Concurrency: Intro and Threads CSE 333 Autumn 2019

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About how long did Exercise 16 take?

- A. 0-1 Hours
- B. 1-2 Hours
- **C. 2-3 Hours**
- **D. 3-4 Hours**
- E. 4+ Hours
- F. I prefer not to say

Administrivia

- HW4 due two Thursdays from now (12/05)
 - You can use at most ONE late day
- Short week next week:
 - Wed lecture cancelled (but OH available in AND 223 at 11:30)
 - Fri holiday 🖾

Lecture Outline

- * HTTP/2 Review
- From Query Processing to a Search Server
- Intro to Concurrency
- Threads
- Search Server with pthreads

HTTP/1.1 Feature: Persistent connections

- Establishing a TCP connection is costly
 - Multiple network round trips to set up the TCP connection
 - TCP has a feature called "slow start"; slowly grows the rate at which a TCP connection transmits to avoid overwhelming networks
- A web page consists of multiple objects and a client probably visits several pages on the same server
 - Bad idea: separate TCP connection for each object
 - Better idea: single TCP connection, multiple requests

Conn:

stream

HTTP/2 (2 of 3)

- Based on Google SPDY (2010) ; standardized in 2015
- Features:
 - Same core request/response model (GET, POST, OK, ...)
 - Binary protocol
 - Easier parsing by machines (harder for humans)
 - Sizes in headers, not discovered as requests are processed
 - Headers compressed and deduplicated by default!
 - Multiple data steams multiplexed on single TCP connection
 - Fixes "head-of-line blocking"
 - With priorities on the streams!
 - Server push and more...

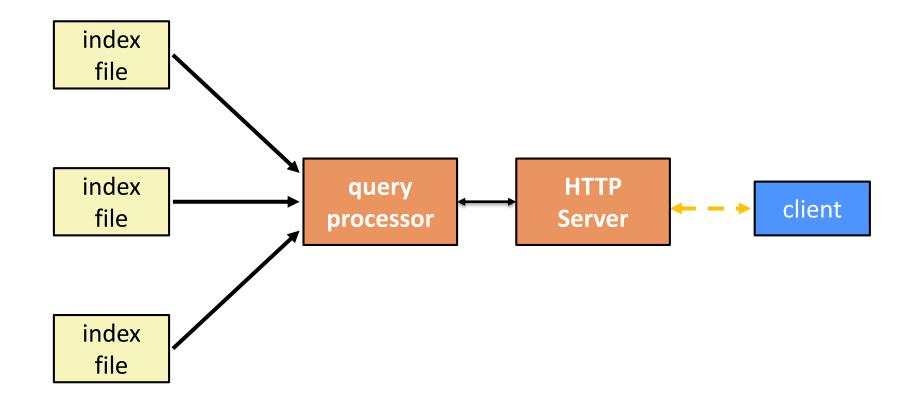
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Building a Web Search Engine

- We have:
 - A web index
 - A map from <word> to <list of documents containing the word>
 - This is probably *sharded* over multiple files
 - A query processor
 - Accepts a query composed of multiple words
 - Looks up each word in the index
 - Merges the result from each word into an overall result set
- ✤ We need:
 - Something that turns HTTP requests into well-formed queries

Search Engine Architecture



Search Engine (Pseudocode)

