CSE 333 Lecture 17 -- network programming intro

Hal Perkins

Department of Computer Science & Engineering University of Washington



Administrivia

HW3 due tomorrow night

- hang in there!

HW4 out by end of the week

- due on the last Thursday of the quarter

One exercise over the weekend - out tomorrow, due before class next Wednesday

Today

Network programming

- dive into the Berkeley / POSIX sockets API

Files and file descriptors

Remember open, read, write, and close?

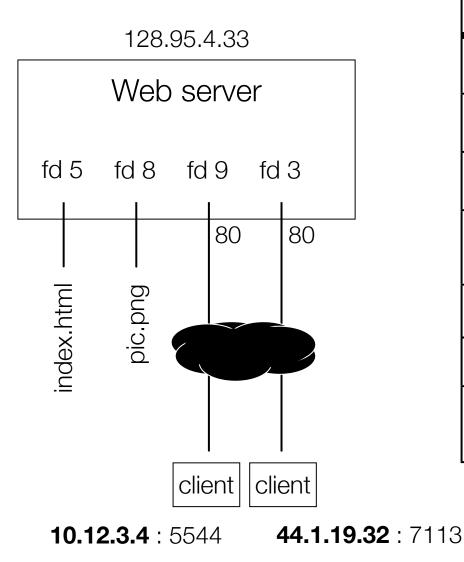
- POSIX system calls for interacting with files
- open() returns a *file descriptor*
 - an integer that represents an open file
 - inside the OS, it's an index into a table that keeps track of any state associated with your interactions, such as the file position
 - you pass the file descriptor into read, write, and close

Networks and sockets

UNIX likes to make all I/O look like file I/O

- the good news is that you can use read() and write() to interact with remote computers over a network!
- just like with files....
 - your program can have multiple network channels open at once
 - you need to pass read() and write() a *file descriptor* to let the OS know which network channel you want to write to or read from
- a file descriptor used for network communications is a **socket**

Pictorially



OS's descriptor table

file descriptor	type	connected to?
0	pipe	stdin (console)
1	pipe	stdout (console)
2	pipe	stderr (console)
3	TCP socket	local: 128.95.4.33:80 remote: 44.1.19.32:7113
5	file	index.html
8	file	pic.png
9	TCP socket	local: 128.95.4.33:80 remote: 102.12.3.4:5544

Types of sockets

Stream sockets

- for connection-oriented, point-to-point, reliable bytestreams
 - uses TCP, SCTP, or other stream transports

Datagram sockets

- for connection-less, one-to-many, unreliable packets
 - uses UDP or other packet transports

Raw sockets

- for layer-3 communication (raw IP packet manipulation)

Stream sockets

Typically used for client / server communications

- but also for other architectures, like peer-to-peer

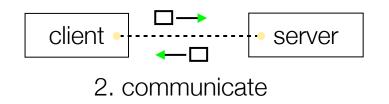
Client

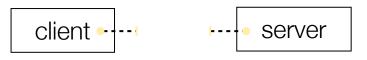
- an application that establishes a connection to a server

Server

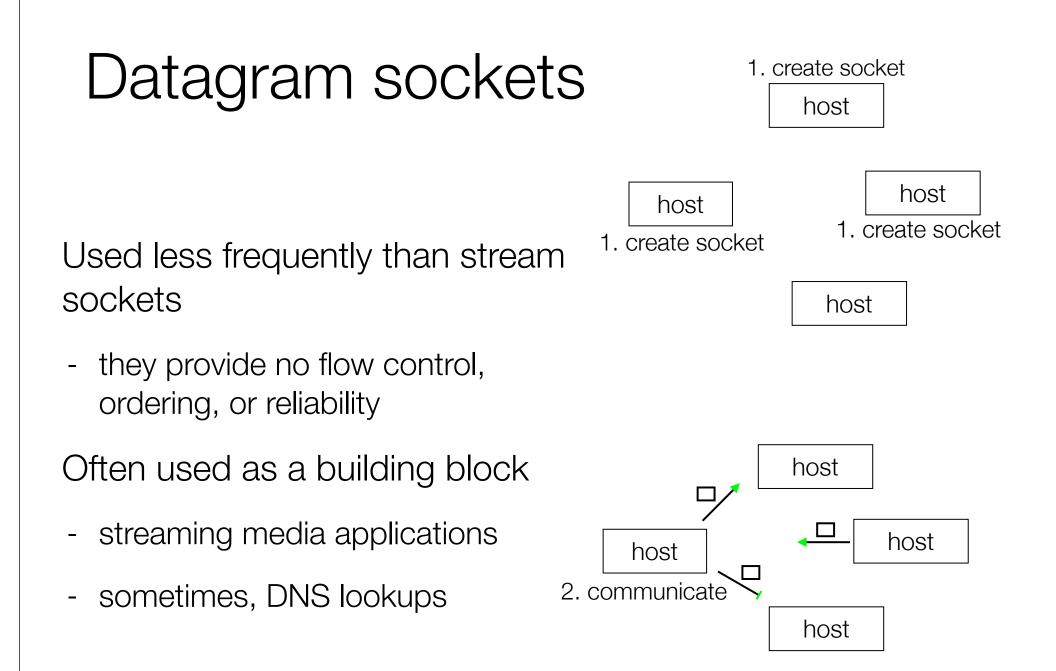
- an application that receives connections from clients











