

CSE 332 Summer 2026

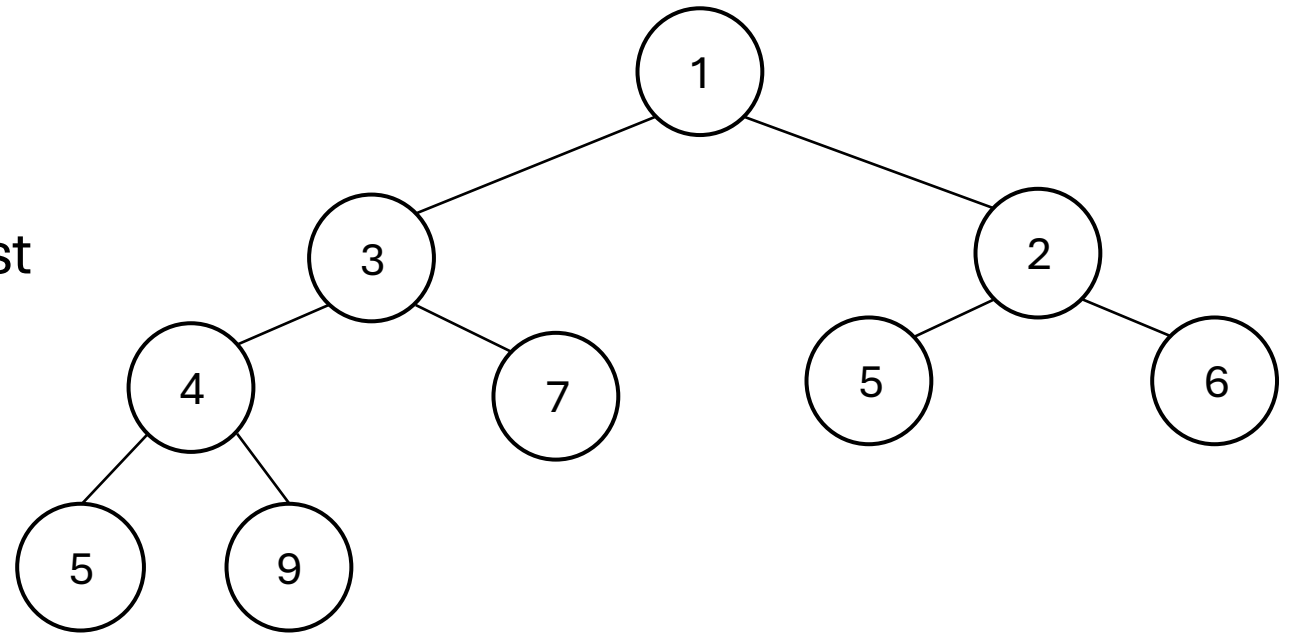
Lecture 6: Heap Wrapup, Dictionaries

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<http://www.cs.uw.edu/332>

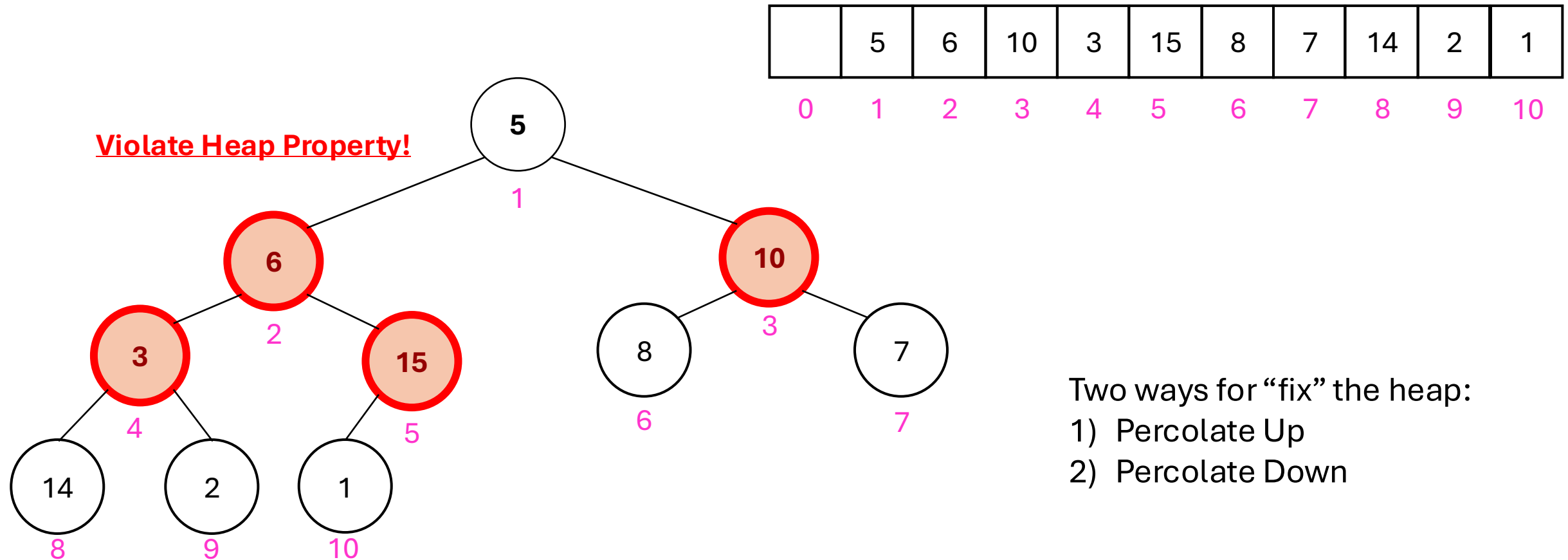
Reminder: Heap Data Structure (for priority queue ADT)

- **Invariant 1:** tree will be “complete”
 - All layers full except possibly last one, filled left to right
- **Invariant 2:** $\text{priority}(\text{parent}) \leq \text{priority}(\text{children})$
 - “Heap Property”
- Stored with an Array



Building a Heap From “Scratch”

- Suppose we had n items and wanted to “heapify” them



Two ways for “fix” the heap:
1) Percolate Up
2) Percolate Down

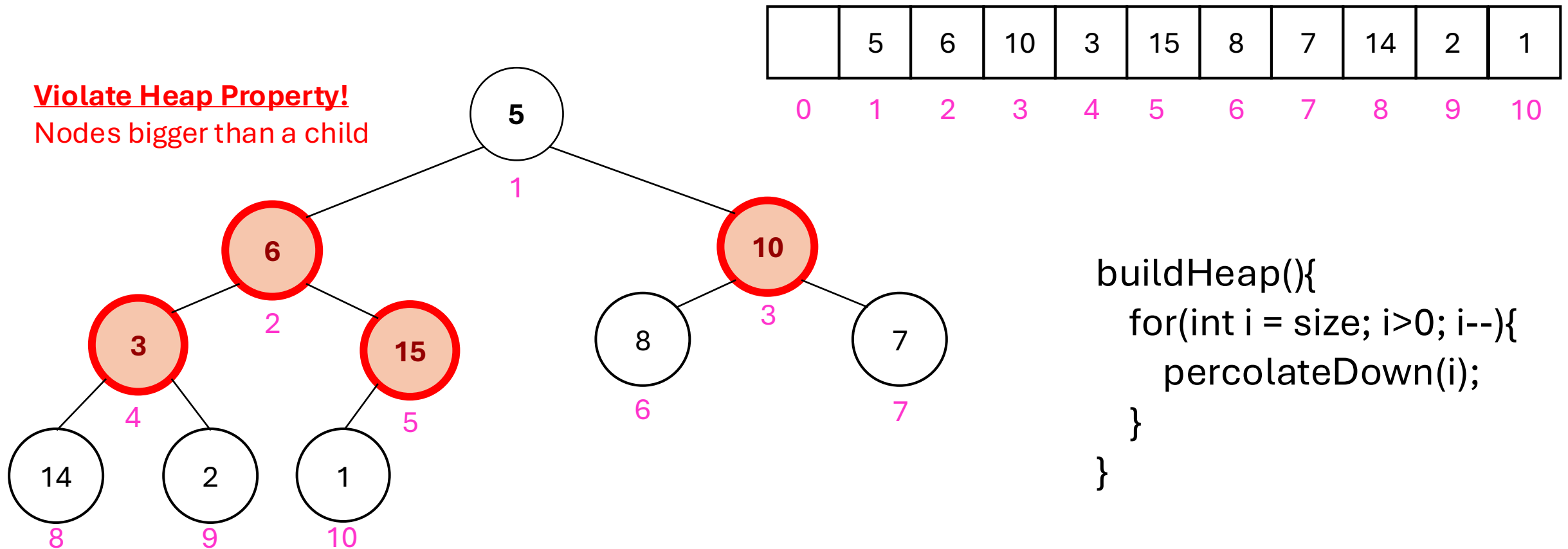
Floyd's buildHeap method

- **Starting from the leaves**, one row at a time, percolate down

```
buildHeap(){  
    for(int i = size; i>0; i--){  
        percolateDown(i);  
    }  
}
```

Floyd's buildHeap method (Percolate 15)

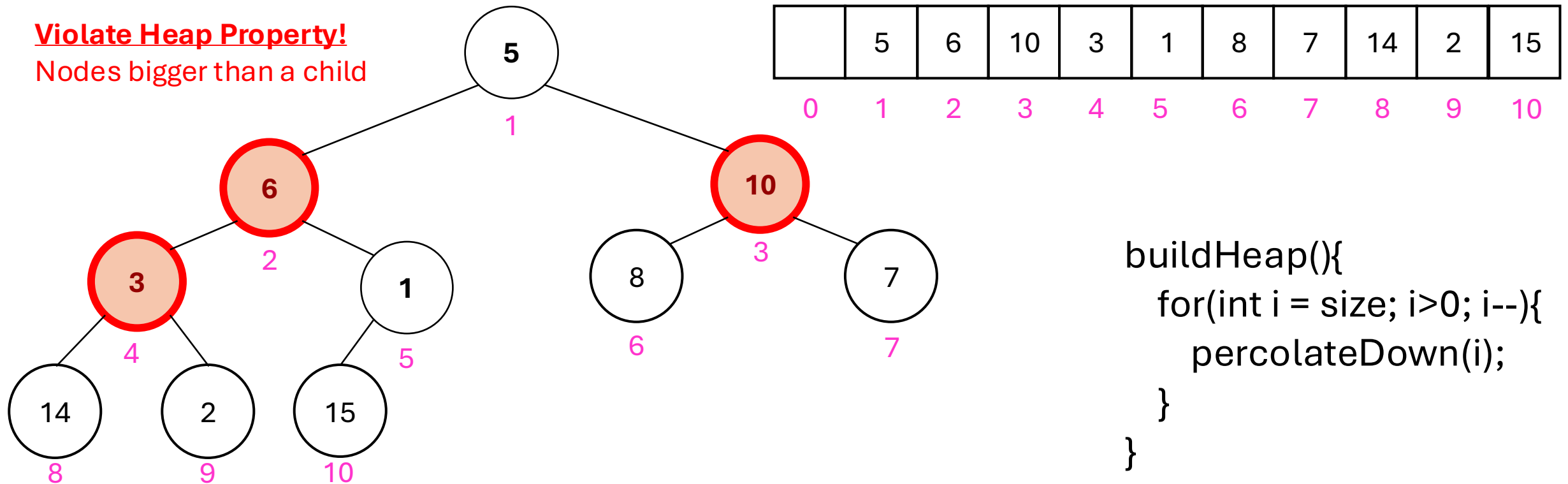
- Suppose we had n items and wanted to “heapify” them



```
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    }  
}
```

