#### Introduction to Data Management CSE 344

Unit 4: RDBMS Internals Logical and Physical Plans Query Execution Query Optimization

(3 lectures)

#### Introduction to Data Management CSE 344

#### Lecture 15: Introduction to Query Evaluation

#### Announcements

Makeup lecture tomorrow, 4:30pm, BAG 131

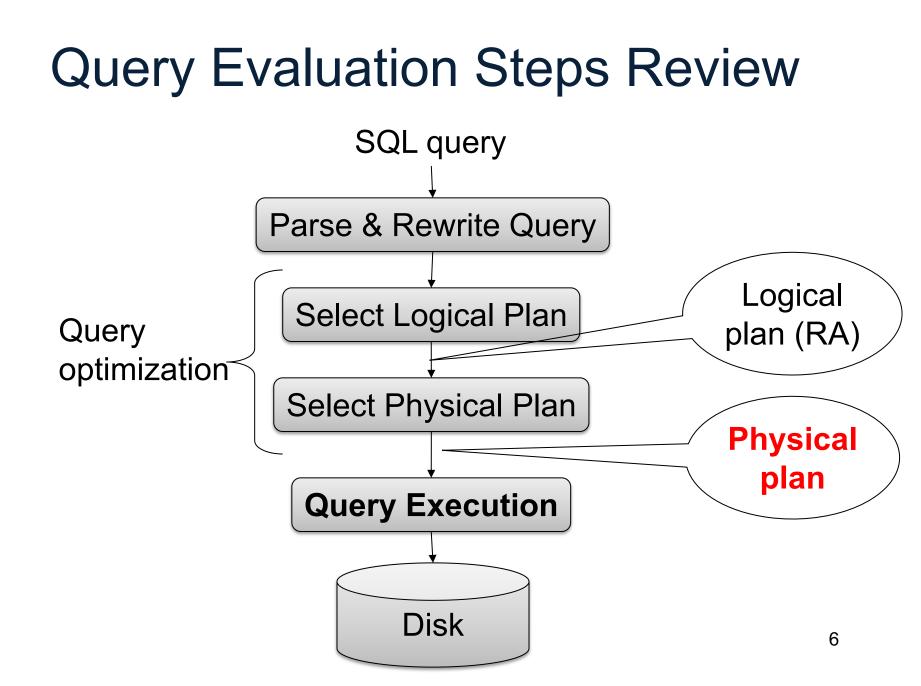
HW6: we will use AWS. Do the setup early:

- If no account yet, sign up <u>aws.amazon.com</u>
- Request credits <u>aws.amazon.com/awscredits</u>

#### **Class Overview**

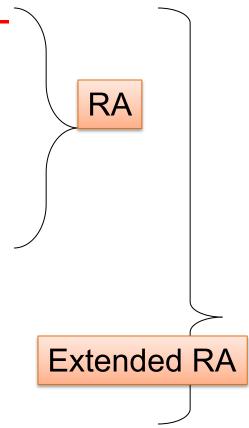
- Unit 1: Intro
- Unit 2: Relational Data Models and Query Languages
- Unit 3: Non-relational data
- Unit 4: RDMBS internals and query optimization
- Unit 5: Parallel query processing
- Unit 6: DBMS usability, conceptual design
- Unit 7: Transactions
- Unit 8: Advanced topics (time permitting)

### From Logical RA Plans to Physical Plans



## **Relational Algebra Operators**

- Union ∪, intersection ∩, difference -`
- Selection  $\sigma$
- Projection  $\pi$
- Cartesian product ×, join
- (Rename p)
- Duplicate elimination  $\delta$
- Grouping and aggregation y
- Sorting τ



### **Physical Operators**

- For each operators above, several possible algorithms
- Main memory or external memory algorithms
- Examples:
  - Main memory hash join
  - External memory merge join
  - External memory partitioned hash join
  - Sort-based group by
  - Etc, etc

Supplier(sid, sname, scity, sstate)
Supply(sid, pno, quantity)

## Main Memory Algorithms

Logical operator:

Supplier ⋈<sub>sid=sid</sub> Supply

Propose three physical operators for the join, assuming the tables are in main memory:

1.

2.

3.

Supplier(sid, sname, scity, sstate)
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# Main Memory Algorithms

Logical operator:

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Propose three physical operators for the join, assuming the tables are in main memory:

- 1. Nested Loop Join
- 2. Merge join
- 3. Hash join

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# Main Memory Algorithms

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 $O(n^2)$   $O(n \log n)$  $O(n) \dots O(n^2)$ 

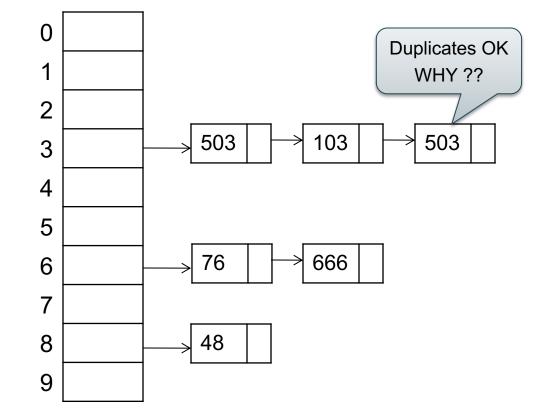
## **BRIEF Review of Hash Tables**

Separate chaining:

A (naïve) hash function:

h(x) = x mod 10

Operations:



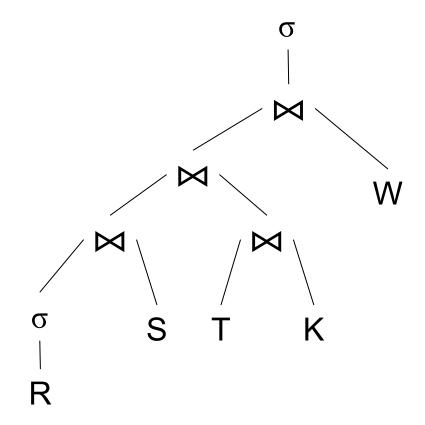
#### **BRIEF Review of Hash Tables**

- insert(k, v) = inserts a key k with value v
- Many values for one key
   Hence, duplicate k's are OK
- find(k) = returns the <u>list</u> of all values v associated to the key k

## Recap of Main Memory Algorithms

- Join ⊠:
  - Nested loop join
  - Hash join
  - Merge join
- Selection σ
  - "on-the-fly"
  - Index-based selection (next lecture)
- Group by **y** 
  - Hash–based
  - Merge-based

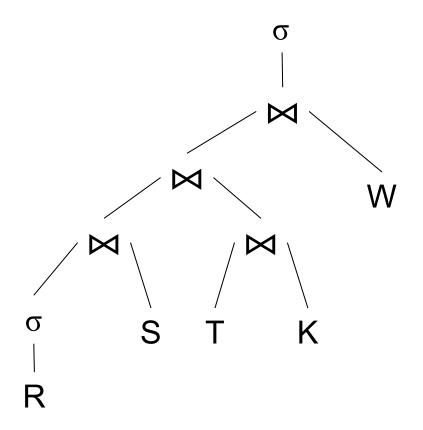
#### How Do We Combine Them?



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The *Iterator Interface* 

- open()
- next()
- close()



Example "on the fly" selection operator

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```
// initializes operator state
// and sets parameters
void open (...);
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// produces output tuple(s)
// returns null when done
Tuple next ();
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```
class Select implements Operator {...
  void open (Predicate p,
             Operator c) {
    this.p = p; this.c = c; c.open();
    }
  Tuple next () {
    boolean found = false;
    Tuple r = null;
    while (!found) {
       r = c.next();
       if (r == null) break;
       found = p(r);
    }
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void close () { c.close(); }
```

```
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```

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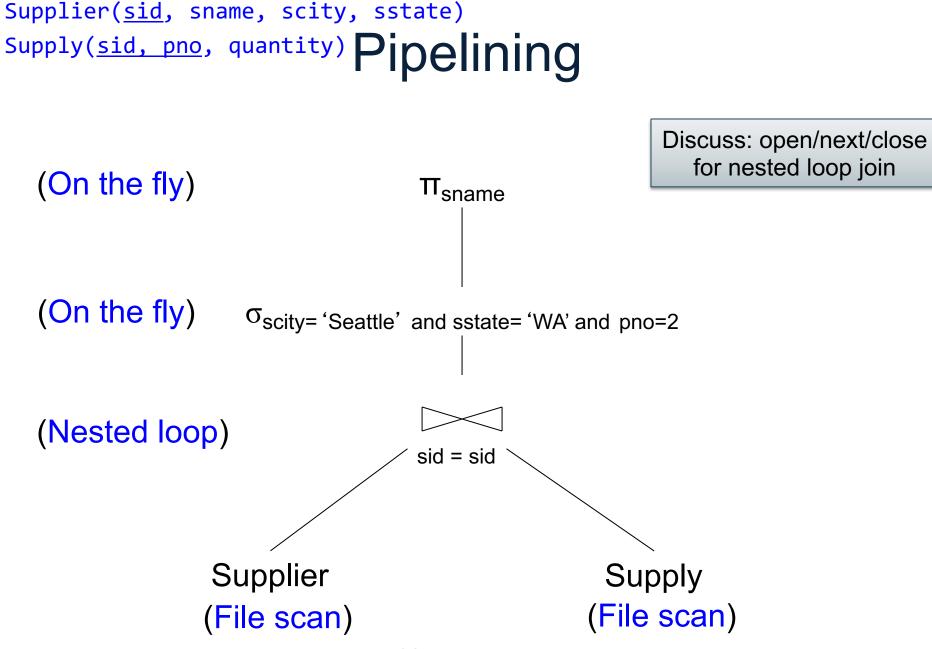
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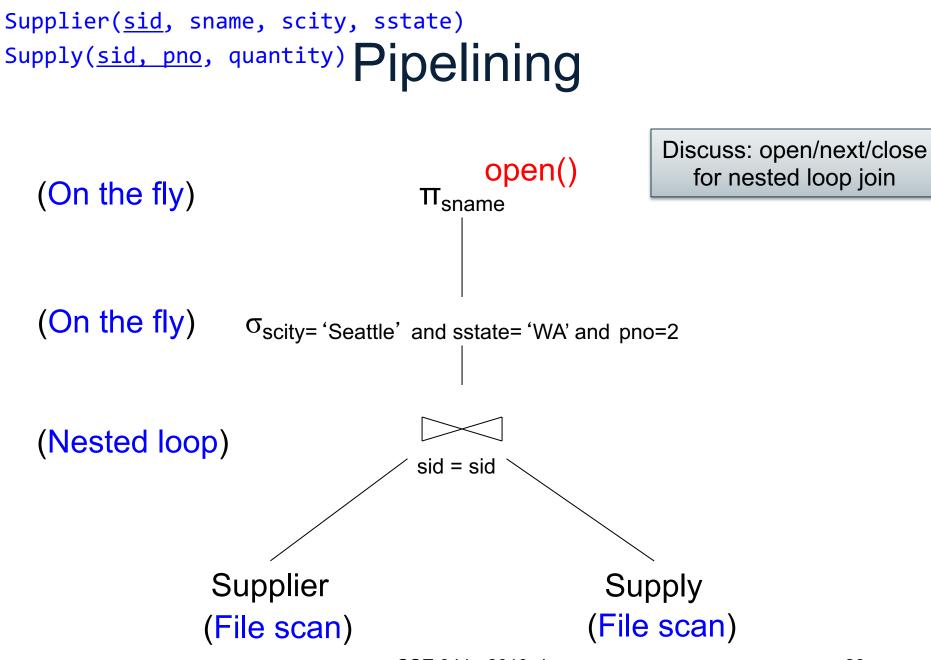
## // cleans up (if any) void close ();

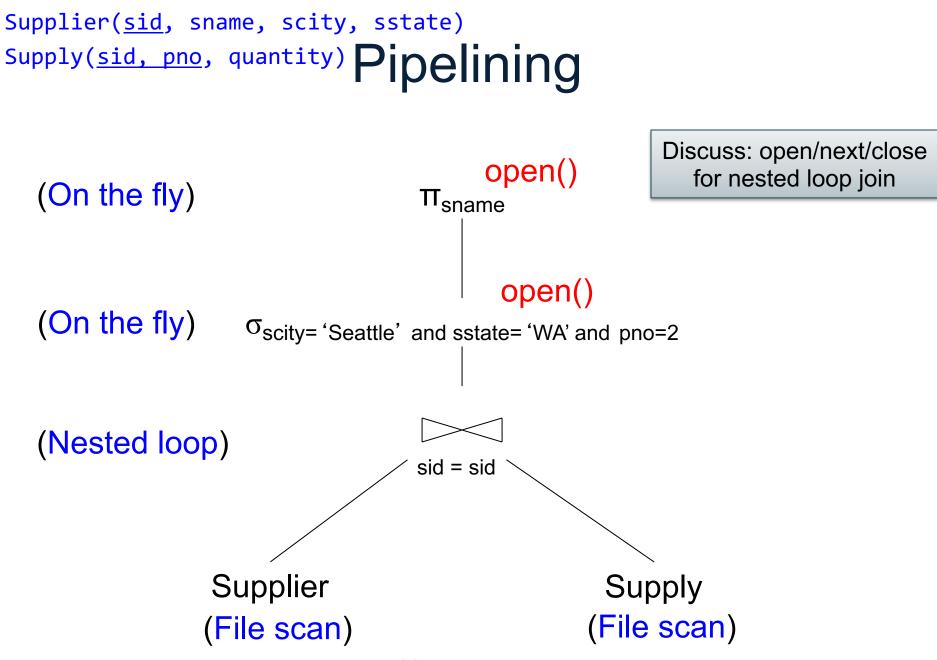
#### Query plan execution

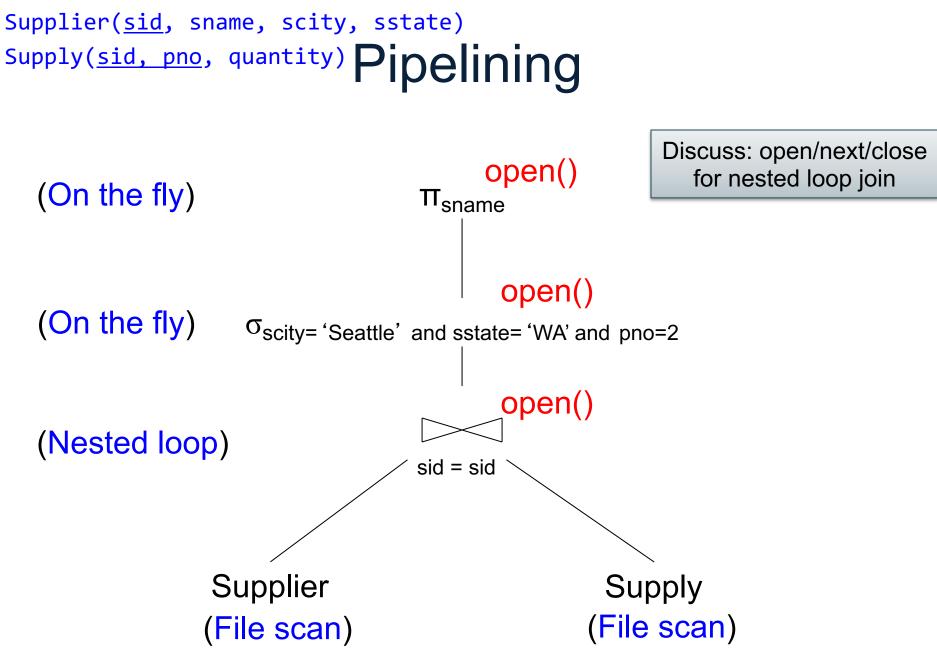
```
Operator q = parse("SELECT ...");
q = optimize(q);
```

