

# CSE 333

## Section 6

HW3, C++, and Inheritance

When you mistype a keyword in C++



Ever have a moment like this  
when programming?

# Logistics

- Exercise 11 due **Tomorrow!**
- HW3 due in 3 weeks (Nov 19).
  - Please please please start early :)



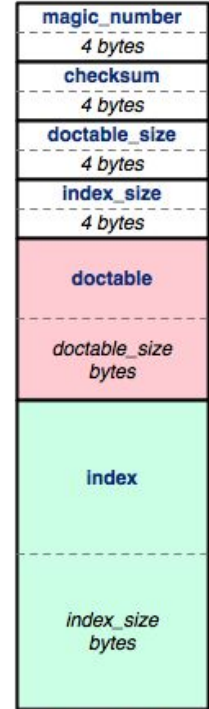
# HW 3 Overview



# Index File

Crawling the whole file tree takes a long time!

To save time we'll write the completed DocTable and MemIndex into a file!



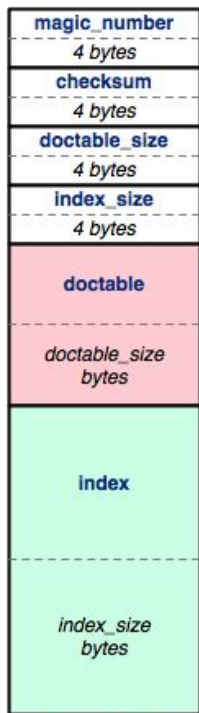
index file

# Byte Ordering and Endianness

- Network (Disk) Byte Order (Big Endian)
  - The most significant byte is stored in the highest address
- Host byte order
  - Might be big or little endian, depending on the hardware
- To convert between orderings, we can use
  - `uint32_t htonl (uint32_t hostlong); // host to network`
  - `uint32_t ntohl (uint32_t netlong); // network to host`
- Pro-tip:

The structs in HW3 have `toDiskFormat()` and `toHostFormat()` functions that will convert endianness for you.

# Index File Components



index file

Header (metadata)

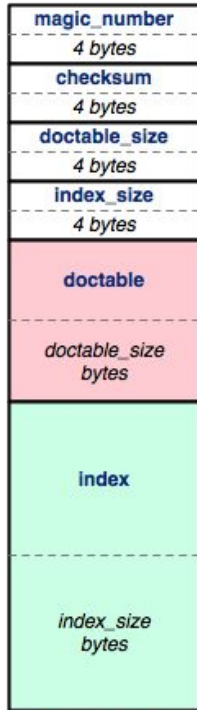
---

DocTable

---

MemIndex

# Index File Header



index file

- magic\_number: 0xCAFEF00D
- checksum: mathematical signature
- doctable\_size: in bytes
- index\_size: in bytes

# Index File Header - HEX

1. Find a hex editor/viewer of your choice
  - `xxd <indexfile>`
  - `hexdump -vC <indexfile>`
  - Pipe the output into a file or into `less` to view

```
0000000: cafe f00d 1c42 4620 0000 205b 0000 075d  ....BF .. [...]
0000010: 0000 0400 0000 0000 0000 2014 0000 0001  .....
0000020: 0000 2014 0000 0001 0000 2031 0000 0001  .. ..... 1...
0000030: 0000 204e 0000 0000 0000 206b 0000 0000  .. N..... k...
0000040: 0000 206b 0000 0000 0000 206b 0000 0000  .. k..... k...
0000050: 0000 206b 0000 0000 0000 206b 0000 0000  .. k..... k...
```

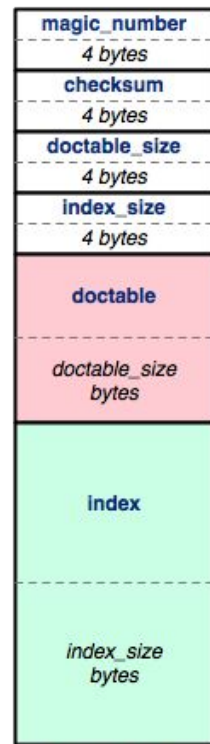
The header:

Magic word

Checksum

Doctable size

Index size



index file



# Hex View

- emacs – “M-x hexl-mode”

```
File Edit Options Buffers Tools Hexl Help
87654321 0011 2233 4455 6677 8899 aabb ccdd eeff 0123456789abcdef
00000000: cafe f00d ff48 a0a1 0000 006a 0000 024e .....H.....j...N
00000010: 0000 0001 0000 0002 0000 001c 0000 0024 .....$
00000020: 0000 0054 0000 0000 0000 0002 0026 2e2f ...T.....&./
00000030: 7465 7374 5f74 7265 652f 7469 6e79 2f68 test_tree/tiny/h
00000040: 6f6d 652d 6f6e 2d74 6865 2d72 616e 6765 ome-on-the-range
00000050: 2e74 7874 0000 0000 0000 0001 001c 2e2f .txt...../
```

- vim – “:%!xxd”

```
00000000: cafe f00d ff48 a0a1 0000 006a 0000 024e .....H.....j...N
00000010: 0000 0001 0000 0002 0000 001c 0000 0024 .....$
00000020: 0000 0054 0000 0000 0000 0002 0026 2e2f ...T.....&./
00000030: 7465 7374 5f74 7265 652f 7469 6e79 2f68 test_tree/tiny/h
00000040: 6f6d 652d 6f6e 2d74 6865 2d72 616e 6765 ome-on-the-range
00000050: 2e74 7874 0000 0000 0000 0001 001c 2e2f .txt...../
```

