

Lecture 13 (Graphs 2)

Def (Undirected) $G = (V, E)$

$V =$ set of vertices/nodes

$V = \{1, 2, 3, 4, 5, 6\}$

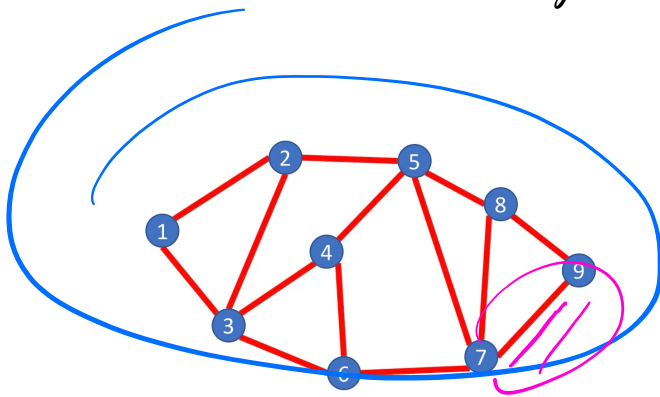
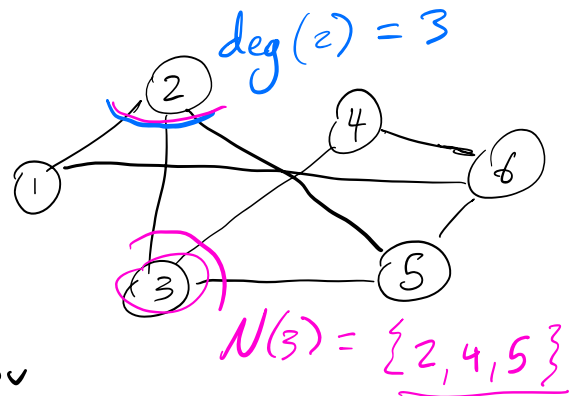
$E = \{(1, 2), (1, 6), (4, 6), \dots\}$

degree

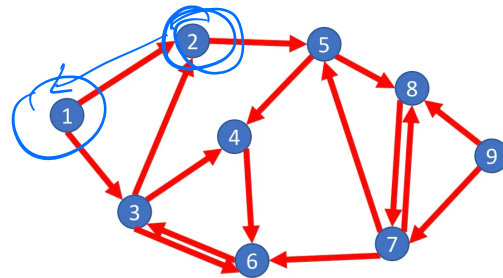
$\deg(v) = \#$ of edges touching v .

neighbors/adjacent:

$N(v) =$ all nodes connected with v single edge to v



Connected



Not (strongly) Connected

But is "weakly" connected.

maximum # of edges?

undirected, simple:

$$\frac{n \cdot (n-1)}{2}$$

$\Rightarrow$ n choices for 1st vertex in edge
 $n-1$ choices for 2nd

directed, simple:

$$n \cdot (n-1)$$

it self loops? n^2

$\Theta(n^2)$

"dense": $\Omega(n^2)$

"sparse": $O(n)$ edges or $o(n^2)$

In general, $|E|$ and $|V|$ very different, so runtime should be a function of both $|E|$ and $|V|$

usually $\log |E| = O(\log |V|)$

But

$$|E| \neq O(|V|)$$

question: if G connected, min # of edges?

$$n-1$$

proof] Base case ✓

start with $n+1$ vtx graph, remove arbitrary vtx u

in general, m connected components. $C_1, \dots, C_m$
each C_i requires $v_i - 1$ edges by induction.

$$v_i = \text{vtx in } C_i$$

$$\leq v_i - 1$$

u must connect to every C_i

m edges

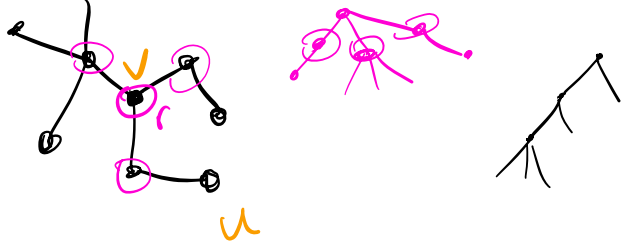
$$m + \sum_{i=1}^m (v_i - 1) = \sum v_i = n$$

$$\left(\sum_{i=1}^m v_i \right) - m$$

trees have $n-1$ edges

Def] (Tree)

A graph with no cycles.



Graph ADT

nodes with edges in between

weighted?

directed?