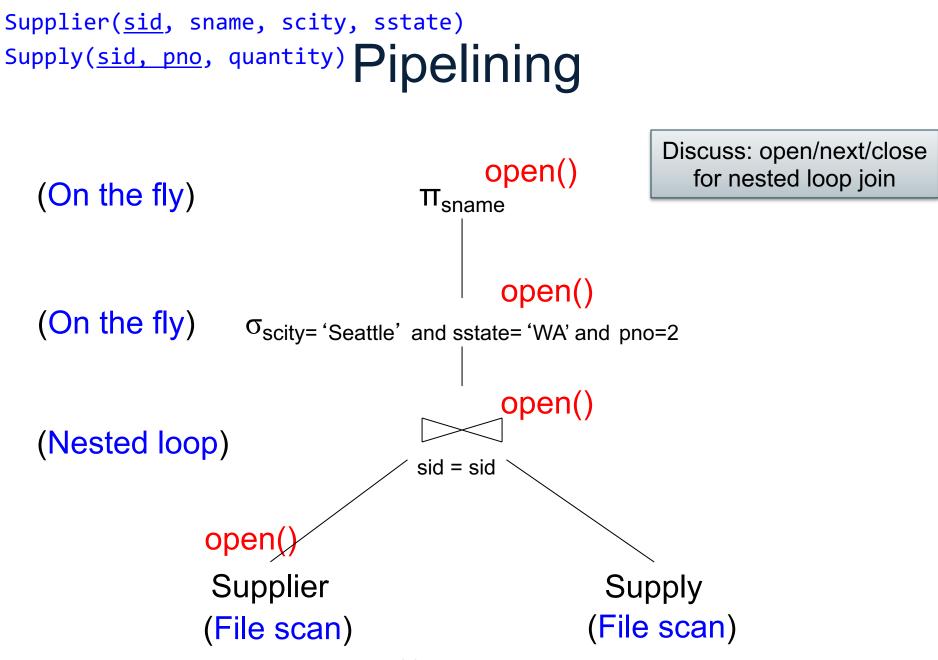
```
q.open();
while (true) {
  Tuple t = q.next();
  if (t == null) break;
  else printOnScreen(t);
}
q.close();
```

