CSE 332 Spring 2026
Lecture 13: Sorting 2

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http://www.cs.uw.edu/332

Sorting

- Rearrangement of items into some defined sequence
  - Usually: reordering a list from smallest to largest according to some metric
- Why sort things?
  - Enable things like binary search
    - It makes some algorithms faster
  - Nicer for human algorithms too
  - Data organization

More Formal Definition

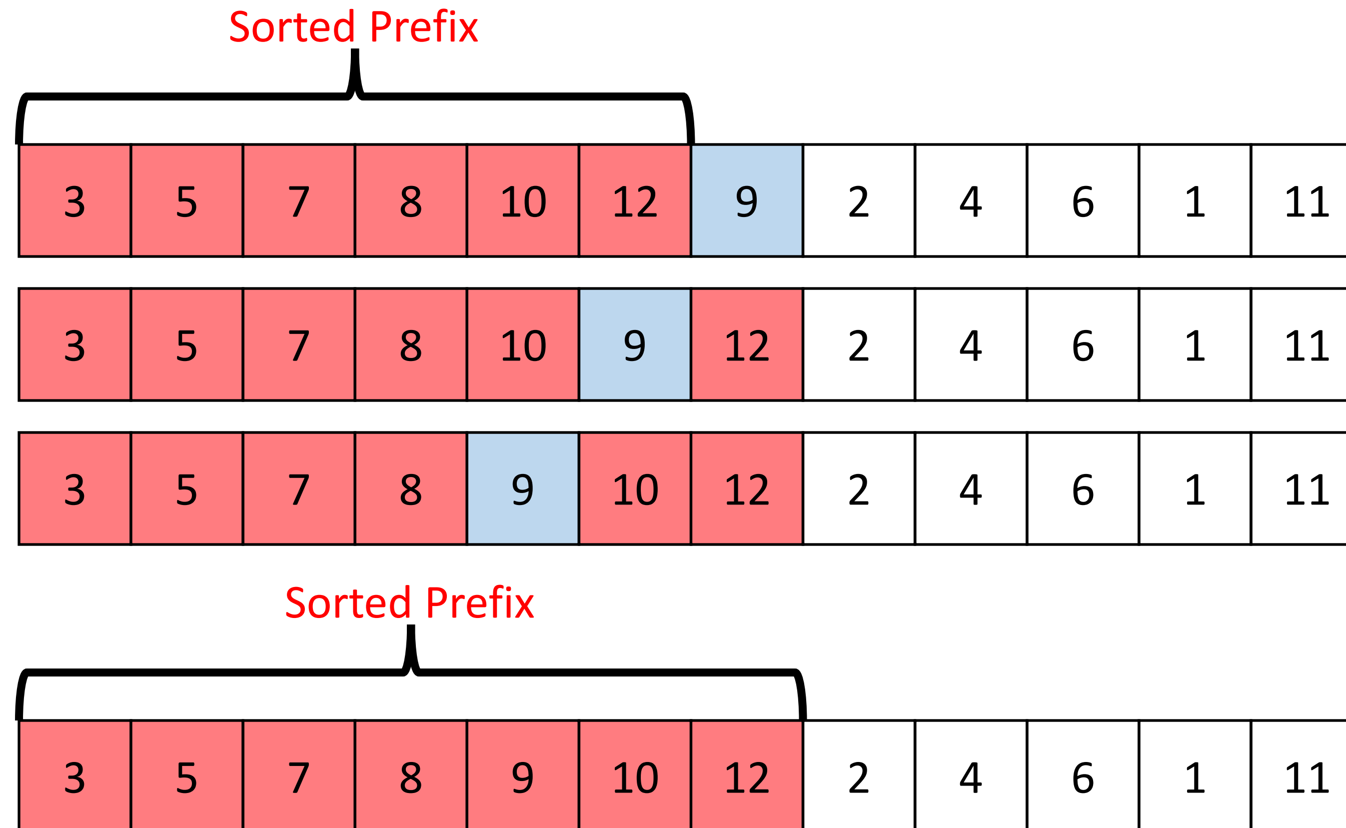
- Input:
  - An array A of items
  - A comparison function for these items
    - Given two items x and y, we can determine whether $x < y$, $x > y$, or $x = y$
- Output:
  - A permutation of A such that if $i \leq j$ then $A[i] \leq A[j]$
  - Permutation: a sequence of the same items but perhaps in a different order

Sorting “Landscape”

- There is no singular best algorithm for sorting
- Some are faster, some are slower
- Some use more memory, some use less
- Some are super extra fast if your data matches particular assumptions
- Some have other special properties that make them valuable
- No sorting algorithm can have only all the “best” attributes