The sockets API

Berkeley sockets originated in 4.2 BSD Unix circa 1983

- it is the standard API for network programming
 - available on most OSs

POSIX socket API

- a slight updating of the Berkeley sockets API
 - a few functions were deprecated or replaced
 - better support for multi-threading was added

Let's dive into it!

We'll start by looking at the API from the point of view of a client connecting to a server over TCP

- there are five steps:
 - 1. figure out the IP address and port to which to connect
 - 2. create a socket
 - 3. connect the socket to the remote server
 - 4. read() and write() data using the socket
 - 5. close the socket

Connecting from a client to a server.

Step 1. Figure out the IP address and port to which to connect.

Network addresses

For IPv4, an IP address is a 4-byte tuple

- e.g., 128.95.4.1 (80:5f:04:01 in hex)

For IPv6, an IP address is a 16-byte tuple

- e.g., 2d01:0db8:f188:0000:0000:0000:0000:1f33
 - 2d01:0db8:f188::1f33 in shorthand

IPv4 address structures

```
// Port numbers and addresses are in *network order*.
// A mostly-protocol-independent address structure.
struct sockaddr {
   short int sa family; // Address family; AF INET, AF INET6
                sa data[14]; // 14 bytes of protocol address
   char
};
// An IPv4 specific address structure.
struct sockaddr in {
   short int sin family; // Address family, AF INET == IPv4
   unsigned short int sin port; // Port number
   struct in addr sin addr; // Internet address
   unsigned char sin zero[8]; // Same size as struct sockaddr
};
struct in addr {
   uint32 t s addr; // IPv4 address
};
```

IPv6 address structures

```
// A structure big enough to hold either IPv4 or IPv6 structures.
struct sockaddr storage {
   sa family t ss family; // address family
   // a bunch of padding; safe to ignore it.
   char ____ss_pad1[_SS_PAD1SIZE];
   int64 t ss align;
   char ss pad2[ SS PAD2SIZE];
};
// An IPv6 specific address structure.
struct sockaddr in6 {
   u_int16_t sin6_family; // address family, AF_INET6
   u int16 t sin6 port; // Port number
   u int32 t sin6 flowinfo; // IPv6 flow information
   struct in6 addr sin6 addr; // IPv6 address
   u int32 t sin6 scope id; // Scope ID
};
struct in6 addr {
   unsigned char s6 addr[16]; // IPv6 address
};
```

Generating these structures

Often you have a string representation of an address

- how do you generate one of the address structures?

```
#include <stdlib.h> genaddr.cc
#include <arpa/inet.h>

int main(int argc, char **argv) {
   struct sockaddr_in sa; // IPv4
   struct sockaddr_in6 sa6; // IPv6

   // IPv4 string to sockaddr_in.
   inet_pton(AF_INET, "192.0.2.1", &(sa.sin_addr));

   // IPv6 string to sockaddr_in6.
   inet_pton(AF_INET6, "2001:db8:63b3:1::3490", &(sa6.sin6_addr));

   return EXIT_SUCCESS;
}
```

Generating these structures

How about going in reverse?

```
genstring.cc
#include <stdlib.h>
#include <arpa/inet.h>
#include <iostream>
int main(int argc, char **argv) {
 struct sockaddr in6 sa6; // IPv6
 char astring[INET6 ADDRSTRLEN]; // IPv6
 // IPv6 string to sockaddr in6.
 inet pton(AF INET6, "2001:db8:63b3:1::3490", &(sa6.sin6 addr));
 // sockaddr in6 to IPv6 string.
 inet ntop(AF INET6, &(sa6.sin6 addr), astring, INET6 ADDRSTRLEN);
 std::cout << astring << std::endl;</pre>
 return EXIT SUCCESS;
```