# Hex View

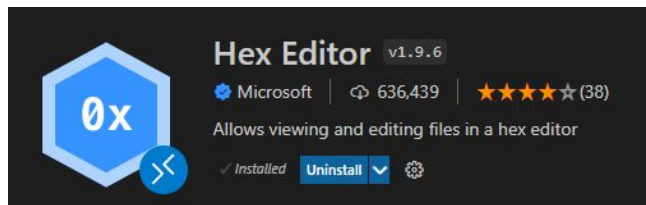
- emacs – “M-x hexl-mode”

```
File Edit Options Buffers Tools Hexl Help
87654321 0011 2233 4455 6677 8899 aabb ccdd eeff 0123456789abcdef
00000000: cafe f00d ff48 a0a1 0000 006a 0000 024e .....H.....j...N
00000010: 0000 0001 0000 0002 0000 001c 0000 0024 .....$
00000020: 0000 0054 0000 0000 0000 0002 0026 2e2f ...T.....&./
00000030: 7465 7374 5f74 7265 652f 7469 6e79 2f68 test_tree/tiny/h
00000040: 6f6d 652d 6f6e 2d74 6865 2d72 616e 6765 ome-on-the-range
00000050: 2e74 7874 0000 0000 0000 0001 001c 2e2f .txt...../
```

- vim – “:%!xxd”

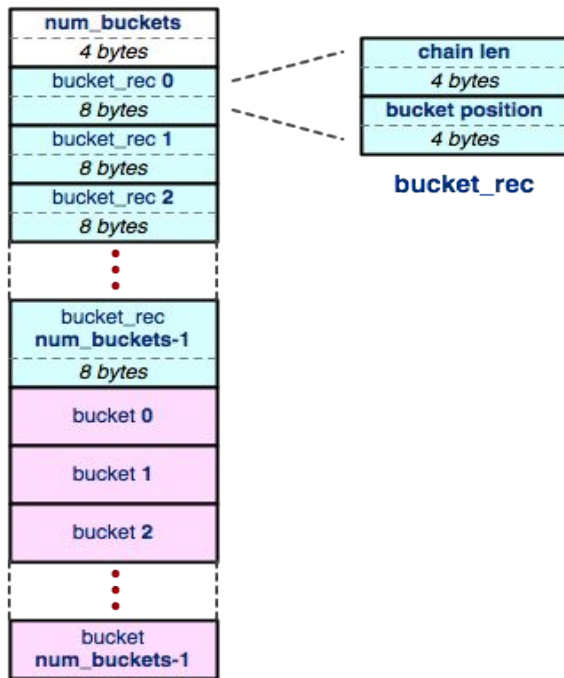
```
00000000: cafe f00d ff48 a0a1 0000 006a 0000 024e .....H.....j...N
00000010: 0000 0001 0000 0002 0000 001c 0000 0024 .....$
00000020: 0000 0054 0000 0000 0000 0002 0026 2e2f ...T.....&./
00000030: 7465 7374 5f74 7265 652f 7469 6e79 2f68 test_tree/tiny/h
00000040: 6f6d 652d 6f6e 2d74 6865 2d72 616e 6765 ome-on-the-range
00000050: 2e74 7874 0000 0000 0000 0001 001c 2e2f .txt...../
```

For those working in VSCode...



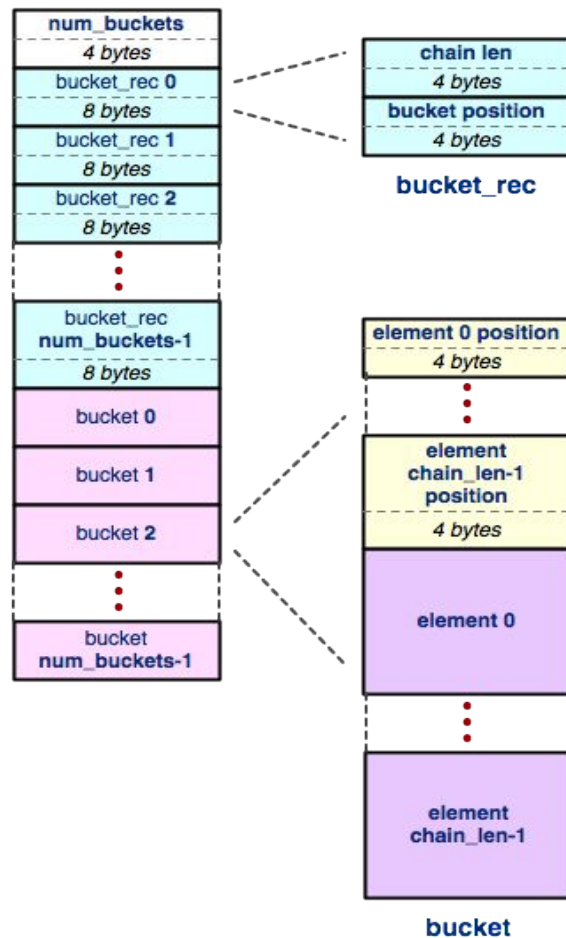
# HashTable

- HashTable can have varying amount of buckets, so start with `num_buckets`.
- Buckets can be of varying lengths. To know the offset, we store some bucket records.

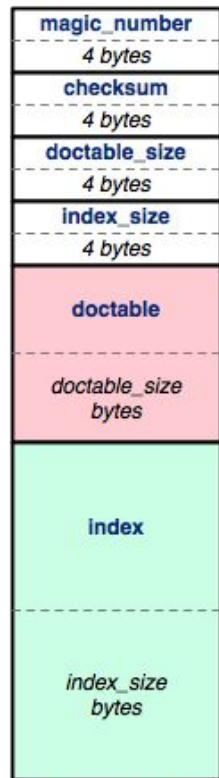


# Buckets

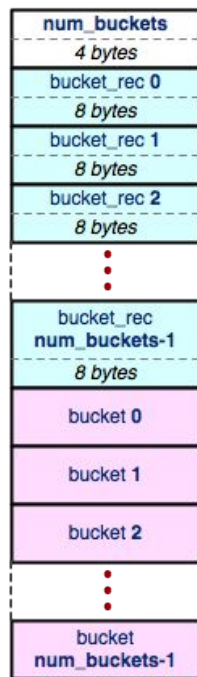
- A bucket is a list that contains elements in the table. Offset to a bucket is found in a bucket record.
- Elements can be of various sizes, so we need to store element positions to know where each element is.