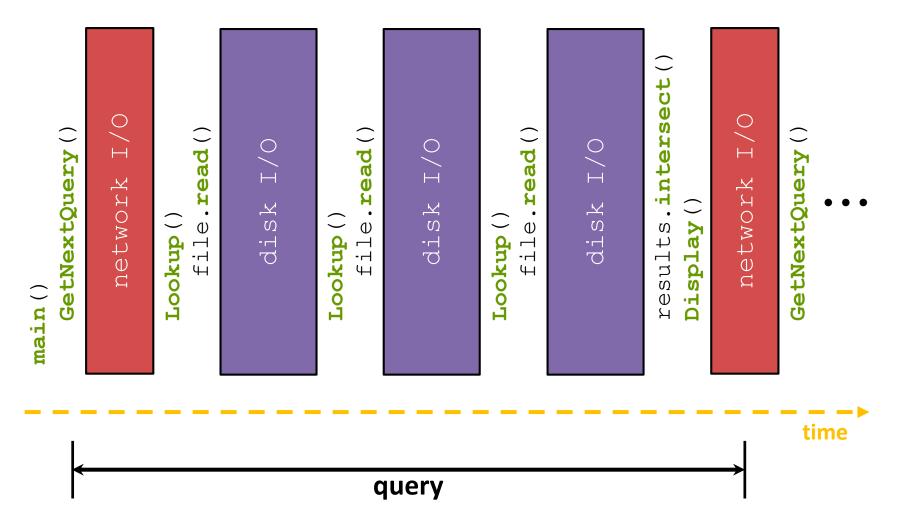
```
doclist Lookup(string word) {
         bucket = hash(word);
         hitlist = file.read(bucket);
          foreach hit in hitlist {
            doclist.append(file.read(hit));
          return doclist;
        }
       main() {
          SetupServerToReceiveConnections();
          while (1) {
            string query words[] = GetNextQuery();
            results = Lookup(query words[0]);
server.
read/writ
1000
            foreach word in query[1..n] {
              results = results.intersect(Lookup(word));
            Display(results);
```

What About I/O-caused Latency?

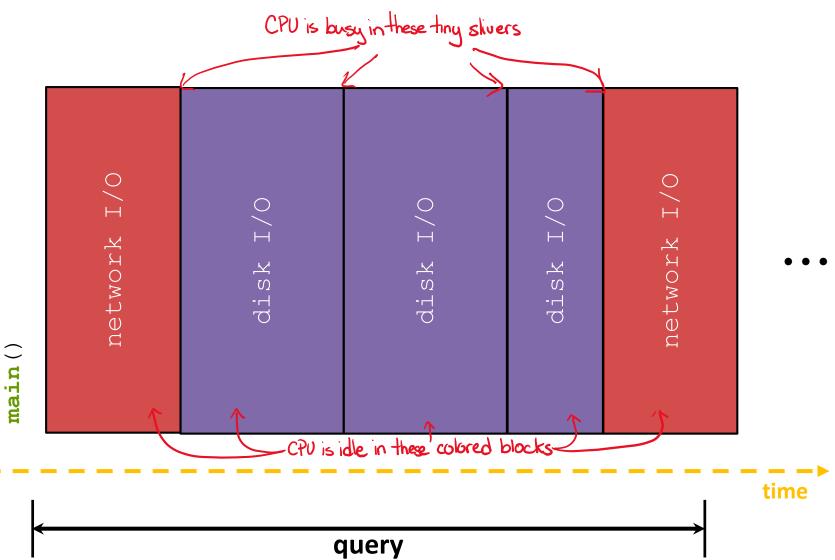
Jeff Dean's "Numbers Everyone Should Know" (LADIS '09)

Numbers Everyone Sho	ould Know
L1 cache reference	0.5 ns
Branch mispredict	5 ns
L2 cache reference	7 ns
Mutex lock/unlock	100 ns
Main memory reference	100 ns
Compress 1K bytes with Zippy	10,000 ns
Send 2K bytes over 1 Gbps network	20,000 ns
Read 1 MB sequentially from memory	250,000 ns
Round trip within same datacenter	500,000 ns
Disk seek	10,000,000 ns
Read 1 MB sequentially from network	10,000,000 ns
Read 1 MB sequentially from disk	30,000,000 ns 🕂
Send packet CA->Netherlands->CA	150,000,000 ns +
	Google -