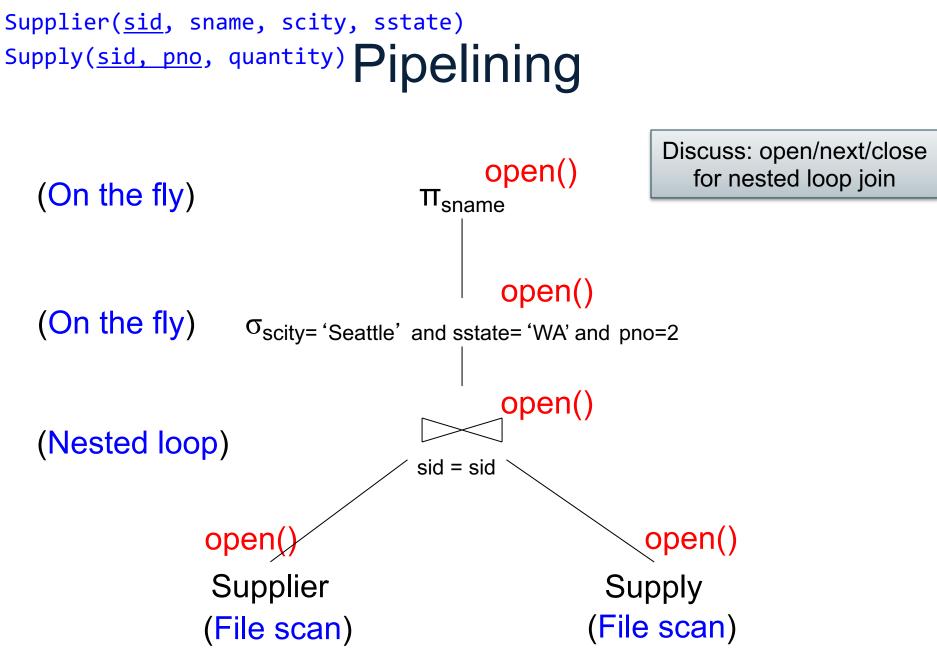


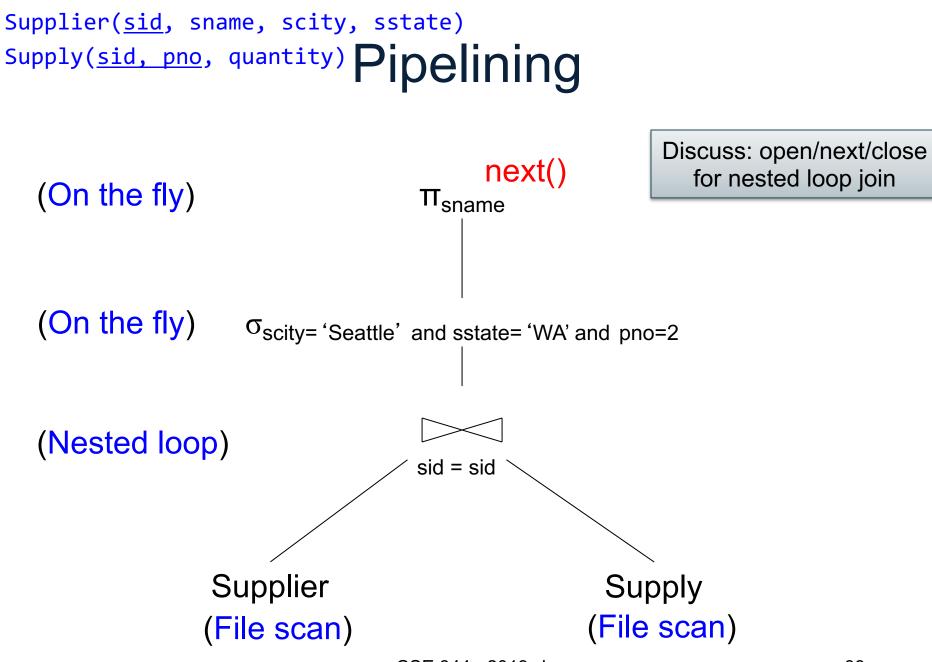


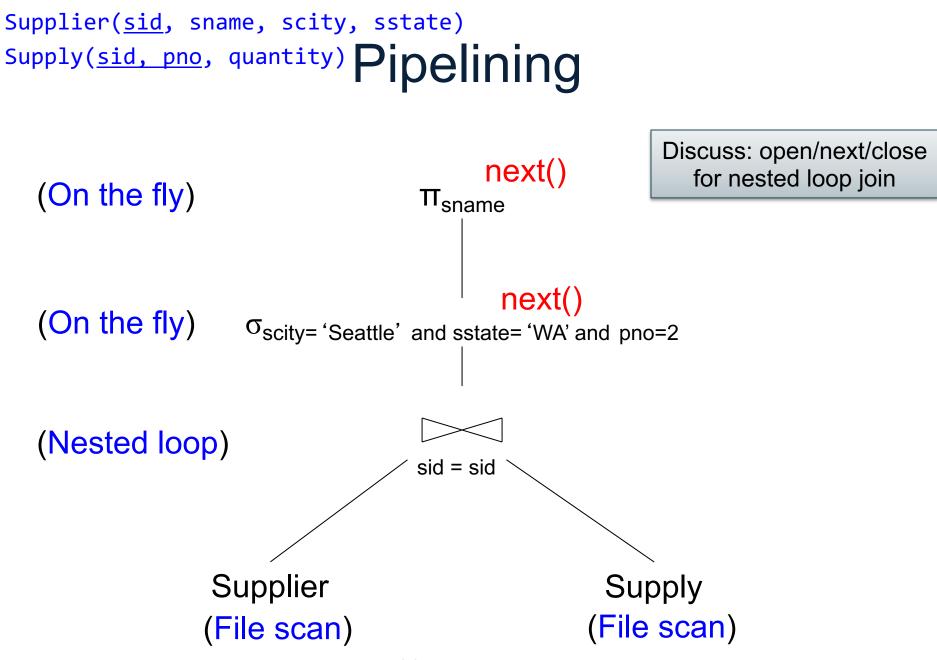


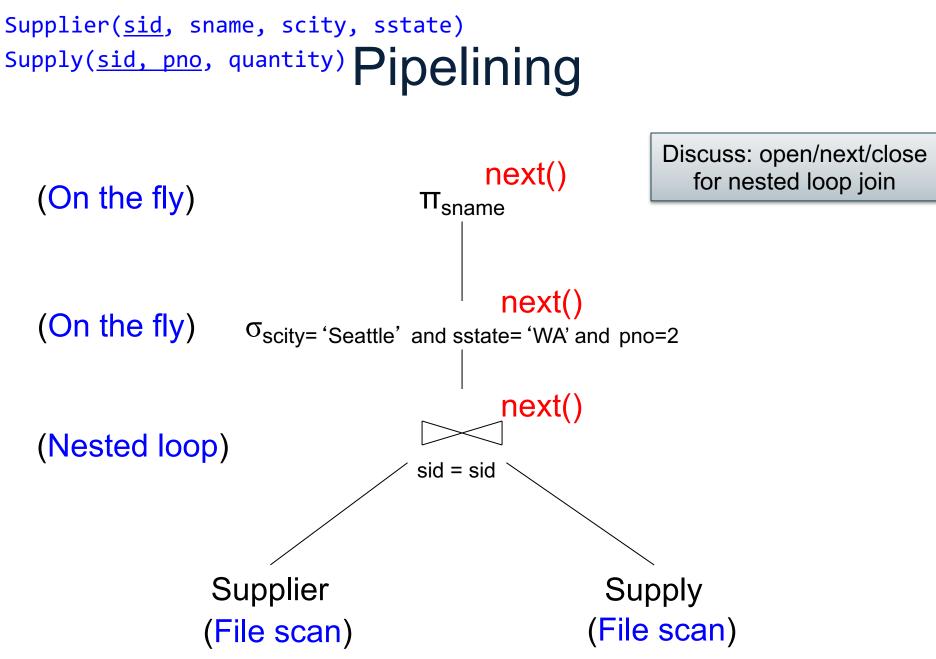


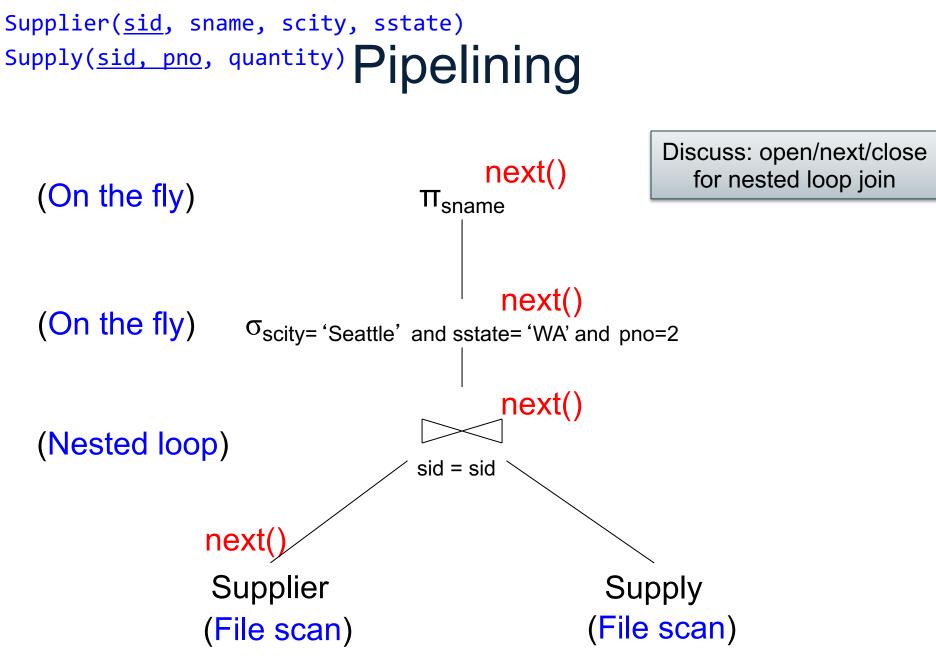


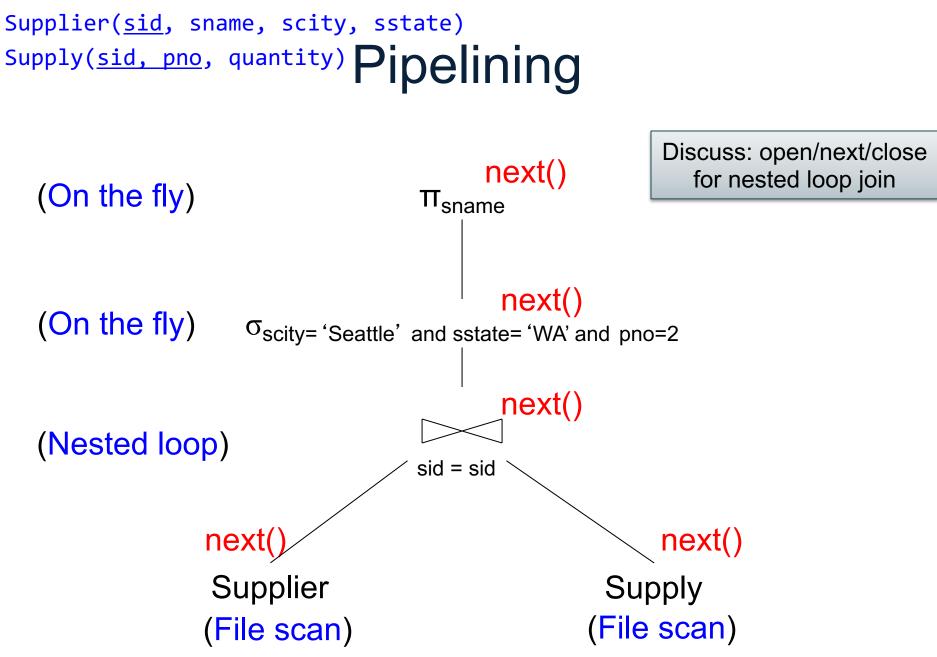


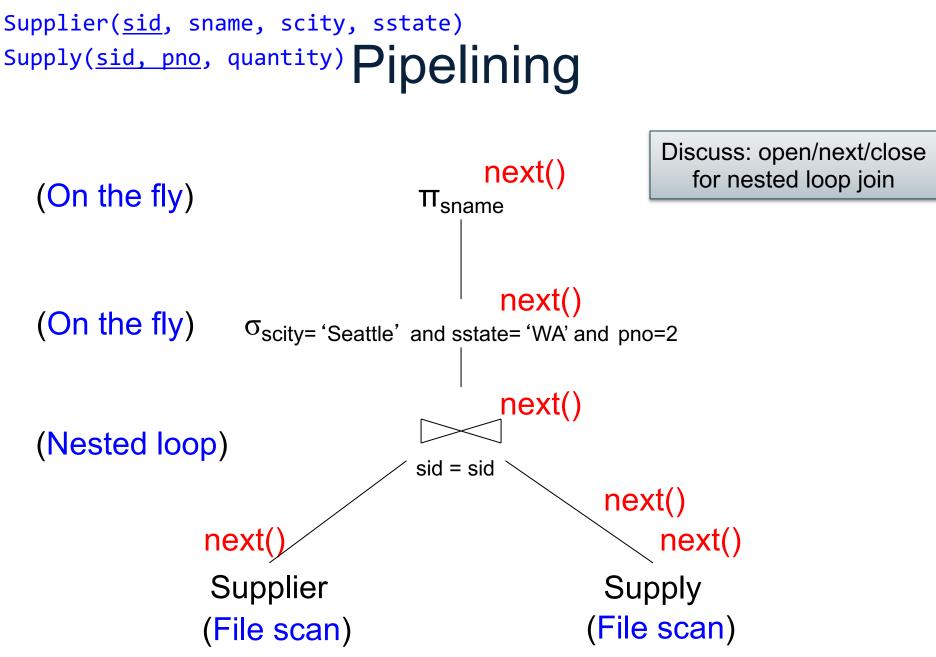


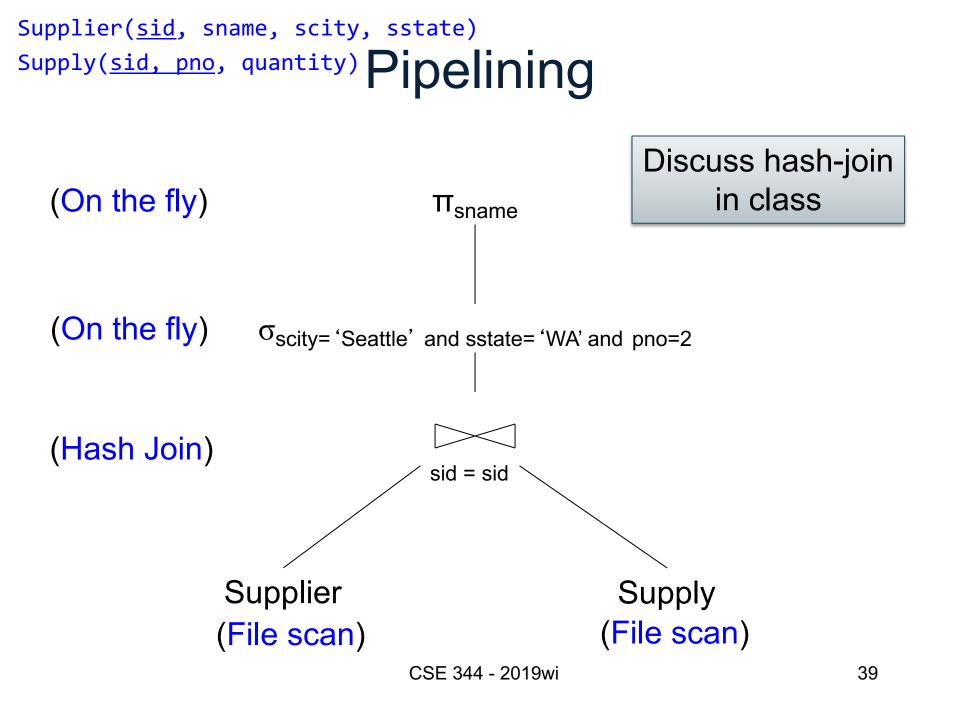


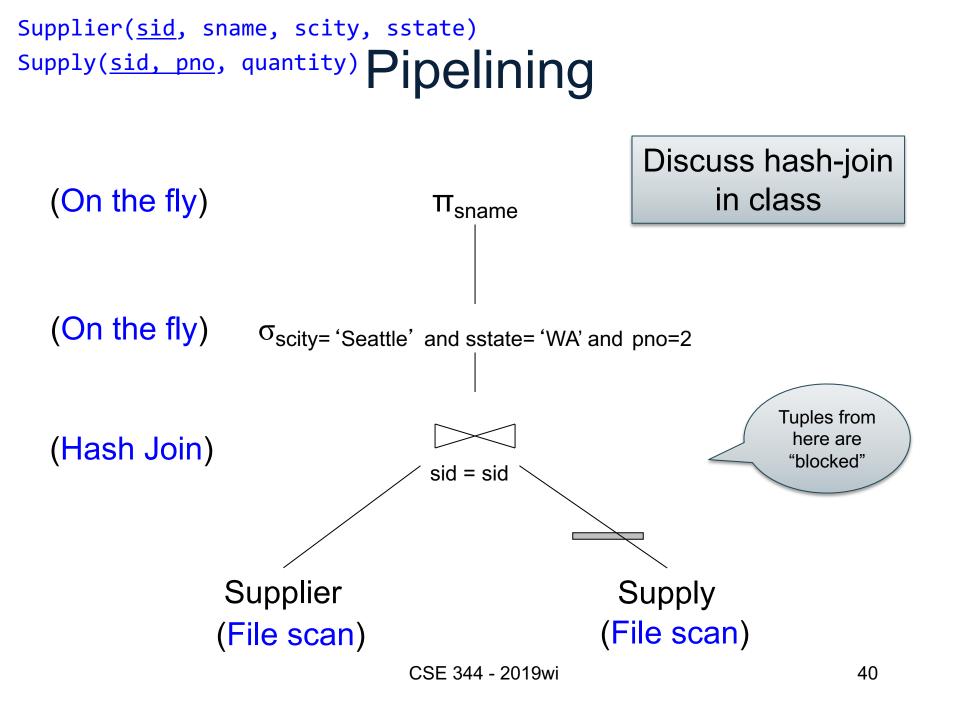


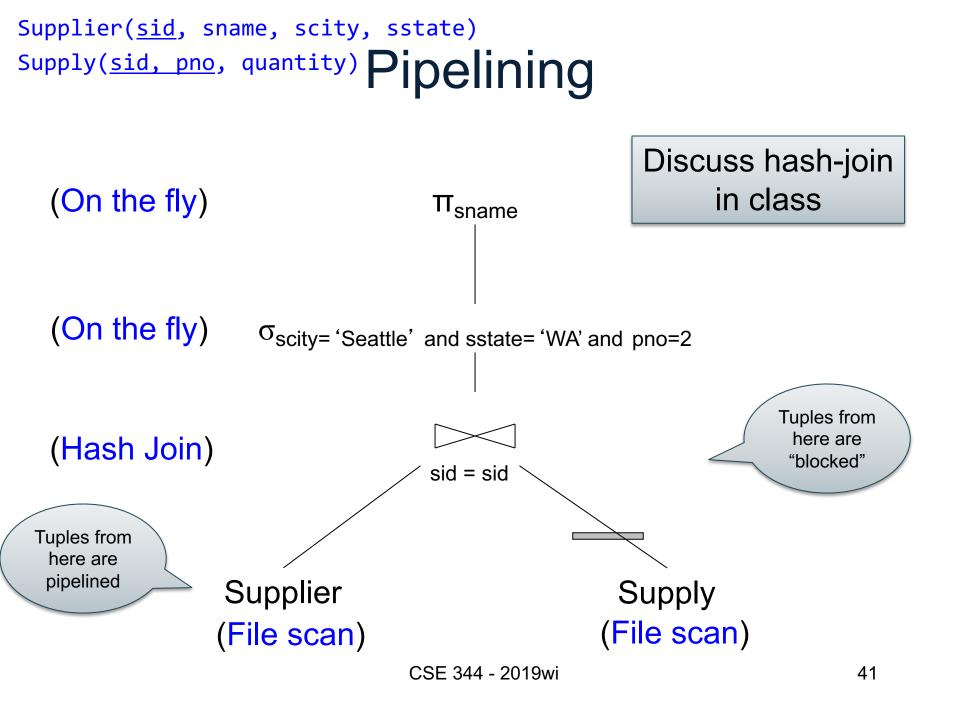




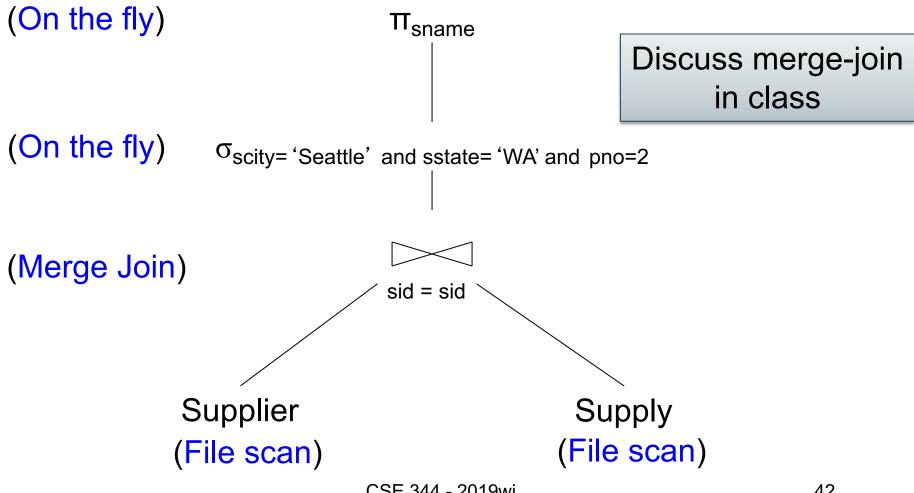




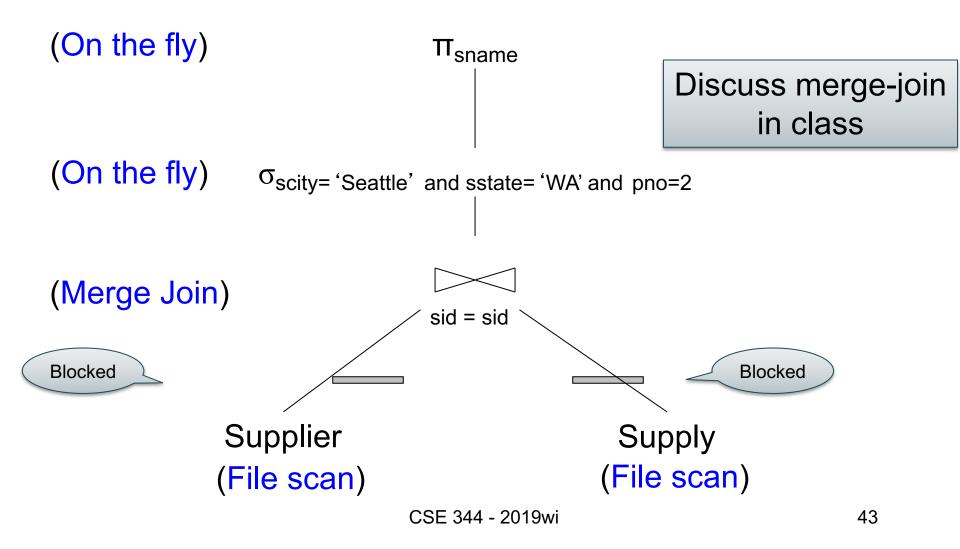




### Supplier(sid, sname, scity, sstate) Supply(sid, pno, que docked Execution



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# Pipeline v.s. Blocking

### Pipeline

- A tuple moves all the way through up the query plan
- Advantages: speed
- Disadvantage: need all hash at the same time in memory
- Blocking
  - The entire result of the subplan is computed (and stored to disk) before the first tuple is sent up the plan
  - Advantage: saves memory
  - Disadvantage: slower

## **Discussion on Physical Plan**

More components of a physical plan:

- Access path selection for each relation
  - Scan the relation or use an index (next lecture)
- Implementation choice for each operator
  - Nested loop join, hash join, etc.
- Scheduling decisions for operators

- Pipelined execution or intermediate materialization

### Introduction to Database Systems CSE 344

### Lecture 16: Basics of Data Storage and Indexes

# **Query Performance**

To understand query performance, we need to understand:

- How is data organized on disk
- How to estimate query costs
- In this course we will focus on disk-based DBMSs

# Hard Disk

- Disks are mechanical devices
- A *block* = unit of read/write
- Once in main memory we call it a *page*
- Read only at the rotation speed!
- Consequence: sequential scan faster than random
  - Good: read blocks 1,2,3,4,5,...
  - Bad: read blocks 2342, 11, 321,9, ...
- Rule of thumb:
  - Random read 1-2% of file  $\approx$  sequential scan entire file;
  - 1-2% decreases over time, because of increased density



#### Student

Data Stora	age
------------	-----

ID	fName	IName
10	Tom	Hanks
20	Amy	Hanks

- DBMSs store data in files
- Most common organization is row-wise storage
- On disk, a file is split into blocks
- Each block contains a set of tuples

10	Tom	Hanks	block 1
20	Amy	Hanks	biook i
50			block 2
200			DIOCK 2
220			block 3
240			DIOCK
420			
800			

In the example, we have 4 blocks with 2 tuples each

#### Student

		fName	IName	
Data File Types	10	Tom	Hanks	
		Amy	Hanks	-

•••

The data file can be one of:

- Heap file
  - Unsorted
- Sequential file

Sorted according to some attribute(s) called <u>key</u>

### Index

• An additional file, that allows fast access to records in the data file given a search key

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- An additional file, that allows fast access to records in the data file given a search key
- The index contains (key, value) pairs:
  - Key = an attribute value (e.g., student ID or name)
  - Value = a pointer to the record OR the record itself

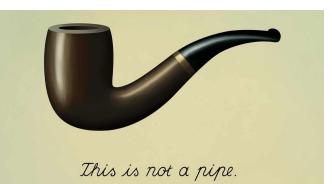
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- The index contains (key, value) pairs:
  - Key = an attribute value (e.g., student ID or name)
  - Value = a pointer to the record OR the record itself
- Could have many indexes for one table

Key = means here search key

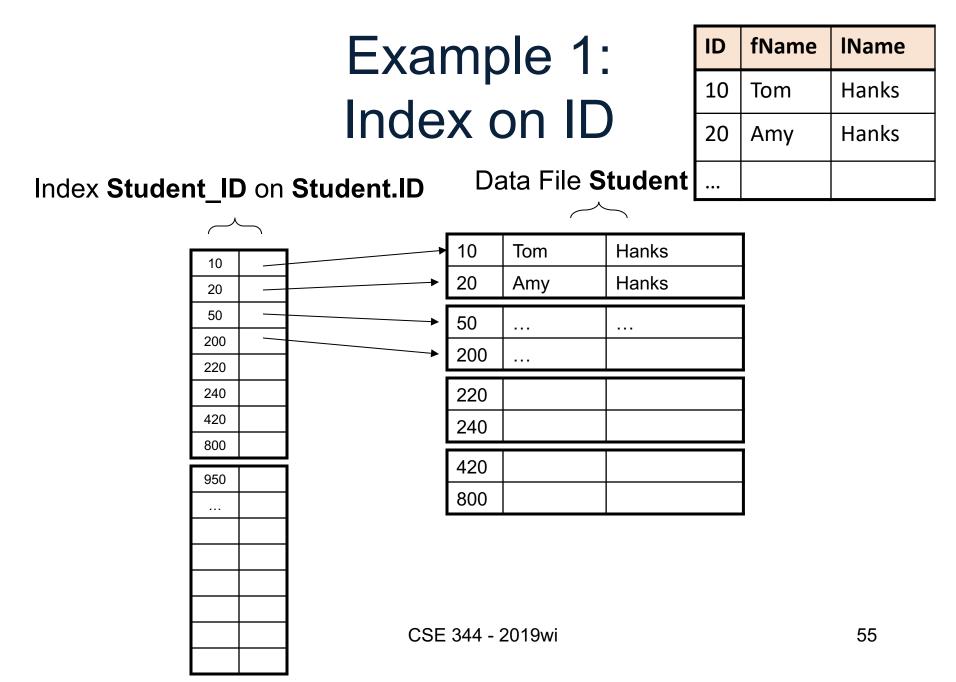


- Primary key uniquely identifies a tuple
- Key of the sequential file how the data file is sorted, if at all
- Index key how the index is organized