Insertion Sort

- Idea: Maintain a sorted list prefix, extend that prefix by "inserting" the next element



Insertion Sort - Summary

- If the items at index 0 and 1 are out of order, swap them
- Keep swapping the item at index 2 with the thing to its left as long as the left thing is larger
- …
- Keep swapping the item at index i with the thing to its left as long as the left thing is larger

```
for (i=1; i<a.length; i++){
	prev = i-1;
	while(a[i] < a[prev] && prev > -1){
		temp = a[i];
		a[i] = a[prev];
		a[prev] = a[i];
		i--;
		prev--;
	}
}
```

Running Time:

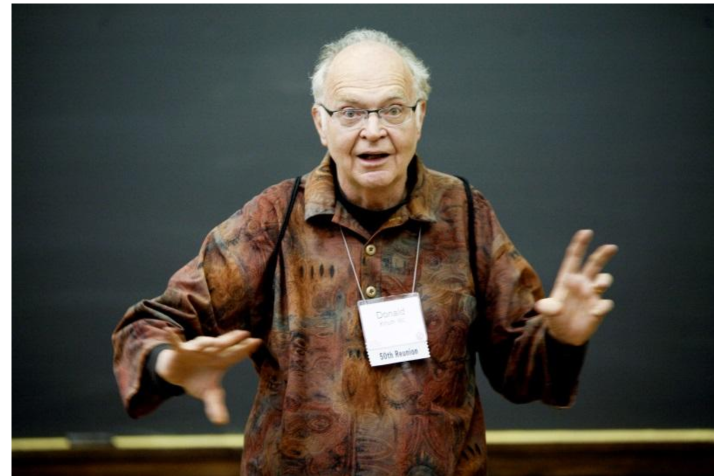
Worst Case: $\Theta(n^2)$

Best Case: $\Theta(n)$

10	77	5	15	2	22	64	41	18	19	30	21	3	24	23	33
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

Aside: Bubble Sort – we won’t cover it

"the bubble sort seems to have nothing to recommend it, except a catchy name and the fact that it leads to some interesting theoretical problems” –Donald Knuth, The Art of Computer Programming



Properties To Consider

- Worst case running time
- In place:
  - We only need to use the pre-existing array to do sorting
  - Constant extra space (only some additional variables needed)
- Adaptive
  - The running improves as the given list is closer to being sorted
  - It should be linear time for a pre-sorted list, and nearly linear time if the list is nearly sorted
- Online
  - We can start sorting before we have the entire list.
- Stable
  - “Tied” elements keep their original order

Insertion Sort Properties

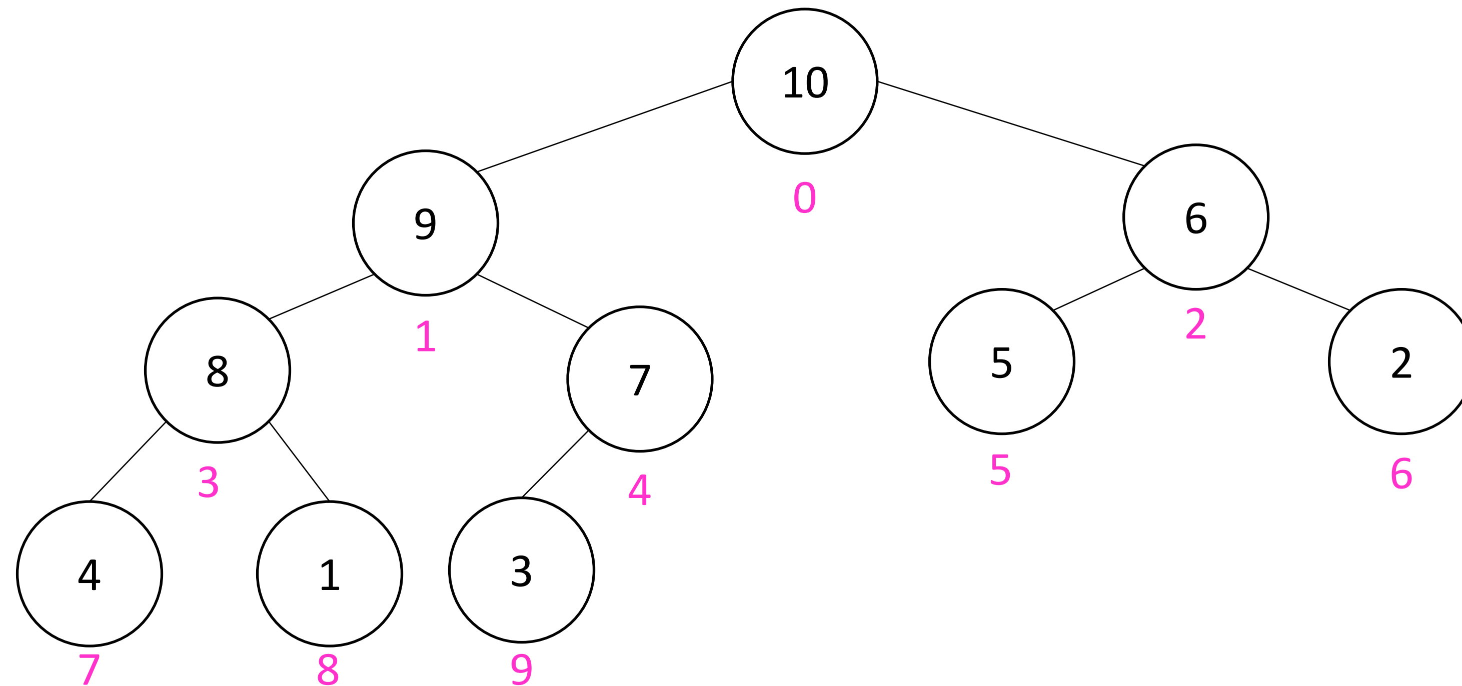
Summary: except for its asymptotic running time, it has everything you might want!

