#### Introduction to Data Management CSE 344

#### Lecture 23: Parallel DBMSs

#### Announcements

- WQ7 due tonight
- HW7 due on Wednesday

## Final Exam

- Thursday 3/16, 2:30-4:20pm
   Location: Here!
- You can bring two letter-sized sheets of notes
  - You can write on both sides
  - You can type / handwrite / print etc
- Exam will be comprehensive
  - Includes all lectures, readings, sections, HWs, WQs
- Final review session this Saturday 3/11
  - EEB 105, 1-2pm

#### Welcome to the 2nd half of 344

- Relational data model
  - Instance
  - Schema
  - Query languages
    - SQL, RA, RC, Datalog
- Query processing
  - Logical & physical plans
  - Indexes
  - Cost estimation
  - Query optimization
- Non-relational data model

- Conceptual design
  - E/R diagrams
  - Converting to SQL
  - Normalization
- Transactions
  - ACID
  - Transaction Implementation
  - Writing DB applications
- Parallel query processing
  - MapReduce
  - Spark

### Today

- Architecture of parallel DBMSs
- Distributing data to multiple machines
- Executing relational query operators in parallel
- Alternative data models for parallel DBMSs

## Why compute in parallel?

- Multi-cores:
  - Most processors have multiple cores
  - This trend will increase in the future
- Big data: too large to fit in main memory
  - Distributed query processing on 100x-1000x servers
  - Widely available now using cloud services

#### Performance Metrics for Parallel DBMSs

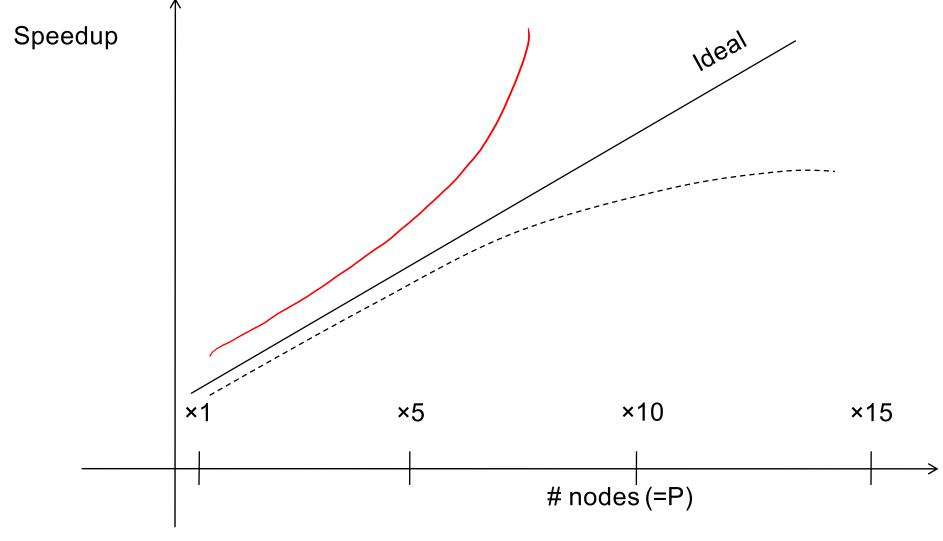
Nodes = processors, computers

• Speedup:

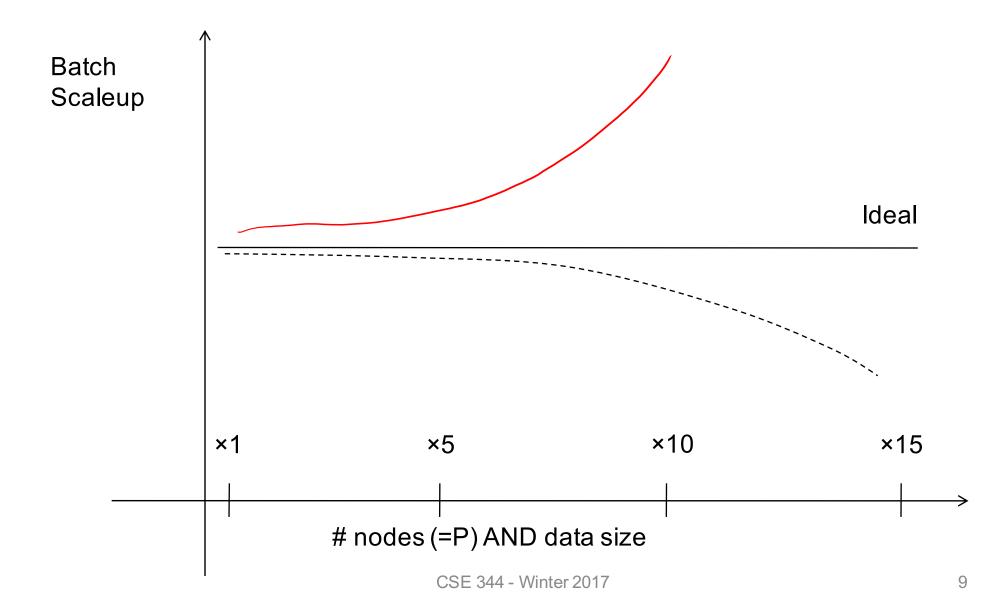
More nodes, same data 
 higher speed

- Scaleup:
  - More nodes, more data 
     same speed

#### Linear v.s. Non-linear Speedup



#### Linear v.s. Non-linear Scaleup



# Why Sub-linear Speedup and Scaleup?

• Startup cost

- Cost of starting an operation on many nodes

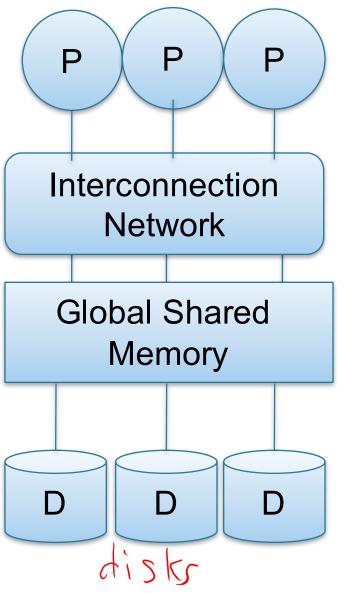
- Interference
  - Contention for resources between nodes
- Skew

- Slowest node becomes the bottleneck

#### Architectures for Parallel Databases

- Shared memory
- Shared disk
- Shared nothing

## Shared Memory

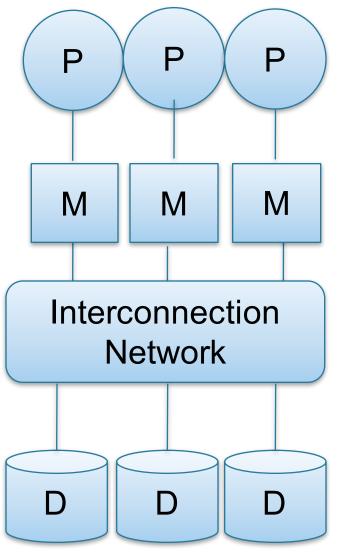


- Nodes share both RAM and disk
- Dozens to hundreds of processors

Example: SQL Server runs on a single machine and can leverage many threads to speed up a query

- check your HW3 query plans
- Easy to use and program
- Expensive to scale
  - last remaining cash cows in the hardware industry

## Shared Disk

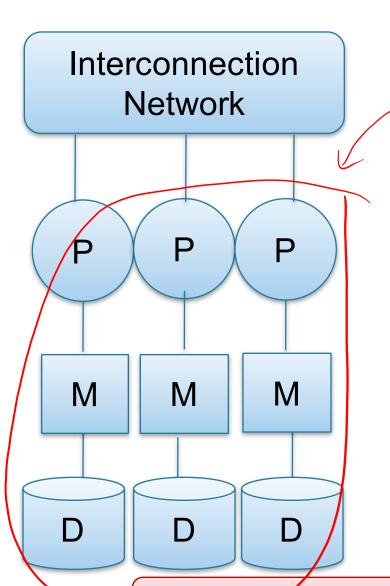


- All nodes access the same disks
- Found in the largest "single-box" (non-cluster) multiprocessors

Example: Oracle

- No need to worry about shared memory
- Hard to scale: existing deployments typically have fewer than 10 machines

## Shared Nothing



- Cluster of commodity machines on high-speed network
- Called "clusters" or "blade servers"
- Each machine has its own memory and disk: lowest contention.

Example: Google

Because all machines today have many cores and many disks, shared-nothing systems typically run many "nodes" on a single physical machine.

- Easy to maintain and scale
- Most difficult to administer and tune.

We discuss only Shared Nothing in class

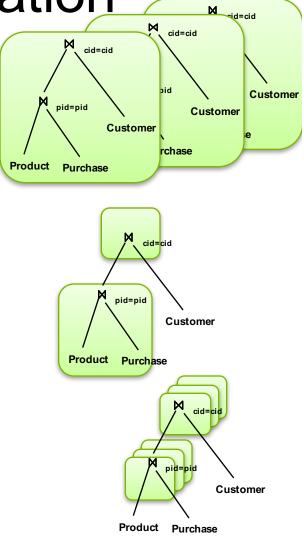


#### Parallel Data Processing @ 1990



#### Approaches to Parallel Query Evaluation

- Inter-query parallelism
  - Transaction per node
  - Good for transactional workloads
- Inter-operator parallelism
  - Operator per node
  - Good for analytical workloads
- Intra-operator parallelism
  - Operator on multiple nodes
  - Good for both?