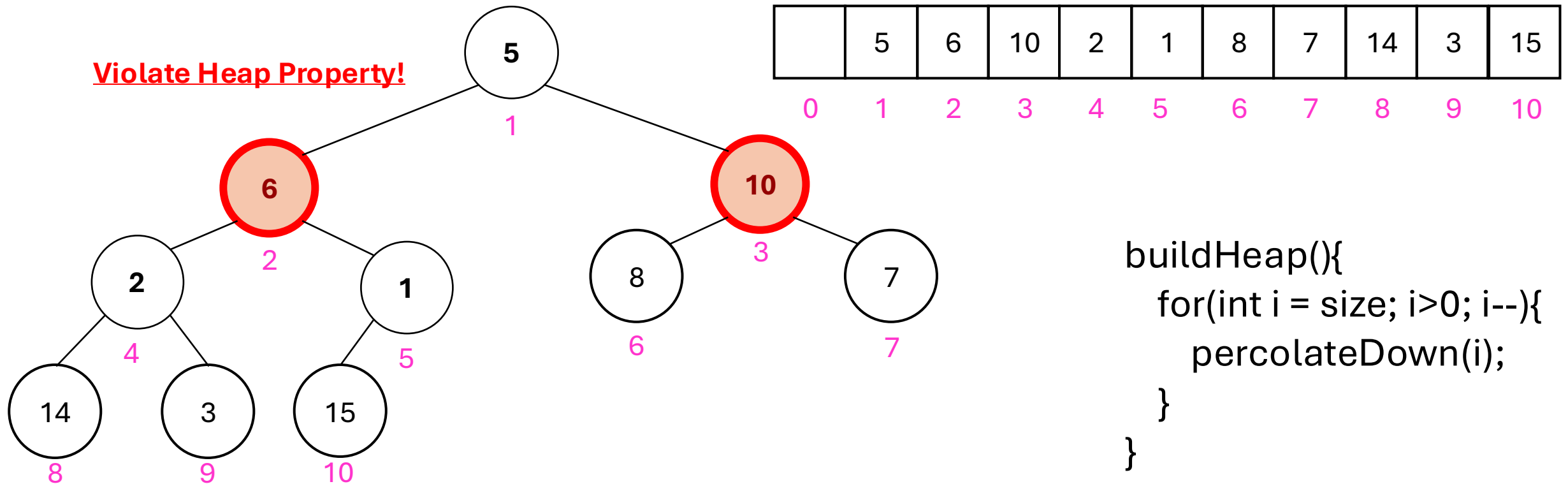
Floyd's buildHeap method (Percolate 3)

- Suppose we had n items and wanted to “heapify” them



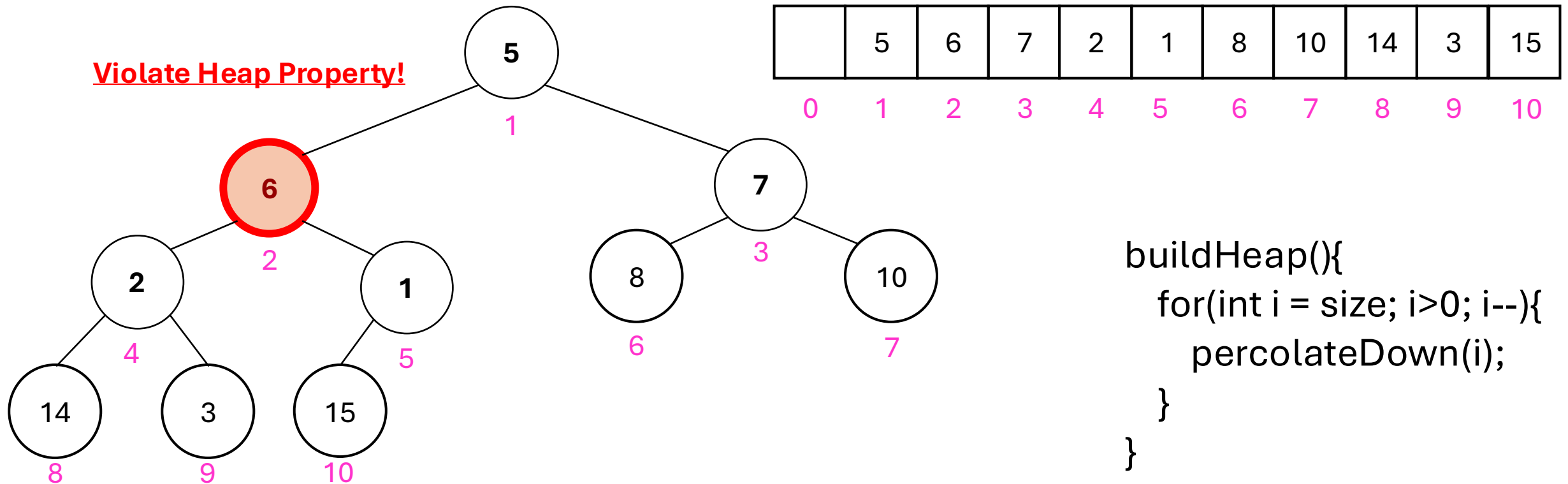
Floyd's buildHeap method (Percolate 10)

- Suppose we had n items and wanted to “heapify” them



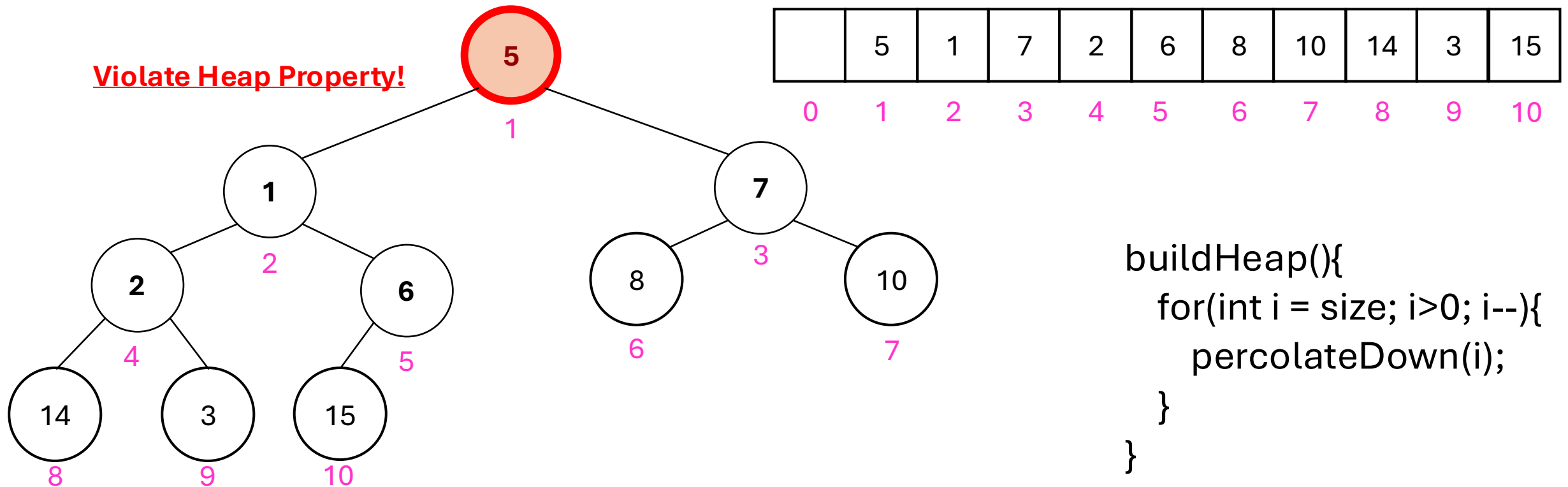
Floyd's buildHeap method (Percolate 6)

- Suppose we had n items and wanted to “heapify” them



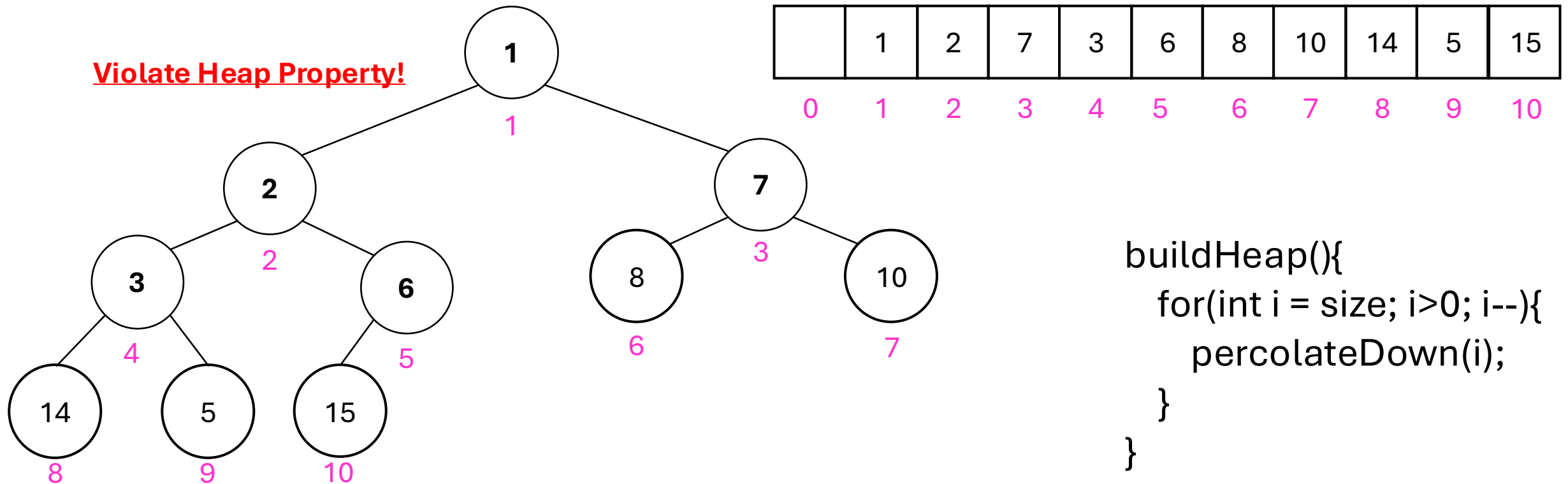
Floyd's buildHeap method (Percolate 5)

- Suppose we had n items and wanted to “heapify” them



Floyd's buildHeap method (Done)

- Suppose we had n items and wanted to “heapify” them



How long did this take?

