CSE 333 Lecture 8 - file and network I/O

Steve Gribble

Department of Computer Science & Engineering University of Washington



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Administrivia

HW1 was due yesterday

phew! how'd it go?

HW2 will go out on Monday

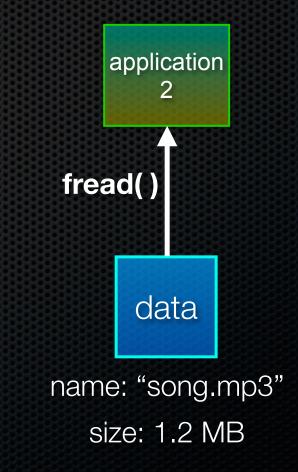
- builds on HW1
- we'll provide libhw1.a as an alternative if you find that your solution is buggy

Files

File I/O



name: "logfile.txt" size: 512KB



Files

Simple semantics

- files are named by filename
 - [directory name] / [filename]
 - e.g., /Users/gribble/files/song.mp3
- files have a current size
 - ► finite
 - discoverable
- programs typically read from, or write to, a file
 - occasionally both (e.g., database)

Let's do some file I/O...

We'll start by using C's standard library

- functions are defined within libC
- they make use of Linux system calls

C's stdio defines the notion of a stream

- a stream is a way of reading or writing a sequence of characters from/to a device
 - a stream can be either *text* or *binary;* Linux does not distinguish
 - a stream is *buffered* by default; libc reads ahead of you
 - three streams are provided by default: stdin, stdout, stderr
 - you can open additional streams to read/write to files