# DocTable



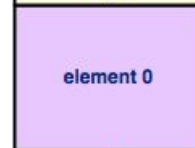
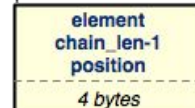
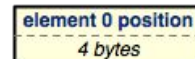
index file



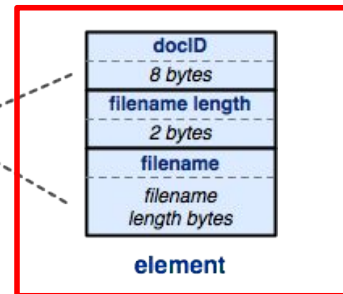
doctable



bucket\_rec

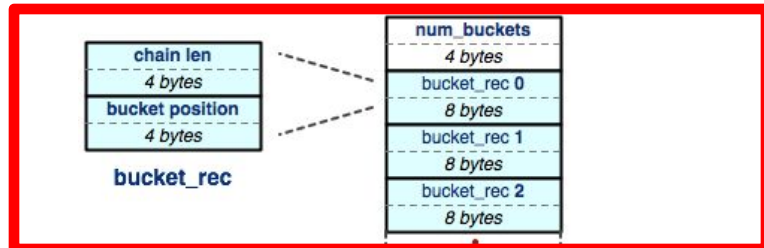


bucket



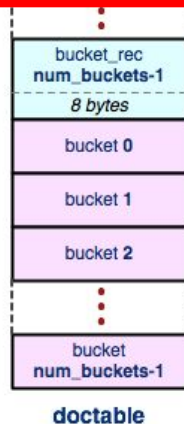
element

# DocTable (Hex)



```

0000000: cafe f00d 1c42 4620 0000 205b 0000 075d .....BF .. [...]
0000010: 0000 0400 0000 0000 0000 2014 0000 0001 .....
0000020: 0000 2014 0000 0001 0000 2031 0000 0001 .. ..... 1...
0000030: 0000 204e 0000 0000 0000 206b 0000 0000 .. N..... k...
0000040: 0000 206b 0000 0000 0000 206b 0000 0000 .. k..... k...
0000050: 0000 206b 0000 0000 0000 206b 0000 0000 .. k..... k...
0002000: 0000 206b 0000 0000 0000 206b 0000 0000 .. k..... k...
0002010: 0000 206b 0000 2018 0000 0000 0000 0001 .. k.. .....
0002020: 000f 736d 616c 6c5f 6469 722f 632e 7478 ..small_dir/c.tx
0002030: 7400 0020 3500 0000 0000 0000 0200 0f73 t.. 5.....s
0002040: 6d61 6c6c 5f64 6972 2f62 2e74 7874 0000 mall_dir/b.txt..
0002050: 2052 0000 0000 0000 0003 000f 736d 616c R.....smal
0002060: 6c5f 6469 722f 612e 7478 7400 0000 8000 l_dir/a.txt....
0002070: 0000 0000 0024 6f00 0000 0000 0024 6f00 .....$o.....$o.
    
```



The header

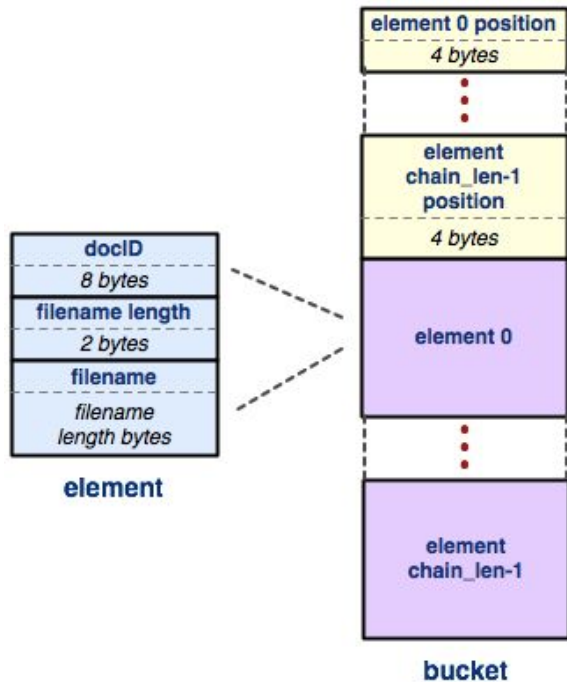
Num buckets ( Chain len Bucket offset )\*



