Caches II

CSE 351 Spring 2019

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Administrivia

- Lab 3, due Wednesday (5/15)
- Homework 4 , due Wed (5/22) (Structs, Caches)

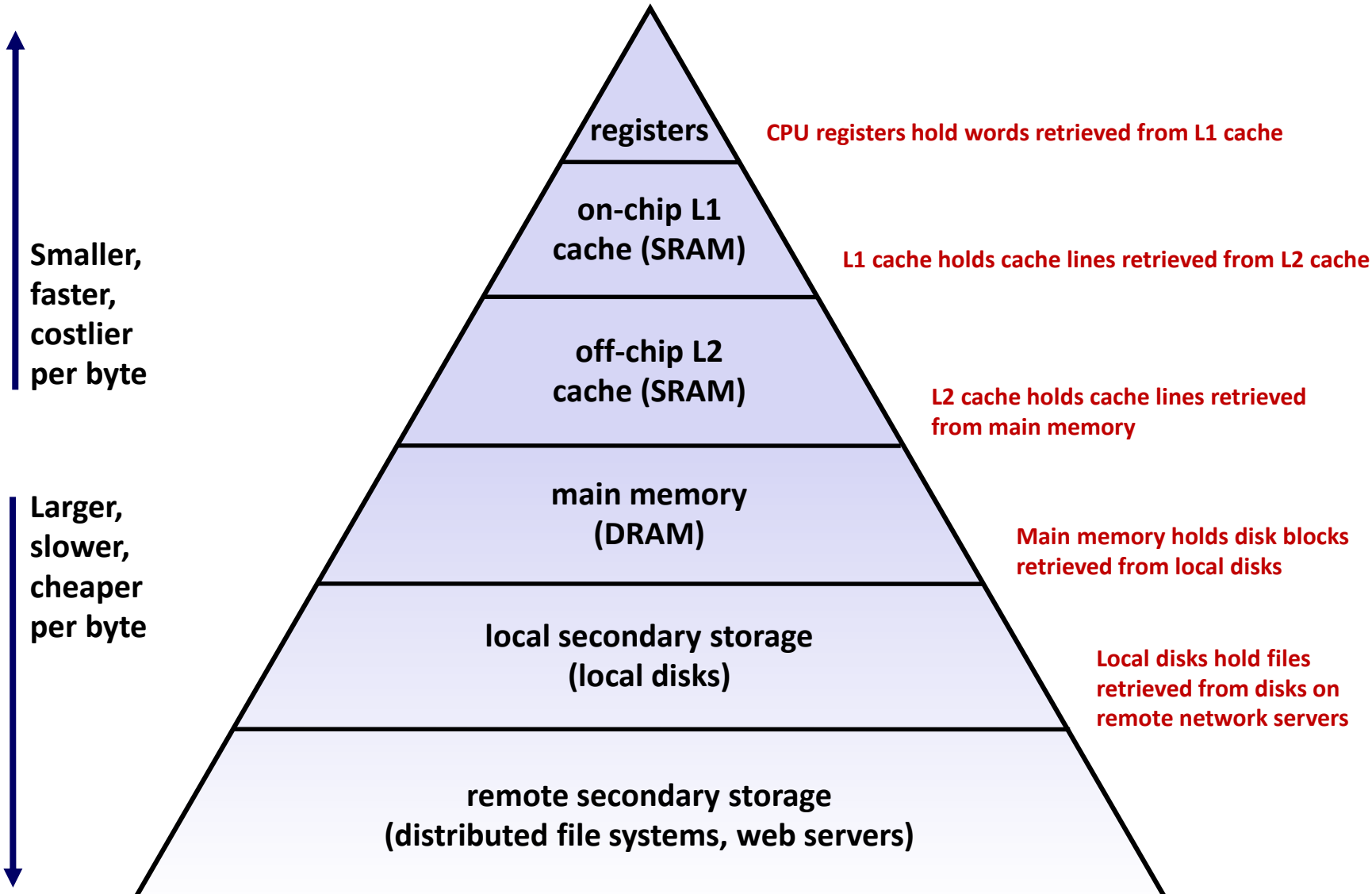
- Midterm Grading completed
  - You should have received an email from Gradescope
  - Solutions posted on website
  - Rubric and grades will be found on Gradescope
  - Regrade requests will be open for a short time after grade release via Gradescope