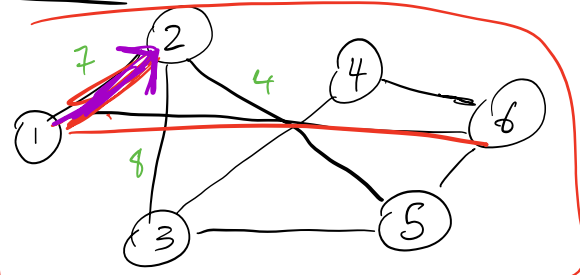
simple?

operations

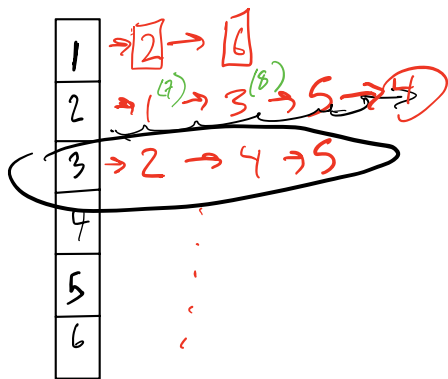
- addEdge
- removeEdge
- exists
- getNeighbors
- removeVertex
- shortestPath.

Data Structures for graphs?

$$G = (V, E) =$$



Adjacency List



$$n := |V| \quad m := |E|$$

memory? $O(n+m)$

Runtimes

addEdge? $\Theta(\deg(v))$
 removeEdge? $\Theta(\deg(v))$
 exists? $\Theta(\deg(v))$
 getNeighbors?
 outgoing $\Theta(\deg(v))$
 incoming $\Theta(n+m)$

worst $O(\min(m, n))$

Adjacency Matrix

	1	2	3	4	5	6
1		7				1
2	7		8		4	
3		8				
4						
5		4				
6	1					

outgoing for 5
incoming for 5

memory? $O(n^2)$

Runtimes

addEdge? $O(1)$
 removeEdge? $O(1)$
 exists? $O(1)$
 getNeighbors?
 outgoing $O(n)$
 incoming $O(n)$

Adjacency list perhaps most common in practice
 many graphs are relatively sparse

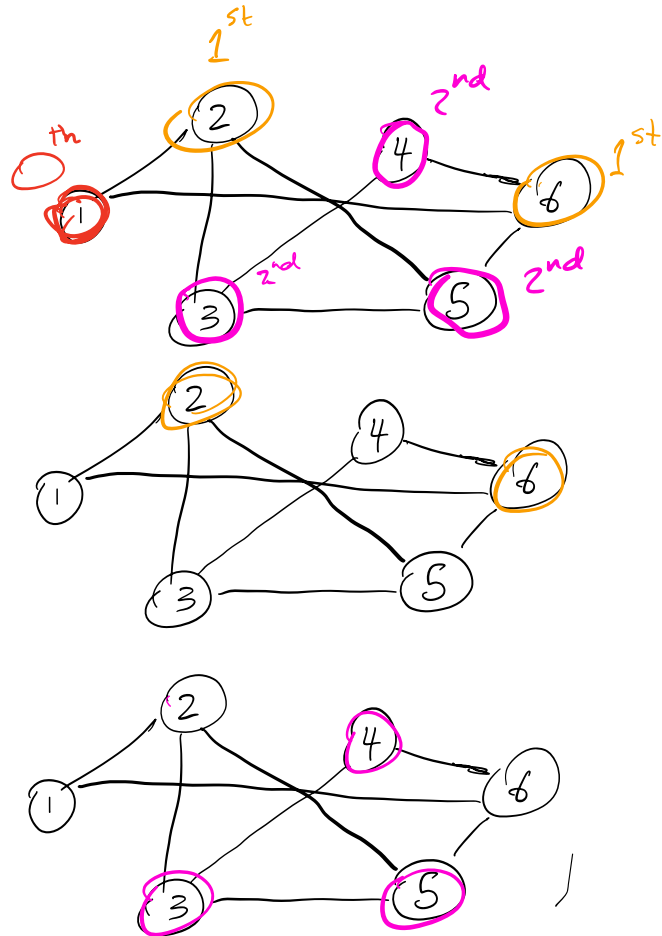
Graph traversals

question: given G , how can/should I visit all the vertices?

Breadth first Search

Idea: pick source node v

- 1) process all nodes 1 away from v
all neighbors
- 2) process all nodes 2 away from v
all neighbors' neighbors
- 3) " " 3 " "
- ...



What can we learn?

shortest path!