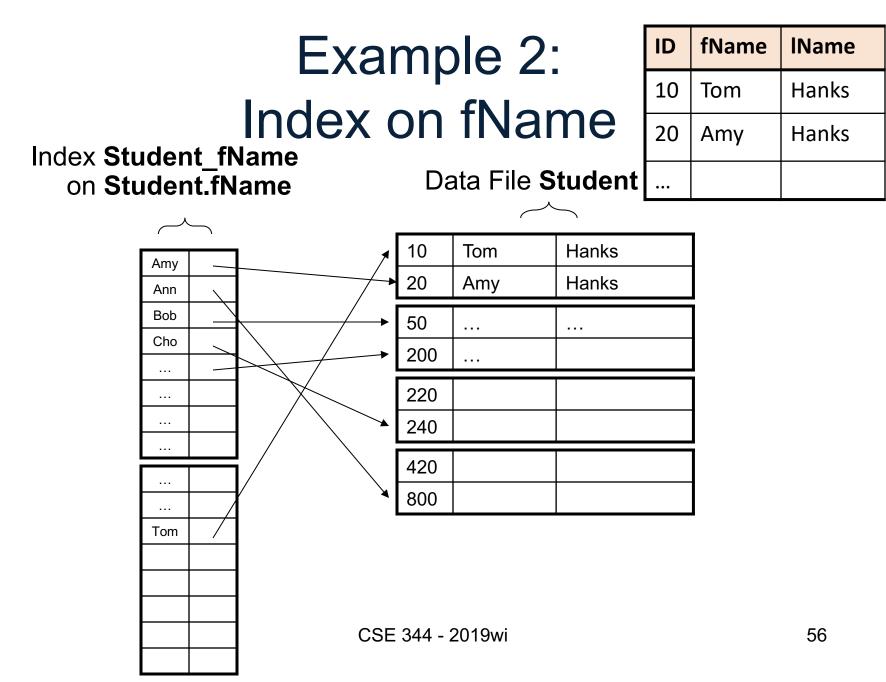




#### Student



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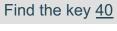


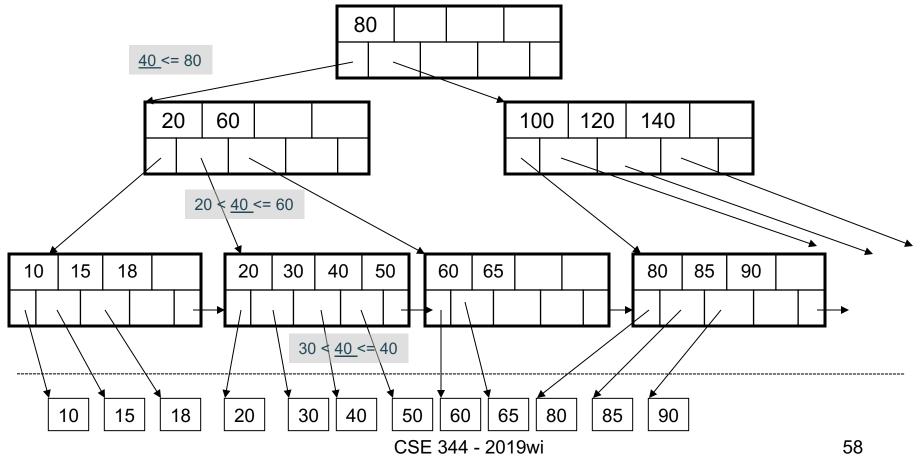
# Index Organization

- Hash table
- B+ trees most common
  - They are search trees, but they are not binary instead have higher fan-out
  - Will discuss them briefly next
- Specialized indexes: bit maps, R-trees, inverted index

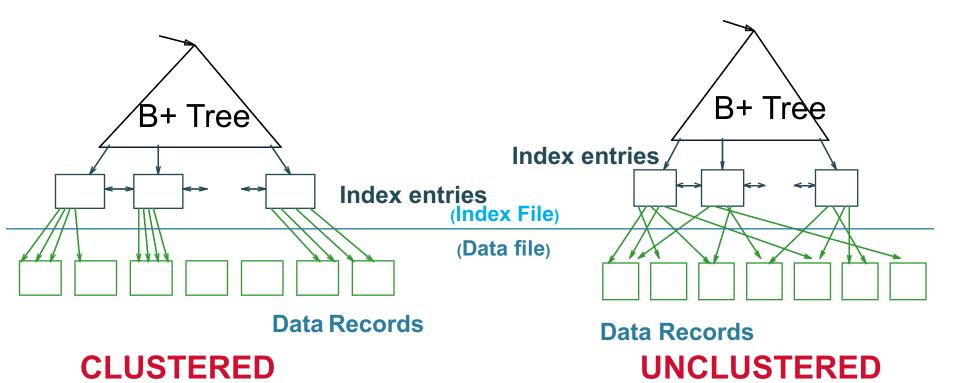
### B+ Tree Index by Example

d = 2





### **Clustered vs Unclustered**



Every table can have **only one** clustered and **many** unclustered indexes Why?

### Index Classification

#### Clustered/unclustered

- Clustered = records close in index are close in data
  - Option 1: Data inside data file is sorted on disk
  - Option 2: Store data directly inside the index (no separate files)
- Unclustered = records close in index may be far in data

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- Meaning 1:
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### Primary/secondary

- Meaning 1:
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- Meaning 2: means the same as clustered/unclustered
- Organization B+ tree or Hash table

# Summary So Far

- Index = a file that enables direct access to records in another data file
  - B+ tree / Hash table
  - Clustered/unclustered
- Data resides on disk
  - Organized in blocks
  - Sequential reads are efficient
  - Random access less efficient
  - Random read 1-2% of data worse than sequential

> σ Student | Takes

SELECT \* FROM Student x, Takes y WHERE x.ID=y.studentID AND y.courseID > 300

## Example

σ Student

SELECT \* FROM Student x, Takes y WHERE x.ID=y.studentID AND y.courseID > 300

### Example

for y in Takes
if courseID > 300 then
for x in Student
if x.ID=y.studentID
output \*

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- Takes\_courseID = index on Takes.courseID
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for y' in Takes\_courseID where y'.courseID > 300
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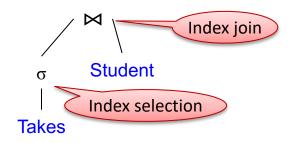
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# Getting Practical: Creating Indexes in SQL

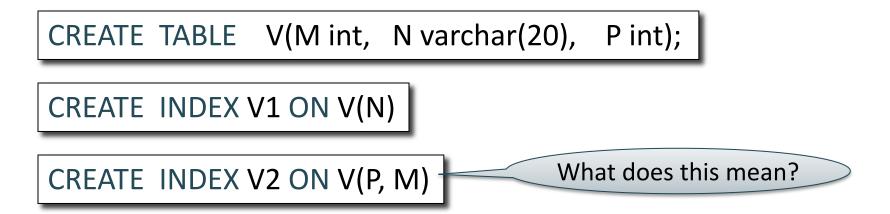
CREATE TABLE V(M int, N varchar(20), P int);

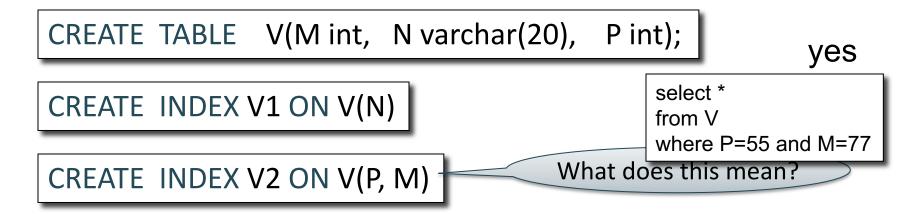
CREATE INDEX V1 ON V(N)

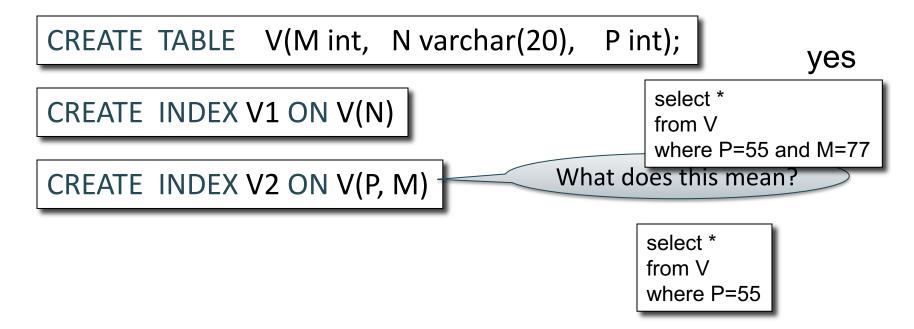
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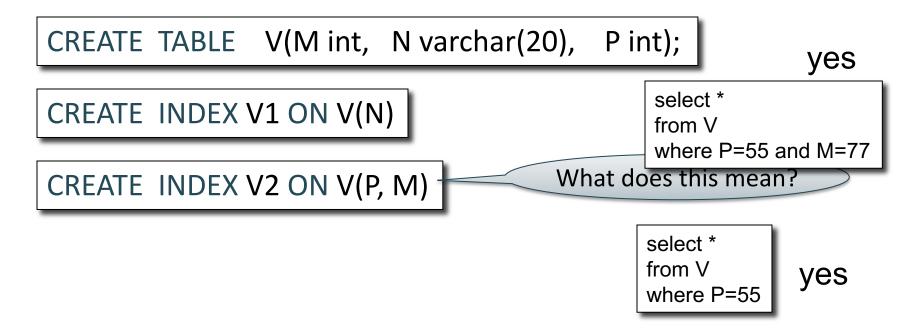
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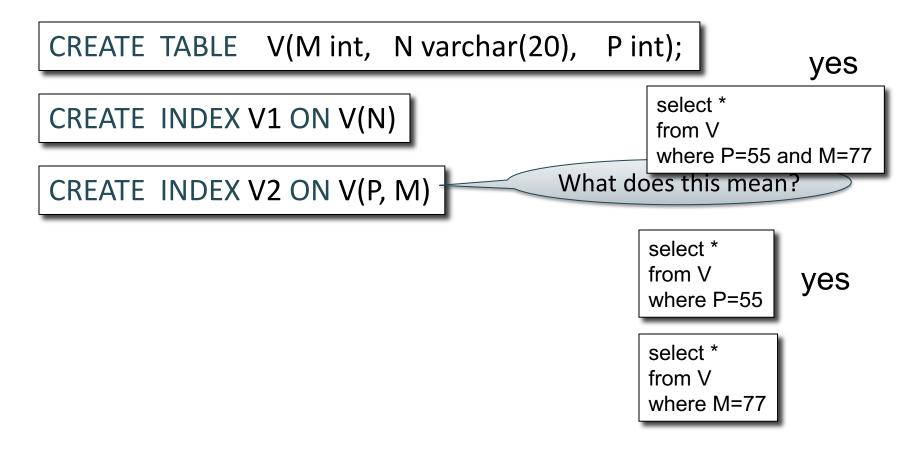
CREATE INDEX V2 ON V(P, M)

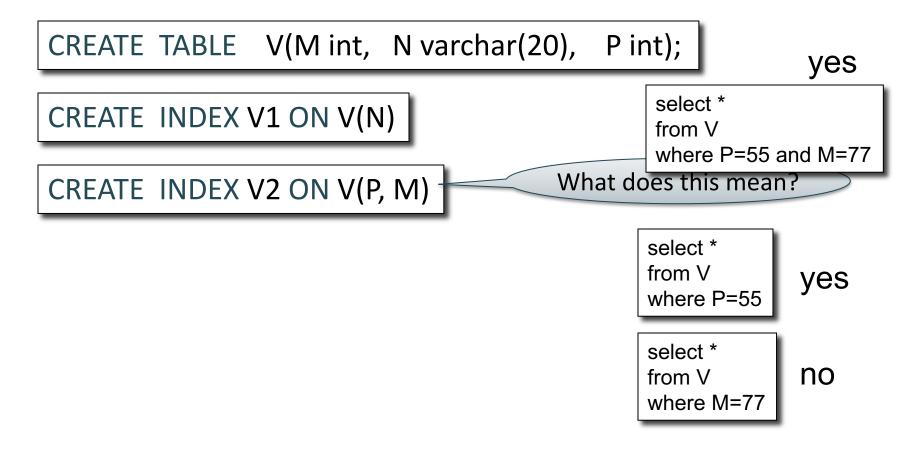


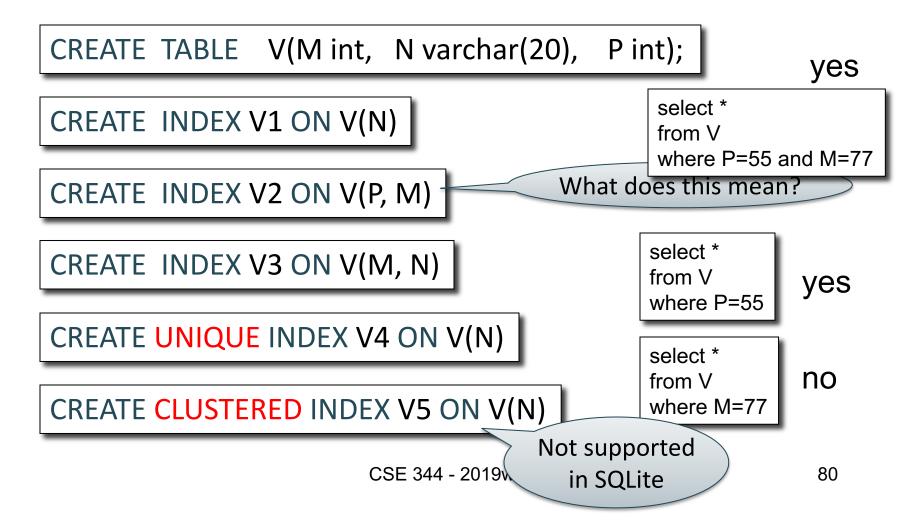












#### Student

Which	Indexes?

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10	Tom	Hanks
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- How many indexes could we create?
- Which indexes should we create?

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Which	Indexes?

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•••		

- How many indexes could we create?
- Which indexes should we create?

### In general this is a very hard problem

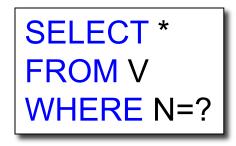
### Index Selection: Which Search Key

- Make some attribute K a search key if the WHERE clause contains:
  - An exact match on K
  - A range predicate on K
  - A join on K



### Your workload is this

100000 queries:



100 queries:



### Your workload is this

100000 queries:



100 queries:



What indexes ?



### Your workload is this

100000 queries:

100 queries:

A: V(N) and V(P) (hash tables or B-trees)

V(M, N, P);

Your workload is this

100000 queries:

100 queries:

SELECT \* FROM V WHERE N>? and N<? SELECT \* FROM V WHERE P=? 100000 queries:



What indexes ?

V(M, N, P);

Your workload is this

100000 queries:

100 queries:

100000 queries:

SELECT \* FROM V WHERE N>? and N<? SELECT \* FROM V WHERE P=? INSERT INTO V VALUES (?, ?, ?)

A: definitely V(N) (must B-tree); unsure about V(P)



#### Your workload is this

100000 queries: 1000000 queries:

100000 queries:



SELECT *	
FROM V	

WHERE N=? and P>?



What indexes ?



#### Your workload is this

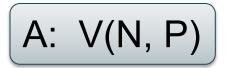
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100000 queries:



**SELECT** \* FROM V WHERE N=? and P>?





How does this index differ from: 1. Two indexes V(N) and V(P)? CSE 3 2. An index V(P, N)?



Your workload is this

1000 queries:

SELECT \* FROM V WHERE N>? and N<? 100000 queries:

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Your workload is this

1000 queries:

SELECT \* FROM V WHERE N>? and N<? 100000 queries:

SELECT \* FROM V WHERE P>? and P<?

A: V(N) secondary, V(P) primary index

### Two typical kinds of queries

SELECT \* FROM Movie WHERE year = ?

- Point queries
- What data structure should be used for index?

SELECT \* FROM Movie WHERE year >= ? AND year <= ?

- Range queries
- What data structure should be used for index?