Memory Hierarchies

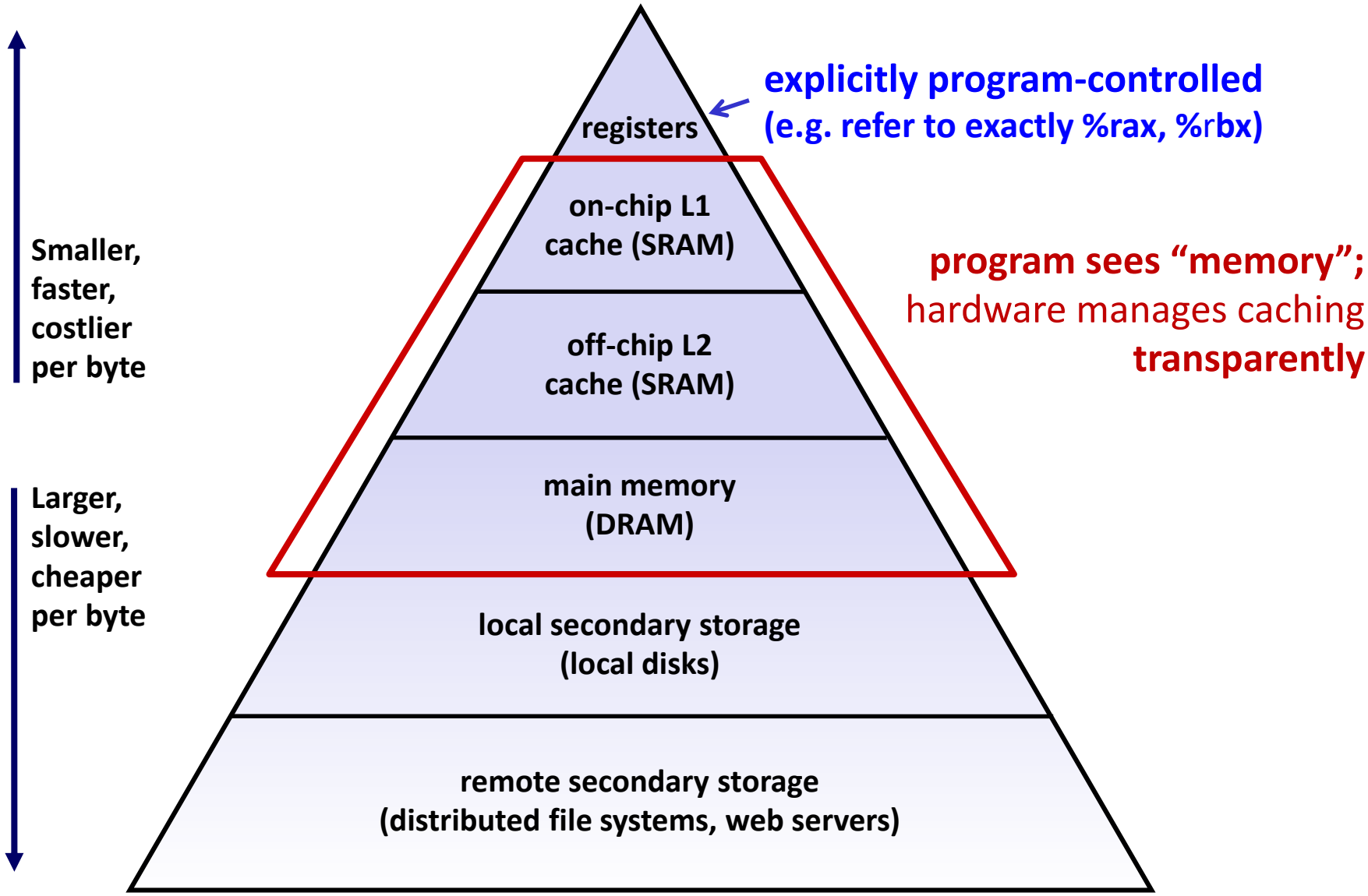
- Some fundamental and enduring properties of hardware and software systems:
  - Faster storage technologies almost always cost more per byte and have lower capacity
  - The gaps between memory technology speeds are widening
    - True for: registers ↔ cache, cache ↔ DRAM, DRAM ↔ disk, etc.
  - Well-written programs tend to exhibit good locality

- These properties complement each other beautifully
  - They suggest an approach for organizing memory and storage systems known as a memory hierarchy
    - For each level k, the faster, smaller device at level k serves as a cache for the larger, slower device at level k+1