BFS Pseudocode

bfs (G, v):

found = new empty queue

found.enqueue (v)

mark v as "visited"

while found is not empty:

curr = found.dequeue()

for u in neighbors(curr):

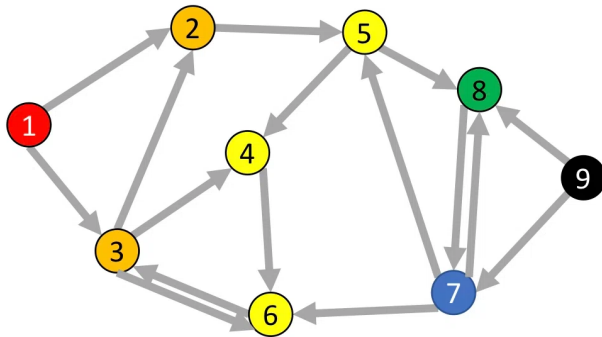
if u not visited already
 found.enqueue(u)
 mark u as "visited"

runtime?

$O(|V| + |E|)$

connected graph $O(|E|)$

Ex



queue:

node	visited?	depth
1	True	0
2		
3		
4		
5		
6		
7		
8		
9		

Find Distance Pseudocode

findDistance(h, s, t)

found = new empty queue

layer = 0

found.enqueue(s)

mark s as "visited"

while found is not empty:

curr = found.dequeue

layer =

for u in neighbors(curr):

if u not visited:

found.enqueue(u)

mark u as "visited"

depth(u) =

return depth(t)

Shortest (unweighted) path?

Depth First Search

Idea: explore each path as deep as possible:

- 1) visit start node s
- 2) visit a neighbor of s , then all nodes reachable from that neighbor,
- 3) repeat with next neighbor

What can we learn from this?

DFS non-recursive Pseudocode

$\text{dfs}(G, s)$:

found = new empty **stack**

found. **push** (s)

mark s as "visited"

while found is not empty:

 curr = _____

 for u in _____:

 if _____:

 found. **P** (u)

 mark u as "visited"

runtime?

recursive implementation?

$dfs(G, curr):$

mark curr as "visited"

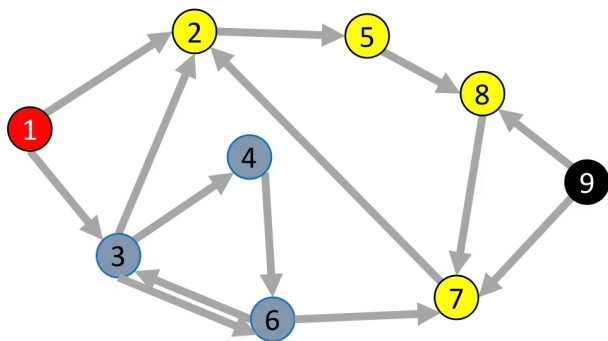
for u in _____:

if _____:

$dfs(G, u)$

mark curr as "done"

Ex



call stack :

--

node visited? done? other...

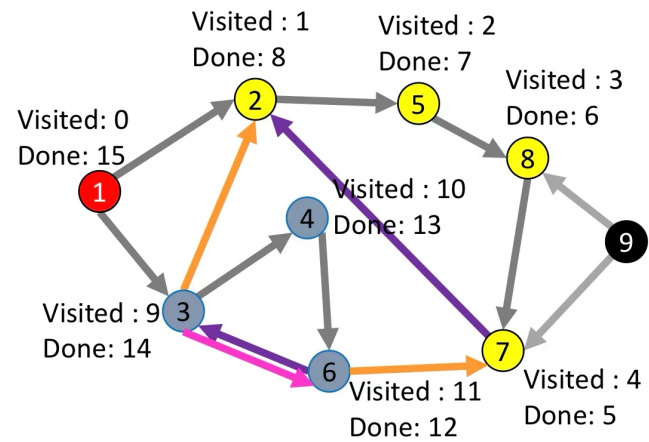
1	True	0	
2			
3			
4			
5			
6			
7			
8			
9			

characterizing Edges in DFS

Tree Edges

cross edges $t_{done}(b) < t_{visit}(a)$

forward edges $t_{\text{visit}}(a) \leq t_{\text{visit}}(b) \leq t_{\text{done}}(b) < t_{\text{done}}(a)$



back edges $t_{\text{visit}}(b) < t_{\text{visit}}(a) \leq t_{\text{done}}(a) < t_{\text{done}}(b)$

current nodes neighbor is "in progress" / reachable



Cycle Detection

idea: look for a back edge!

cycleDetect (G, curr):

mark curr as "visited"

cycleFound = False

for u in neighbors(curr):

if u visited but not done:
cycleFound = True

if u not visited and not cycleFound:

cycleFound = cycleDetect(G, u)

mark curr as "done"

return cycleFound

hasCycle(G)

for each node v :

if v not done:

if hasCycle(G, v):
return True

return False