We study only intra-operator parallelism: most scalable

# Single Node Query Processing (Review)

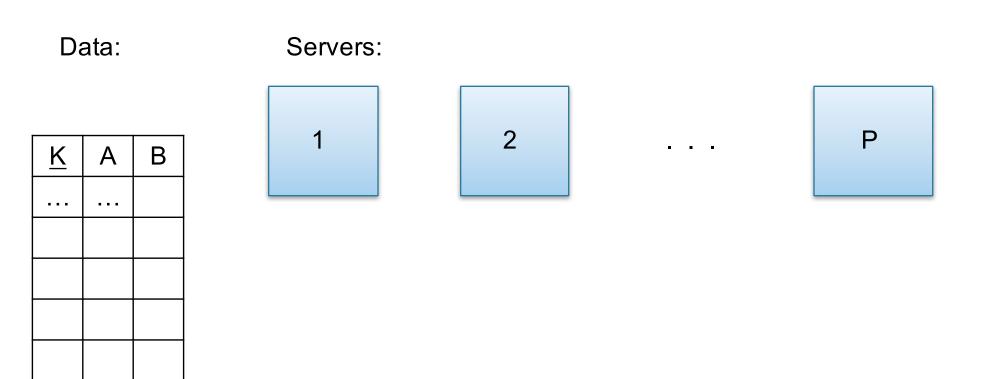
Given relations R(A,B) and S(B, C), no indexes:

- Selection:  $\sigma_{A=123}(R)$ 
  - Scan file R, select records with A=123
- Group-by:  $\gamma_{A,sum(B)}(R)$ 
  - Scan file R, insert into a hash table using A as key
  - When a new key is equal to an existing one, add B to the value
- Join: R <sup>⋈</sup> S
  - Scan file S, insert into a hash table using B as key
  - Scan file R, probe the hash table using B

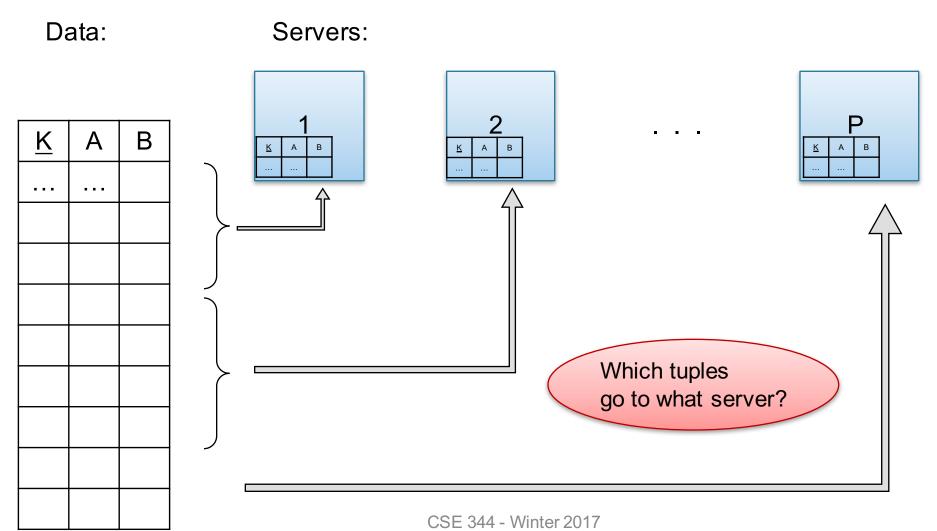
## **Distributed Query Processing**

- Data is horizontally partitioned on many servers
- Operators may require data reshuffling
- First let's discuss how to distribute data across multiple nodes / servers