- Worst case running time of buildHeap:
- No node can percolate down more than the height of its subtree
 - When i is a leaf:
 - When i is second-from-last level:
 - When i is third-from-last level:
- Overall Running time:

```
buildHeap(){  
    for(int i = size; i>0; i--){  
        percolateDown(i);  
    }  
}
```

How long did this take?

- Worst case running time of buildHeap:
- No node can percolate down more than the height of its subtree
 - When i is a leaf ($n/2$ of these): 0 comparisons
 - When i is second-from-last level ($n/4$ of these): ≤ 2 comparisons
 - When i is third-from-last level ($n/8$ of these): ≤ 4 comparisons
 - ...
- Overall Running time:

```
buildHeap(){  
    for(int i = size; i>0; i--){  
        percolateDown(i);  
    }  
}
```

How long did this take?

- Worst case running time of buildHeap: $n \sum_{i=1}^{\log_2(n)} \frac{i}{2^i}$
- No node can percolate down more than the height of its subtree
 - When i is a leaf ($n/2$ of these): 0 comparisons
 - When i is second-from-last level ($n/4$ of these): ≤ 2 comparisons
 - When i is third-from-last level ($n/8$ of these): ≤ 4 comparisons
 - ...

- Overall Running time:

```
buildHeap(){  
    for(int i = size; i>0; i--){  
        percolateDown(i);  
    }  
}
```

A Serious Series Calculation

- **Lemma:** $E := n \sum_{i=1}^{\log_2(n)} \frac{i}{2^i} \in \Theta(n)$
- **Proof:** First term is $n/2$, so $E \in \Omega(n)$ is immediate.

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- Differentiate: $\sum_{i=1}^{\infty} i x^{i-1} = \frac{1}{(1-x)^2}$

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- Differentiate: $\sum_{i=1}^{\infty} i x^{i-1} = \frac{1}{(1-x)^2}$
- Multiply both sides by x : $\sum_{i=1}^{\infty} i x^i = \frac{x}{(1-x)^2}$

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- **Lemma:** $E := n \sum_{i=1}^{\log_2(n)} \frac{i}{2^i} \in \Theta(n)$
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- Multiply both sides by x : $\sum_{i=1}^{\infty} i x^i = \frac{x}{(1-x)^2}$
- Plug in $x = 1/2$: $\sum_{i=1}^{\infty} i/2^i = \frac{1/2}{(1/2)^2} = 2.$

Next up: Dictionaries!

Dictionary (Map) ADT

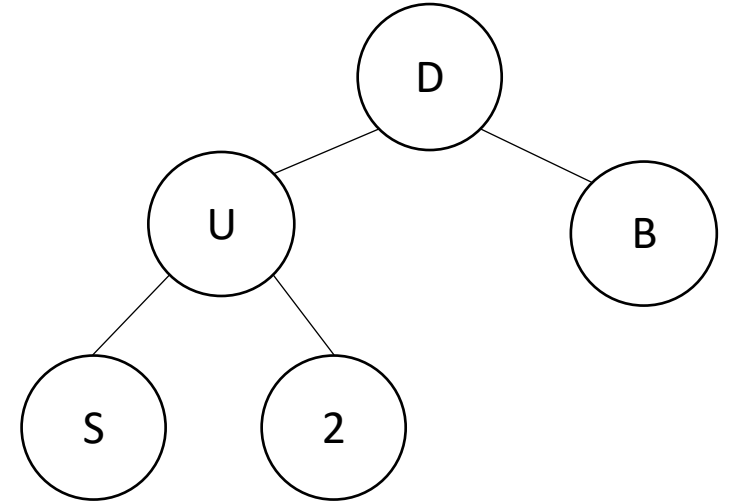
- Contents:
 - Sets of key+value pairs
 - Keys must be comparable
- Operations:
 - **insert(key, value)**
 - Adds the (key,value) pair into the dictionary
 - If the key already has a value, overwrite the old value
 - Consequence: Keys cannot be repeated
 - **find(key)**
 - Returns the value associated with the given key
 - **delete(key)**
 - Remove the key (and its associated value)

Naïve attempts

Data Structure	Time to insert	Time to find	Time to delete
Unsorted Array	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Unsorted Linked List	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Sorted Array	$\Theta(n)$	$\Theta(\log n)$	$\Theta(n)$
Sorted Linked List	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Heap	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Binary Search Tree (worst)	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Binary Search Tree (expected)	$\Theta(\log n)$	$\Theta(\log n)$	$\Theta(\log n)$

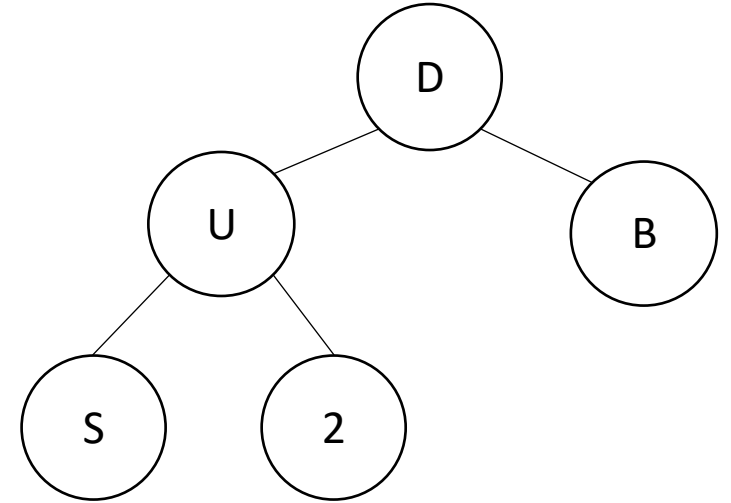
Tree “Vocab”

- Traversal:
 - An algorithm for “visiting/processing” every node in a tree
- Pre-Order Traversal:
 - Root, Left Subtree, Right Subtree
- In-Order Traversal:
 - Left Subtree, Root, Right Subtree
- Post-Order Traversal
 - Left Subtree, Right Subtree, Root

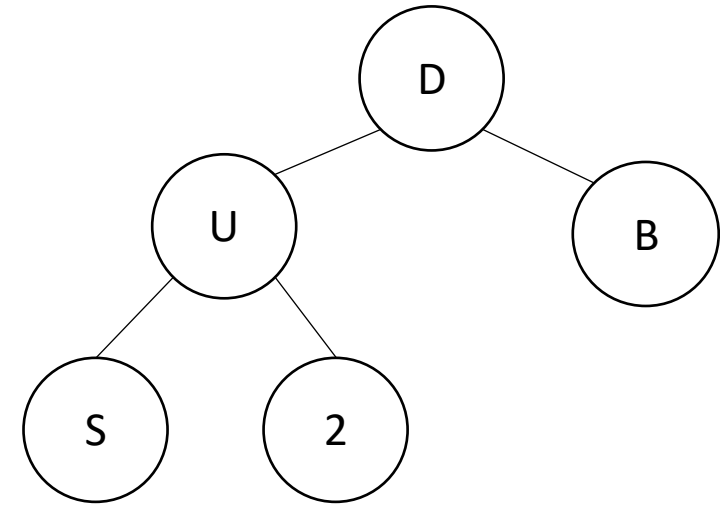


Tree “Vocab”

- Traversal:
 - An algorithm for “visiting/processing” every node in a tree
- Pre-Order Traversal:
 - Root, Left Subtree, Right Subtree
 - D U S 2 B
- In-Order Traversal:
 - Left Subtree, Root, Right Subtree
 - S U 2 D B
- Post-Order Traversal
 - Left Subtree, Right Subtree, Root
 - S 2 U B D



Pre/In/Post Order Trick



Name that Traversal!

```
aOrder(root){  
    if (root.left != Null){  
        aOrder(root.left);  
    }  
    if (root.right != Null){  
        aOrder(root.right);  
    }  
    process(root);  
}
```

```
bOrder(root){  
    process(root);  
    if (root.left != Null){  
        bOrder(root.left);  
    }  
    if (root.right != Null){  
        bOrder(root.right);  
    }  
}
```

```
cOrder(root){  
    if (root.left != Null){  
        cOrder(root.left);  
    }  
    process(root)  
    if (root.right != Null){  
        cOrder(root.right);  
    }  
}
```

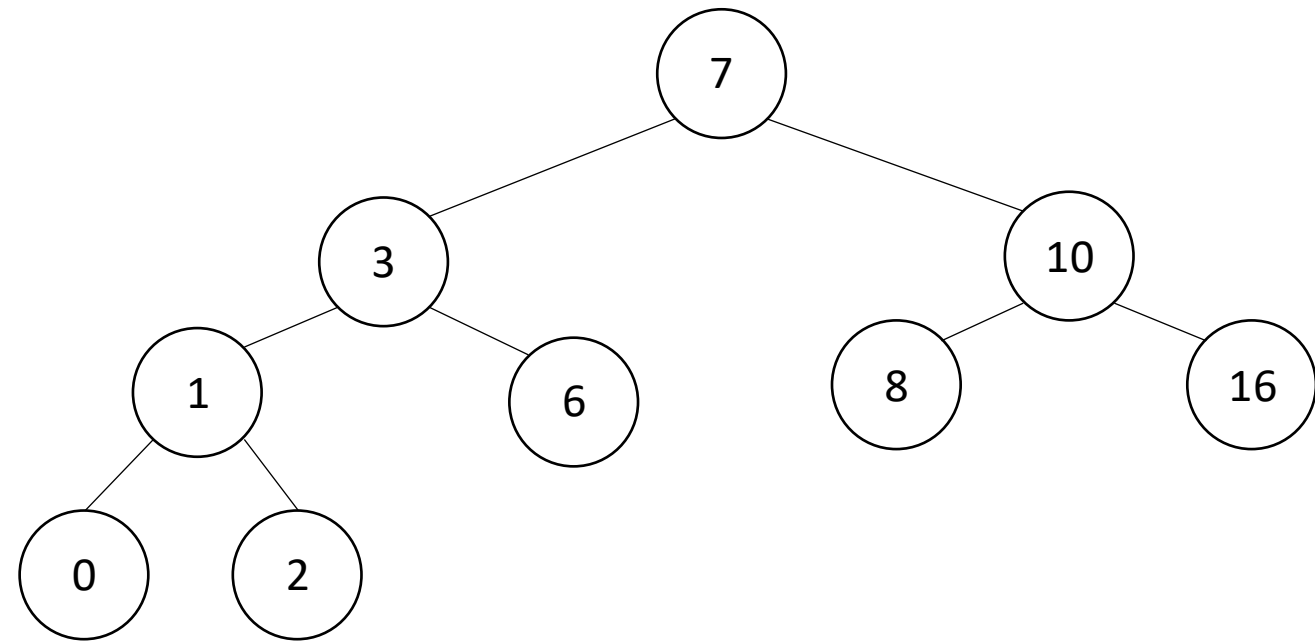
Name that Traversal! (Answers)

```
postOrder(root){  
    if (root.left != Null){  
        postOrder(root.left);  
    }  
    if (root.right != Null){  
        postOrder(root.right);  
    }  
    process(root);  
}
```

```
preOrder(root){  
    process(root);  
    if (root.left != Null){  
        preOrder(root.left);  
    }  
    if (root.right != Null){  
        preOrder(root.right);  
    }  
}
```