# DocTable

```

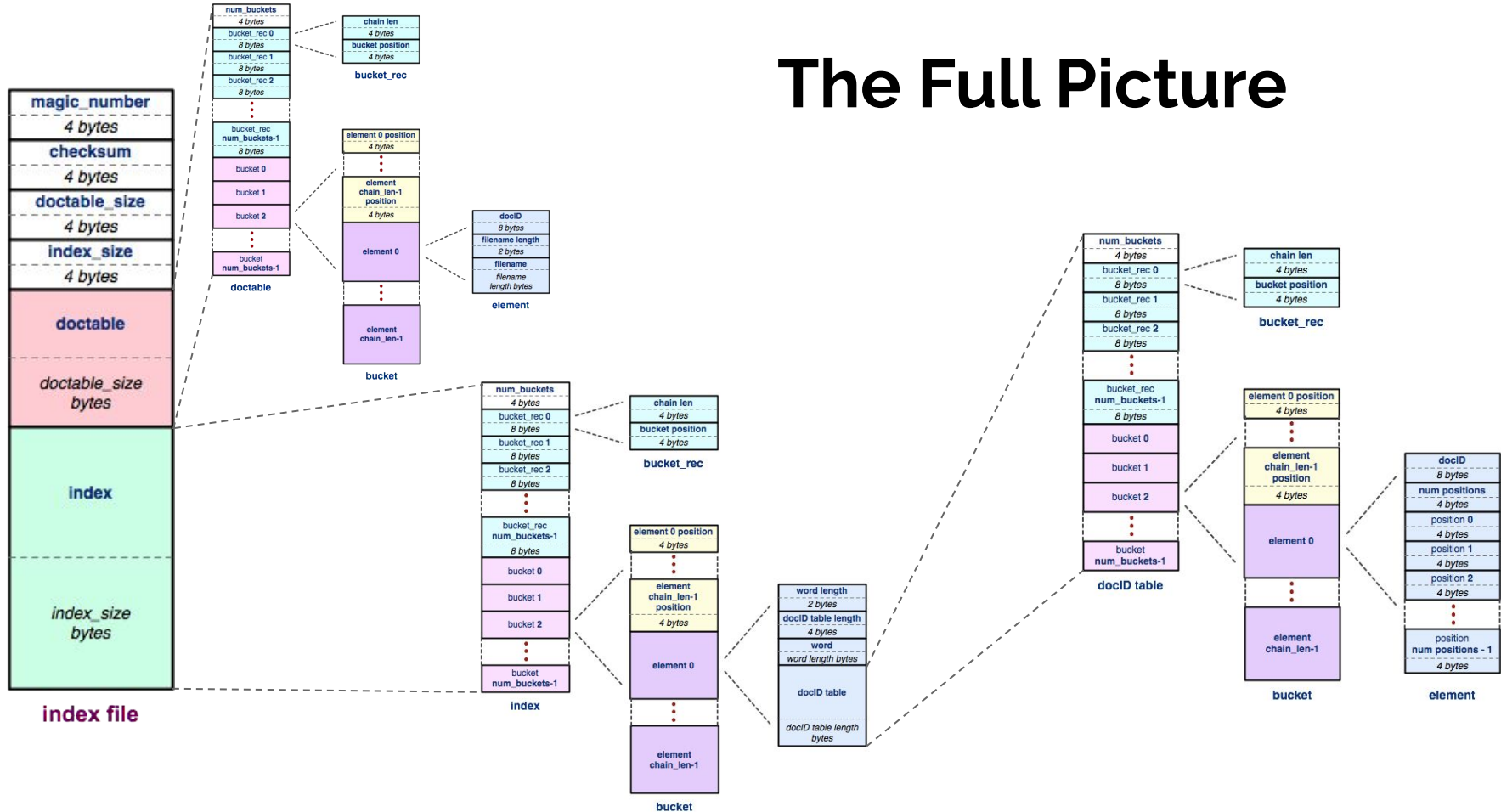
0002000: 0000 206b 0000 0000 0000 206b 0000 0000  .. k..... k....
0002010: 0000 206b 0000 2018 0000 0000 0000 0001  .. k.. .....
0002020: 000f 736d 616c 6c5f 6469 722f 632e 7478  ..small_dir/c.tx
0002030: 7400 0020 3500 0000 0000 0000 0200 0f73  t.. 5.....s
0002040: 6d61 6c6c 5f64 6972 2f62 2e74 7874 0000  mall_dir/b.txt..
  
```



The buckets: where n is equal to the number of elements

$$\left( \left( \text{Element offset} \right)^n \left( \text{DocID} \quad \text{Filename len} \quad \text{Filename} \right)^n \right)^*$$

# The Full Picture



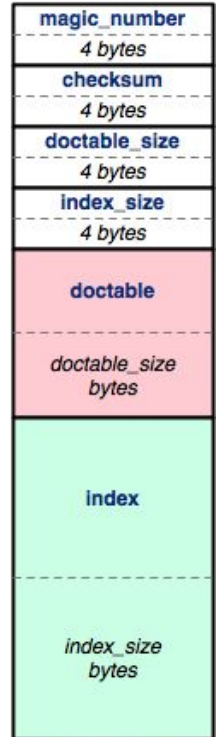


# HW Tips

- When Writing, you should (almost) always:
  1. `.toDiskFormat()`
  2. `fseek()`
  3. `fwrite()`
- When Reading, you should (almost) always:
  1. `fseek()`
  2. `fread()`
  3. `.toHostFormat()`
- The most common bugs in the HW involve forgetting to change byte ordering, or forgetting to `fseek()`.

# HW Tips: Index Checker (hw3fsck)

- Hw3fsck checks fields inside the file for reasonableness. Prints out a helpful message if it spots some kind of problem.
- More rigorous check on your index file you've produced
  - Run `./hw3fsck index_filename`
- Run after finishing WriteIndex.cc
- Can be found in hw3/hw3fsck directory (and compiled version in solution\_binaries also)



index file

# Casting



# Different Flavors of Casting

- `static_cast<type_to>(expression);`  
Casting between related types
- `dynamic_cast<type_to>(expression);`  
Casting pointers of similar types (only used with inheritance)
- `const_cast<type_to>(expression);`  
Adding or removing **const**-ness of a type
- `reinterpret_cast<type_to>(expression);`  
Casting between incompatible types of the **same size** (doesn't do float conversion)

# Tips with Casting

- Style: Use C++ style casting in C++
  - Tradeoff: A little extra programming overhead and typing, but provides **clarity** to your programs
  - Be **explicit as possible** with your casting! This means if you notice multiple operations in an implicit cast, you should explicitly write out each cast!
- Read documentation of casting on which casting to use
  - Documentation: <https://www.cplusplus.com/articles/iG3hAqkS/>
  - The purpose of C++ casting is to be less ambiguous with what the casts you're using are actually doing

