IP Addresses, DNS CSE 333

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Administrivia

- HW3 due tomorrow night, 11pm
 - (plus late days if needed and you have them remaining be sure to check "late days remaining" number on canvas)
 - (any last-minute questions?) observations?)
- Exercise 15 due Monday
 - Client-side TCP connection

Lecture Outline

- Sockets API
 - Sockets Overview
 - Network Addresses
 - API Functions
- DNS
- Client-side Programming

Files and File Descriptors

- * Remember open (), read(), write(), and close()?
 - POSIX system calls for interacting with files
 - **open** () returns a file descriptor
 - An integer that represents an open file
 - This file descriptor is then passed to read(), write(), and close()
 - Inside the OS, the file descriptor is used to index into a table that keeps track of any OS-level state associated with the file, such as the file position

Networks and Sockets

- UNIX likes to make *all* I/O look like file I/O
 - You use read() and write() to communicate with remote computers over the network!
 - A file descriptor used for network communications is called a socket
 - Just like with files:
 - Your program can have multiple network channels open at once
 - You need to pass a file descriptor to read() and write() to let the OS know which network channel to use

File Descriptor Table



OS's File Descriptor Table for the Process

File Descriptor	Туре	Connection
0	pipe	stdin (console)
1	pipe	stdout (console)
2	pipe	stderr (console)
3	TCP socket	local: 128.95.4.33:80 remote: 44.1.19.32:7113
5	file	index.html
8	file	pic.png
9	TCP socket	local: 128.95.4.33:80 remote: 102.12.3.4:5544

Types of Sockets

- Stream sockets
 - For connection-oriented, point-to-point, reliable byte streams
 - Using TCP, SCTP, or other stream transports
- Datagram sockets
 - For connection-less, one-to-many, unreliable packets
 - Using UDP or other packet transports
- Raw sockets
 - For layer-3 communication (raw IP packet manipulation)

Stream Sockets

- Typically used for client-server communications
 - Client: An application that establishes a connection to a server
 - Server: An application that receives connections from clients
 - Can also be used for other forms of communication like peer-to-peer



Datagram Sockets

- Often used as a building block
 - No flow control, ordering, or reliability, so used less frequently
 - e.g. streaming media applications or DNS lookups



The Sockets API

- Berkeley sockets originated in 4.2BSD Unix (1983)
 - It is the standard API for network programming
 - Available on most OSs
 - Written in C
- POSIX Socket API
 - A slight update of the Berkeley sockets API
 - A few functions were deprecated or replaced
 - Better support for multi-threading was added

Lecture Outline

Sockets API

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Step 1: Figure Out IP Address and Port

- Several parts:
 - Network addresses
 - Data structures for address info
 - DNS Doman Name System finding IP addresses

IPv4 Network Addresses

- An IPv4 address is a 4-byte tuple
 - For humans, written in "dotted-decimal notation"
 - e.g. 128.95.4.1 (80:5f:04:01 in hex)

- IPv4 address exhaustion
 - There are 2³² ≈ 4.3 billion IPv4 addresses
 - There are ≈ 8 billion people in the world (July 2024)
 - Last unassigned IPv4 addresses allocated during 2011 to 2019 in various parts of the world

IPv6 Network Addresses

- An IPv6 address is a 16-byte tuple
 - *e.g.* 2d01:0db8:f188:0000:0000:0000:0000:1f33
 - Typically written in "hextets" (groups of 4 hex digits)
 - Can omit leading zeros in hextets
 - Double-colon replaces consecutive sections of zeros
 - e.g. 2d01:db8:f188::1f33
 - Transition is still ongoing
 - IPv4-mapped IPv6 addresses
 - 128.95.4.1 mapped to ::ffff:128.95.4.1 or ::ffff:805f:401

IPv4 Address Structures

```
// IPv4 4-byte address
struct in_addr {
    uint32_t s_addr; // Address in network byte order
}; // (big endian)
// An IPv4-specific address structure
struct sockaddr_in {
    sa_family_t sin_family; // Address family: AF_INET
    in_port_t sin_port; // Port in network byte order
    struct in_addr sin_addr; // IPv4 address
    unsigned char sin_zero[8]; // Pad out to 16 bytes
};
```

struct sockaddr in:

	family	port	addr	zero
C) 2	2 4	٤ ٤	8 1
				6

Working with Socket Addresses

- How to handle both IPv4 and IPv6?
 - Use C structs for each, but make them somewhat similar
 - Use defined constants to differentiate when to use each: AF_INET for IPv4 and AF_INET6 for IPv6

```
// IPv4 4-byte address
struct in_addr {
    uint32_t s_addr;
};
// An IPv4 address structure
struct sockaddr_in {
    sa_family_t sin_family;
    in_port_t sin_port;
    struct in_addr sin_addr;
    unsigned char sin_zero[8];
};
```

```
// IPv6 16-byte address
struct in6_addr {
    uint8_t s6_addr[16]
};
// An IPv6 address structure
struct sockaddr_in6 {
    sa_family_t sin6_family;
    in_port_t sin6_fort;
    uint32_t sin6_flowinfo;
    struct in6_addr sin6_addr;
    uint32_t sin6_scope_id;
};
```