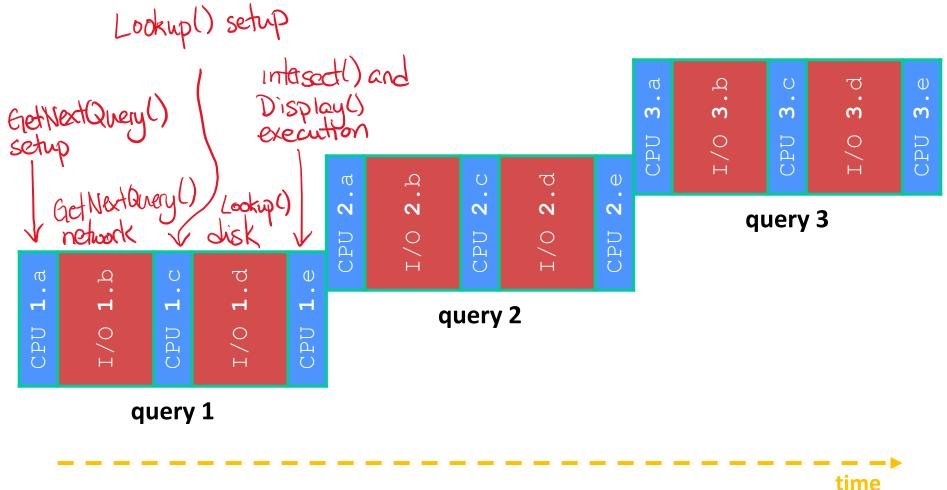
Execution Timeline: One multi-word query