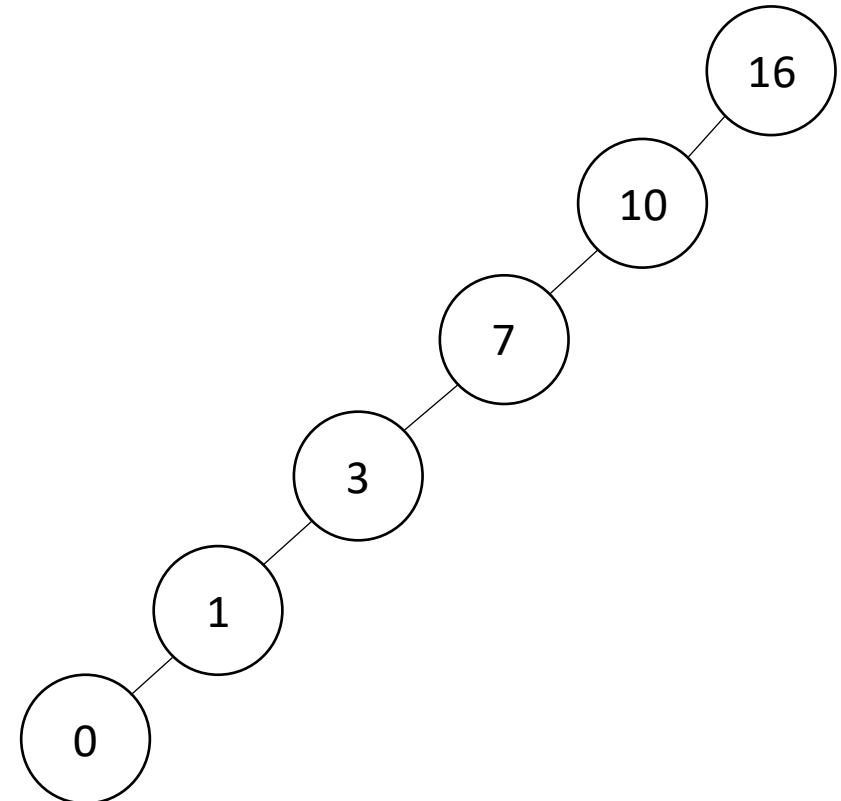
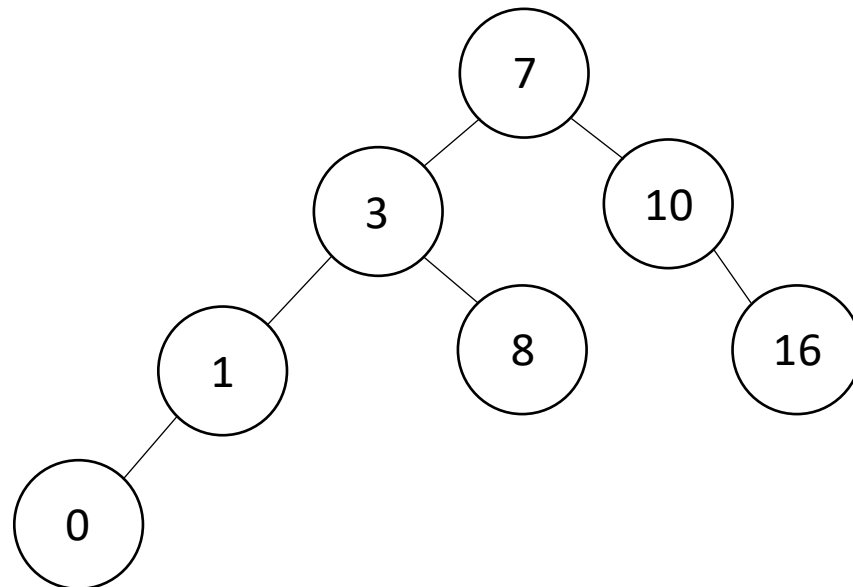
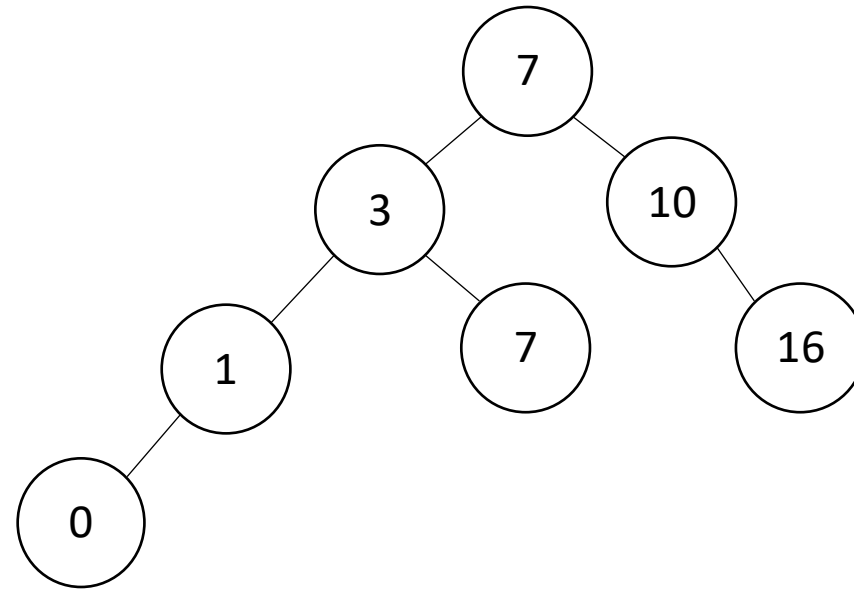
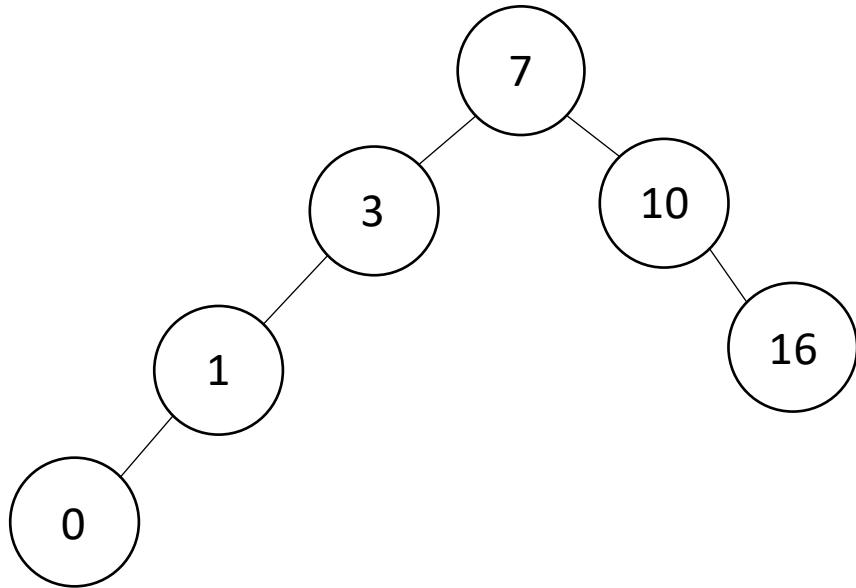
```
inOrder(root){  
    if (root.left != Null){  
        inOrder(root.left);  
    }  
    process(root)  
    if (root.right != Null){  
        inOrder(root.right);  
    }  
}
```

Binary Search Tree

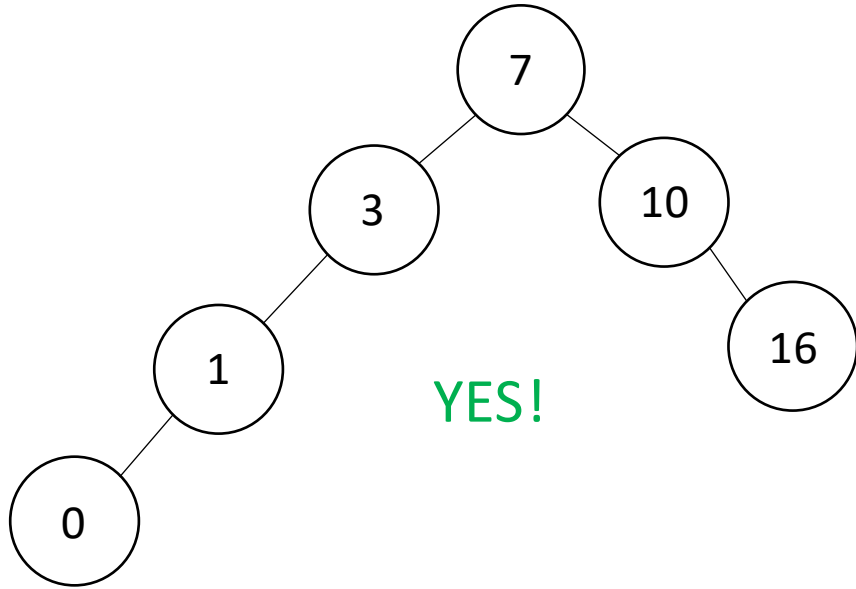


- **Binary Tree**
 - Definition:
 - Tree where each node has at most 2 children
- **Order Property**
 - All keys in the left subtree are smaller than the parent
 - All keys in the right subtree are larger than the parent
 - **Consequence:** cannot have repeated values

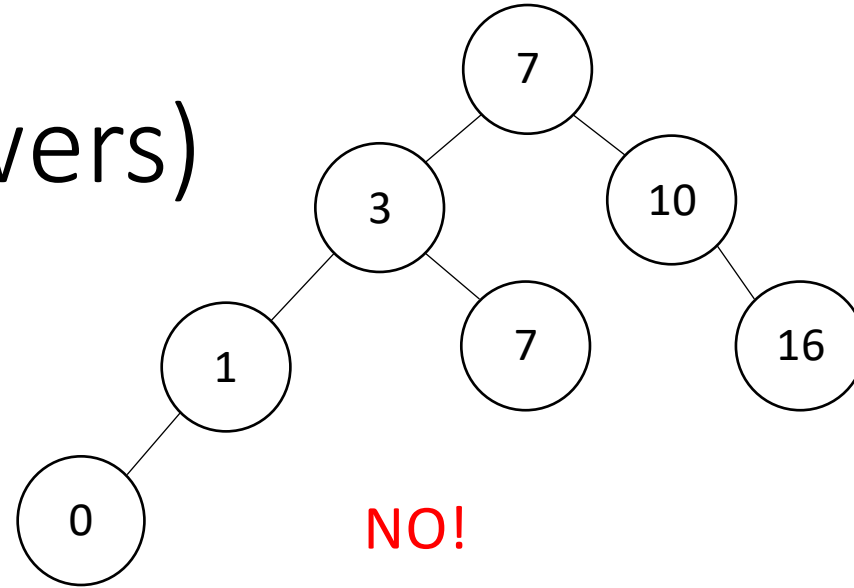
Are these BSTs?