### **Basic Index Selection Guidelines**

- Consider queries in workload in order of importance
- Consider relations accessed by query

   No point indexing other relations
- Look at WHERE clause for possible search key
- Try to choose indexes that speed-up multiple queries

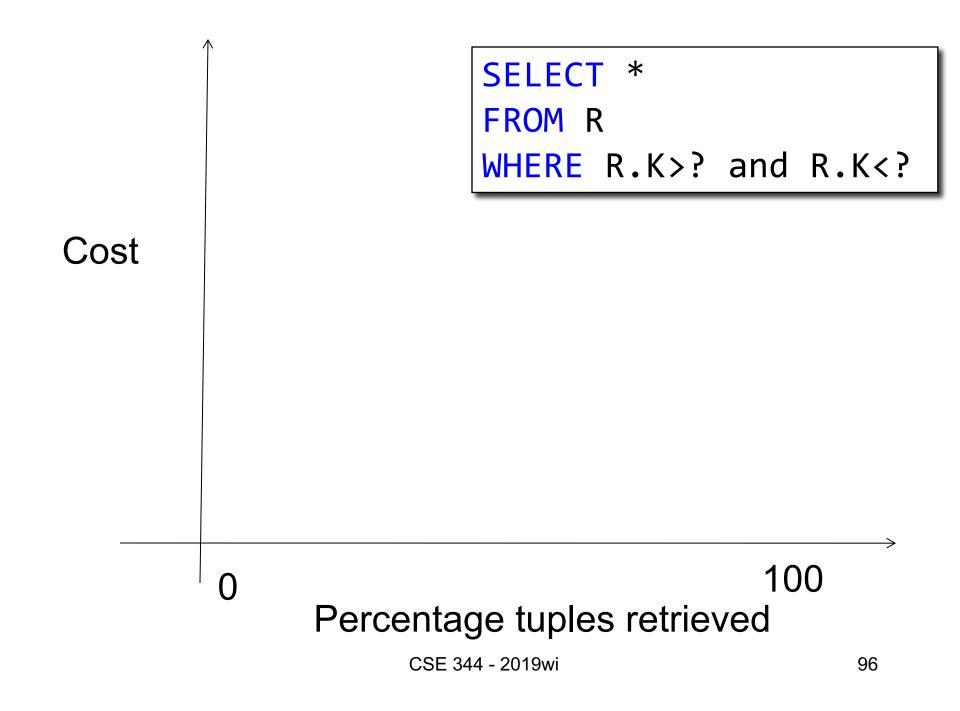
### To Cluster or Not

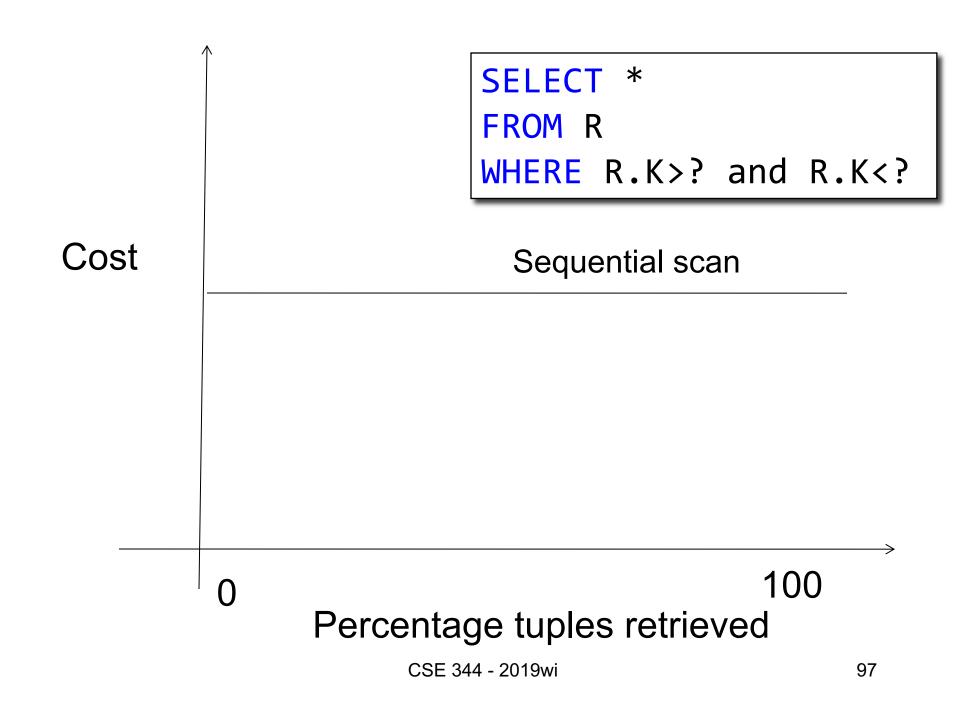
Remember:

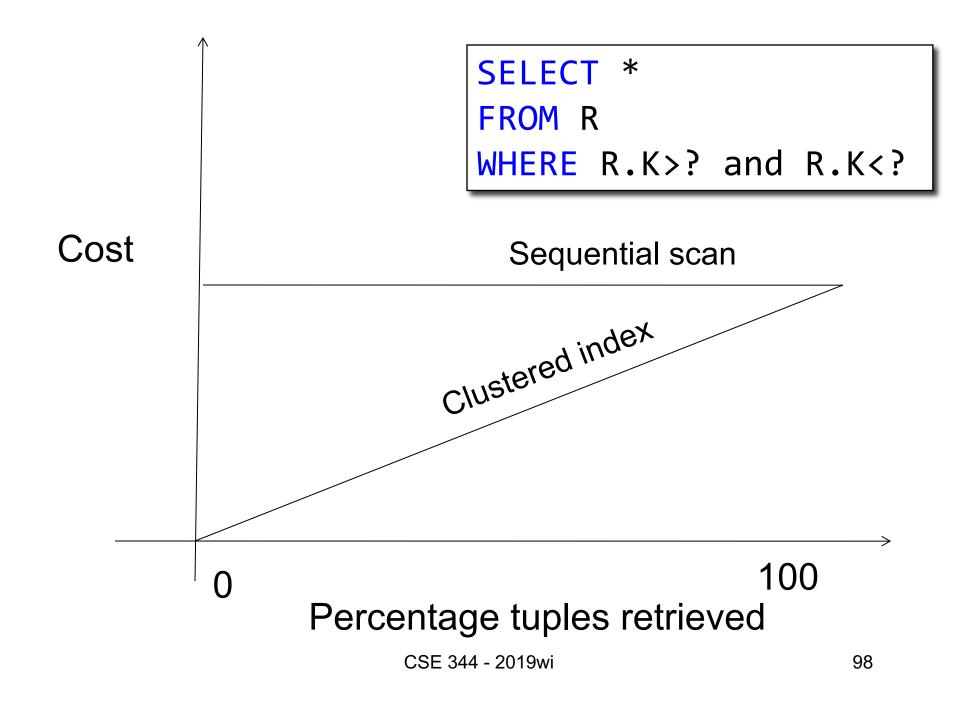
• Rule of thumb:

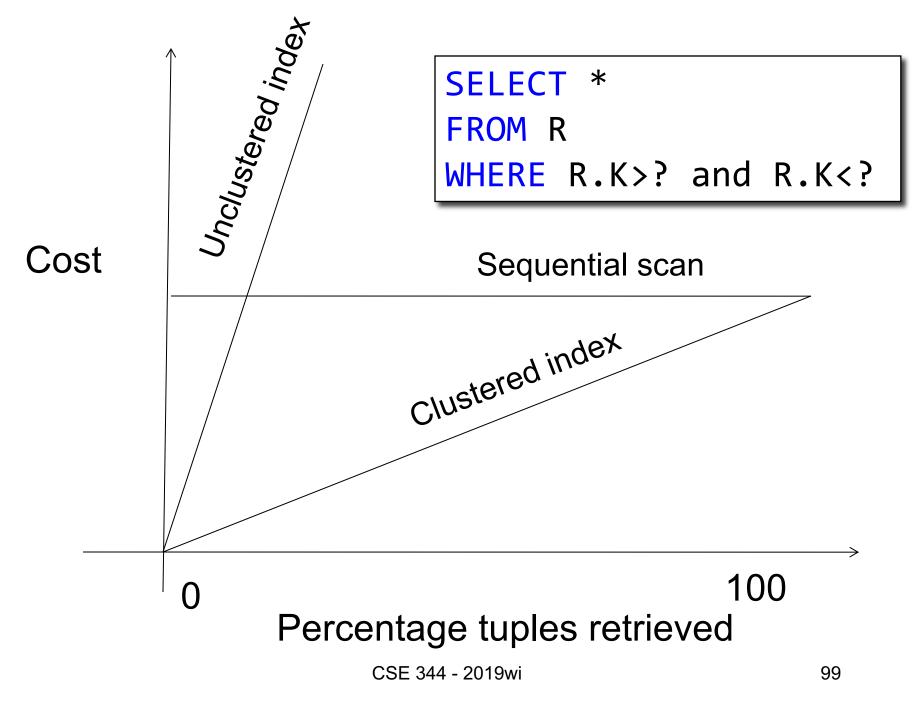
Random reading 1-2% of file  $\approx$  sequential scan entire file;

Range queries benefit mostly from clustering because they may read more than 1-2%









### Introduction to Database Systems CSE 344

### Lecture 17: Basics of Query Optimization and Query Cost Estimation

### **Cost Estimation**

- The optimizer considers several plans, estimates their costs, and chooses the cheapest
- This lecture: cost estimation for relational operators
- The cost is always dominated by the cost of reading from, or writing to disk

### Cost of Reading Data From Disk

### **Cost Parameters**

- Cost = I/O + CPU + Network BW
  - We will focus on I/O in this class
- Parameters (a.k.a. statistics):
  - B(R) = # of blocks (i.e., pages) for relation R
  - T(R) = # of tuples in relation R
  - V(R, a) = # of distinct values of attribute a

### **Cost Parameters**

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When **a** is a key, **V(R,a) = T(R)** When **a** is not a key, **V(R,a)** can be anything <= **T(R)** 

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• DBMS collects statistics about base tables must infer them for intermediate results

### Size Estimation

Main principle:

- Size of the output = some <u>fraction</u> of the size of the input
- The *fraction* is called the *selectivity factor*

### **Selectivity Factors for Conditions**

• A = c /\*  $\sigma_{A=c}(R)$  \*/ - Selectivity f = 1/V(R,A)

Will use mostly this...

...and this

- Selectivity f = (c - min(R, A))/(max(R,A) - min(R,A))

- c1 < A < c2 /\*  $\sigma_{c1 < A < c2}(R)$ \*/ - Selectivity f = (c2 - c1)/(max(R,A) - min(R,A))
- Cond1  $\land$  Cond2  $\land$  Cond3  $\land \dots$ 
  - Selectivity = f1\*f2\*f3\* …(assumes independence)

### Cost of Reading Data From Disk

- Sequential scan for relation R costs B(R)
- Index-based selection
  - Estimate selectivity factor **f** (see previous slide)
  - Clustered index: f\*B(R)
  - Unclustered index f\*T(R)

Note: we ignore I/O cost for index pages

• Example:

$$B(R) = 2000$$
  
T(R) = 100,000  
V(R, a) = 20

cost of  $\sigma_{a=v}(R) = ?$ 

- Table scan:
- Index based selection:

• Example: 
$$B(R) = 2000$$
  
T(R) = 100,000  
V(R, a) = 20

$$\label{eq:cost} \mbox{ of } \sigma_{a=v}(R) = ?$$

• Table scan: B(R) = 2,000 I/Os

Index based selection:

• Example:

cost of  $\sigma_{a=v}(R) = ?$ 

- Table scan: B(R) = 2,000 I/Os
- Index based selection:
  - If index is clustered:
  - If index is unclustered:

• Example: B(R) = 2000T(R) = 100,000 V(R, a) = 20

cost of 
$$\sigma_{a=v}(R) = ?$$

- Table scan: B(R) = 2,000 I/Os
- Index based selection:
  - If index is clustered: B(R) \* 1/V(R,a) = 100 I/Os
  - If index is unclustered:

• Example: 
$$| \begin{array}{c} B(R) = 2000 \\ T(R) = 100,000 \\ V(R, a) = 20 \end{array} |$$

- Table scan: B(R) = 2,000 I/Os
- Index based selection:
  - If index is clustered: B(R) \* 1/V(R,a) = 100 I/Os

- If index is unclustered: T(R) \* 1/V(R,a) = 5,000 I/Os

• Example: 
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  - If index is clustered: B(R) \* 1/V(R,a) = 100 I/Os
  - If index is unclustered: T(R) \* 1/V(R,a) = 5,000 I/Os

#### Lesson: Don't build unclustered indexes when V(R,a) is small !

# Cost of Executing Operators (Focus on Joins)

## Outline

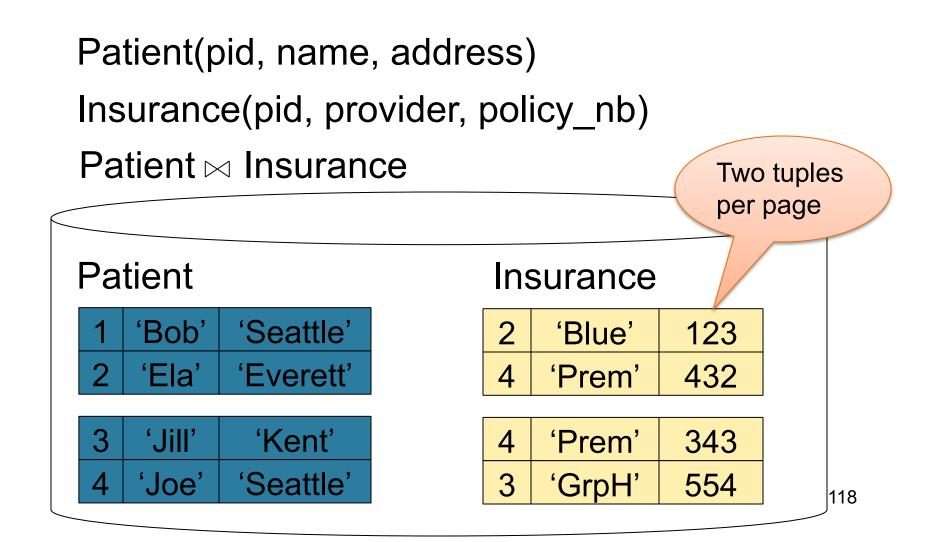
#### Join operator algorithms

- One-pass algorithms (Sec. 15.2 and 15.3)
- Index-based algorithms (Sec 15.6)
- Note about readings:
  - In class, we discuss only algorithms for joins
  - Other operators are easier: read the book

# Join Algorithms

- Nested loop join
- Hash join
- Sort-merge join
- Index-join

# Join Example



# **Nested Loop Joins**

- Tuple-based nested loop R ⋈ S
- R is the outer relation, S is the inner relation

 $\begin{array}{l} \underline{\text{for}} \text{ each tuple } t_1 \text{ in } R \ \underline{\text{do}} \\ \underline{\text{for}} \text{ each tuple } t_2 \text{ in } S \ \underline{\text{do}} \\ \underline{\text{if}} \ t_1 \text{ and } t_2 \text{ join } \underline{\text{then}} \text{ output } (t_1, t_2) \end{array}$ 

What is the Cost?

# **Nested Loop Joins**

- Tuple-based nested loop R ⋈ S
- R is the outer relation, S is the inner relation

 $\begin{array}{l} \label{eq:total_for_each_tuple_t_1} \begin{tabular}{l} for each tuple t_1 in R do \\ \hline for each tuple t_2 in S do \\ \hline if t_1 and t_2 join \underline{then} output (t_1,t_2) \end{array}$ 

• Cost: B(R) + T(R) B(S)

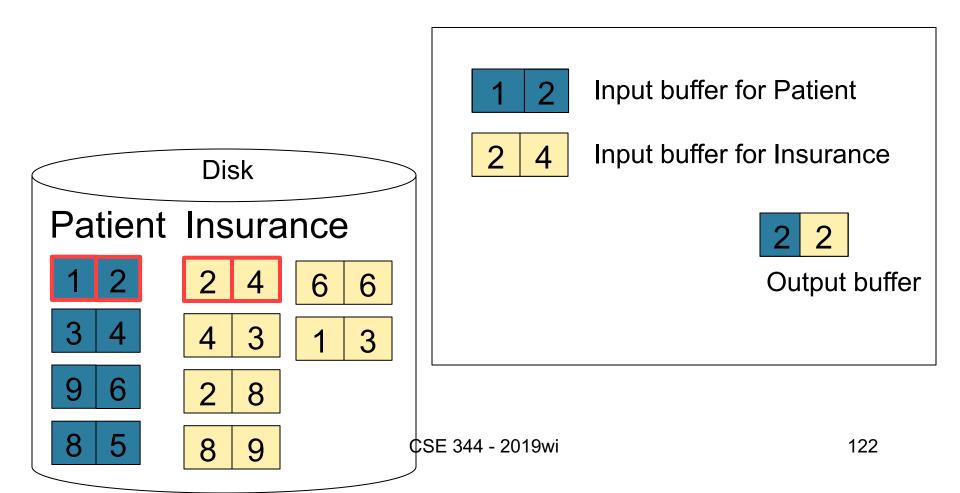
What is the Cost?