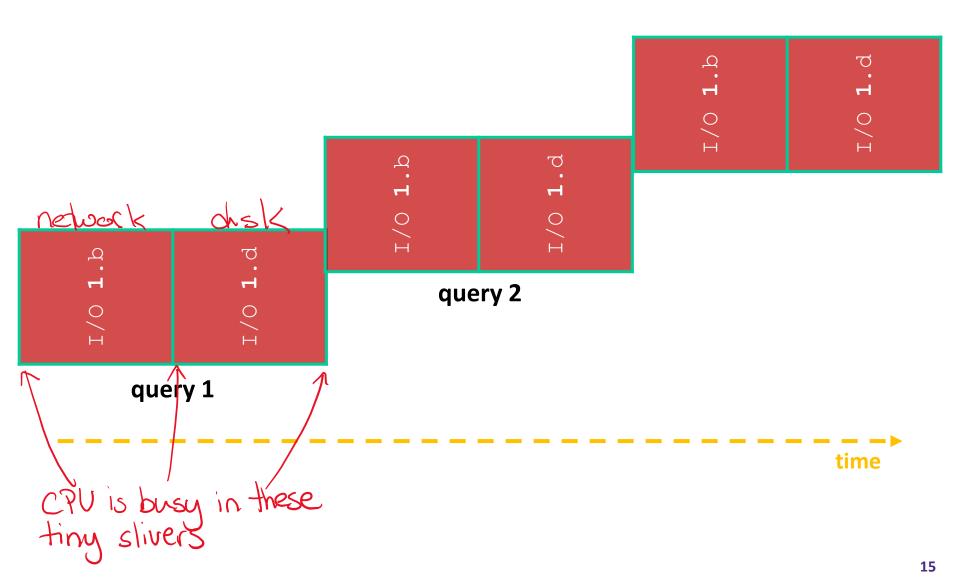
Execution Timeline: To Scale



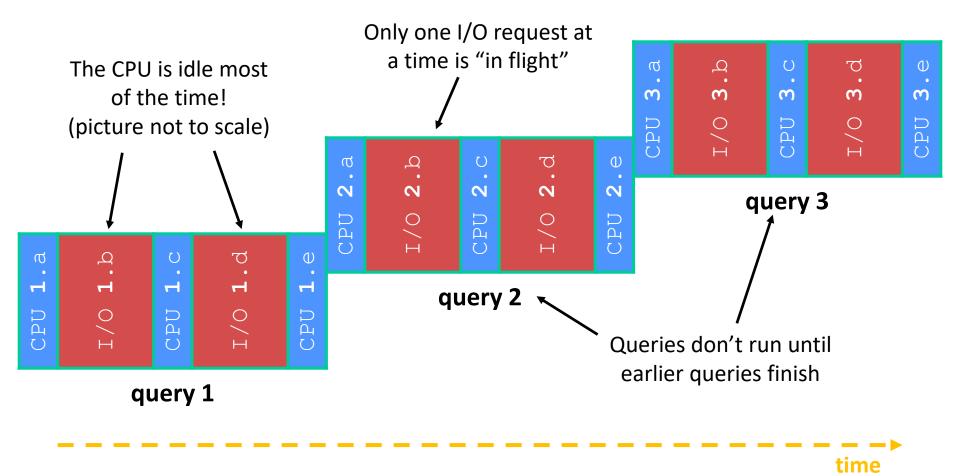
Multiple (Single-Word) Queries



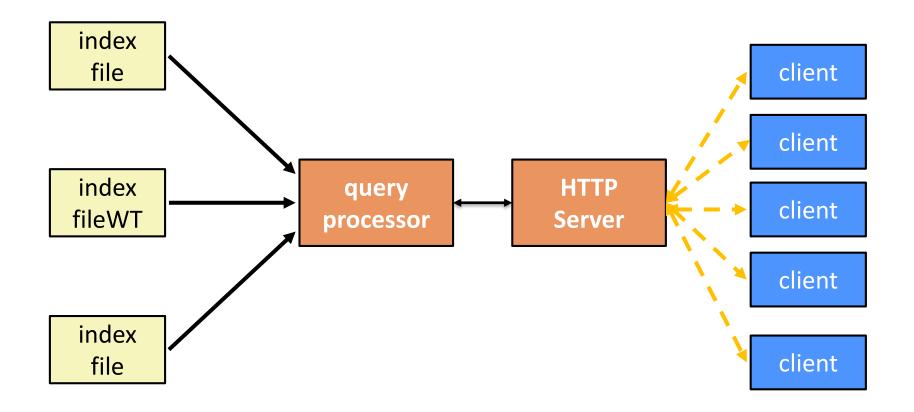
Multiple Queries: To Scale



Uh-Oh (1 of 2)



Uh-Oh (2 of 2)



Sequential Can Be Inefficient

- Only one query is being processed at a time
 - All other queries queue up behind the first one
 - And clients queue up behind the queries ...
- Even while processing one query, the CPU is idle the vast majority of the time
 - It is *blocked* waiting for I/O to complete
 - Disk I/O can be very, very slow (10 million times slower ...)
- At most one I/O operation is in flight at a time
 - Missed opportunities to speed I/O up
 - Separate devices in parallel, better scheduling of a single device, etc.

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Concurrency

- Concurrency != parallelism
 - Concurrency is doing multiple tasks at a time
 - Parallelism is executing multiple CPU instructions simultaneously
- Our search engine could run concurrently:
 - <u>Example</u>: Execute queries one at a time, but issue *I/O requests* against different files/disks simultaneously
 - Could read from several index files at once, processing the I/O results as they arrive
 - <u>Example</u>: Our web server could execute multiple *queries* at the same time
 - While one is waiting for I/O, another can be executing on the CPU

A Concurrent Implementation

- Se multiple "workers"
 - As a query arrives, create a new "worker" to handle it
 - The "worker" reads the query from the network, issues read requests against files, assembles results and writes to the network
 - The "worker" uses blocking I/O; the "worker" alternates between consuming CPU cycles and blocking on I/O
 - The OS context switches between "workers"
 - While one is blocked on I/O, another can use the CPU
 - Multiple "workers'" I/O requests can be issued at once
- So what should we use for our "workers"?