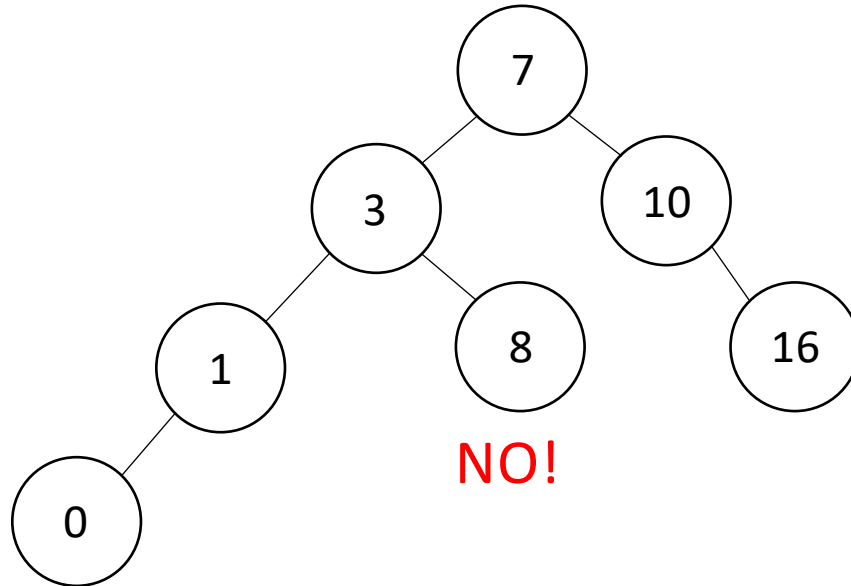
Are these BSTs? (Answers)



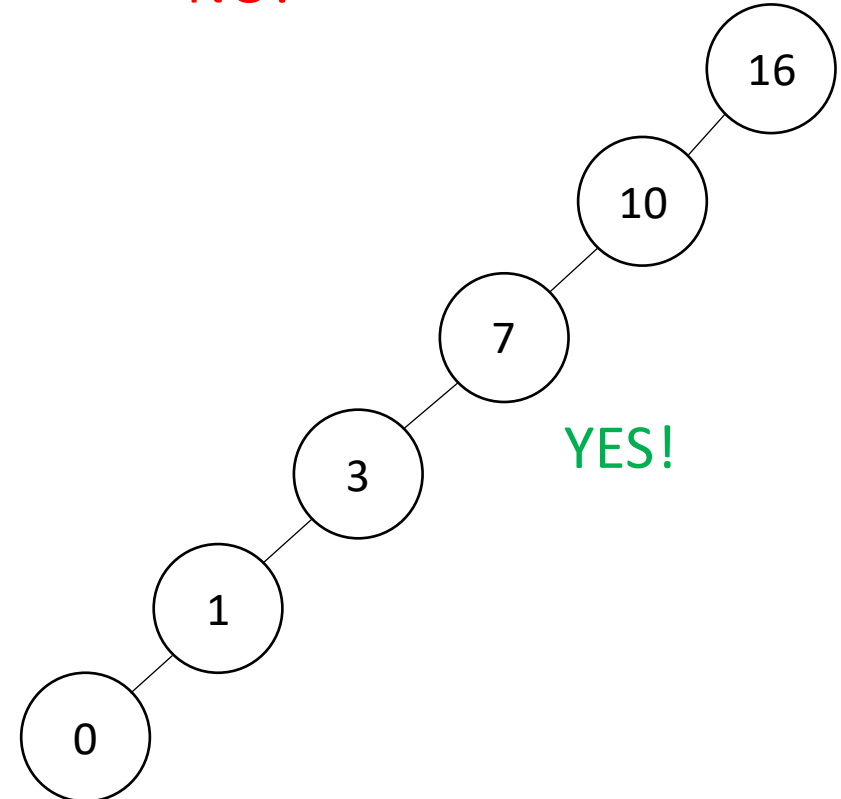
YES!



NO!



NO!



YES!

Aside: Why not use an array?

- We represented a heap using an array, finding children/parents by index
- We will represent BSTs with nodes and references. Why?
 - We might have “gaps” in our tree
 - Memory!
 - 2^n

Find Operation (recursive)

find(key, root):

IF (root == Null):

 RETURN Null

IF (key == root.key):

 RETURN root.value

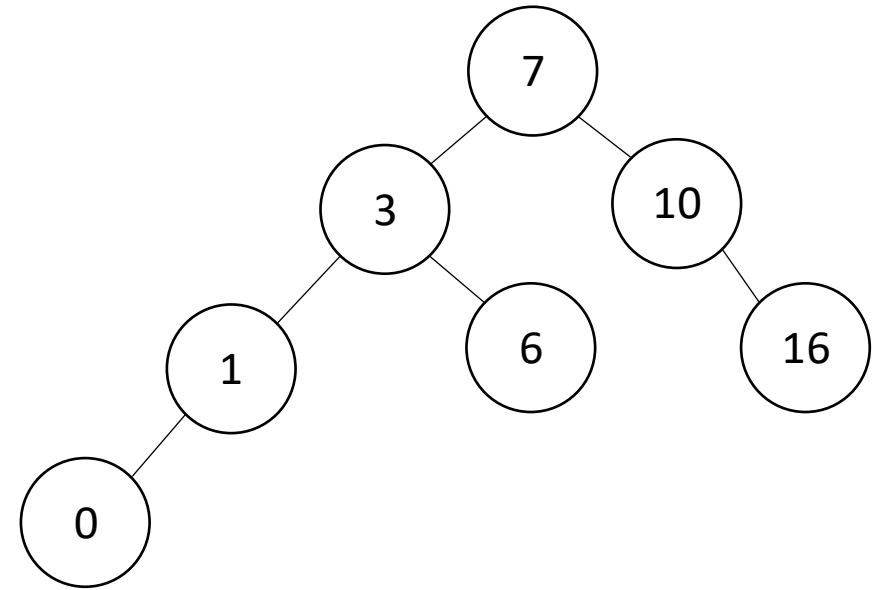
ELSE IF (key < root.key):

 RETURN **find**(key, root.left)

ELSE IF (key > root.key):

 RETURN **find**(key, root.right);

RETURN Null



Find Operation (iterative)

find(key, root):

 WHILE (root $\neq$ Null AND key $\neq$ root.key):

 IF (key < root.key):

 root = root.left

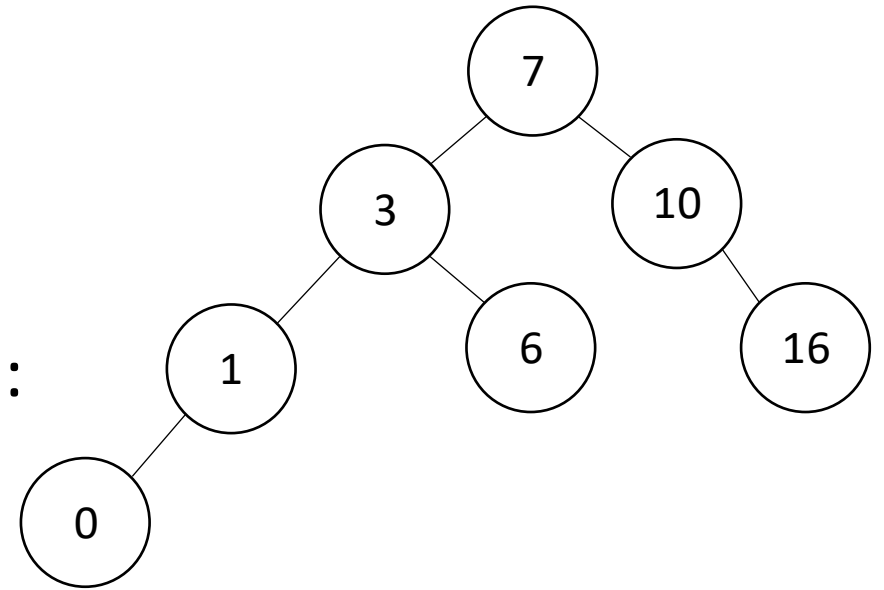
 ELSE IF (key > root.key):

 root = root.right

IF (root == Null):

 RETURN Null

RETURN root.value



Insert Operation (recursive)

insert(key, value, root):

 root = insertHelper(key, value, root)

insertHelper(key, value, root){

 IF (root == null):

 RETURN new Node(key, value)

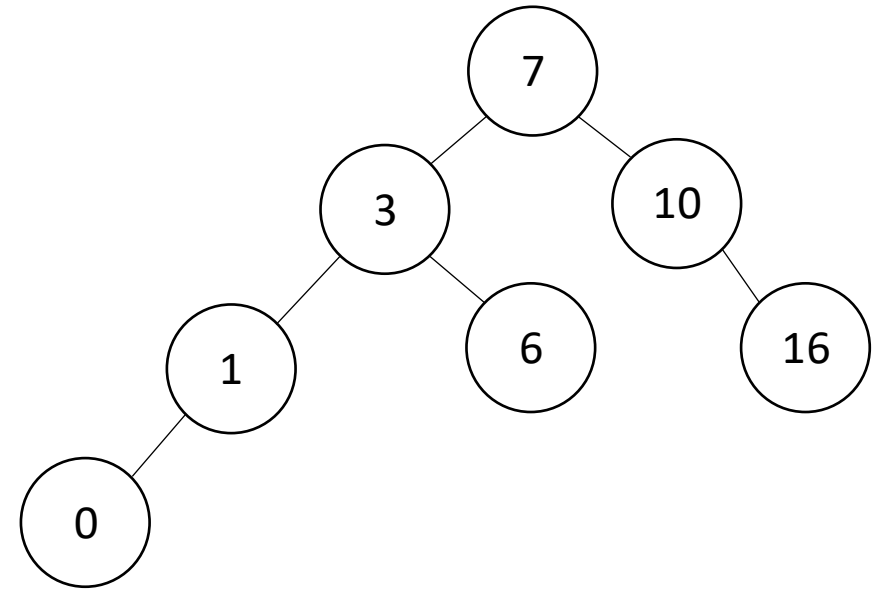
 IF (root.key < key):

 root.right = **insertHelper**(key, value, root.right)

 ELSE:

 root.left = **insertHelper**(key, value, root.left)

 RETURN root



Note: Insert happens only at the leaves!