Using C streams

```
printf(...) is equivalent
#include <stdio.h>
                                             fread_example.c
                                                                   to fprintf(stdout, ...)
#include <stdlib.h>
#include <errno.h>
#define READBUFSIZE 128
int main(int argc, char **argv) {
  FILE *f;
  char readbuf[READBUFSIZE];
  size t readlen;
                                                                   stderr is a stream for
                                                                   printing error output
  if (argc != 2) {
    fprintf(stderr, "usage: ./fread example filename\n");
                                                                 to a console
    return EXIT FAILURE; // defined in stdlib.h
  }
                                                                    fopen opens a
  // Open, read, and print the file
                                                                    stream to read or
  f = fopen(argv[1], "rb"); // "rb" --> read, binary mode
                                                                ← write a file
  if (f == NULL) {
    fprintf(stderr, "%s -- ", argv[1]);
                                                                    perror writes a string
    perror("fopen failed -- ");
    return EXIT FAILURE;
                                                                    describing the last
  }
                                                                    error to stderr
  // Read from the file, write to stdout.
                                                                stdout is for printing
  while ((readlen = fread(readbuf, 1, READBUFSIZE, f)) > 0)
    fwrite(readbuf, 1, readlen, stdout);
                                                                    non-error output to
  fclose(f);
                                                                    the console
  return EXIT SUCCESS; // defined in stdlib.h
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```

Writing is easy too

see cp_example.c

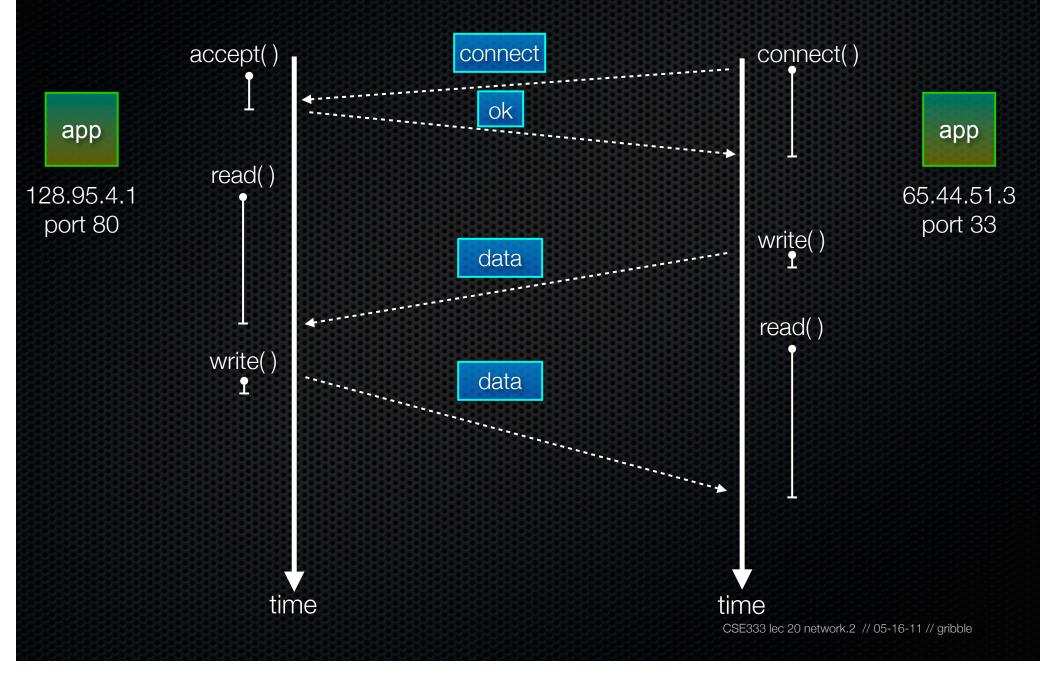
Files and file descriptors

The OS provides open, read, write, and close

- system calls for interacting with files
- open() returns a file descriptor
 - an integer that represents an open file
 - inside the OS, it's an index into a table that keeps track of any state associated with your interactions, such as the file position
 - you pass the file descriptor into read, write, and close
- read() and write() are unbuffered

Network

Network I/O



Network I/O

Complex semantics

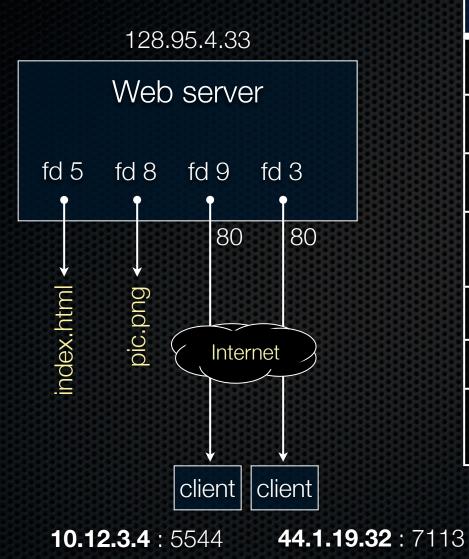
- endpoints named by IP address / port number
 - e.g., IP address 128.95.4.1, port 80
- communication is bidirectional
 - each participant interleaves reading and writing data
 - a protocol dictates who sends what, and when
- an endpoint can't predict how much data will arrive, or when it will arrive