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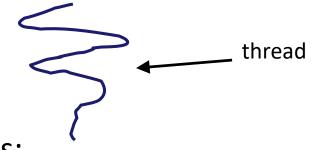
Review: Processes

- To implement a "process", the operating system gives us:
 - Resources such as file handles and sockets
 - Call stack + registers to support (eg, PC, SP)
 - Virtual memory (page tables, TLBs, etc ...)
- If we want concurrency, what is the "minimal set" we need to execute a single line of code?



Introducing Threads

- Separate the concept of a process from the "thread of execution"
 - Usually called a thread, this is a sequential execution stream within a process



- In most modern OS's:
 - Process: address space, OS resources, security attributes
 - <u>Thread</u>: stack, stack pointer, program counter, registers
 - Threads are the unit of scheduling and processes are their containers; every process has at least one thread running in it

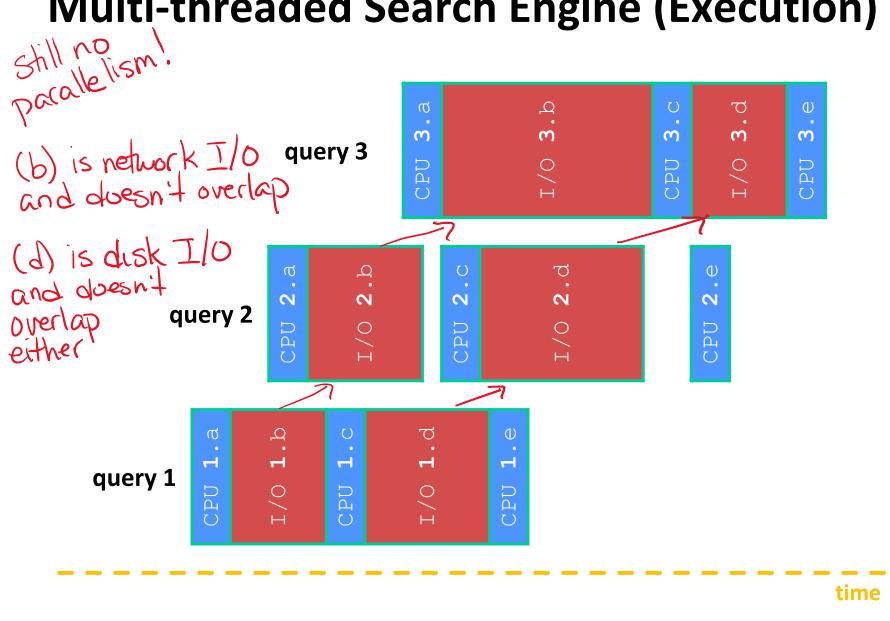
Threads

- Threads were formerly called "lightweight processes"
 - They execute concurrently like processes
 - OS's often treat them, not processes, as the unit of scheduling
 - Parallelism for free! If you have multiple CPUs/cores, can run them simultaneously
 - Unlike processes, threads cohabitate the same address space
 - Threads within a process see the same heap and globals and can communicate with each other through variables and memory
 - But, they can interfere with each other need synchronization for shared resources change virtual mem, register
 - Each thread has its own stack
- What does the OS do when you switch processes?
 - How does that differ from switching threads?

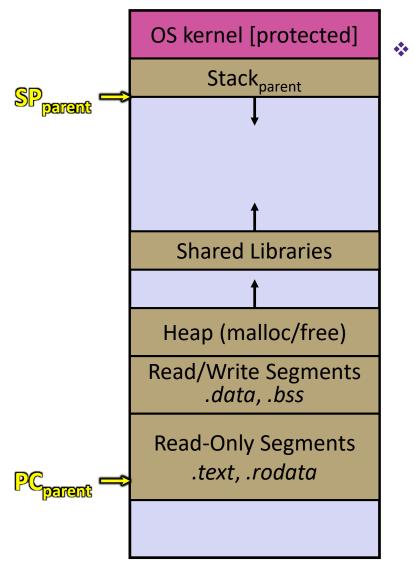
Multi-threaded Search Engine (Pseudocode)