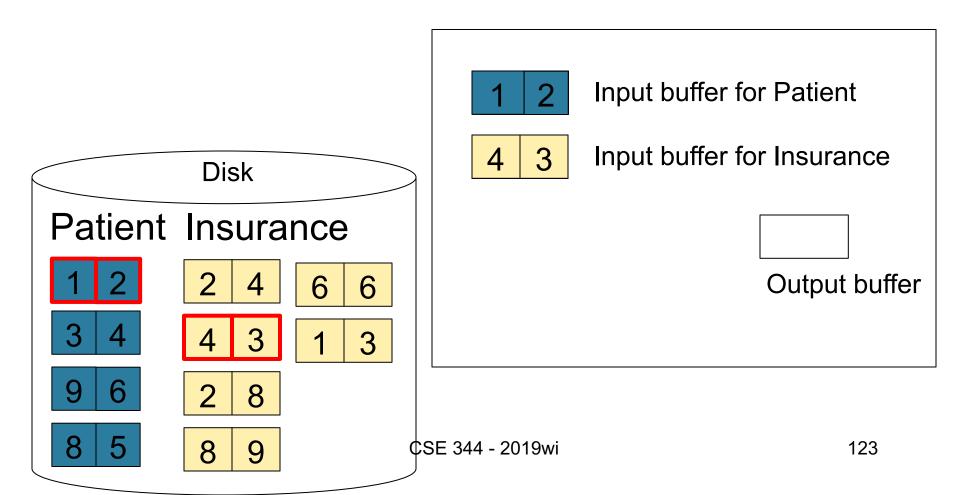
Multiple-pass since S is read many times

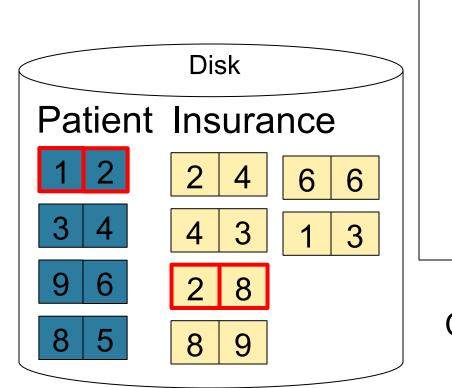
 $\begin{array}{l} \label{eq:starses} \begin{array}{l} \mbox{for each page of tuples r in R } \mbox{do} \\ \mbox{for each page of tuples s in S } \mbox{do} \\ \mbox{for all pairs of tuples } t_1 \mbox{ in r, } t_2 \mbox{ in s} \\ \mbox{if } t_1 \mbox{ and } t_2 \mbox{ join } \mbox{then} \mbox{ output } (t_1,t_2) \end{array}$ 

• Cost: B(R) + B(R)B(S)

What is the Cost?







1 2

Input buffer for Patient



Input buffer for Insurance

Keep going until read all of Insurance



Output buffer

Then repeat for next page of Patient... until end of Patient

Cost: B(R) + B(R)B(S)

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# **Block-Nested-Loop Refinement**

 $\begin{array}{l} \label{eq:starsest} \begin{array}{l} \mbox{for each group of M-1 pages r in R } \mbox{do} \\ \mbox{for each page of tuples s in S } \mbox{do} \\ \mbox{for all pairs of tuples } t_1 \mbox{ in r, } t_2 \mbox{ in s} \\ \mbox{if } t_1 \mbox{ and } t_2 \mbox{ join } \mbox{then} \mbox{ output } (t_1,t_2) \end{array}$ 

• Cost: B(R) + B(R)B(S)/(M-1)

What is the Cost?

# Hash Join

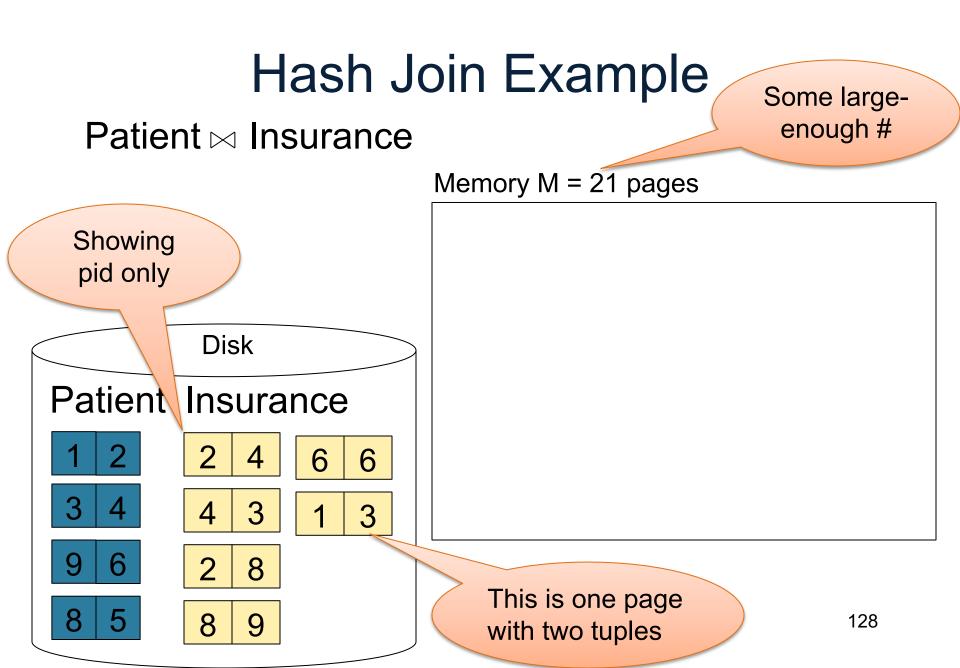
Hash join:  $R \bowtie S$ 

- Scan R, build buckets in main memory
- Then scan S and join
- Cost: B(R) + B(S)
- Which relation to build the hash table on?

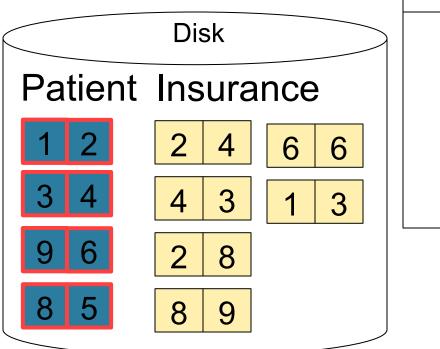
# Hash Join

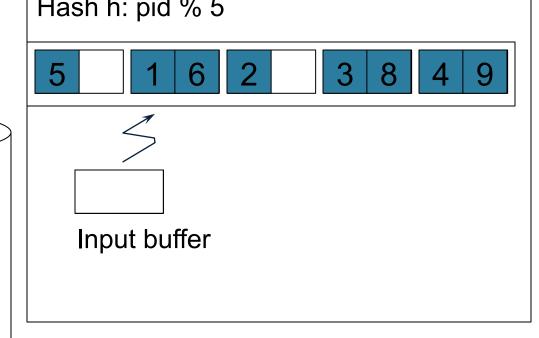
Hash join:  $R \bowtie S$ 

- Scan R, build buckets in main memory
- Then scan S and join
- Cost: B(R) + B(S)
- Which relation to build the hash table on?
- One-pass algorithm when  $B(R) \le M$ 
  - M = number of memory pages available

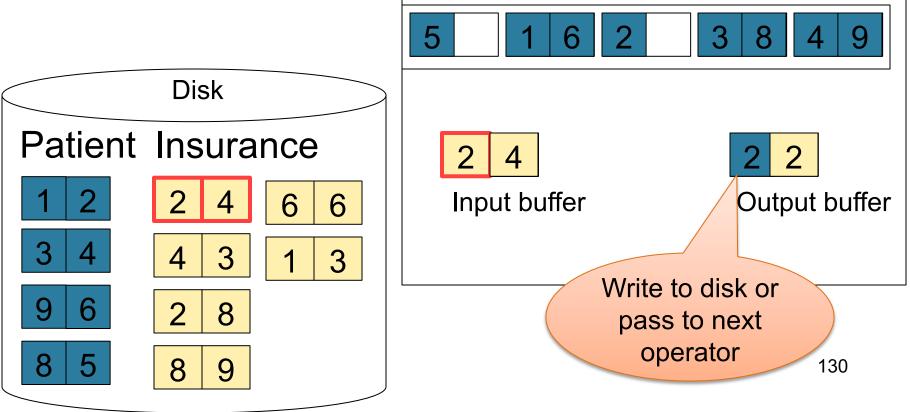


Step 1: Scan Patient and build hash table in memoryCan be done in<br/>method open()Memory M = 21 pagesHash h: pid % 5

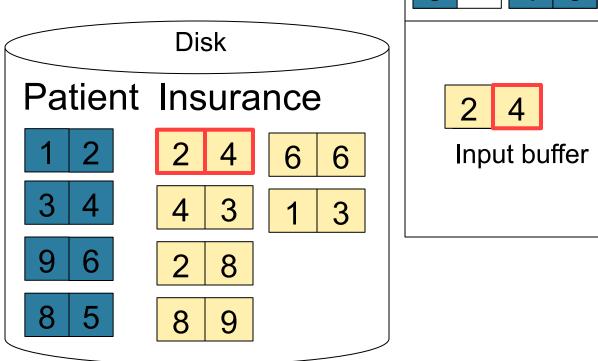


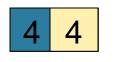


Step 2: Scan Insurance and probe into hash tableDone during<br/>calls to next()Memory M = 21 pagesHash h: pid % 5551623849



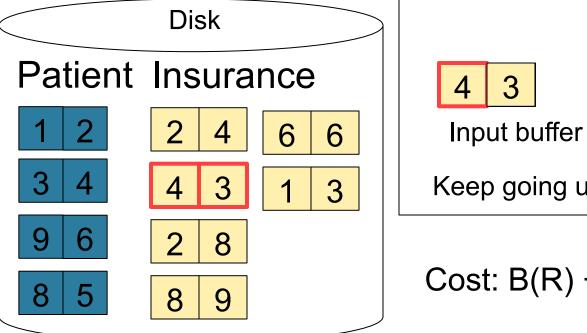
Step 2: Scan Insurance and probe into hash tableDone during<br/>calls to next()Memory M = 21 pagesHash h: pid % 5551623849





Output buffer

Step 2: Scan Insurance and probe into hash table Done during Memory M = 21 pages calls to next() Hash h: pid % 5 5 3 8



4

Output buffer

Keep going until read all of Insurance

Cost: 
$$B(R) + B(S)$$

3

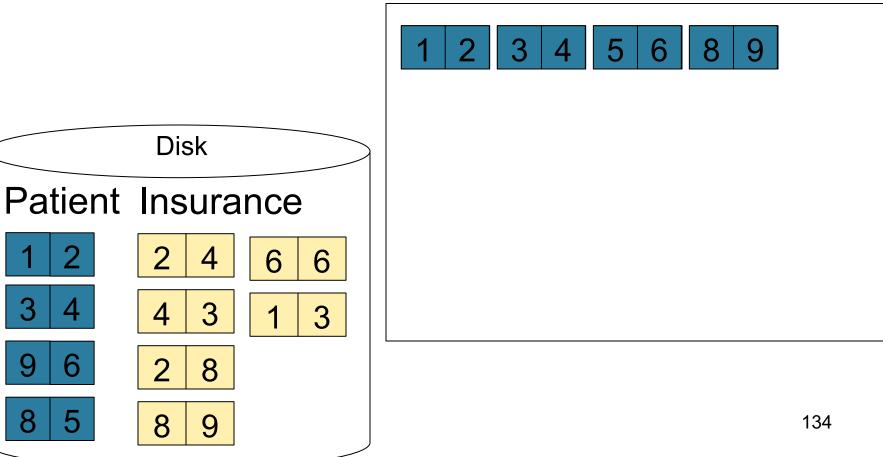
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# Sort-Merge Join

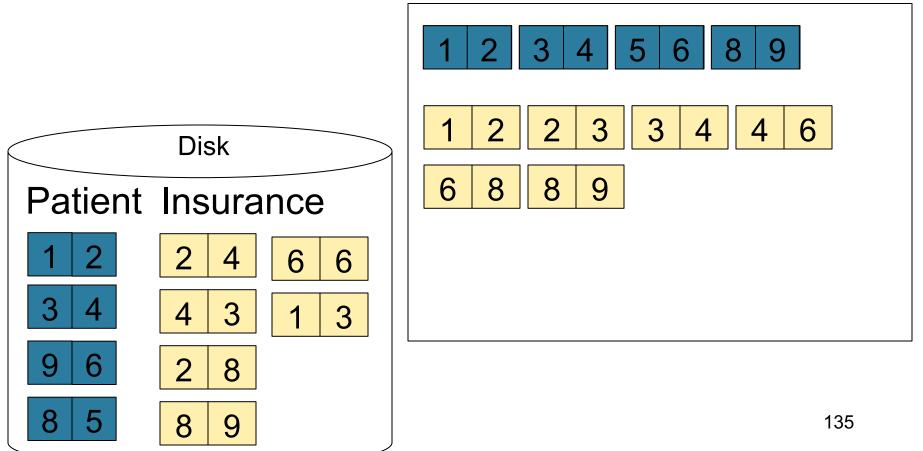
Sort-merge join: R ⋈ S

- Scan R and sort in main memory
- Scan S and sort in main memory
- Merge R and S
- Cost: B(R) + B(S)
- One pass algorithm when B(S) + B(R) <= M
- Typically, this is NOT a one pass algorithm

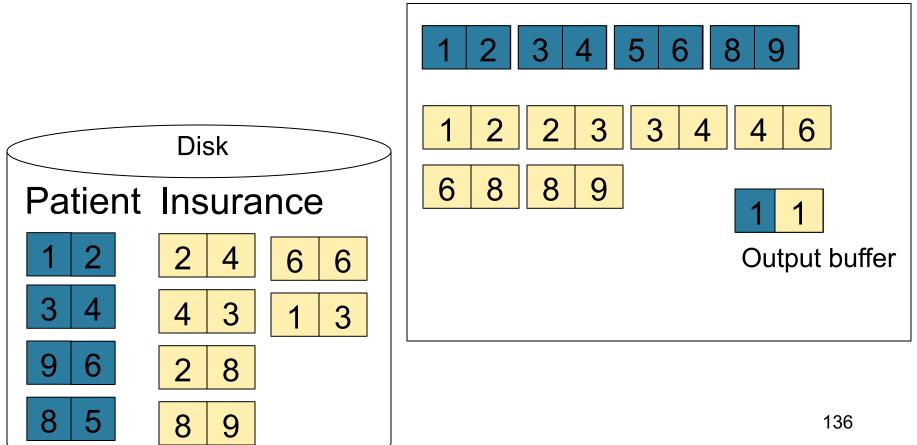
#### Step 1: Scan Patient and sort in memory