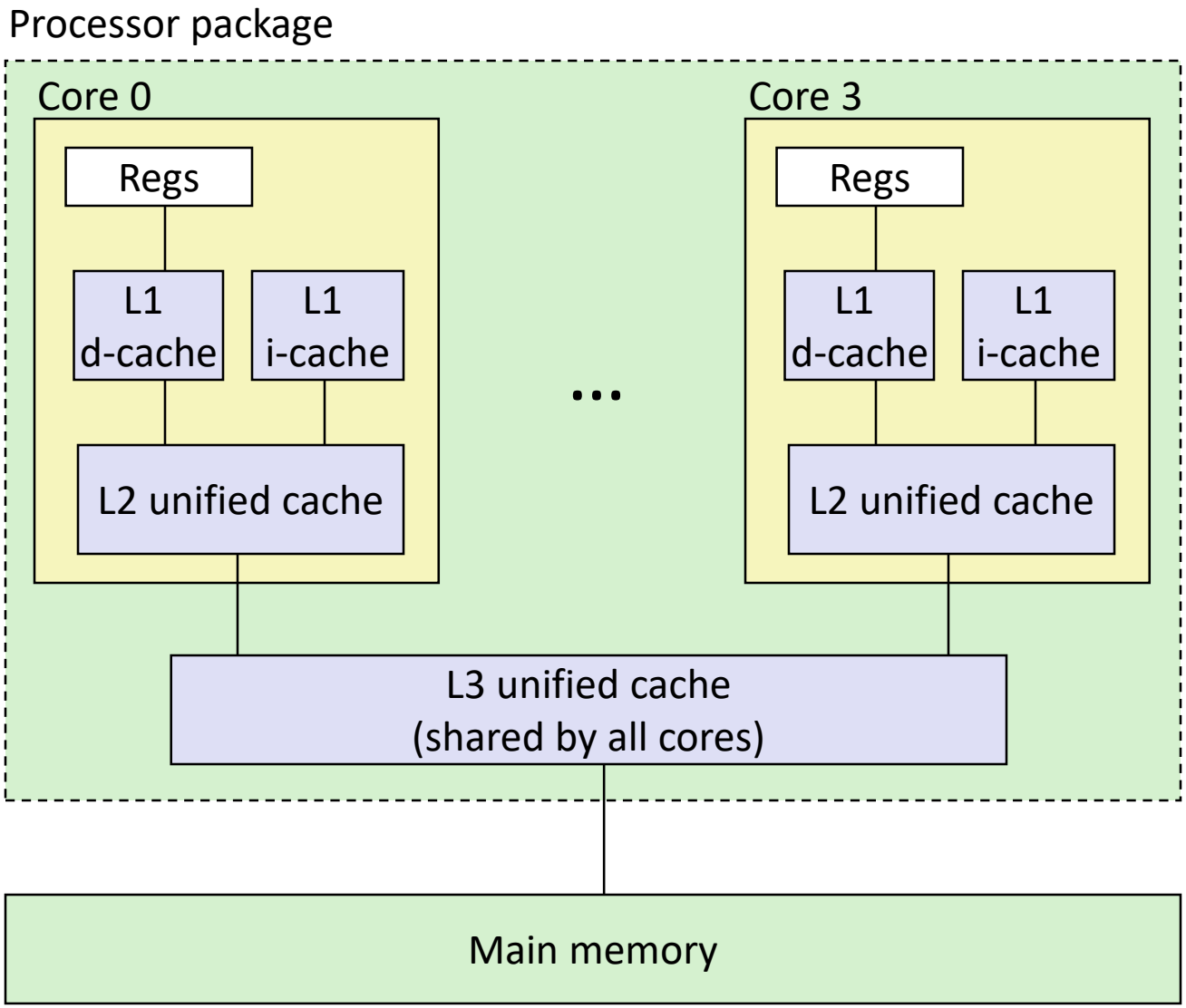
An Example Memory Hierarchy



An Example Memory Hierarchy



Intel Core i7 Cache Hierarchy



Block size:
64 bytes for all caches

L1 i-cache and d-cache:
32 KiB, 8-way,
Access: 4 cycles

L2 unified cache:
256 KiB, 8-way,
Access: 11 cycles

L3 unified cache:
8 MiB, 16-way,
Access: 30-40 cycles

Making memory accesses fast!

- Cache basics
- Principle of locality
- Memory hierarchies
- **Cache organization**
  - **Direct-mapped (*sets*; index + tag)**
  - **Associativity (*ways*)**
  - Replacement policy
  - Handling writes
- Program optimizations that consider caches

Cache Organization (1)

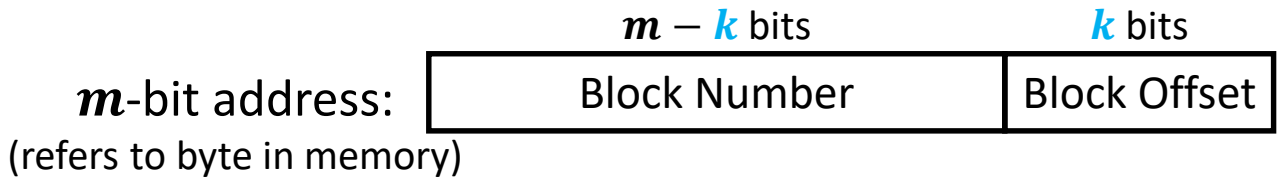
Note: The textbook uses "B" for block size

- Block Size (K): unit of transfer between $ and Mem
  - Given in bytes and always a power of 2 (*e.g.* 64 B)
  - Blocks consist of adjacent bytes (differ in address by 1)
    - Spatial locality!

Cache Organization (1)

Note: The textbook uses "b" for offset bits

- Block Size (K): unit of transfer between $ and Mem
  - Given in bytes and always a power of 2 (*e.g.* 64 B)
  - Blocks consist of adjacent bytes (differ in address by 1)
    - Spatial locality!
- Offset field
  - Low-order $\log_2(K) = \boldsymbol{k}$ bits of address tell you which byte within a block
    - (address) mod 2^n = n lowest bits of address
  - (address) modulo (# of bytes in a block)



Peer Instruction Question

- If we have 6-bit addresses and block size K = 4 B, which block and byte does 0x15 refer to?
  - Vote at: http://PollEv.com/rea

	Block Num	Block Offset
A.	1	1
B.	1	5
C.	5	1
D.	5	5
E.	We're lost…	

Cache Organization (2)

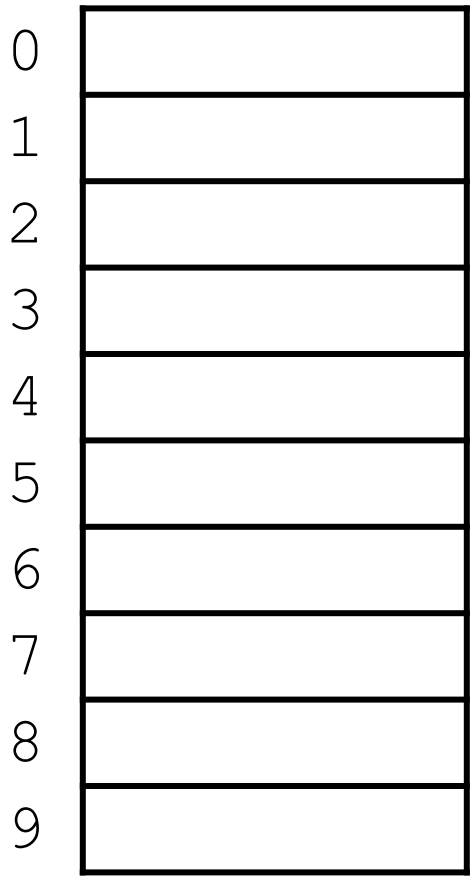
- Cache Size (C): amount of *data* the $ can store
  - Cache can only hold so much data (subset of next level)
  - Given in bytes (C) or number of blocks (C/K)
  - Example: C = 32 KiB = 512 blocks if using 64-B blocks
- Where should data go in the cache?
  - We need a mapping from memory addresses to specific locations in the cache to make checking the cache for an address **fast**
- What is a data structure that provides fast lookup?
  - Hash table!