Multi-threaded Search Engine (Execution)

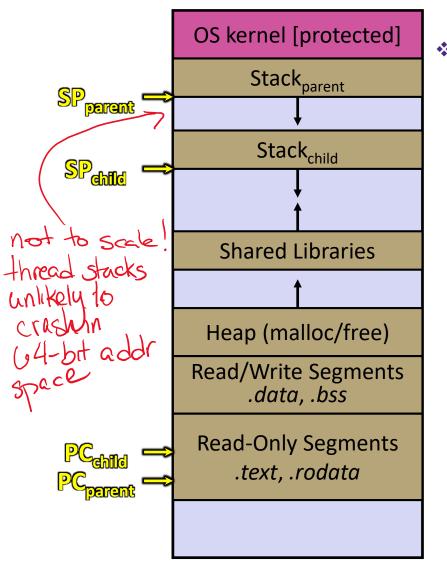


Single-Threaded Address Spaces



- Before creating a thread
 - One thread of execution running in the address space
 - One PC, stack, SP
 - That main thread invokes a function to create a new thread
 - Typically pthread_create()

Multi-threaded Address Spaces



After creating a thread

- Two threads of execution running in the address space
 - Original thread (parent) and new thread (child)
 - New stack created for child thread
 - Child thread has its own values of the PC and SP
- Both threads share the other segments (code, heap, globals)
 - They can cooperatively modify shared data

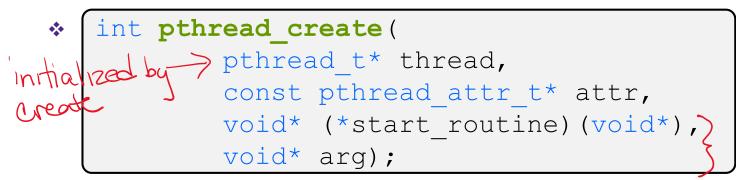
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POSIX Threads (pthreads)

- The POSIX APIs for dealing with threads
 - Declared in pthread.h
 - Not part of the C/C++ language (cf. Java)
 - To enable support for multithreading, must include -pthread flag when compiling and linking with gcc command

Creating and Terminating Threads



- Creates a new thread into *thread, with attributes *attr (NULL means default attributes)
- Returns 0 on success and an error number on error (can check against error constants)
 The new thread runs start_routine (arg) Containing the

```
void pthread exit(void* retval);
*
```

- Equivalent of exit (retval); for a thread instead of a process
- The thread will automatically exit once it returns from start routine()

"real" argi

What To Do After Forking Threads?

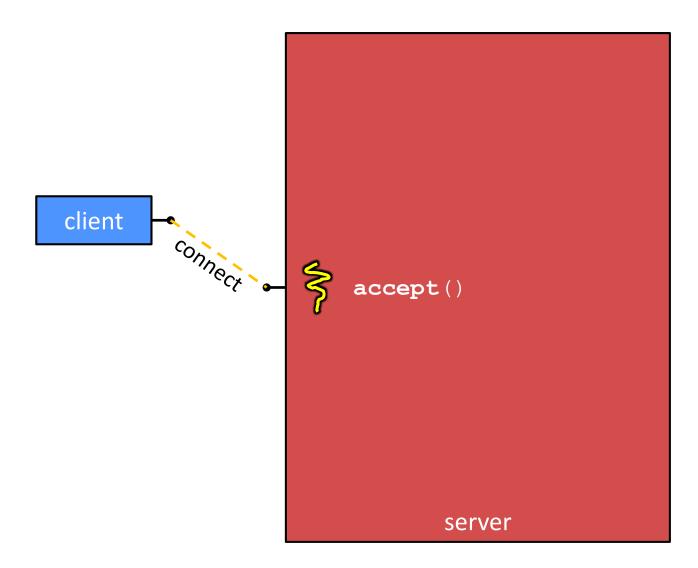
- int pthread_join(pthread_t thread, void** retval);
 - Waits for the thread specified by thread to terminate
 - The thread equivalent of waitpid()
 - The exit status of the terminated thread is placed in **retval