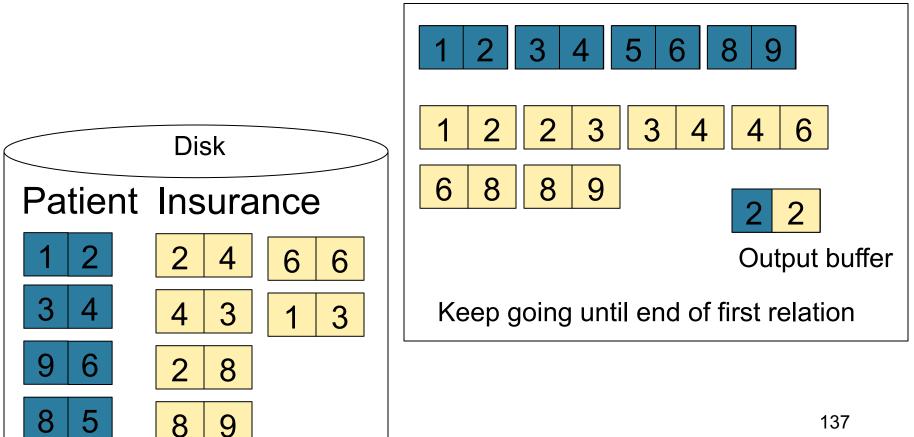
#### Step 2: Scan Insurance and sort in memory



#### Step 3: Merge Patient and Insurance



#### Step 3: Merge Patient and Insurance

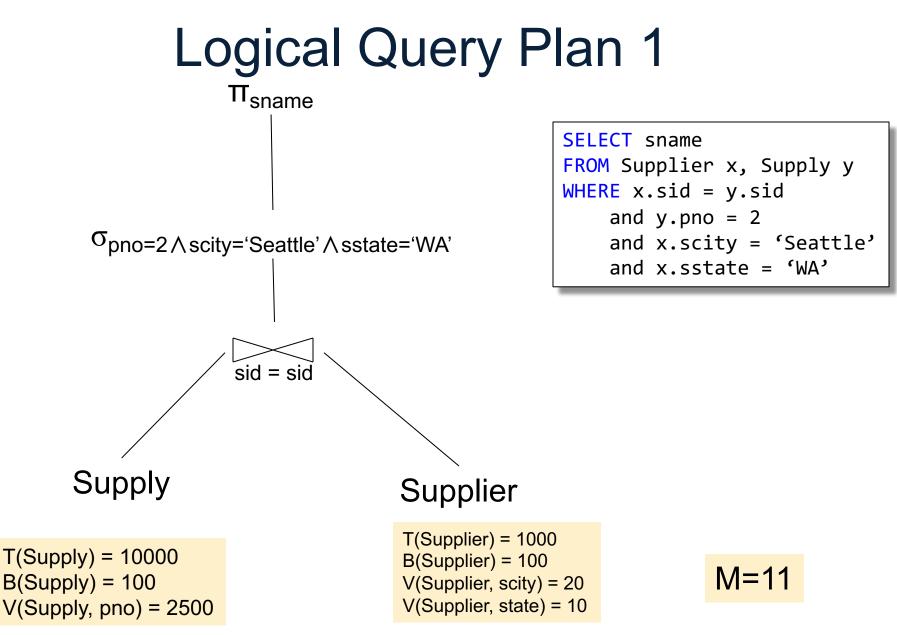


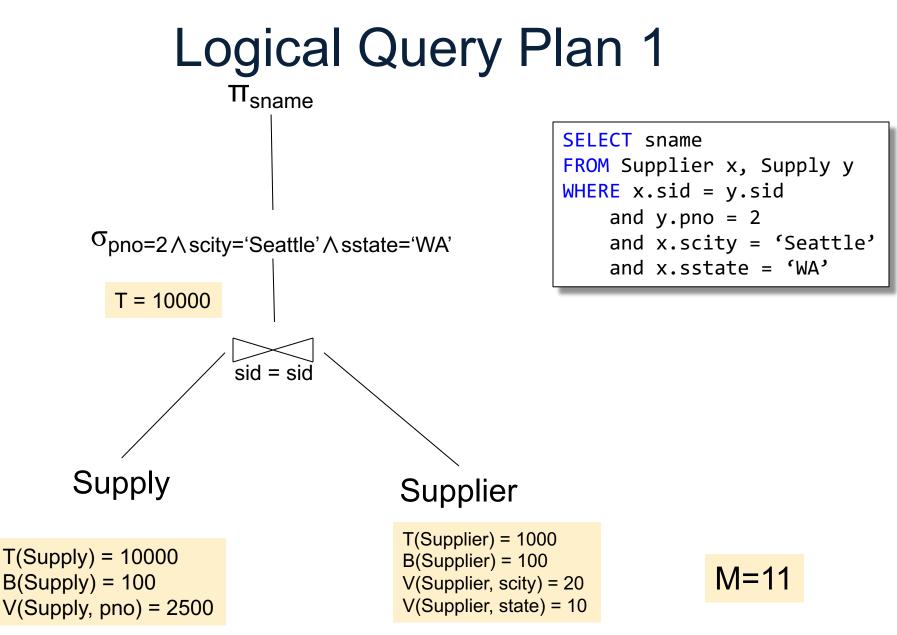
# Index Join

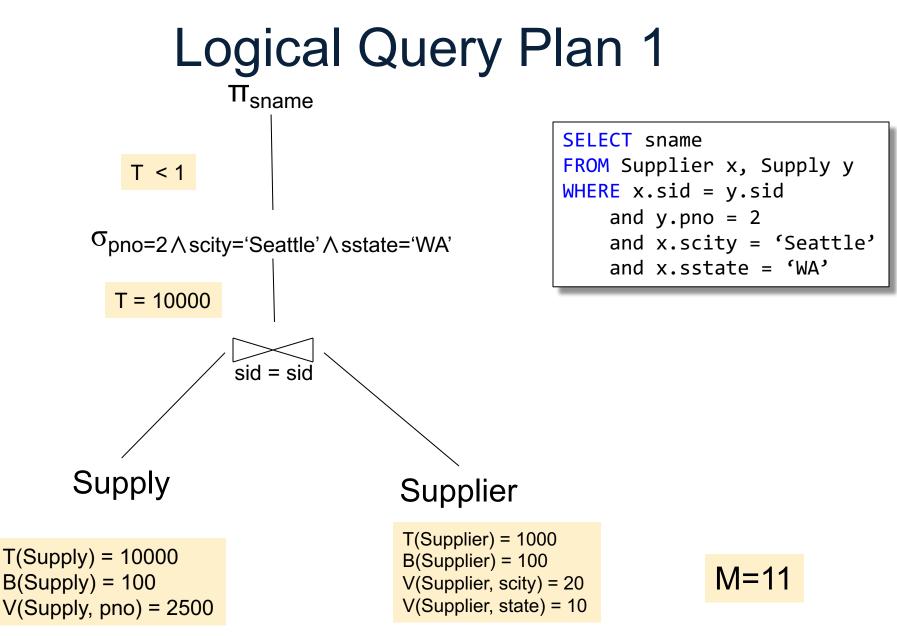
R ⋈ S

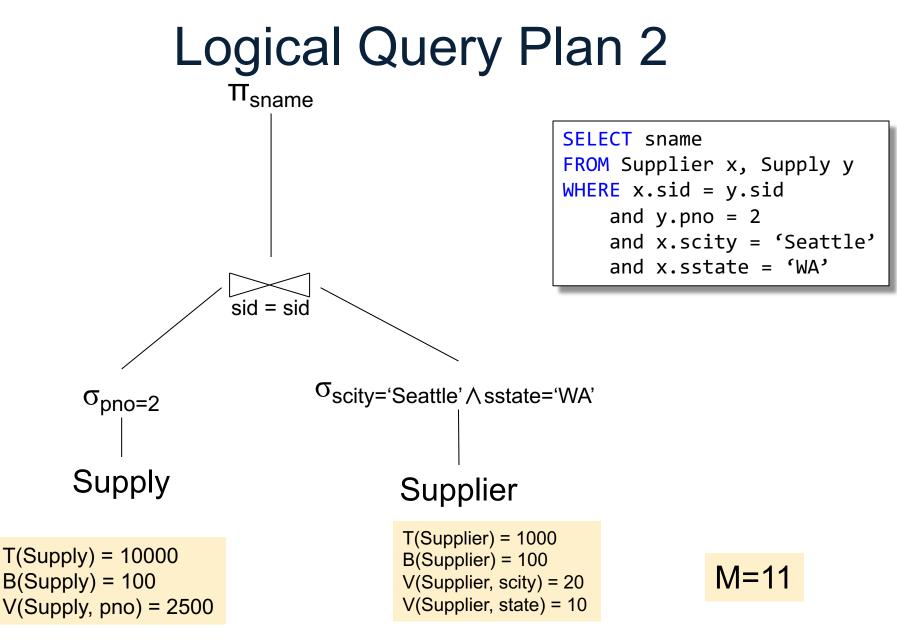
- Assume S has an index on the join attribute
- Iterate over R, for each tuple fetch corresponding tuple(s) from S
- Cost:
  - If index on S is clustered:
     B(R) + T(R) \* (B(S) \* 1/V(S,a))
  - If index on S is unclustered:
     B(R) + T(R) \* (T(S) \* 1/V(S,a))