Review: Hash Tables for Fast Lookup

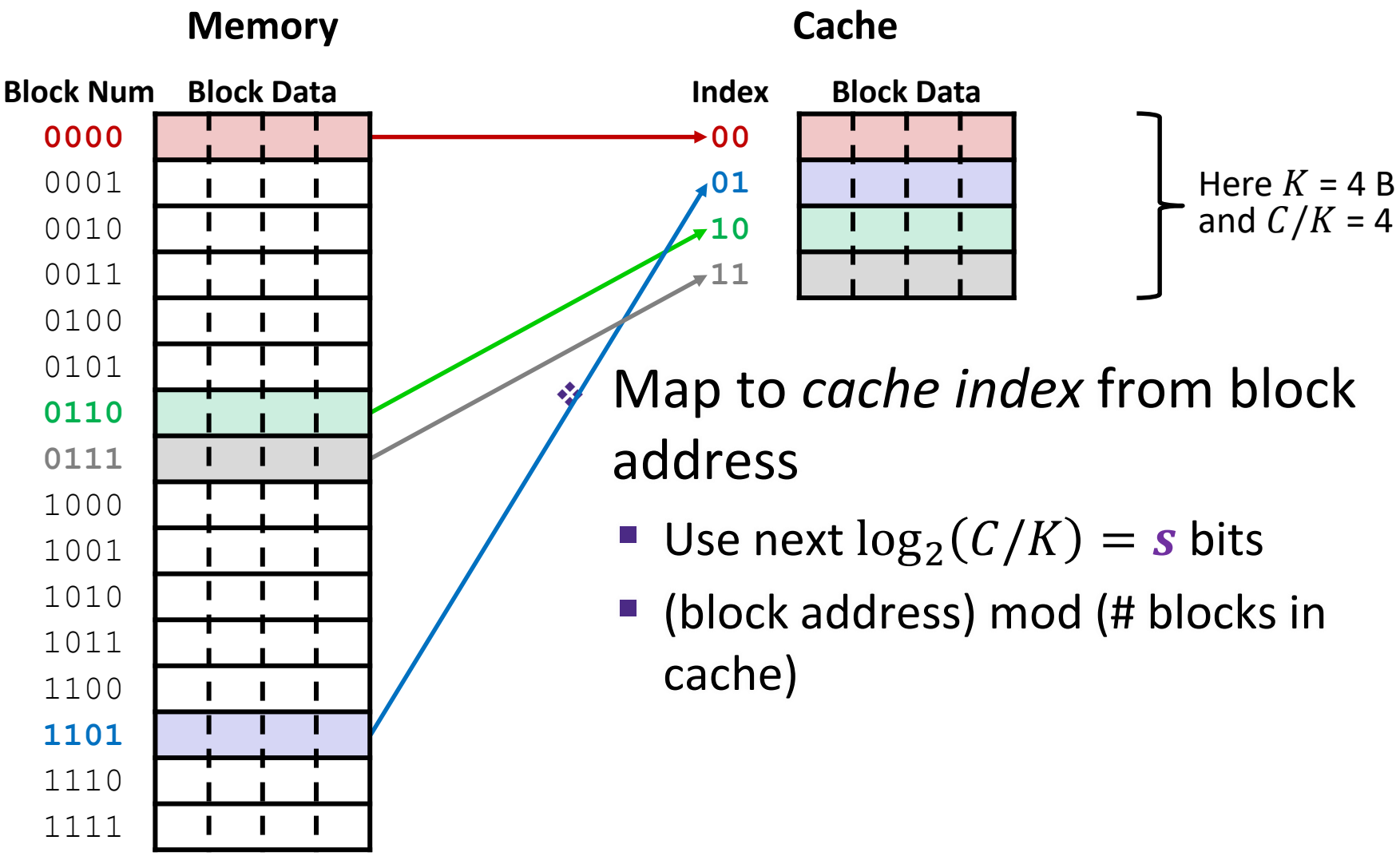
Insert:

5
27
34
102
119

Apply hash function to map data to "buckets"