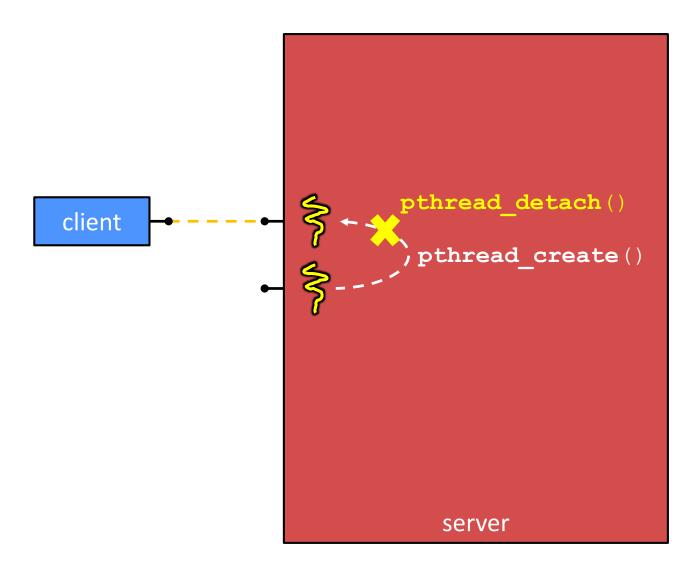
int pthread_detach(pthread_t thread);

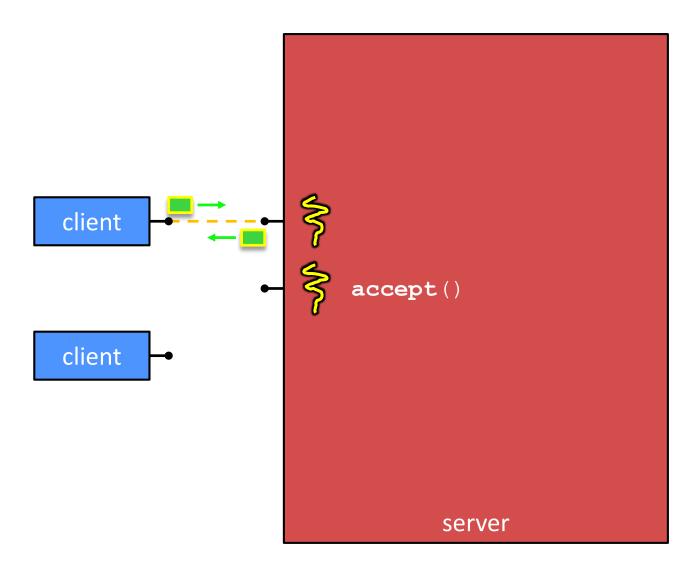
 Mark thread specified by thread as detached – it will clean up its resources as soon as it terminates

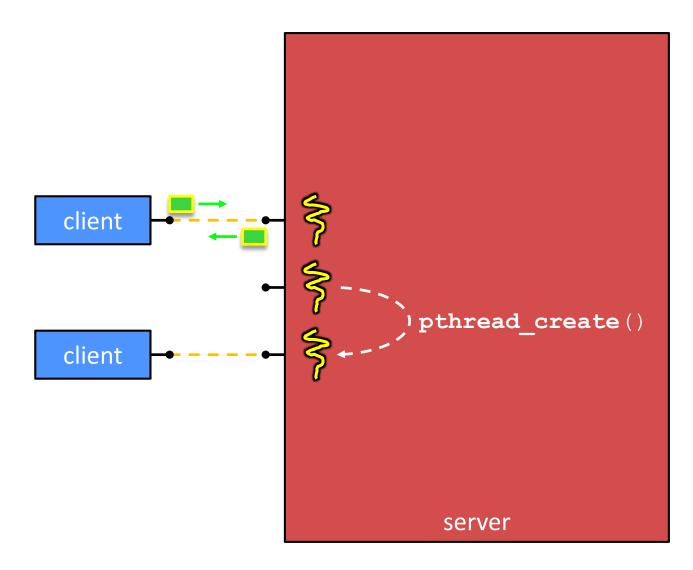
Multi-threaded Search Engine: Architecture