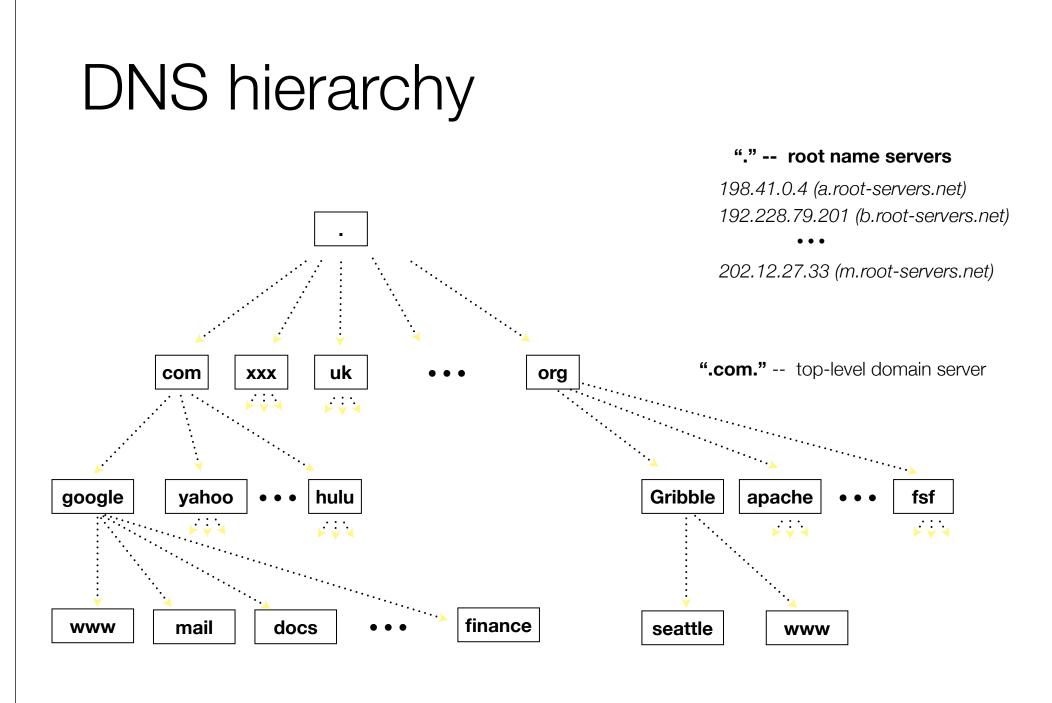
DNS

People tend to use DNS names, not IP addresses

- the sockets API lets you convert between the two
- it's a complicated process, though:
 - a given DNS name can have many IP addresses
 - many different DNS names can map to the same IP address
 - an IP address will reverse map into at most one DNS names, and maybe none
 - a DNS lookup may require interacting with many DNS servers

You can use the "dig" Linux program to explore DNS

- "man dig"



Resolving DNS names

The POSIX way is to use getaddrinfo()

- a pretty complicated system call; the basic idea...
 - set up a "hints" structure with constraints you want respected
 - e.g., IPv6, IPv4, or either
 - tell getaddrinfo() which host and port you want resolved
 - host: a string representation; DNS name or IP address
 - getaddrinfo() gives you a list of results packet in an "addrinfo" struct
 - free the addrinfo structure using freeaddrinfo()

DNS lookup example

see dnsresolve.cc

Connecting from a client to a server.

Step 2. Create a socket.

Creating a socket

Use the **socket** system call

- creating a socket doesn't yet bind it to a local address or port

```
socket.cc
#include <errno.h>
#include <stdlib.h>
#include <string.h>
#include <sys/socket.h>
#include <sys/types.h>
#include <iostream>
int main(int argc, char **argv) {
 int socket fd = socket(PF INET, SOCK STREAM, 0);
 if (socket fd == -1) {
     std::cerr << strerror(errno) << std::endl;</pre>
     return EXIT FAILURE;
 close(socket fd);
 return EXIT SUCCESS;
```

Connecting from a client to a server.

Step 3. Connect the socket to the remote server.

connect()

The **connect()** system call establishes a connection to a remote host

- you pass the following arguments to connect():
 - the socket file descriptor you created in step 2
 - one of the address structures you created in step 1
- connect may take some time to return
 - it is a **blocking** call by default
 - the network stack within the OS will communicate with the remote host to establish a TCP connection to it
 - this involves ~2 round trips across the network

connect example

see connect.cc

Connecting from a client to a server.

Step 4. read() and write() data using the socket.

read()

By default, a blocking call

- if there is data that has already been received by the network stack, then read will return immediately with it
 - thus, read might return with less data than you asked for
- if there is no data waiting for you, by default read() will block until some arrives
 - pop quiz: how might this cause **deadlock**?

write()

By default, a blocking call

- but, in a more sneaky way
- when write() returns, the receiver (i.e., the other end of the connection) probably has not yet received the data
 - in fact, the data might not have been sent on the network yet!
 - write() enqueues your data in a send buffer in the OS, and then returns; the OS will transmit the data in the background
- if there is no more space left in the send buffer, by default write() will block
 - how might this cause **deadlock**?

read/write example

see sendreceive.cc

Connecting from a client to a server.

Step 5. close() the socket.

See you on Friday!

Exercise 1

Write a client that:

- reads DNS names, one per line, from stdin
- translates each name to one or more IP addresses
- prints out each IP address to stdout, one per line