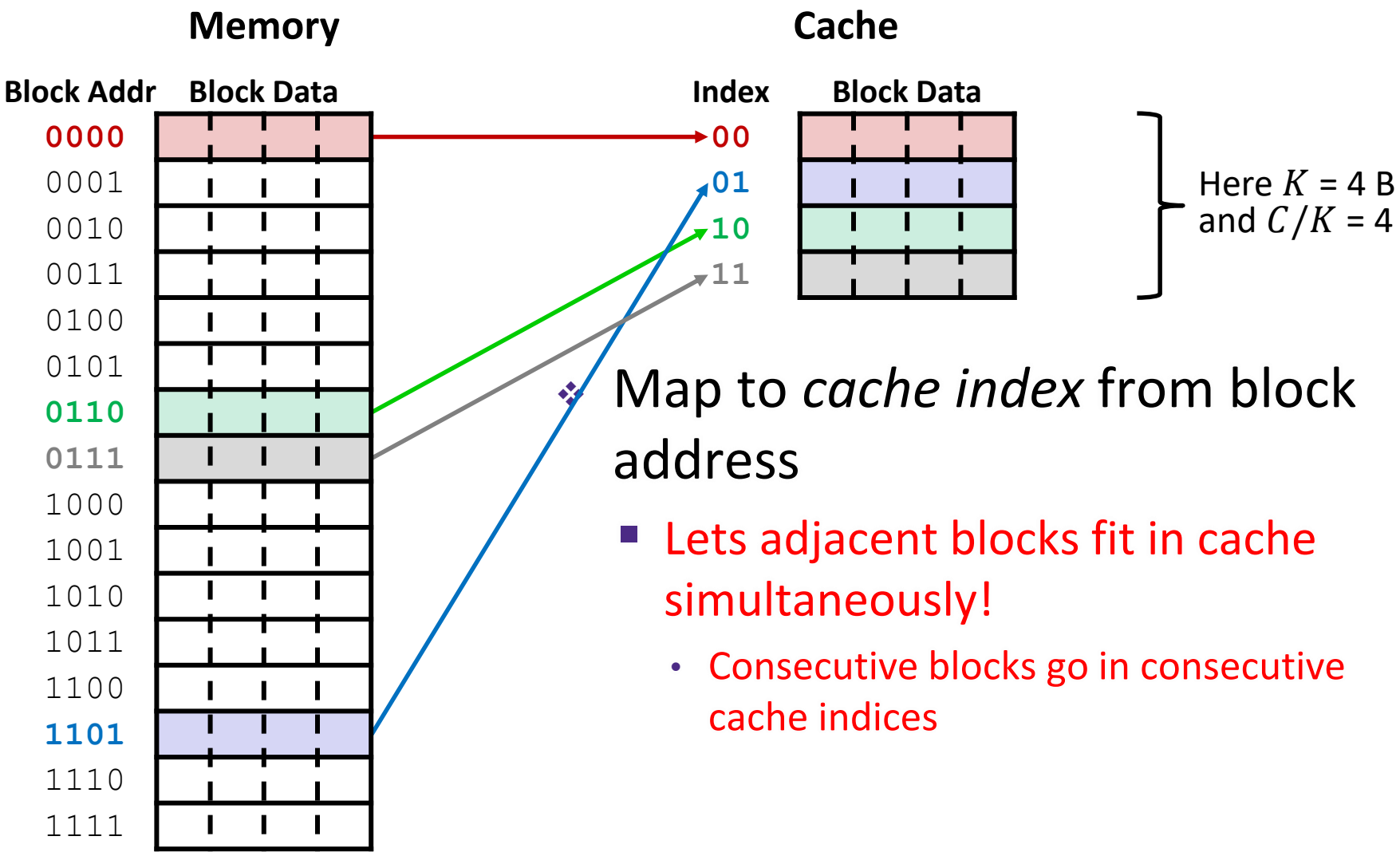
Place Data in Cache by Hashing Address



Map to *cache index* from block address

- Use next $\log_2(C/K) = \boldsymbol{s}$ bits
- (block address) mod (# blocks in cache)

