

CSE 333

Lecture 20 -- network programming intro

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Administrivia

HW3 is due in 2 days!

- 8 bugs in our code on the discussion board thread
- some useful debugging tips

HW3 “gotchas” #1 and #2

go over:

fileindexwriter.cc -- WriteDocPosnListFn()

fileindexwriter.cc -- WriteHashTable()

Today

Network programming

- dive into the Berkeley / POSIX sockets API

Files and file descriptors

Remember open, read, write, and close?

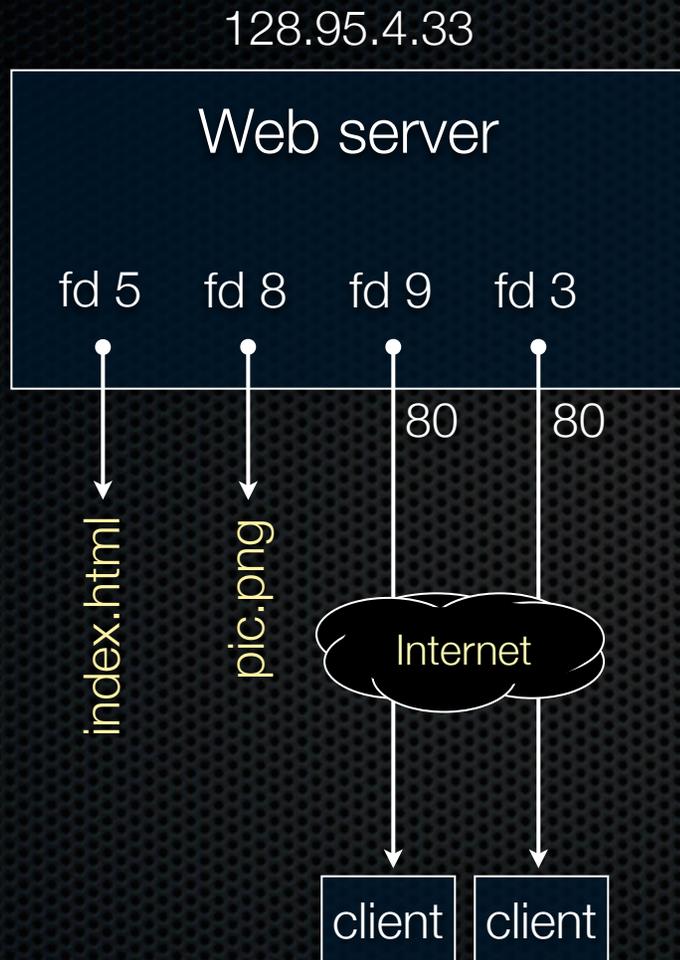
- POSIX system calls for interacting with files
- `open()` returns a *file descriptor*
 - ▶ an integer that represents an open file
 - ▶ inside the OS, it's an index into a table that keeps track of any state associated with your interactions, such as the file position
 - ▶ you pass the file descriptor into read, write, and close

Networks and sockets

UNIX likes to make all I/O look like file I/O

- the good news is that you can use `read()` and `write()` to interact with remote computers over a network!
- just like with files....
 - ▶ your program can have multiple network channels open at once
 - ▶ you need to pass `read()` and `write()` a **file descriptor** to let the OS know which network channel you want to write to or read from
- a file descriptor used for network communications is a **socket**

Pictorially



10.12.3.4 : 5544

44.1.19.32 : 7113

OS's descriptor table

file descriptor	type	connected to?
0	pipe	stdin (console)
1	pipe	stdout (console)
2	pipe	stderr (console)
3	TCP socket	local: 128.95.4.33:80 remote: 44.1.19.32:7113
5	file	index.html
8	file	pic.png
9	TCP socket	local: 128.95.4.33:80 remote: 102.12.3.4:5544

Types of sockets

Stream sockets

- for connection-oriented, point-to-point, reliable bytestreams
 - uses TCP, SCTP, or other stream transports

Datagram sockets

- for connection-less, one-to-many, unreliable packets
 - uses UDP or other packet transports

Raw sockets

- for layer-3 communication (raw IP packet manipulation)