### Horizontal Data Partitioning



### Horizontal Data Partitioning



## Horizontal Data Partitioning

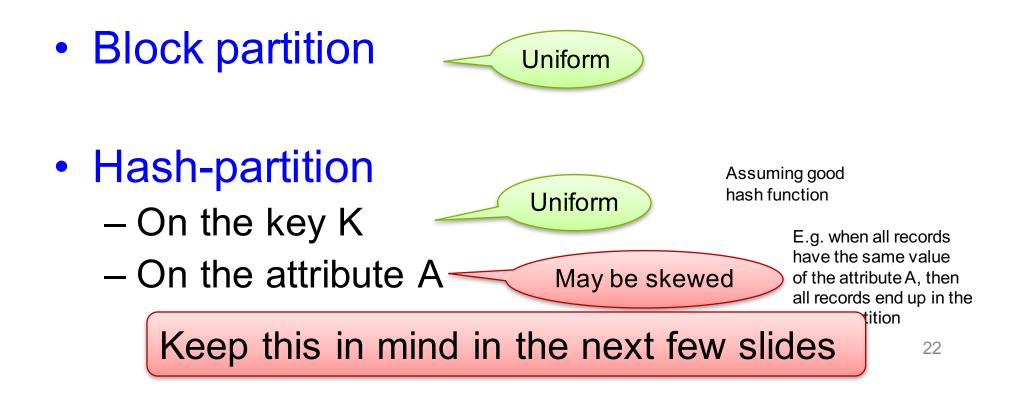
• Block Partition:

− Partition tuples arbitrarily s.t. size( $R_1$ ) ≈ ... ≈ size( $R_P$ )

- Hash partitioned on attribute A:
  - Tuple t goes to chunk i, where  $i = h(t.A) \mod P + 1$
  - Recall: calling hash fn's is free in this class
- Range partitioned on attribute A:
  - Partition the range of A into  $-\infty = v_0 < v_1 < ... < v_P = \infty$
  - Tuple t goes to chunk i, if  $v_{i-1} < t.A < v_i$

## Uniform Data v.s. Skewed Data

 Let R(K,A,B,C); which of the following partition methods may result in skewed partitions?



## Parallel Execution of RA Operators: Grouping

Data: R(<u>K</u>,A,B,C) Query: γ<sub>A,sum(C)</sub>(R)

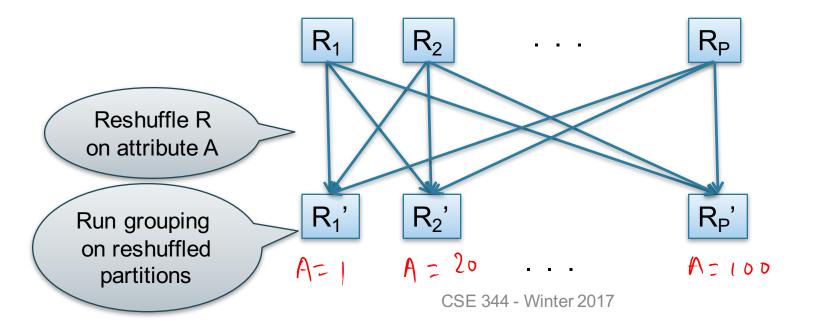
How to compute group by if:

- R is hash-partitioned on A?
- R is block-partitioned ?
- R is hash-partitioned on K?

#### Parallel Execution of RA Operators: Grouping

Data: R(K,A,B,C)Query:  $\gamma_{A,sum(C)}(R)$ 

• R is block-partitioned or hash-partitioned on K

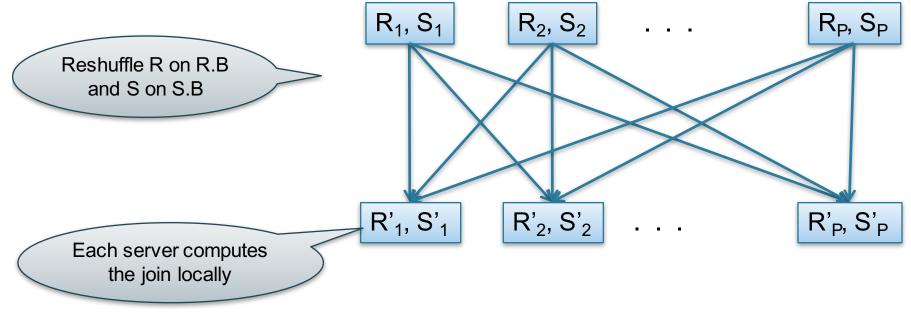


## Speedup and Scaleup

- Consider:
  - Query:  $\gamma_{A,sum(C)}(R)$
  - Runtime: only consider I/O costs
- If we double the number of nodes P, what is the new running time?
  - Half (each server holds ½ as many chunks)
- If we double both P and the size of R, what is the new running time?
  - Same (each server holds the same # of chunks)

#### Parallel Execution of RA Operators: Partitioned Hash-Join

- Data: R(K1, A, B), S(K2, B, C)
- Query:  $R(\underline{K1}, A, \underline{B}) \bowtie S(\underline{K2}, \underline{B}, C)$ 
  - Initially, both R and S are partitioned on K1 and K2



#### Data: R(K1,A, B), S(K2, B, C) Query: R(K1,A,B) $\bowtie$ S(K2,B,C) Parallel Join Illustration