- Worst case running time
  - $\Theta(n^2)$
  - With VERY small constants! (No faster way of sorting a list of ≤ 50ish elements!)
- In place:
  - YES!
  - We only swap items within the given array
- Adaptive
  - YES!
  - The only elements that move are the elements that are out of position
- Online
  - Yes!
  - Each time an item arrives, “insert” it into the sorted prefix
- Stable
  - YES!
  - If the item we’re inserting has a tie with its left neighbor, don’t swap

Heap Sort

- Idea: Build a maxHeap, repeatedly extract the max element from the heap to build sorted list Right-to-Left

Max Heap Property: Each node is larger than its children

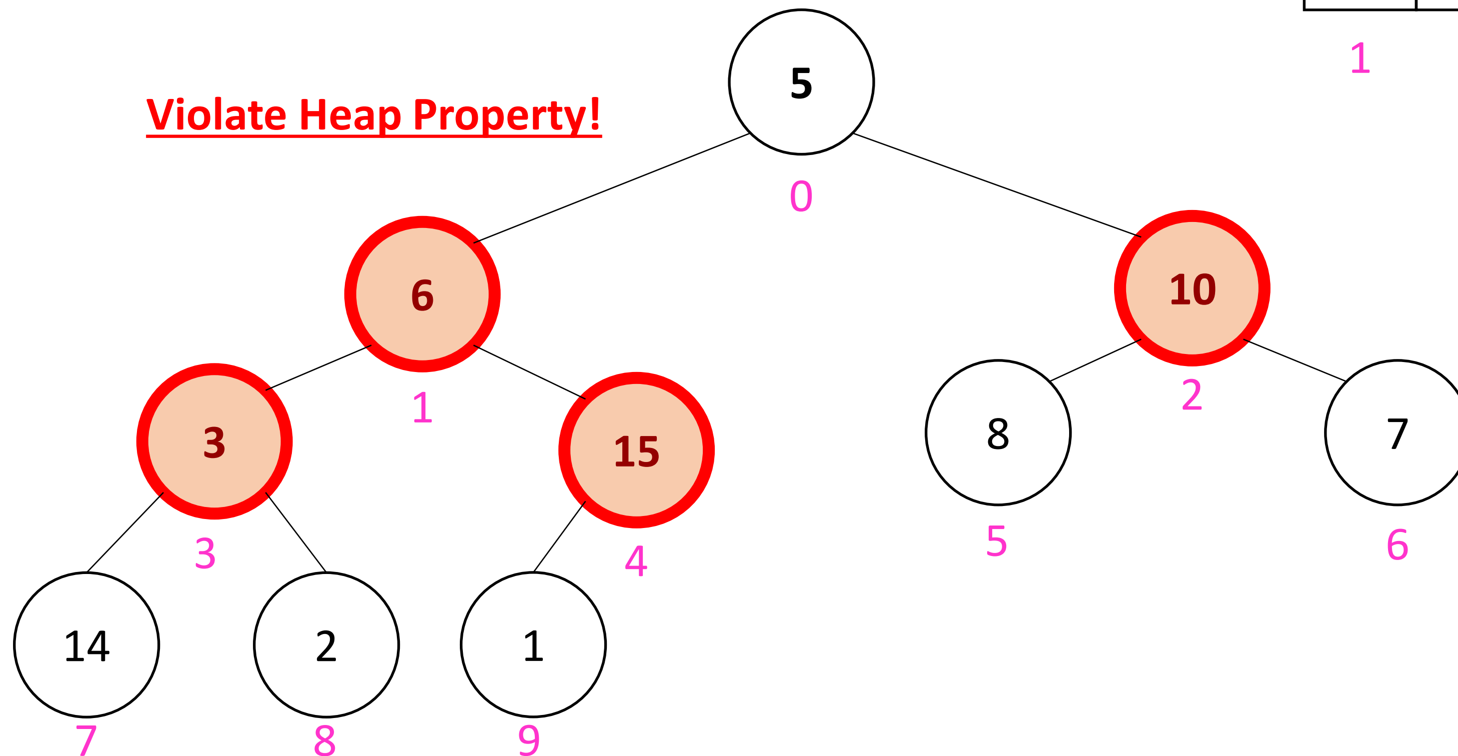


10	9	6	8	7	5	2	4	1	3
0	1	2	3	4	5	6	7	8	9

Building a Heap From “Scratch”

- Suppose we had n items and wanted to “heapify” them

5	6	10	3	15	8	7	14	2	1
1	2	3	4	5	6	7	8	9	10



Two ways for “fix” the heap:

1) Percolate Up
2) Percolate Down

Floyd's buildHeap method

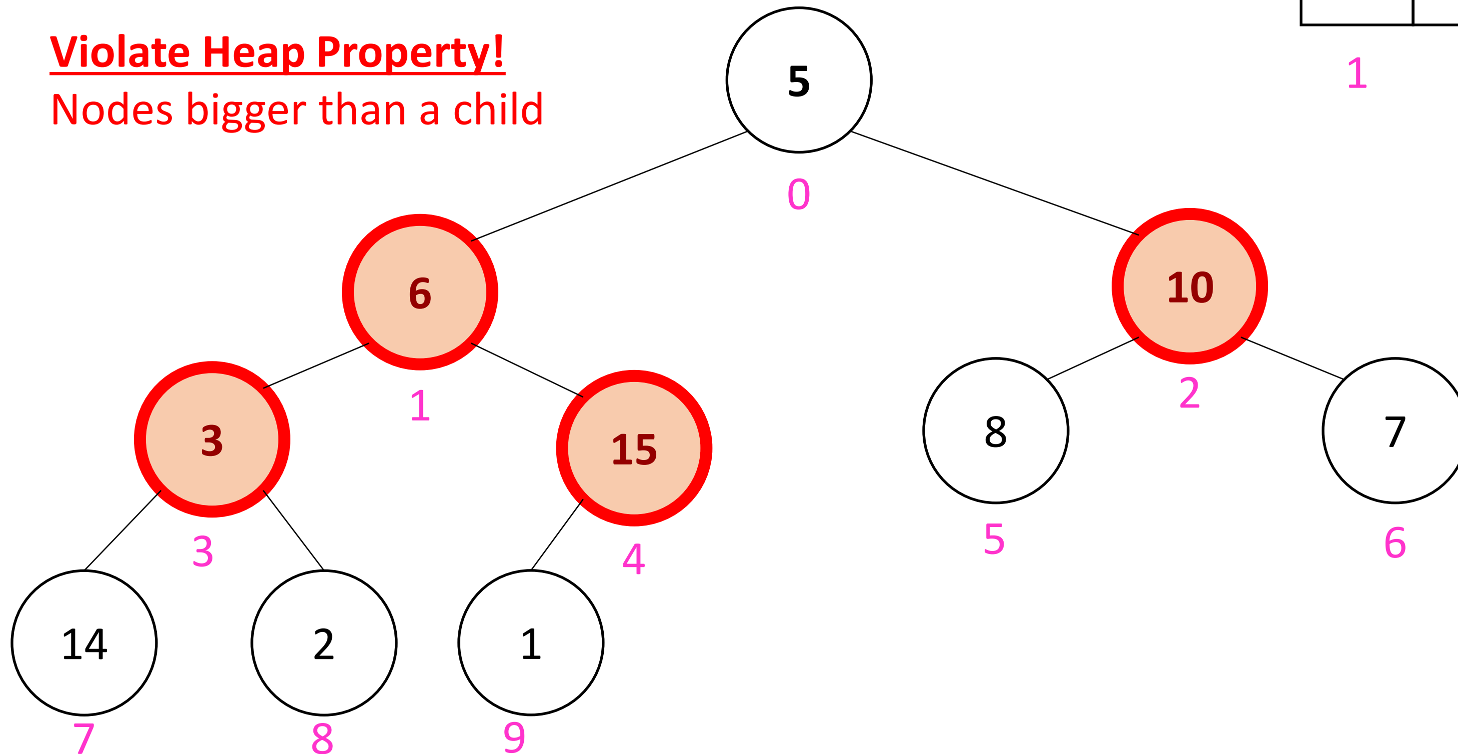
- Working towards the root, one row at a time, percolate down

```
buildHeap(){
    for(int i = size; i>0; i--){
        percolateDown(i);
    }
}
```