 - fread() isn't really appropriate, since it will block until a specified amount of data has been read, or EOF is reached
 - but EOF for network means "other side hung up"

Network I/O

read() is more appropriate than fread()

- read(int fd, void *buf, size_t bufsize)
 - you specify "I'm willing to receive bufsize bytes"
 - read will block in OS until some data is available
 - once data is available, read will return up to **bufsize** bytes
 - will return less than bufsize if less data is available
- lets you block until something can be read
 - without knowing how much you should read

Pictorially



OS's descriptor table

file descriptor	type	connected to?							
0	pipe	stdin (console)							
1	pipe	stdout (console) stderr (console)							
2	pipe								
3	TCP socket	local: 128.95.4.33:80 remote: 44.1.19.32:7113							
5	file	index.html							
8	file	pic.png							
9	TCP socket	local: 128.95.4.33:80 remote: 102.12.3.4:5544							

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Types of sockets

Stream sockets

- for connection-oriented, point-to-point, reliable bytestreams
 - uses TCP, SCTP, or other stream transports

Datagram sockets

- for connection-less, one-to-many, unreliable packets
 - uses UDP or other packet transports

Stream sockets ("TCP")

Typically used for client / server communications

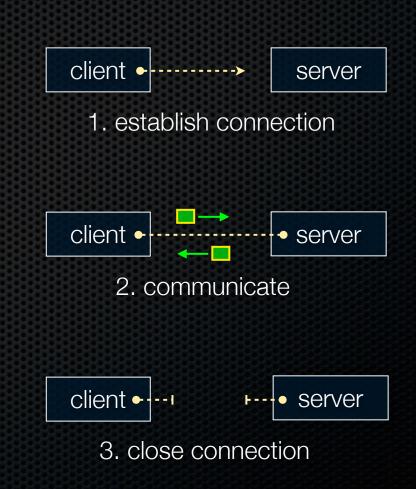
 but also for other architectures, like peer-to-peer

Client

- an application that establishes a connection to a server

Server

- an application that receives connections from clients



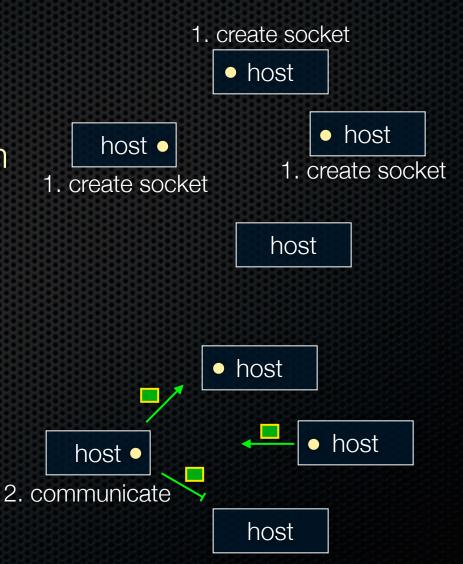
Datagram sockets ("UDP")

Used less frequently than stream sockets

- they provide no flow control, ordering, or reliability

Often used as a building block

- streaming media applications
- sometimes, DNS lookups



The sockets API

Berkeley sockets originated in 4.2 BSD Unix circa 1983

- it is the standard API for network programming
 - available on most OSs

POSIX socket API

- a slight updating of the Berkeley sockets API
 - a few functions were deprecated or replaced
 - better support for multi-threading was added

Let's dive into it!

We'll start by looking at the API from the point of view of a client connecting to a server over TCP

- there are five steps:
 - 1. figure out the address and port to which to connect
 - 2. create a socket
 - 3. connect the socket to the remote server
 - 4. read and write data using the socket
 - 5. close the socket

Connecting from a client to a server.

Step 1. Figure out the address and port to which to connect.

Network addresses

For IPv4, an IP address is a 4-byte tuple
e.g., 128.95.4.1 (80:5f:04:01 in hex)
For IPv6, an IP address is a 16-byte tuple
e.g., 2d01:0db8:f188:0000:0000:0000:0000:1f33

- Cigi, 2001.0000.1100.0000.0000.0000.0000
 - 2d01:0db8:f188::1f33 in shorthand

IPv4 address structures