# Inheritance



# Inheritance

- Motivation: Better modularize our code for similar classes!
- The public interface of a derived class inherits all **non-private** member variables and functions (**except** for ctor, cctor, dtor, op=) from its base class
  - *Similar to:* A subclass inherits from a superclass
- Aside: We will be only using **public, single** inheritance in CSE 333

# Polymorphism: Dynamic Dispatch

- **Polymorphism** allows for you to access objects of related types (base and derived classes) – Allows interface usage instead of class implementation
- **Dynamic dispatch**: Implementation is determined *at runtime* via lookup
  - Allows you to call the **most-derived** version of the actual type of an object
  - Generally want to use this when you have a derived class
- `virtual` replaces the class's default **static dispatch** with **dynamic dispatch**
  - Static dispatch determines implementation at compile time
  - Meaning it does **not** use dynamic dispatch (just calls its function)

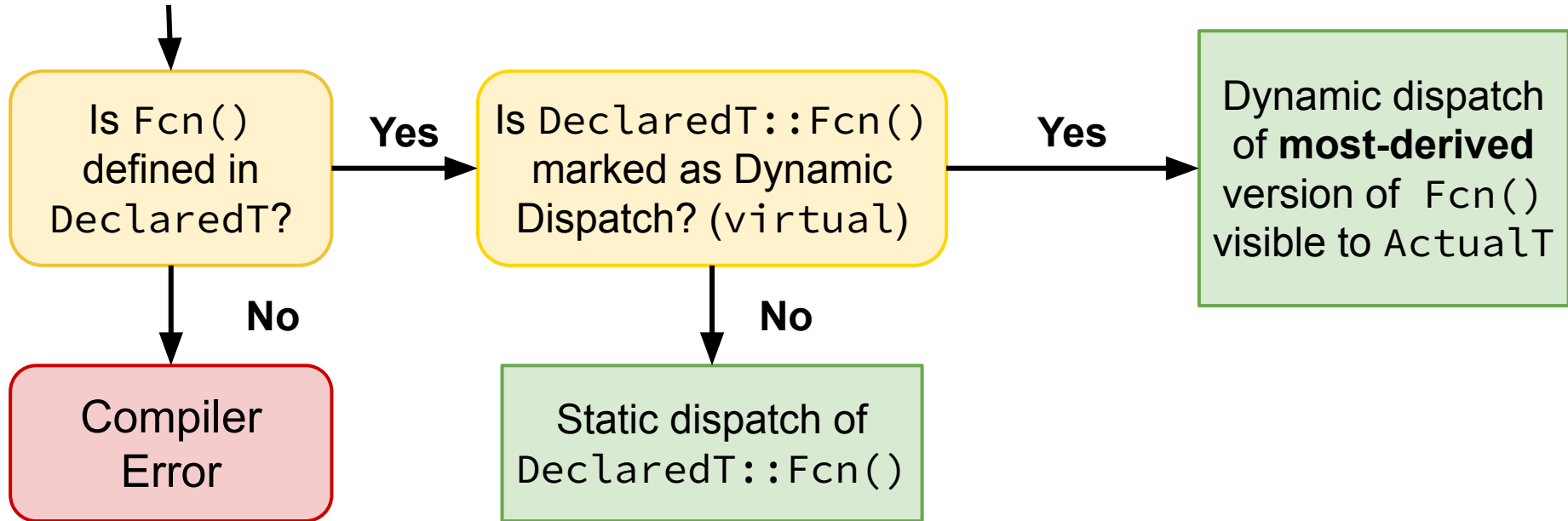


# Dynamic Dispatch: Style Considerations

- Defining Dynamic Dispatch in your code base
  - Use `virtual` **only once** when first defined in the base class
    - (although in older code bases you may see it repeated on functions in subclasses)
  - All derived classes of a base class should use `override` to get the compiler to check that a function overrides a virtual function from a base class
- Use `virtual` for destructors of a base class – Guarantees all derived classes will use dynamic dispatch to ensure use of appropriate destructors

# Dispatch Decision Tree

```
DeclaredT* ptr = new ActualT();  
ptr->Fcn(); // which version is called?
```



# Exercise 1



# Exercise 1: static, dynamic, or error?

```
class Base {  
    void Foo();           //Static Dispatch  
    void Bar();          //Static Dispatch  
    virtual void Baz();  //Dynamic Dispatch  
};
```

```
class Derived : public Base {  
    virtual void Foo();  //Dynamic Dispatch (for more derived)  
    void Bar() override; // Compiler Error!!  
    void Baz();         //Dynamic Dispatch  
};
```