IPv6 Address Structures

```
// IPv6 16-byte address
struct in6_addr {
    uint8_t s6_addr[16]; // Address in network byte order
};
// An IPv6-specific address structure
struct sockaddr_in6 {
    sa_family_t sin6_family; // Address family: AF_INET6
    in_port_t sin6_port; // Port number
    uint32_t sin6_flowinfo; // IPv6 flow information
    struct in6_addr sin6_addr; // IPv6 address
    uint32_t sin6_scope_id; // Scope ID
};
```

struct sockaddr_in6:



Address Structs: Generic?

 Let's compare the memory layout of the IPv4 and IPv6 socket structs



Generic Address Structures

```
// A mostly-protocol-independent address structure.
// Pointer to this is parameter type for socket system calls.
struct sockaddr {
 sa family t sa family; // Address family (AF * constants)
 char sa data[14]; // Socket address (size varies
                           // according to socket domain)
};
// A structure big enough to hold either IPv4 or IPv6 structs
struct sockaddr storage {
 sa_family_t ss_family; // Address family
 // padding and alignment; don't worry about the details
 char ss pad1[ SS PAD1SIZE];
 int64 t ss align;
 char ss pad2[ SS PAD2SIZE];
};
```

Commonly create struct sockaddr_storage, then pass pointer cast as struct sockaddr* to connect()

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Working with Socket Addresses

- Structures, constants, and helper functions available in #include <arpa/inet.h>
- Addresses stored in network byte order (big endian)
- Converting between host and network byte orders:
 - uint32_t htonl(uint32_t hostlong);
 - uint32_t ntohl(uint32_t netlong);
 - 'h' for host byte order and 'n' for network byte order
 - Also versions with 's' for short (uint16_t instead)

Address Conversion

- * int inet_pton(int af, const char* src, void* dst);
 - Converts human-readable string representation ("presentation") to network byte ordered address
 - Returns 1 (success), 0 (bad src), or -1 (error)

genaddr.cc

```
#include <stdlib.h>
#include <arpa/inet.h>
int main(int argc, char **argv) {
   struct sockaddr_in sa; // IPv4
   struct sockaddr_in6 sa6; // IPv6
   // IPv4 string to sockaddr_in (192.0.2.1 = C0:00:02:01).
   inet_pton(AF_INET, "192.0.2.1", &(sa.sin_addr));
   // IPv6 string to sockaddr_in6.
   inet_pton(AF_INET6, "2001:db8:63b3:1::3490", &(sa6.sin6_addr));
   return EXIT_SUCCESS;
}
```

Address Conversion

- - Converts network addr in src into buffer dst of size size

genstring.cc

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DNS

Client-side Programming

Domain Name System

- People tend to use domain names, not IP addresses
 - The Sockets API lets you convert between the two
 - It's a complicated process, though:
 - A given domain name can have many IP addresses
 - Many different IP addresses can map to the same domain name
 - An IP address will reverse map into at most one domain name
 - A DNS lookup may require interacting with many DNS servers
- You can use the Linux program "dig" to explore DNS
 - dig @server name type (+short)
 - server: specific name server to query (optional)
 - type: A (IPv4), AAAA (IPv6), ANY (includes all types)

A few other sections **Dig example** not important to this class > dig <u>www.google.com</u> A . . . ;; ANSWER SECTION: www.google.com. 146 IN A 142.250.217.68 ;; Query time: 19 msec ;; SERVER: 8.8.8.8#53(8.8.8.8) (UDP) . . . > dig <u>www.google.com</u> AAAA ;; ANSWER SECTION: www.google.com. 34 IN AAAA 2607:f8b0:400a:804::2004 ;; Query time: 23 msec ;; SERVER: 8.8.8.8#53(8.8.8.8) (UDP) . . .

DNS Hierarchy

The dots in a web address actually have a meaning!

- Each web address component is a different "level" of DNS
- Read from right to left

www.google.com



DNS Hierarchy



Resolving DNS Names

- The POSIX way is to use getaddrinfo()
 - A complicated system call found in #include <netdb.h>
 - - Tell getaddrinfo() which host and port you want resolved
 - String representation for host: DNS name or IP address
 - Set up a "hints" structure with constraints you want respected
 - getaddrinfo() gives you a list of results packed into an "addrinfo" structure/linked list
 - Returns 0 on success; returns negative number on failure
 - Free the struct addrinfo list later using freeaddrinfo()

getaddrinfo

See dnsresolve.cc

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getaddrinfo

getaddrinfo() arguments:

- hostname domain name or IP address string
- service port # (e.g. "80") or service name (e.g. "www")
 or NULL/nullptr

	struct addrinfo {				
_	<pre>int ai_flags;</pre>	// additional flags			
	<pre>int ai_family;</pre>	// AF_INET, AF_INET6, AF_UNSPEC			
	<pre>int ai_socktype;</pre>	// SOCK_STREAM, SOCK_DGRAM, 0			
	<pre>int ai_protocol;</pre>	// IPPROTO_TCP, IPPROTO_UDP, 0			
	<pre>size_t ai_addrlen;</pre>	<pre>// length of socket addr in bytes</pre>			
	<pre>struct sockaddr* ai_addr;</pre>	// pointer to socket addr			
	<pre>char* ai_canonname;</pre>	// canonical name			
	<pre>struct addrinfo* ai_next;</pre>	// can form a linked list			
	};				

• See dnsresolve.cc

Socket API: Client TCP Connection

- There are five steps:
 - 1) Figure out the IP address and port to connect to
 - 2) Create a socket
 - 3) **connect**() the socket to the remote server
 - 4) **read**() and **write**() data using the socket
 - 5) Close the socket

Step 2: Creating a Socket

- int socket(int domain, int type, int protocol);
 - Creating a socket doesn't bind it to a local address or port yet
 - Returns file descriptor or -1 on error

socket.cc

```
#include <arpa/inet.h>
#include <stdlib.h>
#include <string.h>
#include <unistd.h>
#include <iostream>
int main(int argc, char** argv) {
 int socket fd = socket(AF INET, SOCK STREAM, 0);
 if (socket fd == -1) {
     std::cerr << strerror(errno) << std::endl;</pre>
     return EXIT FAILURE;
 close(socket fd);
  return EXIT SUCCESS;
```

Step 3: Connect to the Server

- The connect() system call establishes a connection to a remote host
 - - sockfd: Socket file description from Step 2
 - addr and addrlen: Usually from one of the address structures returned by getaddrinfo in Step 1 (DNS lookup)
 - Returns 0 on success and -1 on error

connect() may take some time to return

- It is a *blocking* call by default
- The network stack within the OS will communicate with the remote host to establish a TCP connection to it
 - This involves ~2 round trips across the network

How long are two "round trips"?

- Remember this table?
 - Exact numbers change somewhat over time, but you should know the order-of-magnitudes here

Numbers Everyone Should Know							
L1 cache reference	0.5 ns						
Branch mispredict	5 ns						
L2 cache reference	7 ns						
Mutex lock/unlock	25 ns						
Main memory reference	100 ns						
Compress 1K bytes with Zippy	3,000 ns						
Send 2K bytes over 1 Gbps network	20,000 ns						
Read 1 MB sequentially from memory	250,000 ns						
Round trip within same datacenter	500,000 ns						
Disk seek	10,000,000 ns						
Read 1 MB sequentially from disk	20,000,000 ns						
Send packet CA->Netherlands->CA	150,000,000 ns						

Connect Example

See connect.cc

```
// Get an appropriate sockaddr structure.
struct sockaddr storage addr;
size t addrlen;
LookupName(argv[1], port, &addr, &addrlen);
// Create the socket.
int socket fd = socket(addr.ss family, SOCK STREAM, 0);
if (socket fd == -1) {
  cerr << "socket() failed: " << strerror(errno) << endl;</pre>
 return EXIT FAILURE;
}
// Connect the socket to the remote host.
int res = connect(socket fd,
                  reinterpret cast<sockaddr*>(&addr),
                   addrlen);
if (res == -1) {
  cerr << "connect() failed: " << strerror(errno) << endl;</pre>
```

Step 4: read()

- If there is data that has already been received by the network stack, then read will return immediately with it
 - read() might return with less data than you asked for
- If there is no data waiting for you, by default read()
 will *block* until something arrives
 - This might cause *deadlock*!
 - Can read() return 0?

Step 4: read()

- Assume we have:

 - char readbuf[BUF]; // read buffer
 - int res; // to store read result
- Write C++ code to read in BUF characters from socket_fd
 - If error occurs, send error message to user and exit()

Step 4: write()

- write() enqueues your data in a send buffer in the OS and then returns
 - The OS transmits the data over the network in the background
 - When write() returns, the receiver probably has not yet received the data!
- If there is no more space left in the send buffer, by default
 write() will *block*

Read/Write Example

```
while (1) {
  int wres = write(socket fd, readbuf, res);
  if (wres == 0) {
    cerr << "socket closed prematurely" << endl;</pre>
    close(socket fd);
    return EXIT FAILURE;
  }
  if (wres == -1) {
    if (errno == EINTR)
      continue:
    cerr << "socket write failure: " << strerror(errno) << endl;
    close(socket fd);
    return EXIT FAILURE;
 break;
```

See sendreceive.cc

Demo

Step 5: close()

* int close(int fd);

- Nothing special here it's the same function as with file I/O
- Shuts down the socket and frees resources and file descriptors associated with it on both ends of the connection

Extra Exercise #1

- Write a program that:
 - Reads DNS names, one per line, from stdin
 - Translates each name to one or more IP addresses
 - Prints out each IP address to stdout, one per line