Insert Operation (iterative)

insert(key, value, root):

IF (root == Null):

 root = new Node(key, value)

parent = Null

WHILE (root $\neq$ Null AND key $\neq$ root.key):

 parent = root

 IF (key < root.key):

 root = root.left

 ELSE IF (key > root.key):

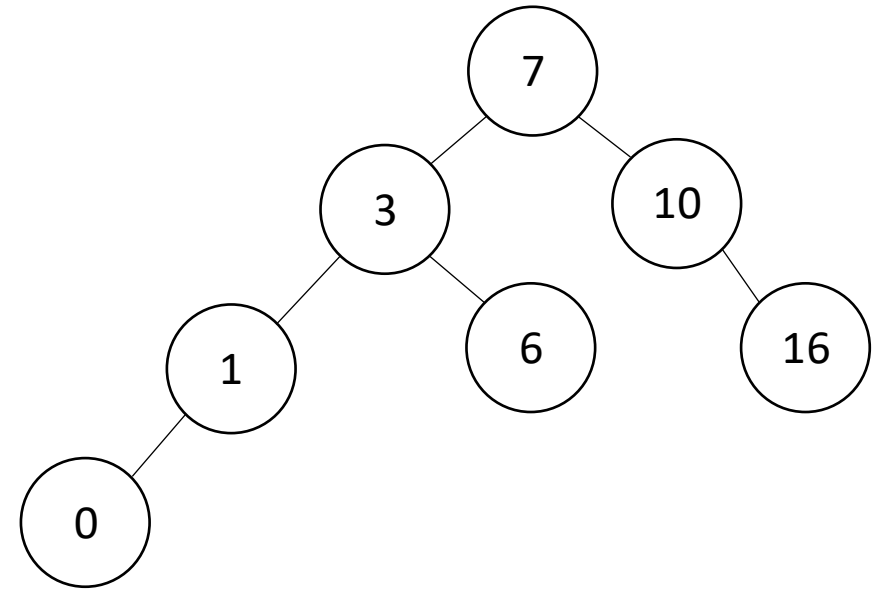
 root = root.right

IF (key == root.key) THEN root.value = value

ELSE IF (key < parent.key) THEN parent.left = new Node(key, value)

ELSE: parent.right = new Node (key, value)

Note: Insert happens only at the leaves!



Delete Operation (iterative, incomplete)

delete(key, root):

WHILE (root $\neq$ Null AND key $\neq$ root.key):

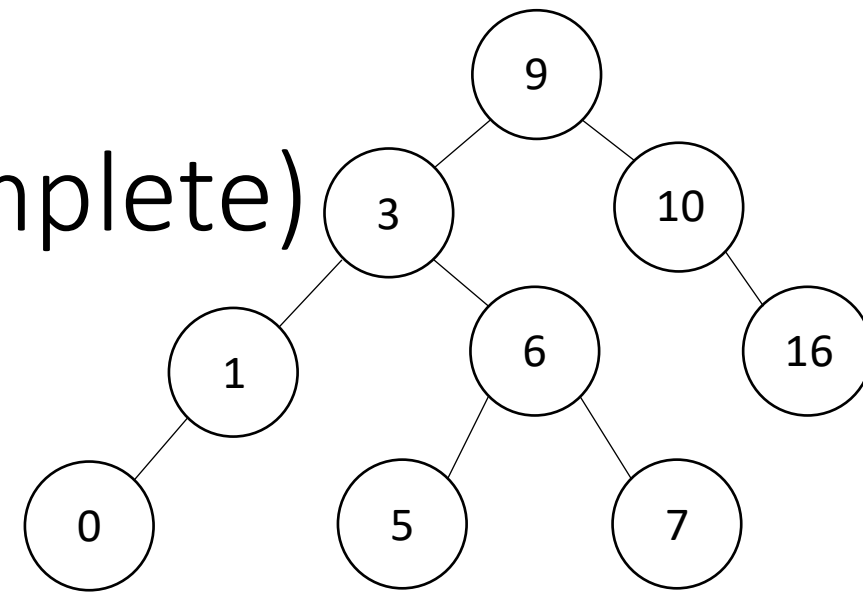
IF (key < root.key) THEN root = root.left

ELSE IF (key > root.key) THEN root = root.right

IF (root == Null) THEN RETURN

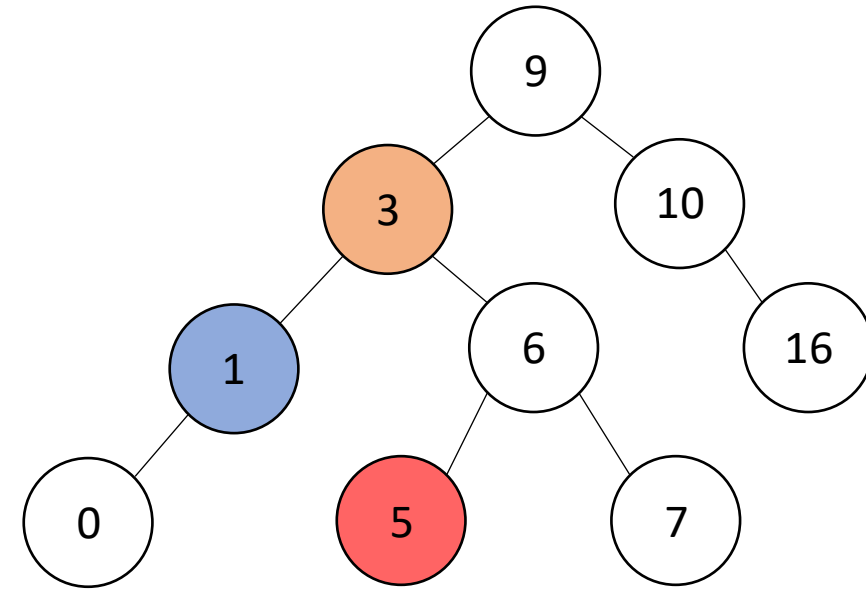
// Now we have found the node to delete, what happens next?

}



Delete – 3 Cases

- 0 Children (i.e. it's a leaf)
- 1 Child
 - Replace the deleted node with its child
- 2 Children
 - Replace the deleted with the largest node to its left or alternatively the smallest node to its right

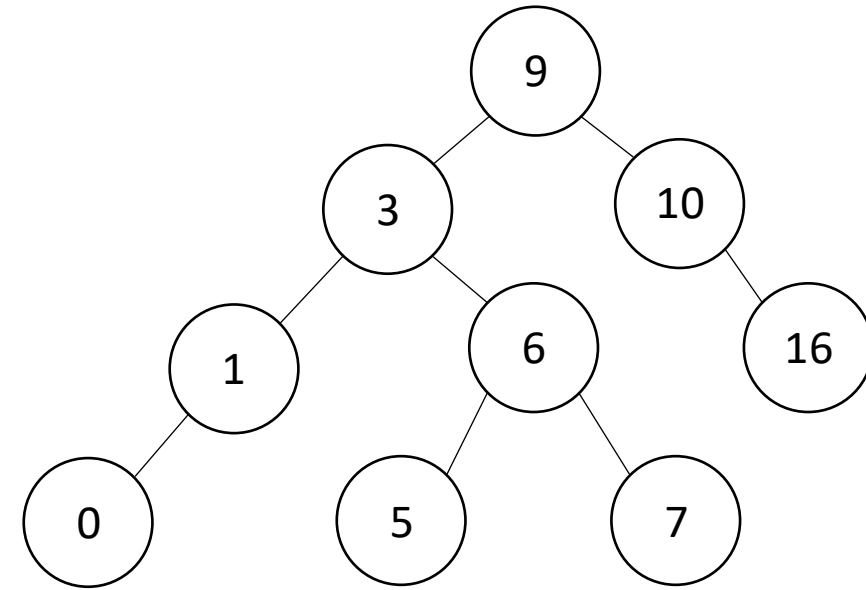


Finding the Max and Min

- Max of a BST:
 - Right-most Thing
- Min of a BST:
 - Left-most Thing

```
maxNode(root):  
    IF (root == Null):  
        RETURN Null  
    WHILE (root.right ≠ Null):  
        root = root.right  
    RETURN root
```

```
minNode(root){  
    IF (root == Null)  
        return Null  
    WHILE (root.left ≠ Null):  
        root = root.left  
    RETURN root
```



Delete Operation (iterative)

delete(key, root):

WHILE (root $\neq$ Null AND key $\neq$ root.key):

IF (key < root.key):

root = root.left

ELSE IF (key > root.key):

root = root.right

IF (root == Null) THEN RETURN

IF (root has no children):

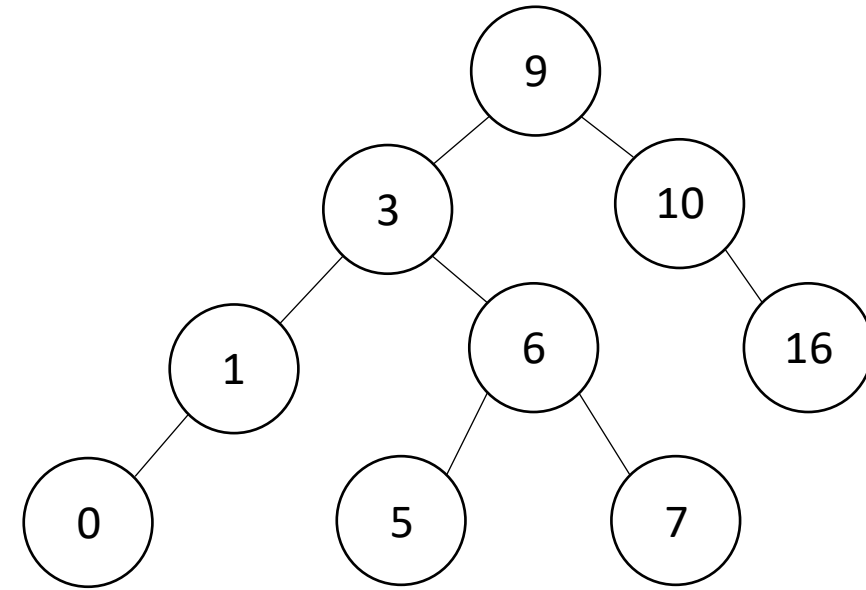
make parent point to Null Instead

IF (root has one child):

make parent point to that child instead

IF (root has two children):

make parent point to either the max from the left or min from the right



Delete Operation (recursive)

```
delete(key, root){
```

```
  IF (root == Null) THEN RETURN // key not present
```

```
  IF (root.key == key):
```

```
    IF (root has no children):
```

```
      RETURN Null
```

```
    IF (root has one child):
```