Place Data in Cache by Hashing Address



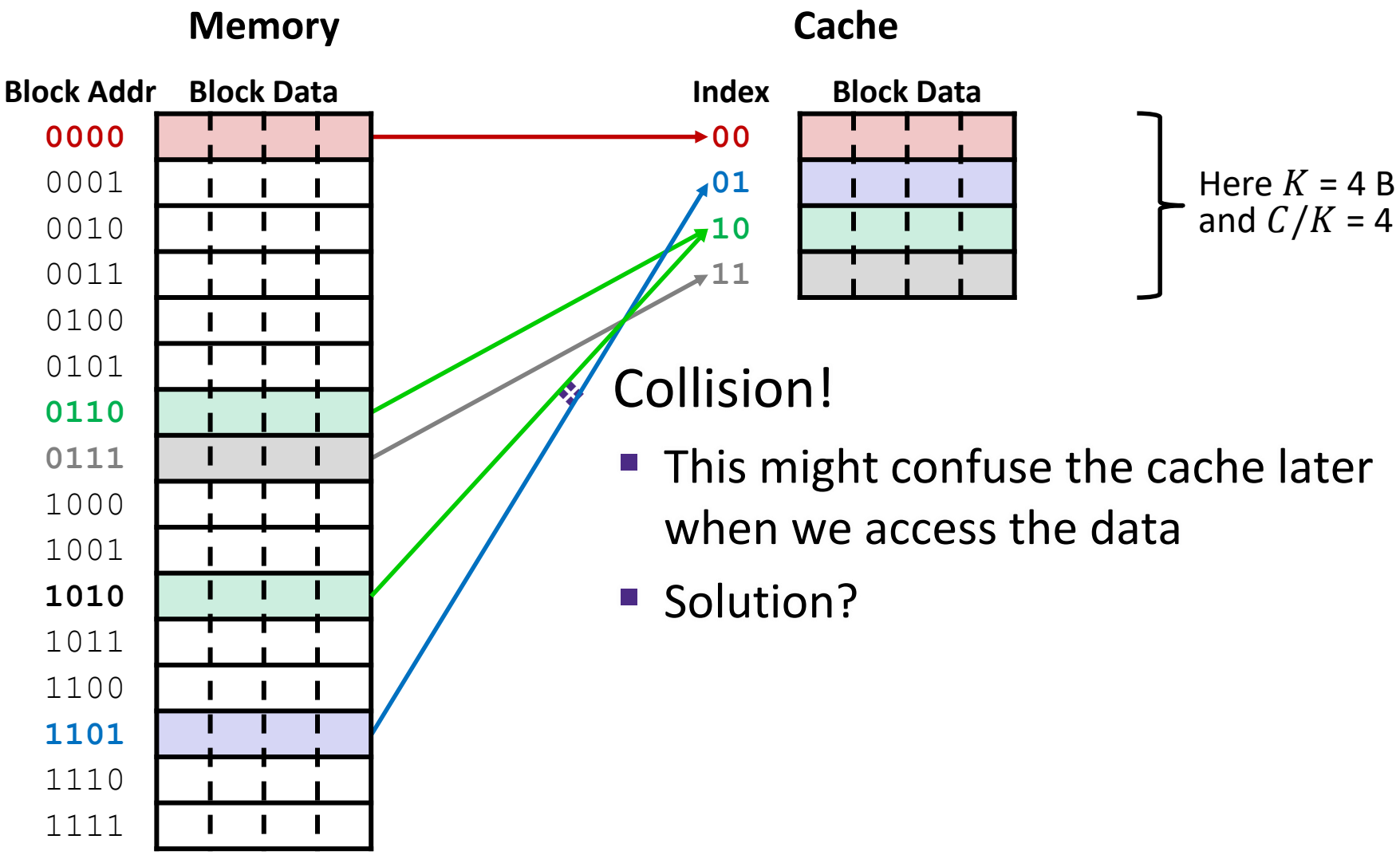
Map to *cache index* from block address

- Lets adjacent blocks fit in cache simultaneously!
  - Consecutive blocks go in consecutive cache indices

Practice Question

- 6-bit addresses, block size K = 4 B, and our cache holds S = 4 blocks.
- A request for address **0x2A** results in a cache miss. Which index does this block get loaded into and which 3 other addresses are loaded along with it?
  - No voting for this question

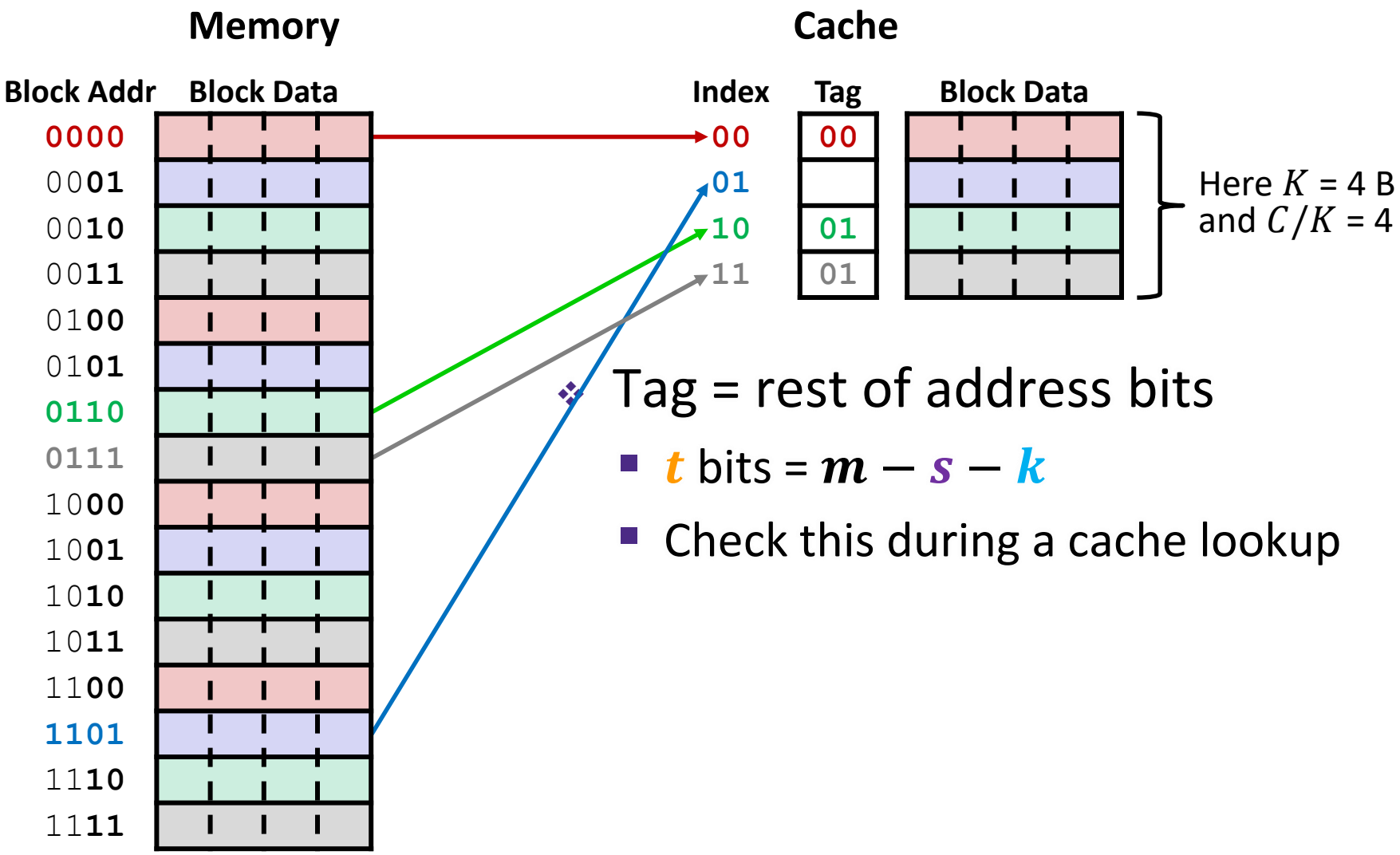
Place Data in Cache by Hashing Address



Collision!