```
// Port numbers and addresses are in *network order*.
// A mostly-protocol-independent address structure.
struct sockaddr {
   short int sa family; // Address family; AF INET, AF INET6
              sa data[14]; // 14 bytes of protocol address
   char
};
// An IPv4 specific address structure.
struct sockaddr in {
   short int
                     sin family; // Address family, AF INET == IPv4
   unsigned short int sin_port; // Port number
   struct in addr sin addr; // Internet address
   unsigned char sin zero[8]; // Padding
struct in addr {
   uint32 t s addr; // IPv4 address
};
```

IPv6 address structures

```
// A structure big enough to hold either IPv4 or IPv6 structures.
struct sockaddr storage {
   sa_family_t ss_family; // address family
   // a bunch of padding; safe to ignore it.
   char _____ss_pad1[_SS_PAD1SIZE];
   int64 t ss_align;
   char ss pad2[ SS PAD2SIZE];
};
// An IPv6 specific address structure.
struct sockaddr in6 {
   u_int16_t sin6_family; // address family, AF INET6
   u_int16_t sin6_port; // Port number
   u int32 t sin6 flowinfo; // IPv6 flow information
   struct in6 addr sin6 addr; // IPv6 address
   u_int32_t sin6_scope_id; // Scope ID
};
struct in6 addr {
   unsigned char s6_addr[16]; // IPv6 address
};
```

Generating these structures

Often you have a string representation of an address

- how do you generate one of the address structures?

```
#include <stdlib.h> genaddr.cc
#include <arpa/inet.h> genaddr.cc
int main(int argc, char **argv) {
    struct sockaddr_in sa; // IPv4
    struct sockaddr_in6 sa6; // IPv6
    // IPv4 string to sockaddr_in.
    inet_pton(AF_INET, "192.0.2.1", &(sa.sin_addr));
    // IPv6 string to sockaddr_in6.
    inet_pton(AF_INET6, "2001:db8:63b3:1::3490", &(sa6.sin6_addr));
```

```
return EXIT SUCCESS;
```

Generating these structures

How about going in reverse?

#include <stdio.h
#include <stdlib.h>
#include <arpa/inet.h>
int main(int argc, char **argv) {
 struct sockaddr_in6 sa6; // IPv6
 char astring[INET6 ADDRSTRLEN]; // IPv6

// IPv6 string to sockaddr_in6.
inet pton(AF INET6, "2001:db8:63b3:1::3490", &(sa6.sin6 addr));

```
// sockaddr_in6 to IPv6 string.
inet_ntop(AF_INET6, &(sa6.sin6_addr), astring, INET6_ADDRSTRLEN);
printf("%s", astring);
```

```
return EXIT SUCCESS;
```

genstring.cc

DNS

People tend to use DNS names, not IP addresses

- the sockets API lets you convert between the two
- it's a complicated process, though:
 - a given DNS name can have many IP addresses
 - many different DNS names can map to the same IP address
 - an IP address will reverse map into at most one DNS names, and maybe none
 - a DNS lookup may require interacting with many DNS servers

You can use the "dig" Linux program to explore DNS

- "man dig"

Resolving DNS names

The POSIX way is to use getaddrinfo()

- a pretty complicated system call; the basic idea...
 - set up a "hints" structure with constraints you want respected
 - e.g., IPv6, IPv4, or either
 - tell getaddrinfo() which host and port you want resolved
 - host: a string representation; DNS name or IP address
 - getaddrinfo() returns a list of results packed in an "addrinfo" struct
 - free the addrinfo structure using freeaddrinfo()

DNS lookup example

see dnsresolve.cc

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Connecting from a client to a server.

Step 2. Create a socket.

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Creating a socket

Use the **socket** system call

- creating a socket doesn't yet bind it to a local address or port

```
socket.cc
```

```
#include <errno.h>
#include <stdlib.h>
#include <stdlib.h>
#include <string.h>
#include <sys/socket.h>
#include <sys/types.h>
#include <iostream>