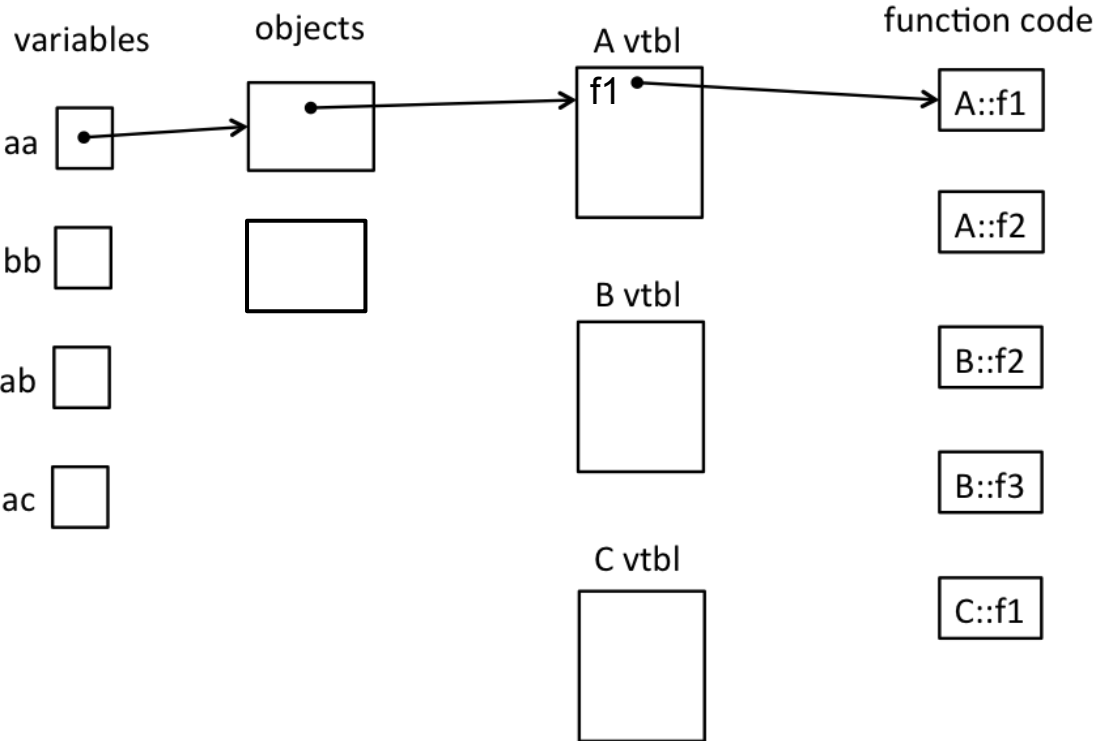
# Exercise 1: static, dynamic, or error?

```
class Base {  
    void Foo();           // static dispatch  
    void Bar();          // static dispatch  
    virtual void Baz();  // dynamic dispatch  
};
```

```
class Derived : public Base {  
    virtual void Foo();  // now dynamic (for more derived)  
    void Bar();          // static dispatch  
    void Baz() override; // still dynamic (sticky!)  
};
```

# Exercise 2

# Exercise 2 (Drawing vtable diagram)



# Exercise 2 Solution (pointers)

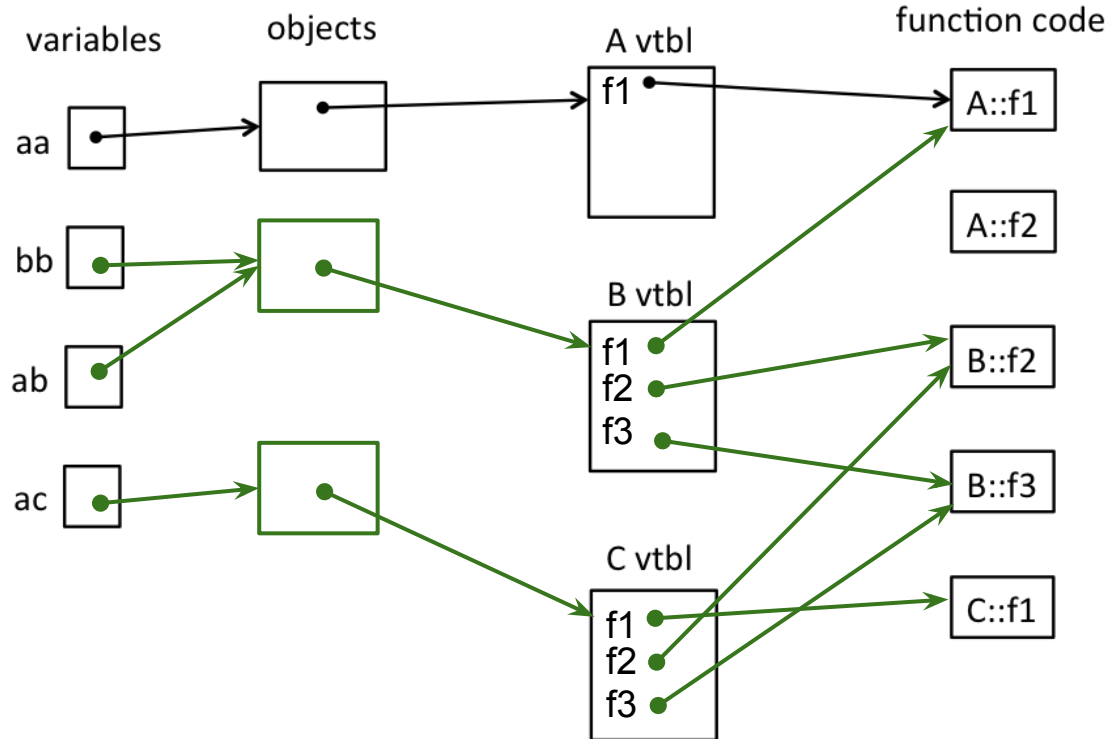
```
#include <iostream>
using namespace std;
```

```
class A {
public:
    virtual void f1() { f2(); cout << "A::f1" << endl; }
    void f2() { cout << "A::f2" << endl; }
};
```

```
class B: public A {
public:
    virtual void f3() { f1(); cout << "B::f3" << endl; }
    virtual void f2() { cout << "B::f2" << endl; }
};
```

```
class C: public B {
public:
    void f1() { f2(); cout << "C::f1" << endl; }
};
```

```
int main() {
    A* aa = new A();
    B* bb = new B();
    A* ab = bb;
    A* ac = new C();
}
```