- This might confuse the cache later when we access the data
- Solution?

Tags Differentiate Blocks in Same Index



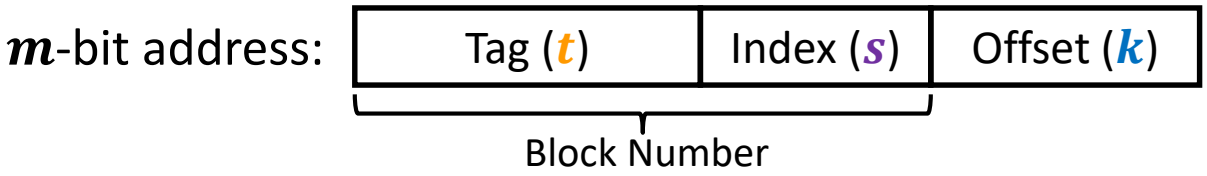
Tag = rest of address bits

- t bits = $m - s - k$
- Check this during a cache lookup

Checking for a Requested Address

- CPU sends address request for chunk of data
  - Address and requested data are not the same thing!
    - Analogy: your friend ≠ his or her phone number

- TIO address breakdown:



  - **Index** field tells you where to look in cache
  - **Tag** field lets you check that data is the block you want
  - **Offset** field selects specified start byte within block

  - **Note:** t and s sizes will change based on hash function

Cache Puzzle

Vote at http://pollev.com/rea

- Based on the following behavior, which of the following block sizes is NOT possible for our cache?
  - Cache starts *empty*, also known as a *cold cache*
  - Access (addr: hit/miss) stream:
    - (14: miss), (15: hit), (16: miss)