Stream sockets

Typically used for client / server communications

- but also for other architectures, like peer-to-peer

Client

- an application that establishes a connection to a server

Server

- an application that receives connections from clients



1. establish connection



2. communicate



3. close connection

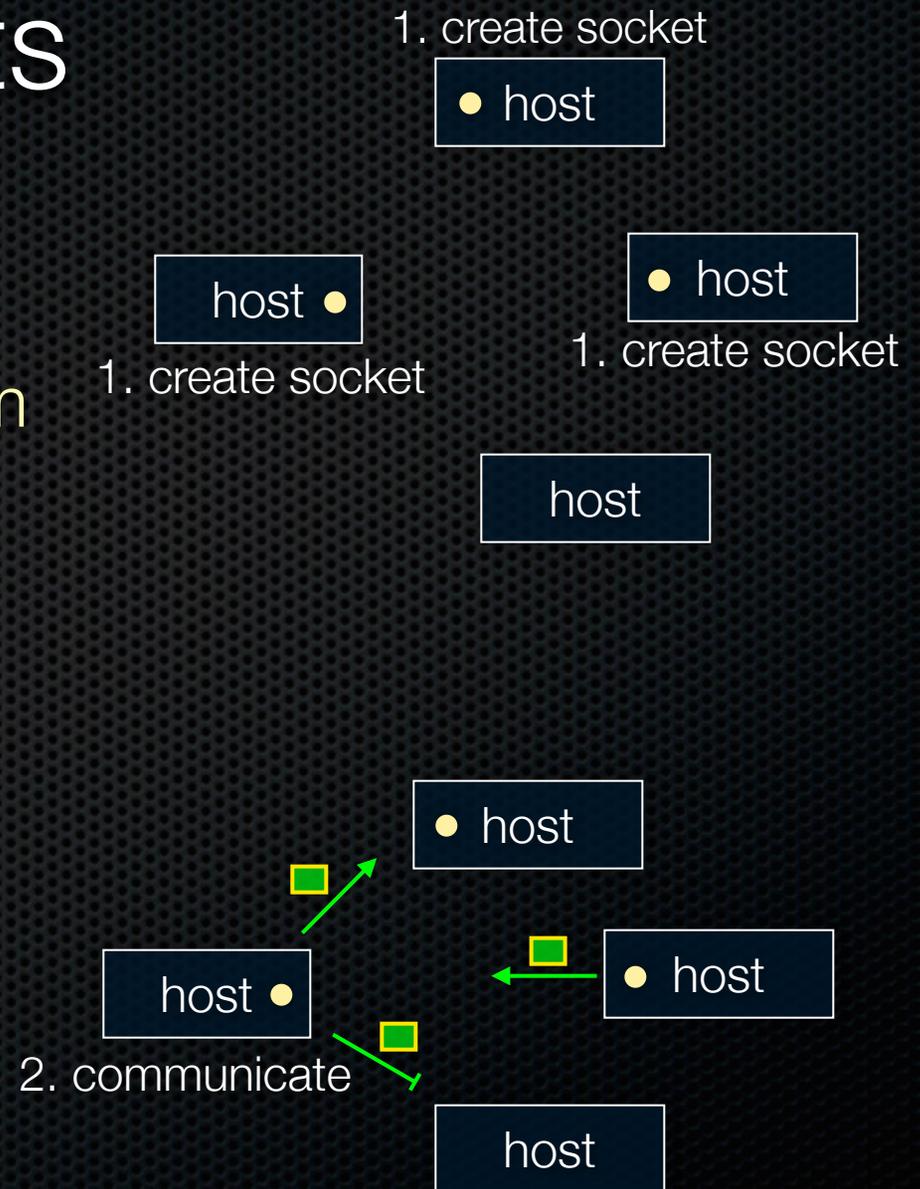
Datagram sockets

Used less frequently than stream sockets

- they provide no flow control, ordering, or reliability

Often used as a building block

- streaming media applications
- sometimes, DNS lookups



The sockets API

Berkeley sockets originated in 4.2 BSD Unix circa 1983

- it is the standard API for network programming
 - ▶ available on most OSs

POSIX socket API

- a slight updating of the Berkeley sockets API
 - ▶ a few functions were deprecated or replaced
 - ▶ better support for multi-threading was added

Let's dive into it!

We'll start by looking at the API from the point of view of a client connecting to a server over TCP

- there are five steps:
 1. figure out the address and port to which to connect
 2. create a socket
 3. connect the socket to the remote server
 4. read() and write() data using the socket
 5. close the socket

Connecting from a client to a server.

Step 1. Figure out the address and port to which to connect.

Network addresses

For IPv4, an IP address is a 4-byte tuple

- e.g., 128.95.4.1 (80:5f:04:01 in hex)

For IPv6, an IP address is a 16-byte tuple

- e.g., 2d01:0db8:f188:0000:0000:0000:0000:1f33
 - ▶ 2d01:0db8:f188::1f33 in shorthand

IPv4 address structures

```
// Port numbers and addresses are in *network order*.

// A mostly-protocol-independent address structure.
struct sockaddr {
    short int    sa_family;    // Address family; AF_INET, AF_INET6
    char        sa_data[14];  // 14 bytes of protocol address
};

// An IPv4 specific address structure.
struct sockaddr_in {
    short int    sin_family;   // Address family, AF_INET == IPv4
    unsigned short int sin_port; // Port number
    struct in_addr sin_addr;   // Internet address
    unsigned char sin_zero[8]; // Same size as struct sockaddr
};

struct in_addr {
    uint32_t s_addr; // IPv4 address
};
```

