, rst, Q0, Q1, Q2, Z);
input clk, X, rst;
                                                                     if (rst) state = S0;
output Q0, Q1, Q2, Z;
                                                                      else
                                                                        S0: if (X) state = S4 else state = S1;
parameter S0 = [0,0,0]; //reset state
parameter S1 = [0,0,1]; //strings ending in ...0 parameter S2 = [0,1,0]; //strings ending in ...01 parameter S3 = [0,1,1]; //strings ending in ...010
                                                                       S1: if (X) state = S2 else state = S1;
S2: if (X) state = S4 else state = S3;
S3: if (X) state = S2 else state = S6;
parameter S4 = [1,0,0]; //strings ending in ...1
                                                                        S4: if (X) state = S4 else state = S5;
S5: if (X) state = S2 else state = S6;
parameter S5 = [1,0,1]; //strings ending in ...10
parameter S6 = [1,1,0]; //strings ending in ...100
                                                                        S6: state = S6;
                                                                         default: begin
                                                                             $display ("invalid state reached");
                                                                            state = 3'bxxx;
assign Q0 = state[0];
                                                                          end
assign Q1 = state[1];
                                                                        endcase
assign Q2 = state[2];
assign Z = (state == S3);
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```

Finite string pattern recognizer

- Review of process
 - understanding problem
 - write down sample inputs and outputs to understand specification
 - derive a state diagram
 - write down sequences of states and transitions for sequences to be recognized
 - minimize number of states
 - add missing transitions; reuse states as much as possible
 - state assignment or encoding
 - encode states with unique patterns
 - simulate realization
 - verify I/O behavior of your state diagram to ensure it matches specification

Complex counter

- A synchronous 3-bit counter has a mode control M
 - □ when M = 0, the counter counts up in the binary sequence
 - □ when M = 1, the counter advances through the Gray code sequence

binary: 000, 001, 010, 011, 100, 101, 110, 111 Gray: 000, 001, 011, 010, 110, 111, 101, 100

Valid I/O behavior (partial)

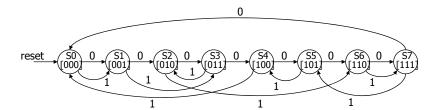
Mode Input M	Current State	Next State		
0	000	001		
0	001	010		
1	010	110		
1	110	111		
1	111	101		
0	101	110		
0	110	111		

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Complex counter (state diagram)

- Deriving state diagram
 - one state for each output combination
 - add appropriate arcs for the mode control



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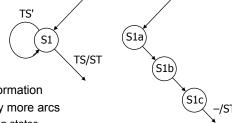
Complex counter (state encoding)

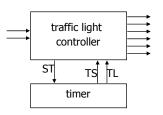
Verilog description including state encoding

```
module string (clk, M, rst, Z0, Z1, Z2);
                                                always @(posedge clk) begin
input clk, X, rst;
                                                  if rst state = S0;
output Z0, Z1, Z2;
                                                  else
                                                    case (state)
parameter S0 = [0,0,0];
                                                      S0: state = S1;
parameter S1 = [0,0,1];
                                                      S1: if (M) state = S3 else state = S2;
parameter S2 = [0,1,0];
                                                      S2: if (M) state = S6 else state = S3;
parameter S3 = [0,1,1];
                                                      S3: if (M) state = S2 else state = S4;
parameter S4 = [1,0,0];
                                                      S4: if (M) state = S0 else state = S5;
parameter S5 = [1,0,1];
                                                      S5: if (M) state = S4 else state = S6;
parameter S6 = [1,1,0];
                                                      S6: if (M) state = S7 else state = S7;
parameter S7 = [1, 1, 1];
                                                      S7: if (M) state = S5 else state = S0;
                                                 endcase
reg state[0:2];
                                                end
assign Z0 = state[0];
assign Z1 = state[1];
                                                endmodule
assign Z2 = state[2];
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                                                                                             11
```

Traffic light controller as two communicating FSMs

- Without separate timer
 - S0 would require 7 states
 - S1 would require 3 states
 - S2 would require 7 states
 - S3 would require 3 states
 - S1 and S3 have simple transformation
 - S0 and S2 would require many more arcs
 - C could change in any of seven states
- By factoring out timer
 - greatly reduce number of states
 - 4 instead of 20
 - counter only requires seven or eight states
 - 12 total instead of 20





12

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Traffic light controller FSM

Specification of inputs, outputs, and state elements

```
module FSM(HR, HY, HG, FR, FY, FG, ST, TS, TL, C, reset, Clk);
 output
            HR;
 output
 output
            HG;
                                       parameter highwaygreen = 6'b001100;
 output
            FR;
                                        parameter highwayyellow = 6'b010100;
 output
            FY;
                                       parameter farmroadgreen = 6'b100001;
            FG;
 output
                                        parameter farmroadyellow = 6'b100010;
  output
            ST;
            TS;
 input
 input
           TL;
                                       assign HR = state[6];
            C:
 input
                                       assign HY = state[5];
  input
            reset;
                                        assign HG = state[4];
            Clk;
 input
                                       assign FR = state[3];
                                        assign FY = state[2];
 reg [6:1] state;
                                        assign FG = state[1];
            ST;
  reg
       specify state bits and codes
       for each state as well as
13
```