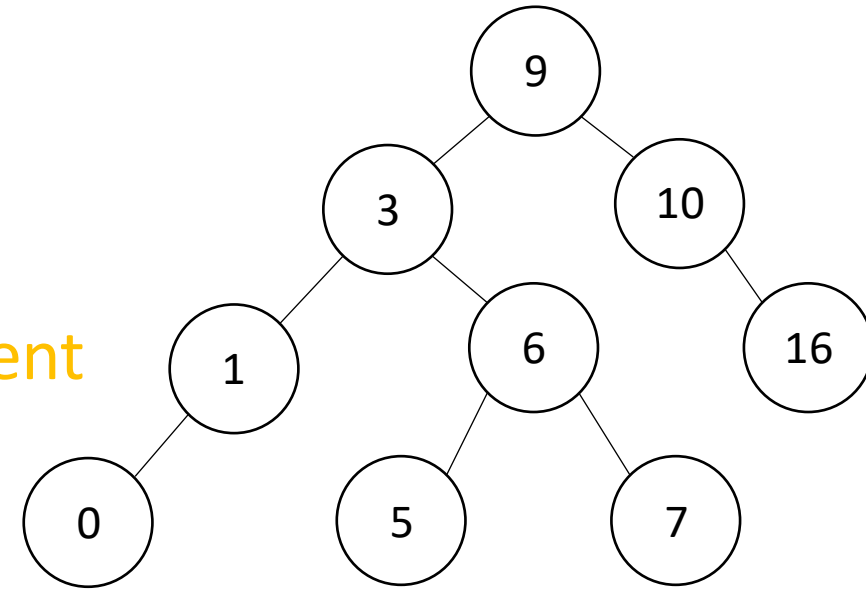
```
      RETURN that child
```

```
    IF (root has two children)
```

```
      RETURN removeMax(root.left)
```

```
  IF (root.key < key): THEN root.right = delete(key, root.right)
```

```
  ELSE: root.left = delete(key, root.left)
```



Worst Case Analysis

- For each of Find, insert, Delete:
 - Worst case running time matches height of the tree
- What is the maximum height of a BST with n nodes?
 - $\Theta(n)$

Improving the worst case

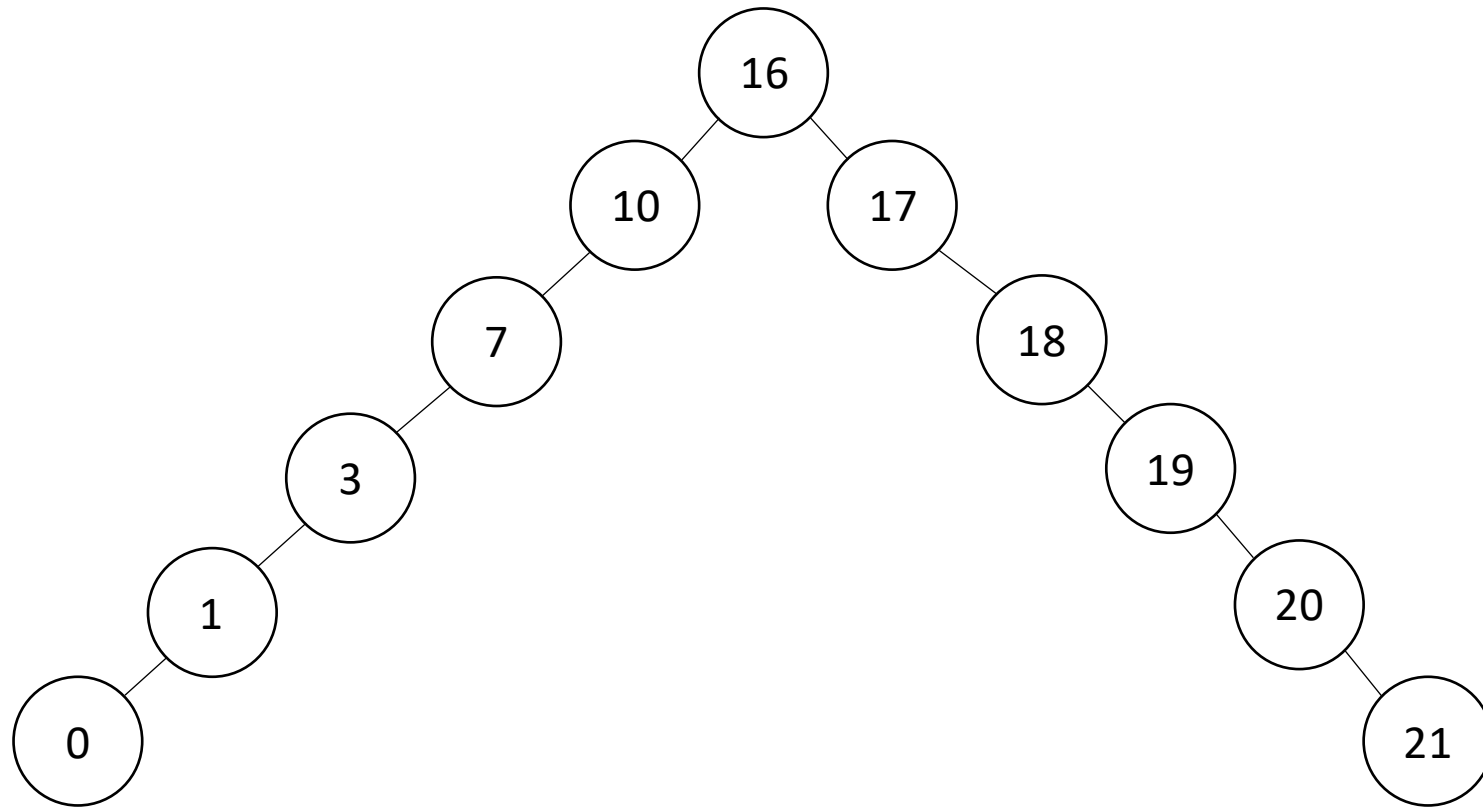
- How can we get a better worst case running time?
 - Add rules about the shape of our BST
- AVL Tree
 - A BST with some shape rules
 - Algorithms need to change to accommodate those

“Balanced” Binary Search Trees

- We get better running times by having “shorter” trees
- Trees get tall due to them being “sparse” (many one-child nodes)
- Idea: modify how we insert/delete to keep the tree more “full”
 - Encourage Branches!

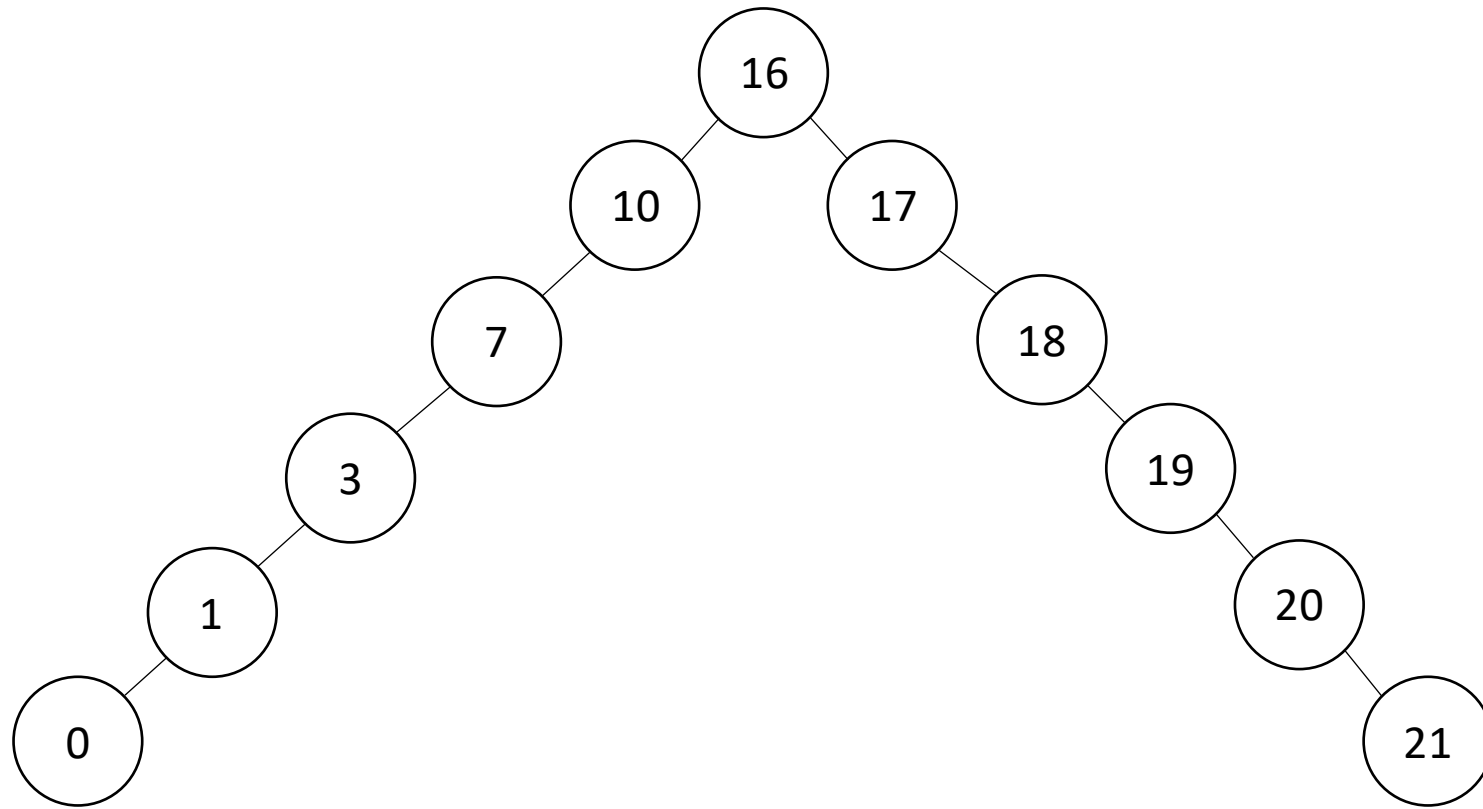
Idea 1: Both Subtrees of Root have same #
Nodes

Idea 1: Both Subtrees of Root have same #
Nodes - Issue



Idea 2: Both Subtrees of Root have same height

Idea 2: Both Subtrees of Root have same height - Issue



Idea 3: Both Subtrees of every Node have same # Nodes

Idea 3: Both Subtrees of every Node have same # Nodes - Issue

Not all tree sizes are possible!

For example, cannot have a tree of size 2.