# Exercise 2 Solution (output)

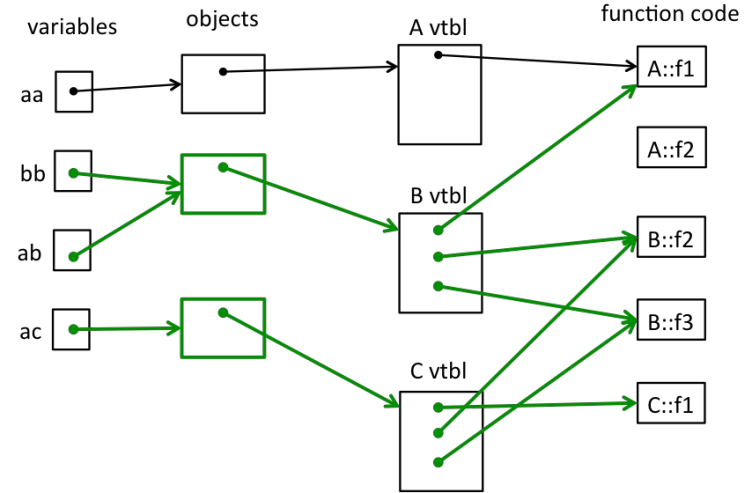
```

#include <iostream>
using namespace std;

class A {
public:
    virtual void f1() { f2(); cout << "A::f1" << endl; }
    void f2() { cout << "A::f2" << endl; }
};

class B: public A {
public:
    virtual void f3() { f1(); cout << "B::f3" << endl; }
    virtual void f2() { cout << "B::f2" << endl; }
};

class C: public B {
public:
    void f1() { f2(); cout << "C::f1" << endl; }
};
    
```



```
A* aa = new A();
```

```
aa->f1();
```

A	B	C	D
B::f2	A::f2	A::f2	B::f2
A::f1	C::f1	A::f1	C::f1

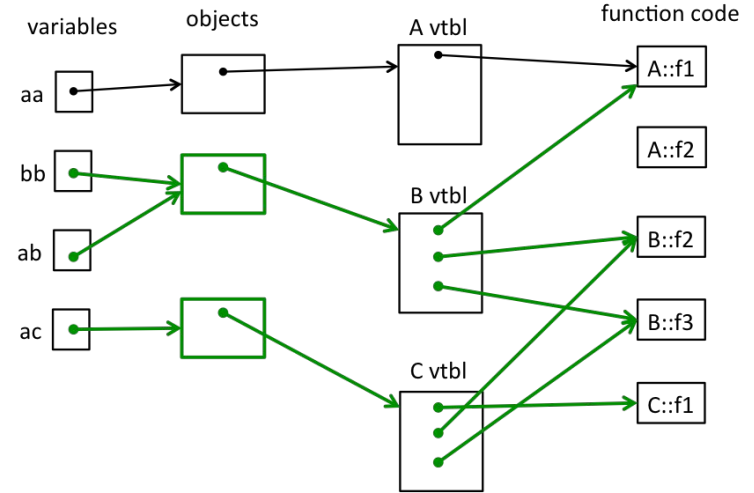
# Exercise 2 Solution (output)

```
#include <iostream>
using namespace std;

class A {
public:
    virtual void f1() { f2(); cout << "A::f1" << endl; }
    void f2() { cout << "A::f2" << endl; }
};

class B: public A {
public:
    virtual void f3() { f1(); cout << "B::f3" << endl; }
    virtual void f2() { cout << "B::f2" << endl; }
};

class C: public B {
public:
    void f1() { f2(); cout << "C::f1" << endl; }
};
```



```
B* bb = new B();
```

```
bb->f1();
```

A	B	C	D
B::f2	A::f2	A::f2	B::f2
A::f1	C::f1	A::f1	C::f1

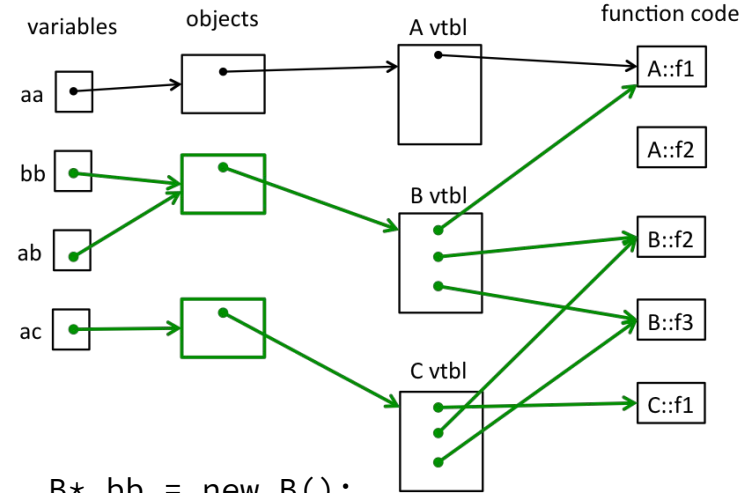
# Exercise 2 Solution (output)

```
#include <iostream>
using namespace std;

class A {
public:
    virtual void f1() { f2(); cout << "A::f1" << endl; }
    void f2() { cout << "A::f2" << endl; }
};

class B: public A {
public:
    virtual void f3() { f1(); cout << "B::f3" << endl; }
    virtual void f2() { cout << "B::f2" << endl; }
};

class C: public B {
public:
    void f1() { f2(); cout << "C::f1" << endl; }
};
```