Traffic light controller FSM (cont'd)

```
initial begin state = highwaygreen; ST = 0; end
  always @(posedge Clk) 👞
                                                             case statement
    begin
                                                             triggerred by
       if (reset)
                                                             clock edge
        begin state = highwaygreen; ST = 1; end
         begin
           ST = 0;
           case (state) *
             highwaygreen:
               if (TL & C) begin state = highwayyellow; ST = 1; end
             highwayyellow:
               if (TS) begin state = farmroadgreen; ST = 1; end
             farmroadgreen:
               if (TL | !C) begin state = farmroadyellow; ST = 1; end
             farmroadyellow:
               if (TS) begin state = highwaygreen; ST = 1; end
           endcase
         end
    end
endmodule
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```

Timer for traffic light controller

Another FSM

```
module Timer(TS, TL, ST, Clk);
  output TS;
  output TL;
  input ST;
  input Clk;
  integer value;

  assign TS = (value >= 4); // 5 cycles after reset
  assign TL = (value >= 14); // 15 cycles after reset
  always @(posedge ST) value = 0; // async reset
  always @(posedge Clk) value = value + 1;
endmodule
```

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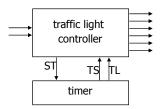
15

Complete traffic light controller

- Tying it all together (FSM + timer)
 - structural Verilog (same as a schematic drawing)

```
module main(HR, HY, HG, FR, FY, FG, reset, C, Clk);
output HR, HY, HG, FR, FY, FG;
input reset, C, Clk;

Timer part1(TS, TL, ST, Clk);
FSM part2(HR, HY, HG, FR, FY, FG, ST, TS, TL, C, reset, Clk);
endmodule
```

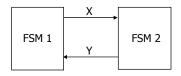


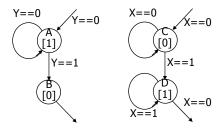
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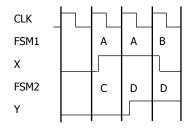
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Communicating finite state machines

• One machine's output is another machine's input







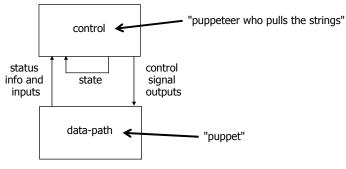
machines advance in lock step initial inputs/outputs: X = 0, Y = 0

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Data-path and control

- Digital hardware systems = data-path + control
 - datapath: registers, counters, combinational functional units (e.g., ALU), communication (e.g., busses)
 - control: FSM generating sequences of control signals that instructs datapath what to do next



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18

Digital combinational lock

- Door combination lock:
 - punch in 3 values in sequence and the door opens; if there is an error the lock must be reset; once the door opens the lock must be reset
 - inputs: sequence of input values, reset
 - outputs: door open/close
 - memory: must remember combination or always have it available
 - open questions: how do you set the internal combination?
 - stored in registers (how loaded?)
 - hardwired via switches set by user

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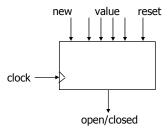
19

Implementation in software

```
integer combination lock ( ) {
   integer v1, v2, v3;
    integer error = 0;
    static integer c[3] = 3, 4, 2;
    while (!new_value());
    v1 = read value();
    if (v1 != c[1]) then error = 1;
    while (!new_value());
    v2 = read_value();
    if (v2 != c[2]) then error = 1;
    while (!new_value());
    v3 = read value();
    if (v2 != c[3]) then error = 1;
    if (error == 1) then return(0); else return (1);
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```

Determining details of the specification

- How many bits per input value?
- How many values in sequence?
- How do we know a new input value is entered?
- What are the states and state transitions of the system?



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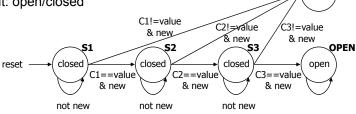
ERR

closed

21

Digital combination lock state diagram

- States: 5 states
 - represent point in execution of machine
 - each state has outputs
- Transitions: 6 from state to state, 5 self transitions, 1 global
 - changes of state occur when clock says its ok
- based on value of inputs
- Inputs: reset, new, results of comparisons
- Output: open/closed

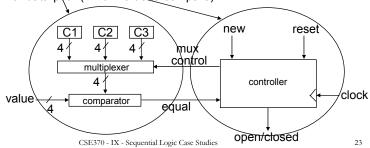


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- Data-path
 - storage registers for combination values
 - multiplexer
 - comparator
- Control ~
 - finite-state machine controller
 - control for data-path (which value to compare)



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State table for combination lock

- Finite-state machine
 - refine state diagram to take internal structure into account
 - state table ready for encoding