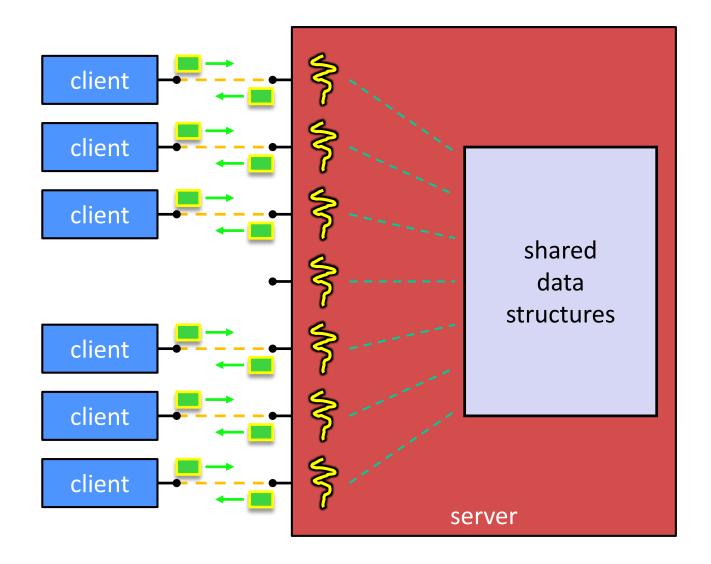
- A single *process* handles all of the connections, but a parent *thread* dispatches (creates) a new thread to handle each connection
 - The child thread handles the new connection and subsequent I/O, then exits when the connection terminates
- * See searchserver_threads/ for code if curious











pthread Examples

- * pthread.c: pthreads in C
- * pthread.cc: Same, but in C++
- * searchserver_threads: Non-trivial example
- Things to keep in mind while reading:
 - More instructions per thread = higher likelihood of interleaving
 - How do you handle memory management?
 - Who allocates and deallocates memory?
 - Can two threads call new at the same time?
 - When calling pthread_create(), start_routine points to a function that takes only one argument (a void*)
 - To pass complex arguments into the thread, create a struct to bundle the necessary data

Why Threads? (1 of 2)

- Advantages:
 - Almost as simple to code as sequential
 - In fact, most of the code is identical! (but a bit more complicated to dispatch a thread)
 - Threads can run in parallel if you have multiple CPUs/cores
 - Concurrent execution with good CPU and network utilization
 - Some overhead, but less than processes
 - Shared-memory communication is possible

Why Threads? (2 of 2)

- Disadvantages:
 - Need language and OS support for threads
 - If threads share data, you need locks or other synchronization
 - See next lecture: Very bug-prone and difficult to debug
 - Threads can introduce overhead
 - See next lecture: Lock contention, context switch overhead, CPU thrashing, and other issues
 - Also cognitive overhead for future programmers!
 - Threads within the same process have a "shared fate"
 - Eg, shared file-handle limits, no crash isolation, etc.

Why Sequential?

- Advantages:
 - Simple to write, maintain, debug
 - The default, supported everywhere
- Disadvantages:
 - Depending on application, poor performance
 - One slow client will cause *all* others to block
 - Poor utilization of resources (CPU, network, disk)