A. 4 bytes

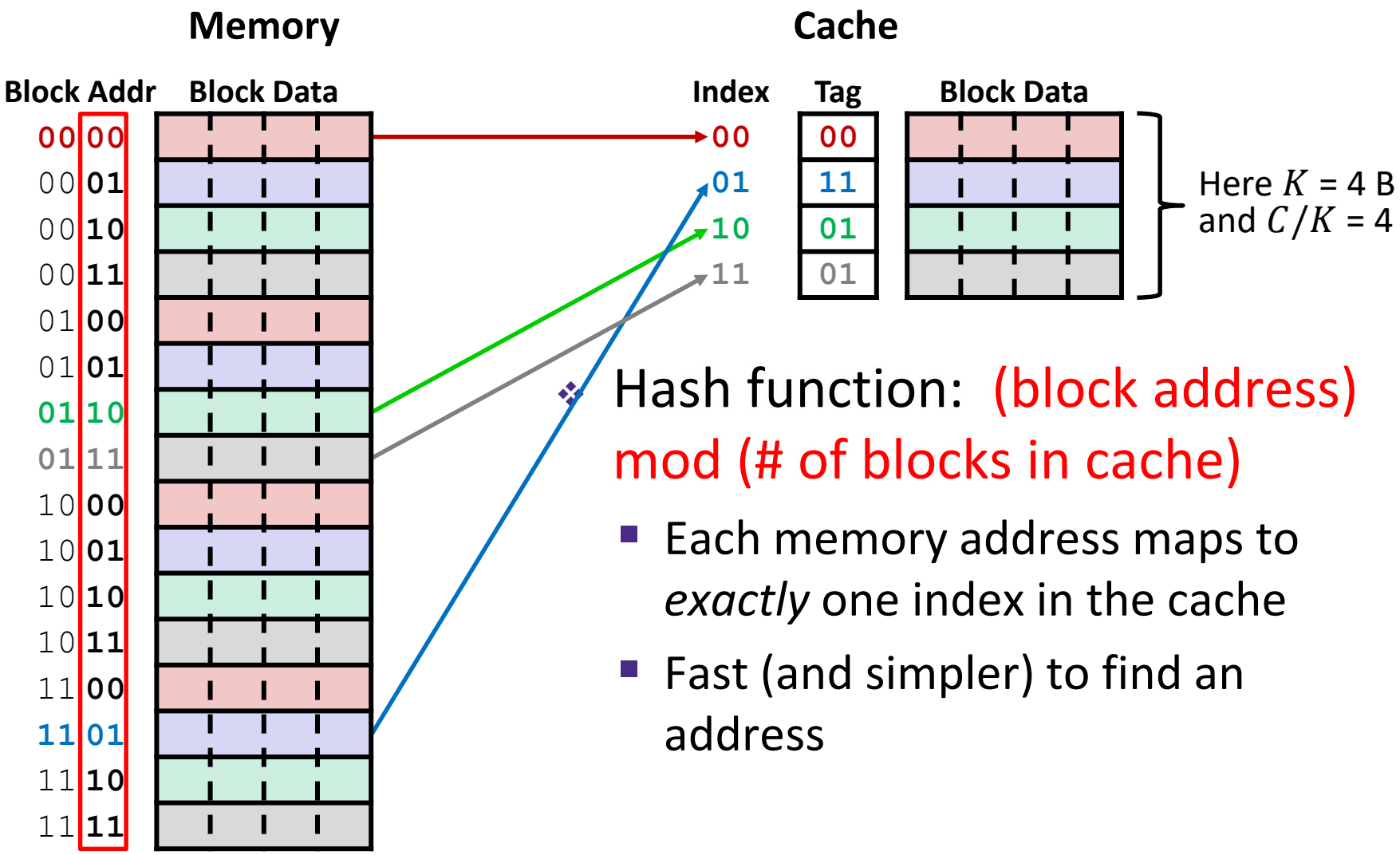
B. 8 bytes

C. 16 bytes

D. 32 bytes

E. We're lost…

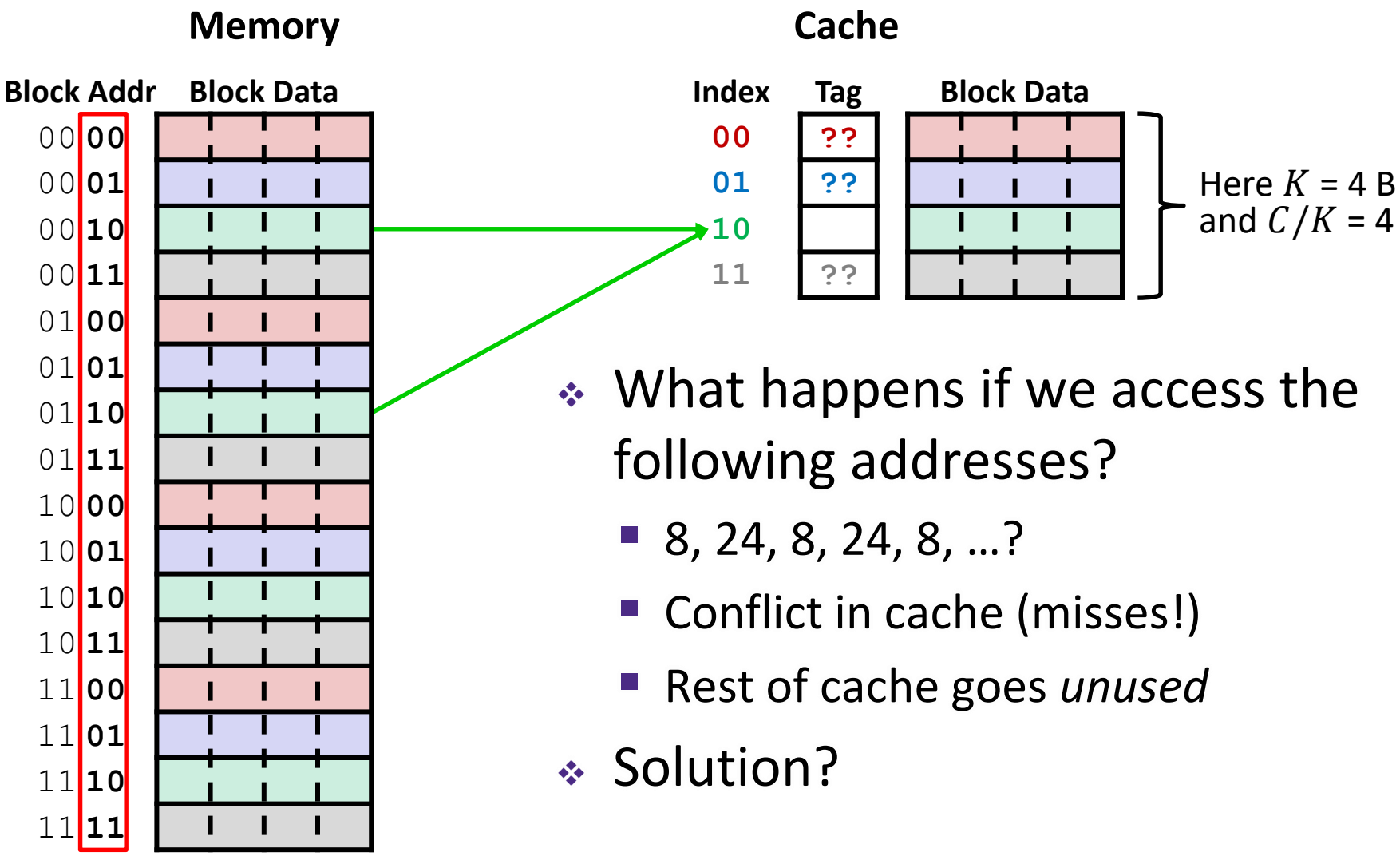
Direct-Mapped Cache



Hash function: (block address) mod (# of blocks in cache)

- Each memory address maps to *exactly* one index in the cache
- Fast (and simpler) to find an address

Direct-Mapped Cache Problem



- What happens if we access the following addresses?
  - 8, 24, 8, 24, 8, …?
  - Conflict in cache (misses!)
  - Rest of cache goes *unused*
- Solution?

Associativity

- What if we could store data in any place in the cache?
  - More complicated hardware = more power consumed, slower
- So we *combine* the two ideas:
  - Each address maps to exactly one **set**
  - Each set can store block in more than one **way**