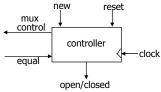
reset	new	egual	state	next state	mux	open/closed
1	-	-	_	S1	C1	closed
0	0	-	S1	S1	C1	closed
0	1	0	S1	ERR	_	closed
0	1	1	S1	S2	C2	closed
0	1	1	S3	OPEN	-	open

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Encodings for combination lock

- Encode state table
 - state can be: S1, S2, S3, OPEN, or ERR
 - needs at least 3 bits to encode: 000, 001, 010, 011, 100
 - and as many as 5: 00001, 00010, 00100, 01000, 10000
 - choose 4 bits: 0001, 0010, 0100, 1000, 0000
 - output mux can be: C1, C2, or C3
 - needs 2 to 3 bits to encode
 - choose 3 bits: 001, 010, 100
 - output open/closed can be: open or closed
 - needs 1 or 2 bits to encode
 - choose 1 bit: 1, 0



reset	new	equal	state	state	mux	open,	/closed
1	-	-	-	0001	001	0	
0	0	-	0001	0001	001	0	mux is ic
0	1	0	0001	0000	-	0	open/clo
0	1	1	0001	0010	010	0	therefore
							FFs to ho
0	1	1	0100	1000	-	1	
				'			

dentical to last 3 bits of state osed is identical to first bit of state re, we do not even need to implement nold state, just use outputs

25

Data-path implementation for combination lock

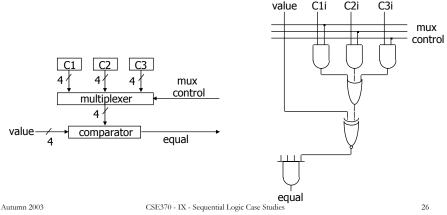
Multiplexer

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easy to implement as combinational logic when few inputs

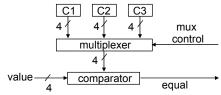
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logic can easily get too big for most PLDs



Data-path implementation (cont'd)

- Tri-state logic
 - utilize a third output state: "no connection" or "float"
 - connect outputs together as long as only one is "enabled"
 - open-collector gates can only output 0, not 1
 - can be used to implement logical AND with only wires



value C1i C2i C3i

mux
control

tri-state driver
(can disconnect
from output)

open-collèctor connection (zero whenever one connection is zero, one otherwise – wired AND)

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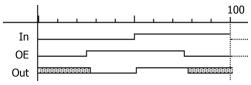
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21

Tri-state gates

- The third value
 - logic values: "0", "1"
 - don't care: "X" (must be 0 or 1 in real circuit!)
 - □ third value or state: "Z" high impedance, infinite R, no connection
- Tri-state gates
 - □ additional input output enable (OE)
 - output values are 0, 1, and Z
 - when OE is high, the gate functions normally
 - when OE is low, the gate is disconnected from wire at output
 - allows more than one gate to be connected to the same output wire
 - as long as only one has its output enabled at any one time (otherwise, sparks could fly)

In	OE	Out
X	0	Z
0	1	0
1	1	1



In

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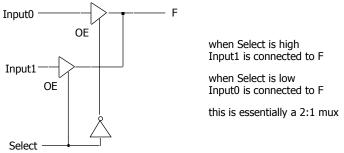
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Out

OE

Tri-state and multiplexing

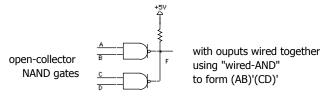
- When using tri-state logic
 - (1) make sure never more than one "driver" for a wire at any one time (pulling high and low at the same time can severely damage circuits)
 - (2) make sure to only use value on wire when its being driven (using a floating value may cause failures)
- Using tri-state gates to implement an economical multiplexer



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Open-collector gates and wired-AND

- Open collector: another way to connect gate outputs to the same wire
 - gate only has the ability to pull its output low
 - □ it cannot actively drive the wire high (default pulled high through resistor)
- Wired-AND can be implemented with open collector logic
 - □ if A and B are "1", output is actively pulled low
 - □ if C and D are "1", output is actively pulled low
 - if one gate output is low and the other high, then low wins
 - if both gate outputs are "1", the wire value "floats", pulled high by resistor
 - low to high transition usually slower than it would have been with a gate pulling high
 - hence, the two NAND functions are ANDed together



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Digital combination lock (new data-path)

- Decrease number of inputs
- Remove 3 code digits as inputs
 - use code registers
 - make them loadable from value
 - □ need 3 load signal inputs (net gain in input (4*3)–3=9)
 - could be done with 2 signals and decoder (ld1, ld2, ld3, load none)

value

Id1 Id2 Id3

| C1 | C2 | C3 | mux | control | comparator | equal

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31

Section summary

- FSM design
 - understanding the problem
 - generating state diagram
 - communicating state machines
- Four case studies
 - understand I/O behavior
 - draw diagrams
 - enumerate states for the "goal"
 - expand with error conditions
 - reuse states whenever possible

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