IPv6 address structures

```
// A structure big enough to hold either IPv4 or IPv6 structures.
struct sockaddr_storage {
    sa_family_t  ss_family;    // address family

    // a bunch of padding; safe to ignore it.
    char        __ss_pad1[_SS_PAD1SIZE];
    int64_t     __ss_align;
    char        __ss_pad2[_SS_PAD2SIZE];
};

// An IPv6 specific address structure.
struct sockaddr_in6 {
    u_int16_t   sin6_family;  // address family, AF_INET6
    u_int16_t   sin6_port;    // Port number
    u_int32_t   sin6_flowinfo; // IPv6 flow information
    struct in6_addr sin6_addr; // IPv6 address
    u_int32_t   sin6_scope_id; // Scope ID
};

struct in6_addr {
    unsigned char s6_addr[16]; // IPv6 address
};
```

Generating these structures

Often you have a string representation of an address

- how do you generate one of the address structures?

```
#include <stdlib.h>
#include <arpa/inet.h>

int main(int argc, char **argv) {
    struct sockaddr_in sa; // IPv4
    struct sockaddr_in6 sa6; // IPv6

    // IPv4 string to sockaddr_in.
    inet_pton(AF_INET, "192.0.2.1", &(sa.sin_addr));

    // IPv6 string to sockaddr_in6.
    inet_pton(AF_INET6, "2001:db8:63b3:1::3490", &(sa6.sin6_addr));

    return EXIT_SUCCESS;
}
```

genaddr.cc

Generating these structures

How about going in reverse?

```
genstring.cc
#include <stdlib.h>
#include <arpa/inet.h>
#include <iostream>

int main(int argc, char **argv) {
    struct sockaddr_in6 sa6;           // IPv6
    char astring[INET6_ADDRSTRLEN];   // IPv6

    // IPv6 string to sockaddr_in6.
    inet_pton(AF_INET6, "2001:db8:63b3:1::3490", &(sa6.sin6_addr));

    // sockaddr_in6 to IPv6 string.
    inet_ntop(AF_INET6, &(sa6.sin6_addr), astring, INET6_ADDRSTRLEN);
    std::cout << astring << std::endl;

    return EXIT_SUCCESS;
}
```

DNS

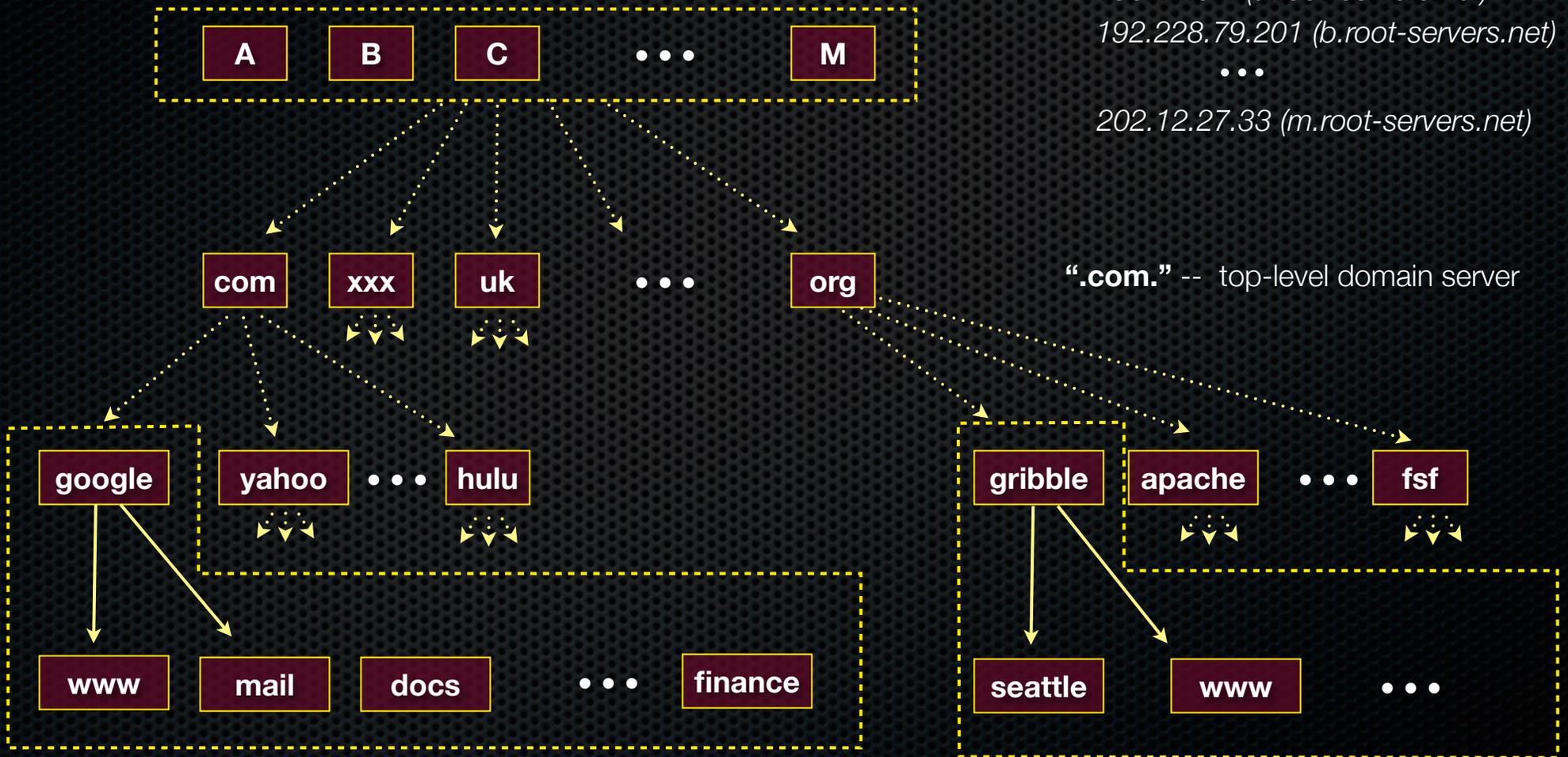
People tend to use DNS names, not IP addresses