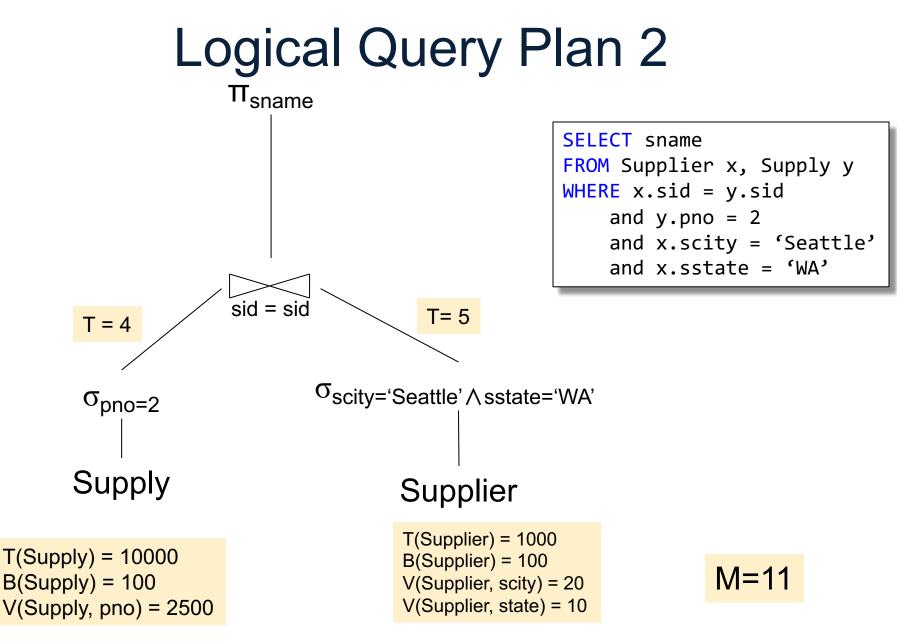
# Cost of Query Plans Example

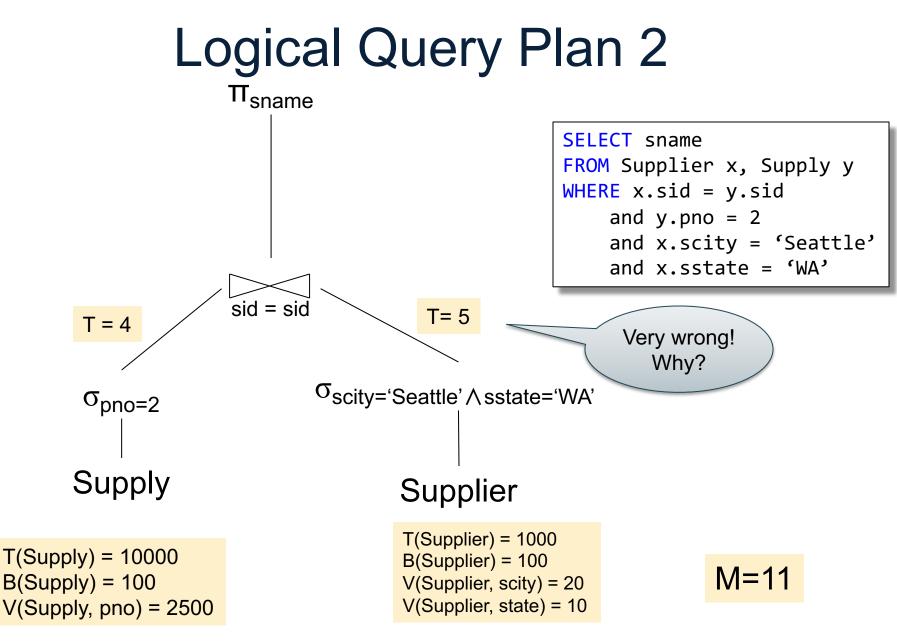


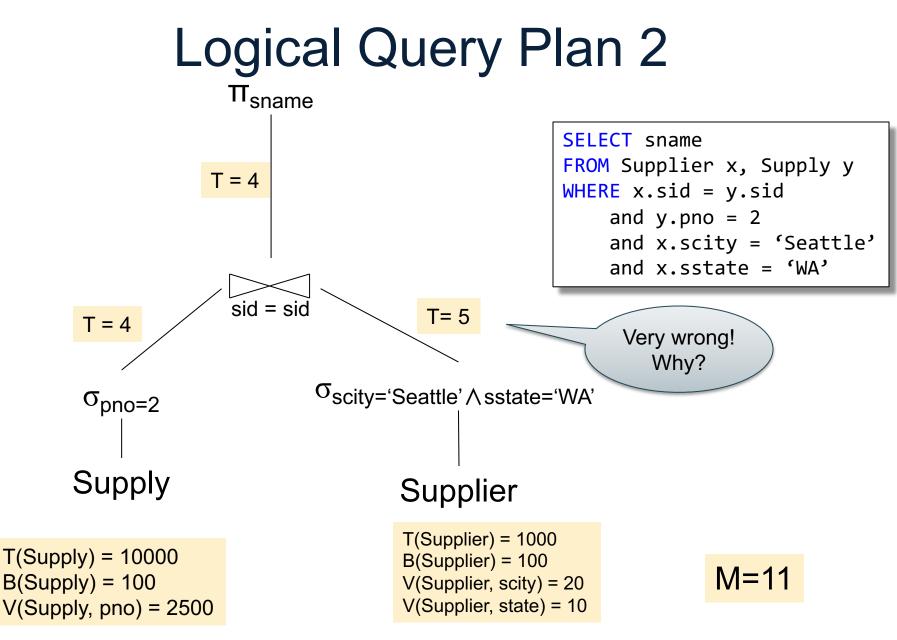


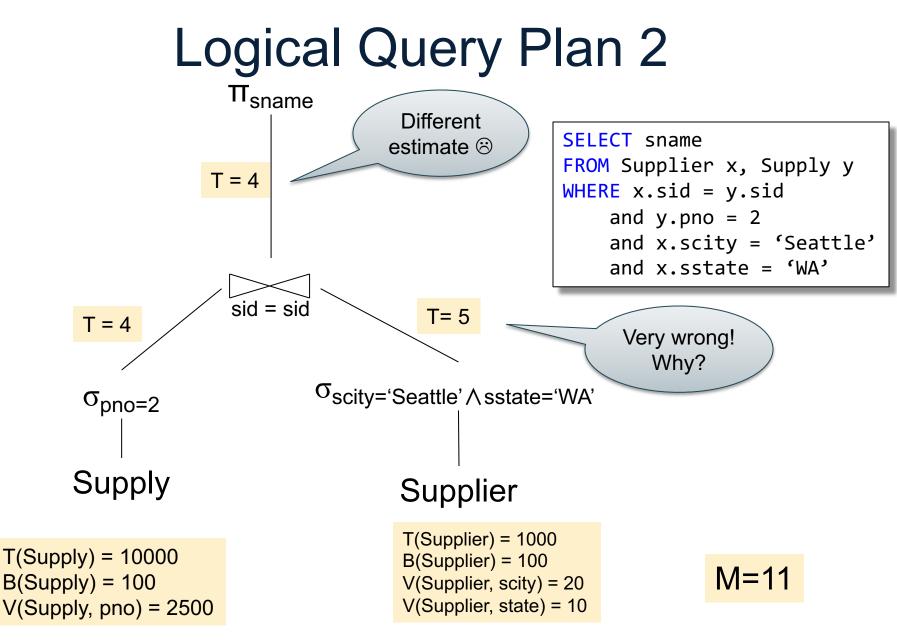


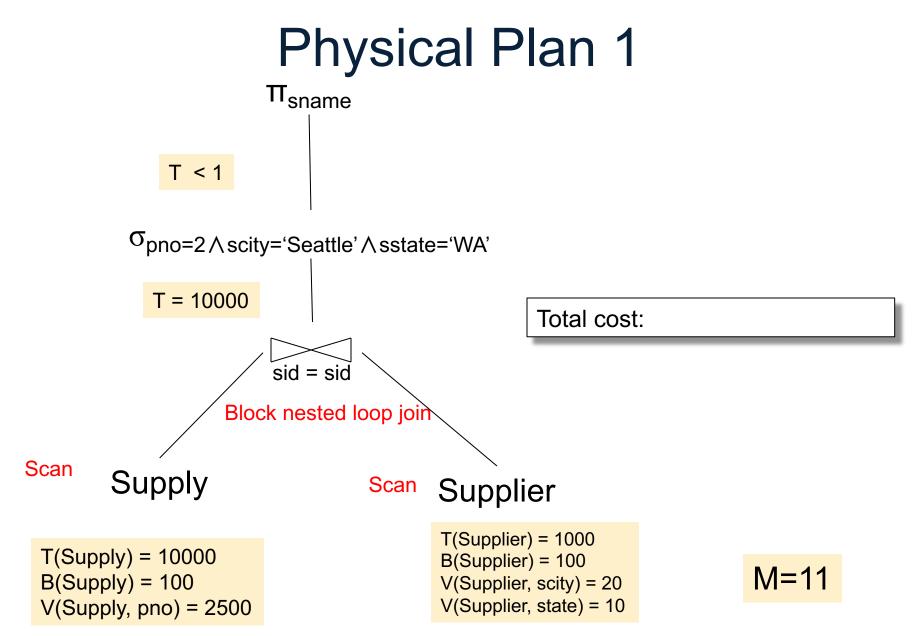


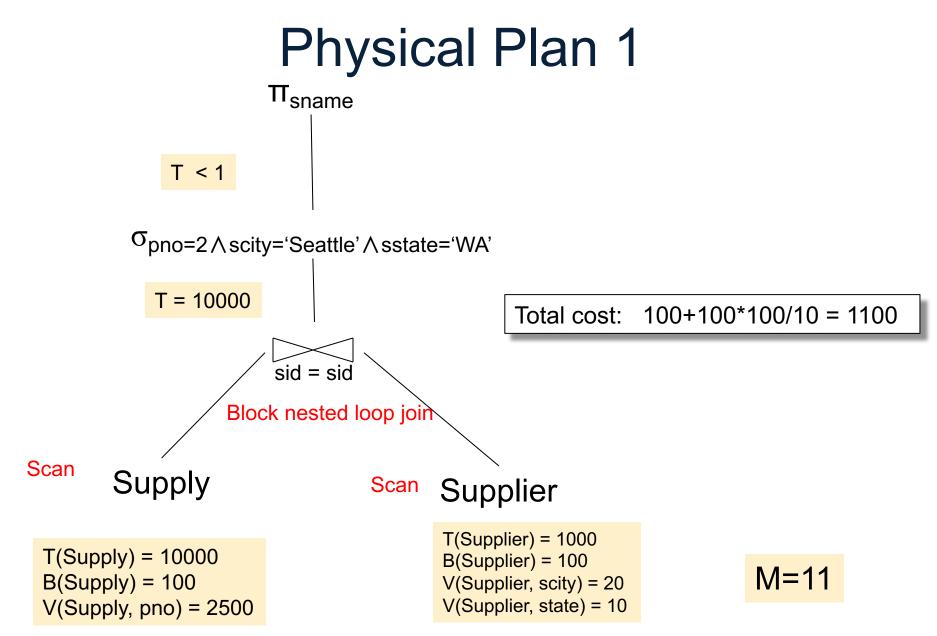


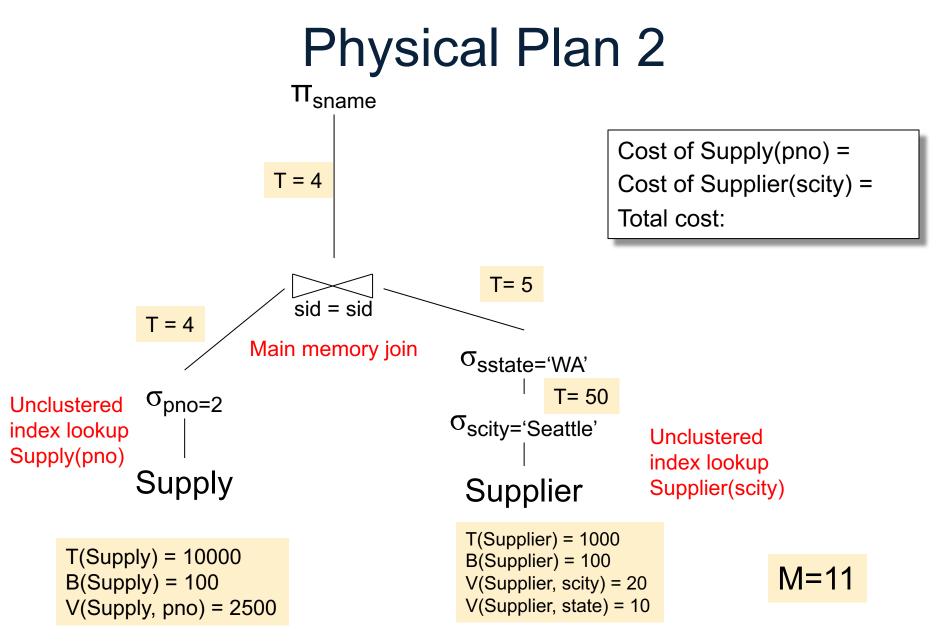


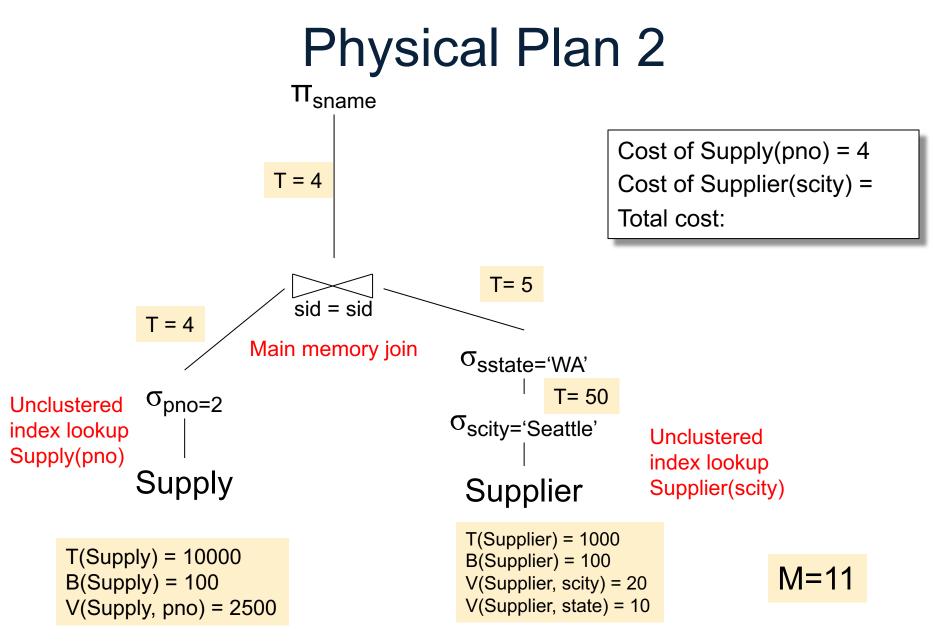


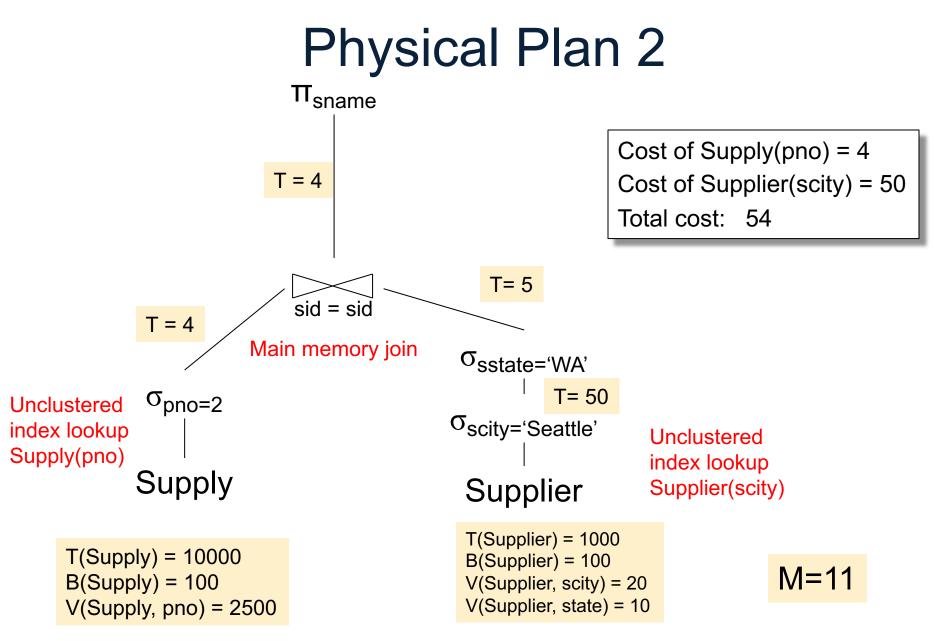


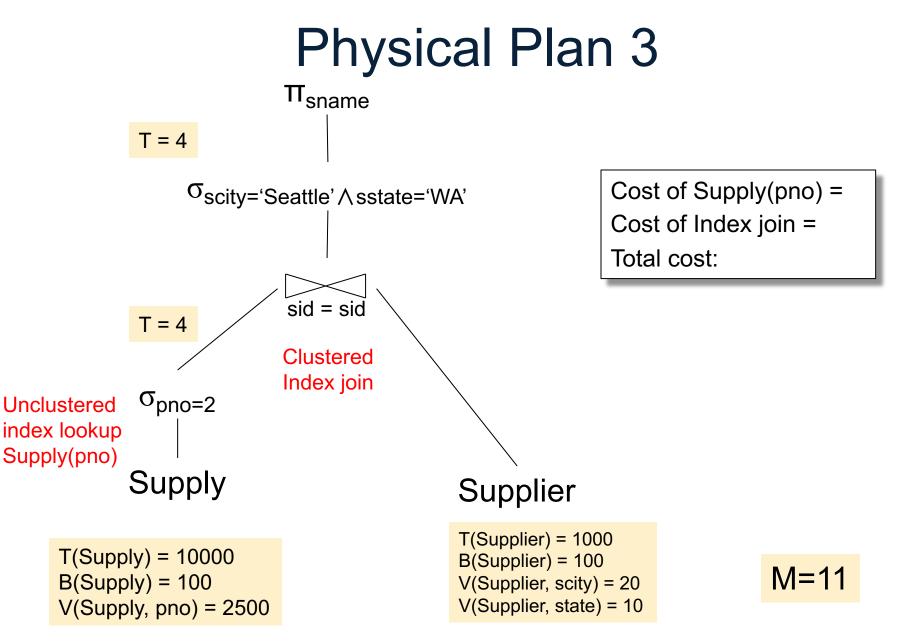


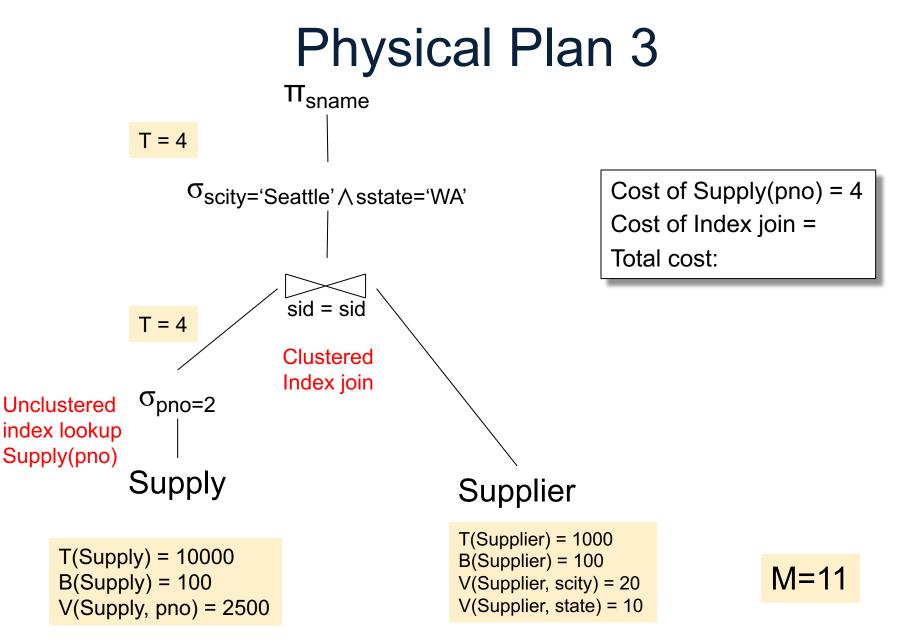


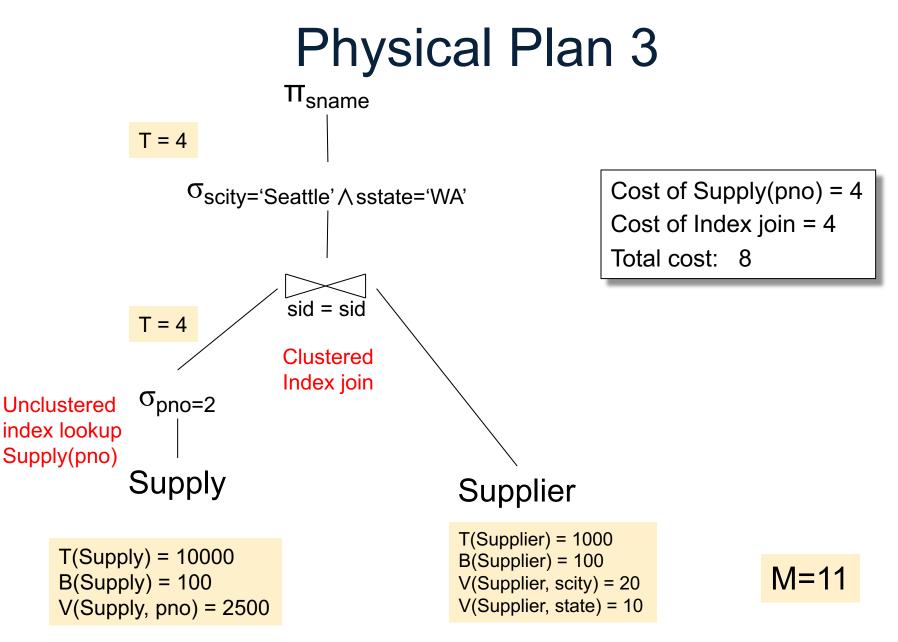












## Query Optimizer Summary

- Input: A logical query plan
- Output: A good physical query plan
- Basic query optimization algorithm
  - Enumerate alternative plans (logical and physical)
  - Compute estimated cost of each plan
  - Choose plan with lowest cost
- This is called cost-based optimization