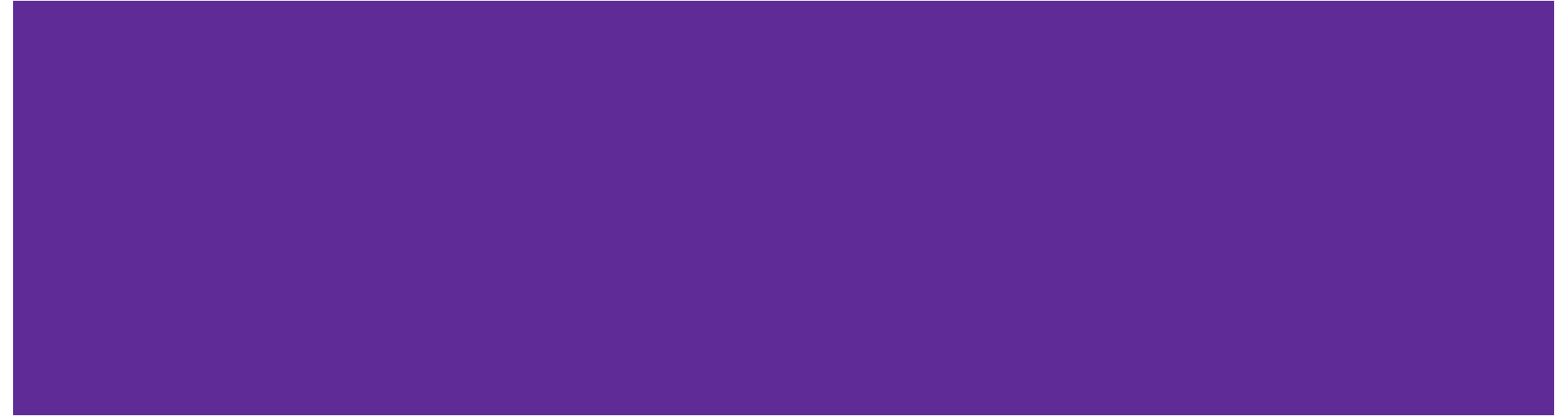


```
B* bb = new B();
A* ab = bb;

bb->f2();
cout << "----" << endl;
ab->f2();
```

A	B	C	D
B::f2	A::f2	B::f2	A::f2
----	----	----	----
B::f2	B::f2	A::f2	A::f2

# Exercise 2 Extension



# Exercise 2 Solution (output)

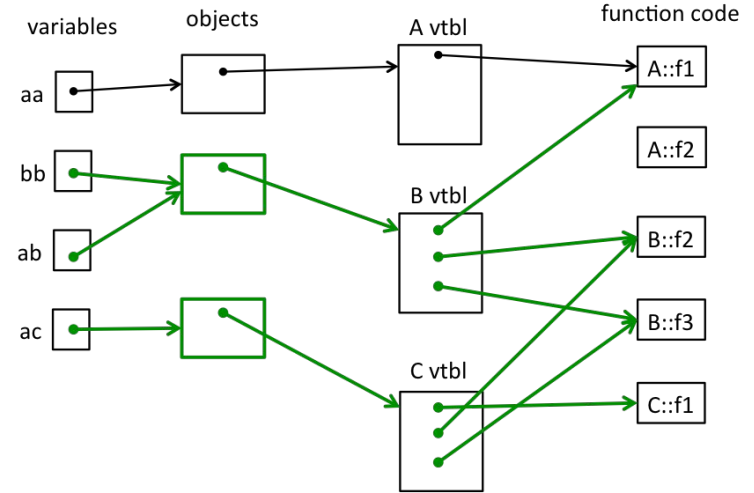
```

#include <iostream>
using namespace std;

class A {
public:
    virtual void f1() { f2(); cout << "A::f1" << endl; }
    void f2() { cout << "A::f2" << endl; }
};

class B: public A {
public:
    virtual void f3() { f1(); cout << "B::f3" << endl; }
    virtual void f2() { cout << "B::f2" << endl; }
};

class C: public B {
public:
    void f1() { f2(); cout << "C::f1" << endl; }
};
    
```



```
B* bb = new B();
```

```
bb->f3();
```

A	B	C	D
B::f2	A::f2	A::f2	B::f2
A::f1	A::f1	C::f1	C::f1
B::f3	B::f3	B::f3	B::f3

# Exercise 2 Solution (output)

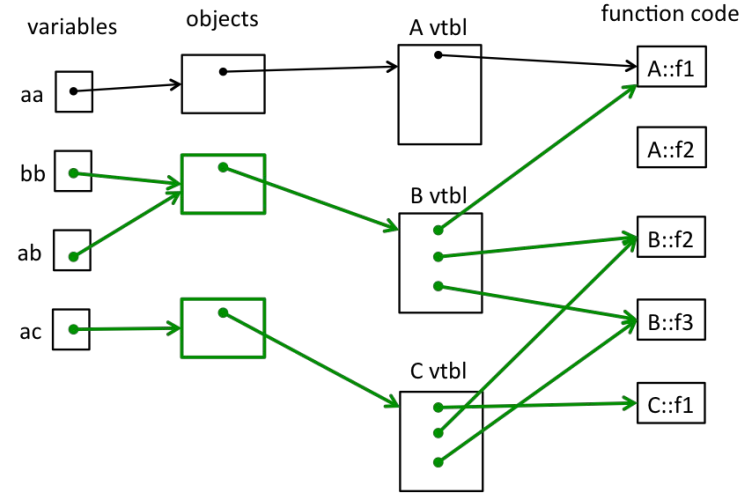
```

#include <iostream>
using namespace std;

class A {
public:
    virtual void f1() { f2(); cout << "A::f1" << endl; }
    void f2() { cout << "A::f2" << endl; }
};

class B: public A {
public:
    virtual void f3() { f1(); cout << "B::f3" << endl; }
    virtual void f2() { cout << "B::f2" << endl; }
};

class C: public B {
public:
    void f1() { f2(); cout << "C::f1" << endl; }
};
    
```



```

A* ac = new C();

ac->f1();
    
```

A	B	C	D
B::f2	A::f2	A::f2	B::f2
A::f1	C::f1	A::f1	C::f1