- the sockets API lets you convert between the two
- it's a complicated process, though:
 - ▶ a given DNS name can have many IP addresses
 - ▶ many different DNS names can map to the same IP address
 - an IP address will reverse map into at most one DNS names, and maybe none
 - ▶ a DNS lookup may require interacting with many DNS servers

You can use the “dig” Linux program to explore DNS

- “man dig”

DNS hierarchy



Resolving DNS names

The POSIX way is to use **getaddrinfo()**

- a pretty complicated system call; the basic idea...
 - ▶ set up a “hints” structure with constraints you want respected
 - e.g., IPv6, IPv4, or either
 - ▶ tell `getaddrinfo()` which host and port you want resolved
 - host: a string representation; DNS name or IP address
 - ▶ `getaddrinfo()` gives you a list of results packet in an “addrinfo” struct
 - ▶ free the addrinfo structure using `freeaddrinfo()`

DNS lookup example

see dnsresolve.cc

Connecting from a client to a server.

Step 2. Create a socket.

Creating a socket

Use the **socket** system call

- creating a socket doesn't yet bind it to a local address or port

socket.cc

```
#include <errno.h>
#include <stdlib.h>
#include <string.h>
#include <sys/socket.h>
#include <sys/types.h>
#include <iostream>

int main(int argc, char **argv) {
    int socket_fd = socket(PF_INET, SOCK_STREAM, 0);
    if (socket_fd == -1) {
        std::cerr << strerror(errno) << std::endl;
        return EXIT_FAILURE;
    }
    close(socket_fd);
    return EXIT_SUCCESS;
}
```

Connecting from a client to a server.

Step 3. Connect the socket to the remote server.

connect()

The **connect()** system call establishes a connection to a remote host

- you pass the following arguments to connect():
 - ▶ the socket file descriptor you created in step 2
 - ▶ one of the address structures you created in step 1
- connect may take some time to return
 - ▶ it is a **blocking** call by default
 - ▶ the network stack within the OS will communicate with the remote host to establish a TCP connection to it
 - ▶ this involves *~2 round trips* across the network

connect example

see connect.cc

Connecting from a client to a server.

Step 4. `read()` and `write()` data using the socket.

read()

By default, a blocking call

- if there is data that has already been received by the network stack, then read will return immediately with it
 - ▶ thus, read might return with less data than you asked for
- if there is no data waiting for you, by default read() will block until some arrives
 - ▶ pop quiz: how might this cause **deadlock**?

write()

By default, a blocking call

- but, in a more sneaky way
- when write() returns, the receiver (i.e., the other end of the connection) probably has not yet received the data
 - ▶ in fact, the data might not have been send on the network yet!
 - ▶ write() enqueues your data in a send buffer in the OS, and then returns; the OS will transmit the data in the background
- if there is no more space left in the send buffer, by default write() will block
 - ▶ how might this cause **deadlock**?

read/write example

see sendreceive.cc

Connecting from a client to a server.

Step 5. `close()` the socket.

See you on Wednesday!