Idea 4: Both Subtrees of every Node have same height

Idea 4: Both Subtrees of every Node have same height - Issue

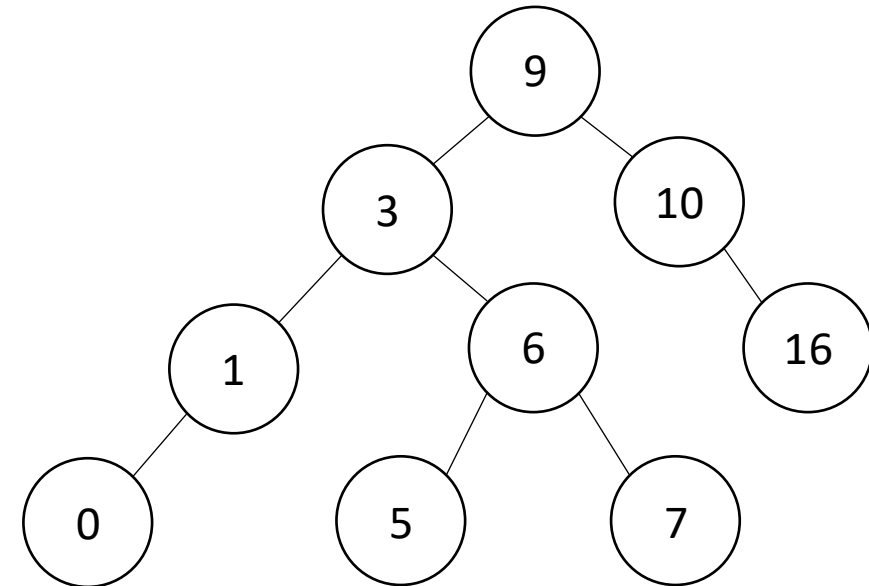
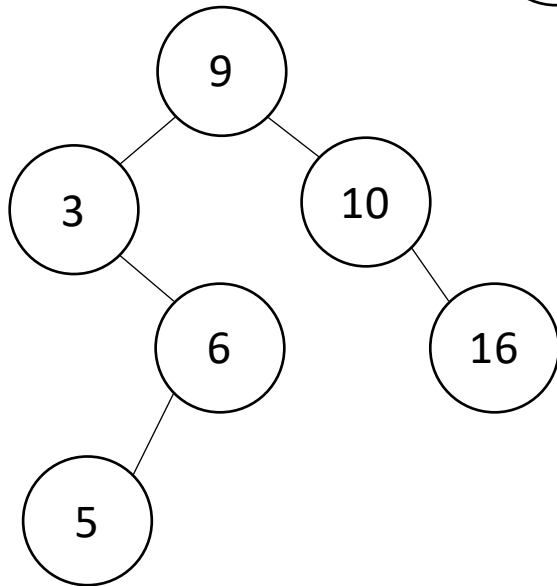
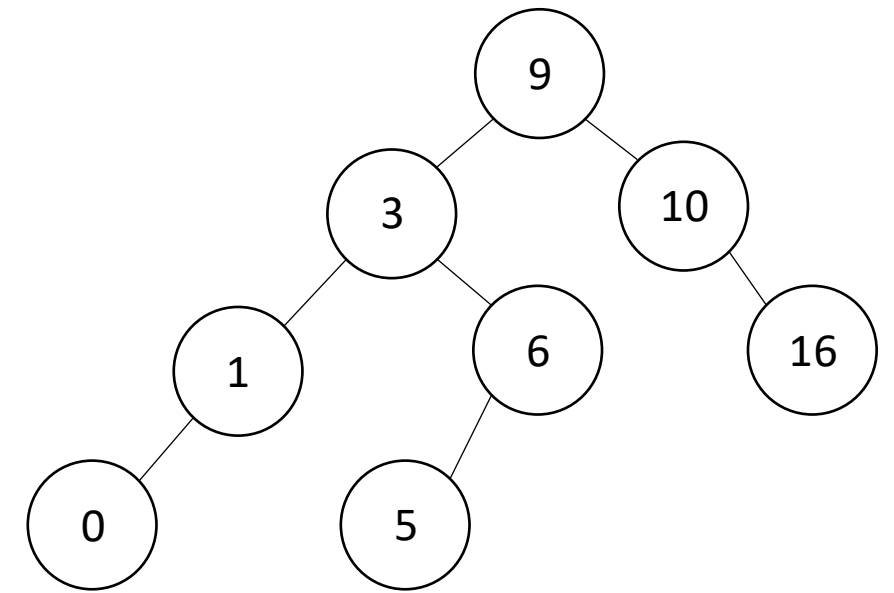
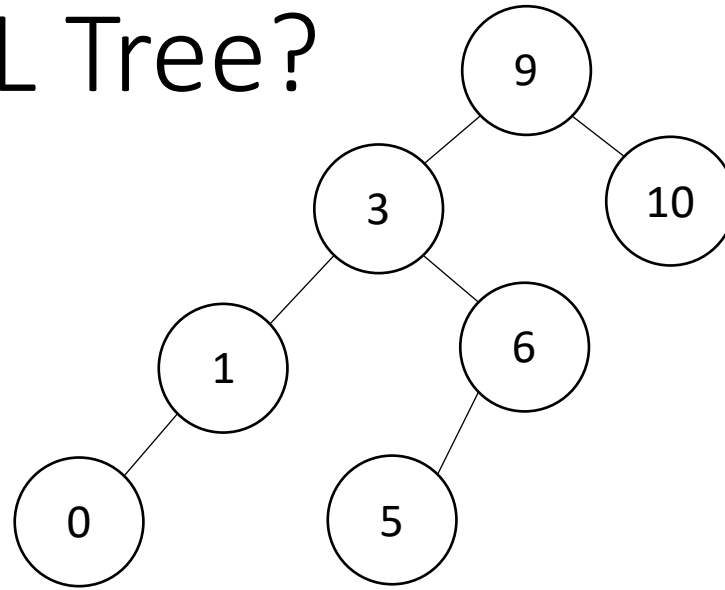
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For example, cannot have a tree of size 2.

AVL Tree

- A Binary Search tree that maintains that the left and right subtrees of every node have heights that differ by at most one.
 - height of left subtree and height of right subtree off by at most 1
 - Not too weak (ensures trees are short)
 - Not too strong (works for any number of nodes)
- Idea of AVL Tree:
 - When you insert/delete nodes, if tree is “out of balance” then modify the tree
 - Modification = “rotation”

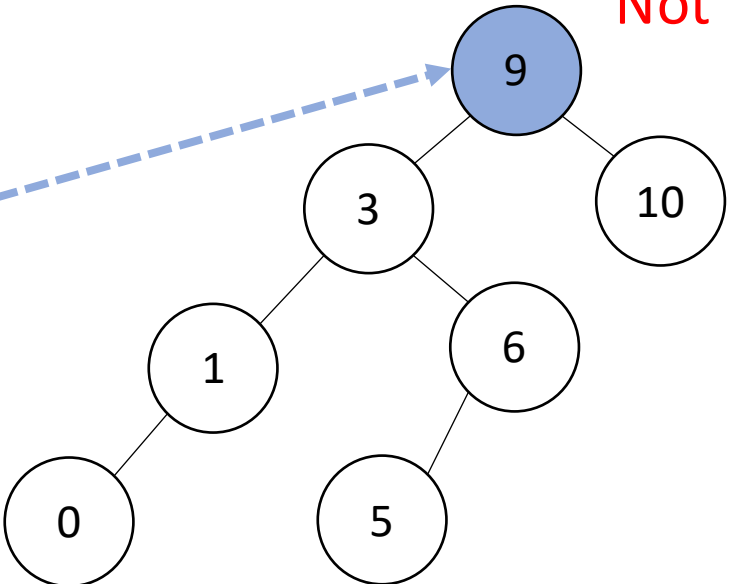
Is it an AVL Tree?



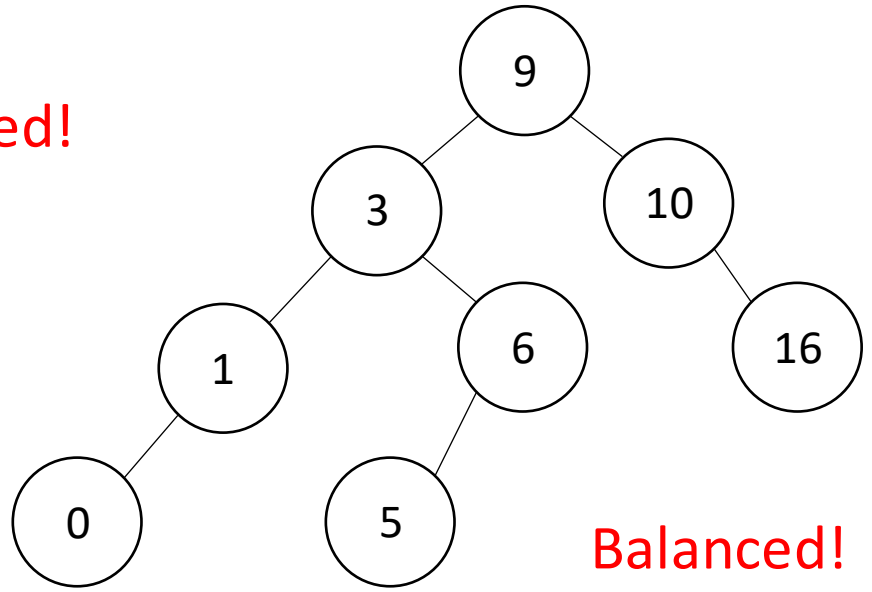
Is it an AVL Tree? (Answers)

“Problem” Node
Its children’s heights differ by more than 1

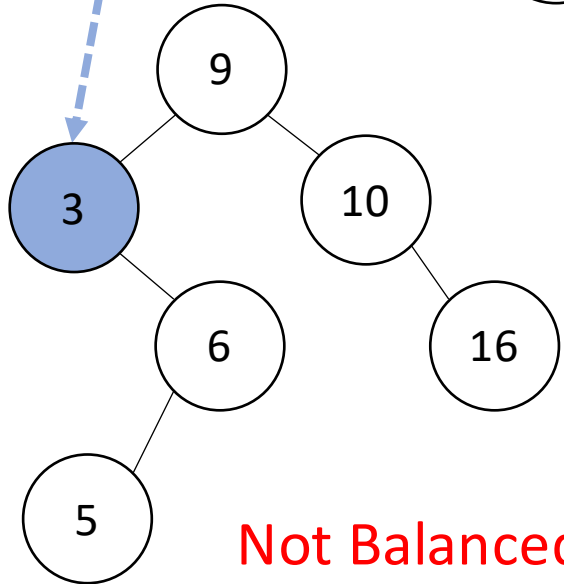
Not Balanced!



Balanced!



Not Balanced!



Balanced!