int main(int argc, char **argv) {
    int socket_fd = socket(PF_INET, SOCK_STREAM, 0);
    if (socket_fd == -1) {
        std::cerr << strerror(errno) << std::endl;
        return EXIT_FAILURE;
    }
    close(socket_fd);
    return EXIT_SUCCESS;
}
</pre>
```

Connecting from a client to a server.

Step 3. Connect the socket to the remote server.

connect()

The **connect()** system call establishes a connection to a remote host

- you pass the following arguments to connect():
 - the socket file descriptor you created in step 2
 - one of the address structures you created in step 1
- connect may take some time to return
 - it is a **blocking** call by default
 - the network stack within the OS will communicate with the remote host to establish a TCP connection to it
 - this involves ~2 round trips across the network

connect example

see connect.cc

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Connecting from a client to a server.

Step 4. read and write data using the socket.

read()

By default, a blocking call

- if there is data that has already been received by the network stack, then read will return immediately with it
 - as mentioned before, read might return with less data than you asked for
- if there is no data waiting for you, by default read() will block until some arrives
 - then will return with whatever data has arrived

write()

By default, also a blocking call

- but, in a more sneaky way
- when write() returns, the receiver (i.e., the other end of the connection) probably has not yet received the data
 - in fact, the data might not have been sent on the network yet!
 - write() enqueues your data in an OS "send buffer" and then returns
 - the OS will transmit the data in the background
- if there is no more space left in the send buffer, by default write() will block

read and write are complex

If you call read, you will block until data is available

- but, for esoteric reasons, read() might return early
 - indicates this by returning -1 (i.e., an error) and setting the global variable errno to EINTR
 - the right thing to do is try your read again
- so, you have to put read in a while loop to handle this case

read/write example

see sendreceive.cc

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Connecting from a client to a server.

Step 5. close() the socket.

See you on Wednesday!

Exercise 1

Write a program that:

- uses argc/argv to receive the name of a text file
- reads the contents of the file a line at a time
- parses each line, converting text into a uint32_t
- builds an array of the parsed uint32_t's
- sorts the array
- prints the sorted array to stdout
 - hints: use "man" to read about getline, sscanf, realloc, and qsort

bash\$	cat	in.txt
1213		
3231		
000005	5	
52		
bash\$	ex1	in.txt
5		
52		
1213		
3231		
bash\$		

Exercise 2

Write a program that:

- loops forever; in each loop, it:
 - prompts the user to input a filename
 - reads from stdin to receive a filename
 - opens and reads the file, and prints its contents to stdout, in the format shown on the right
- hints:
 - use "man" to read about fgets
 - or if you're more courageous, try "man 3 readline" to learn about libreadline.a, and google to learn how to link to it

000	0000	50	4b	03	04	14	00	00	00	00	00	9c	45	26	3c	f1	d5
000	0010	68	95	25	1b	00	00	25	1b	00	00	0d	00	00	00	43	53
000	0020	45	6c	6f	67	6f	2d	31	2e	70	6e	67	89	50	4e	47	0d
000	0030	0a	1a	0a	00	00	00	0d	49	48	44	52	00	00	00	91	00
000	0040	00	00	91	08	06	00	00	00	c3	d 8	5a	23	00	00	00	09
000	0050	70	48	59	73	00	00	0Ъ	13	00	00	0b	13	01	00	9a	9c
000	0060	18	00	00	0a	4f	69	43	43	50	50	68	6f	74	6f	73	68
000	0070	6f	70	20	49	43	43	20	70	72	6f	66	69	6c	65	00	00
000	0800	78	da	9d	53	67	54	53	e9	16	3d	£7	de	£4	42	4b	88
000	0090	80	94	4b	6f	52	15	80	20	52	42	8b	80	14	91	26	2a
000	00a0	21	09	10	4a	88	21	a1	d9	15	51	c1	11	45	45	04	1b
000	00Ъ0	с8	a0	88	03	8e	8e	80	8c	15	51	2c	0c	8a	0a	d 8	07
000	00c0	e4	21	a2	8e	83	a3	88	8a	ca	fb	e1	7b	a3	6b	d6	bc
	etc.																

Exercise 3

Write a program that:

- connects to the hostname and port provided by argv[1] and argv[2]
- reads data from stdin into memory
 - once stdin has closed (you hit EOF), writes the data to the socket
 - once the socket has closed, quits