Floyd’s buildHeap method (Percolate 15)

- Suppose we had n items and wanted to “heapify” them

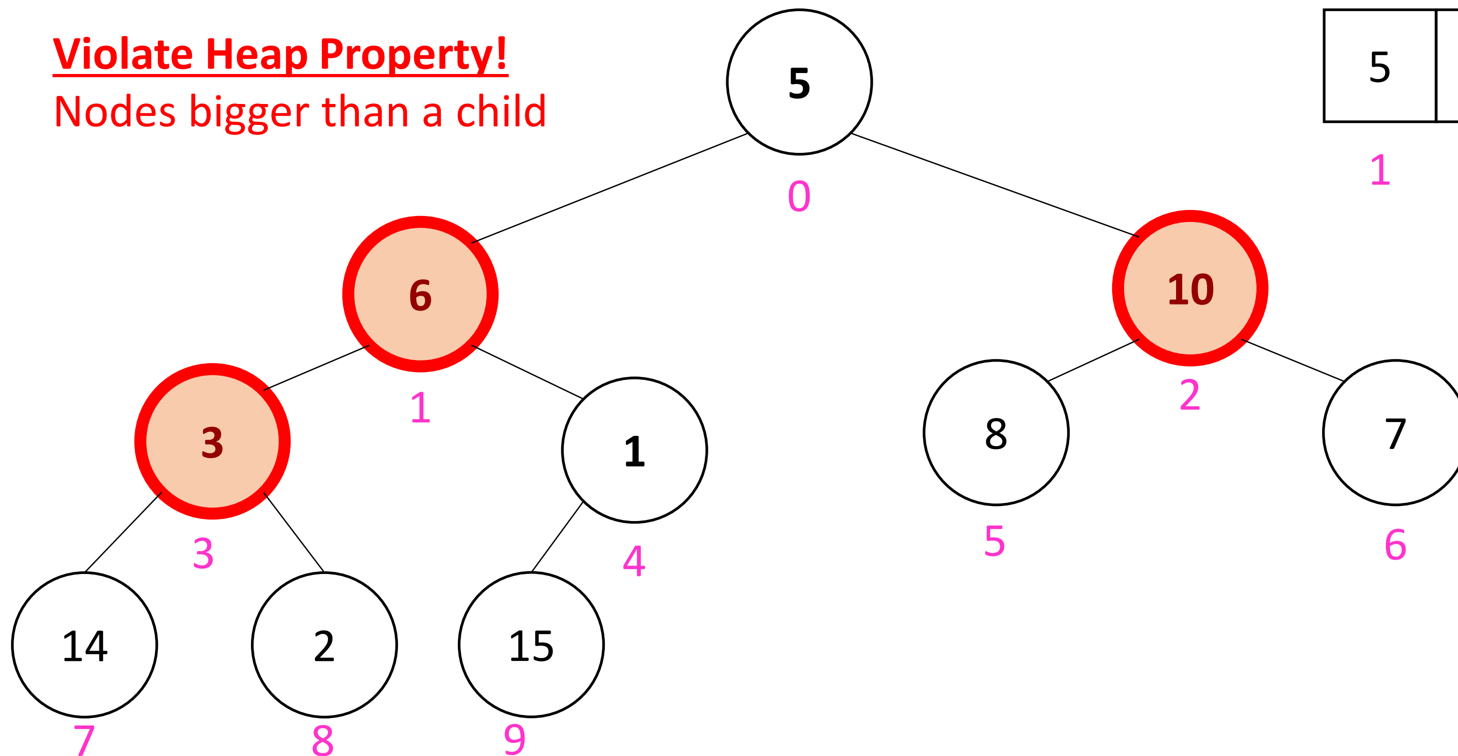
5	6	10	3	15	8	7	14	2	1
1	2	3	4	5	6	7	8	9	10




```
buildHeap(){
    for(int i = size; i>0; i--){
        percolateDown(i);
    }
}
```

Floyd’s buildHeap method (Percolate 3)

- Suppose we had n items and wanted to “heapify” them

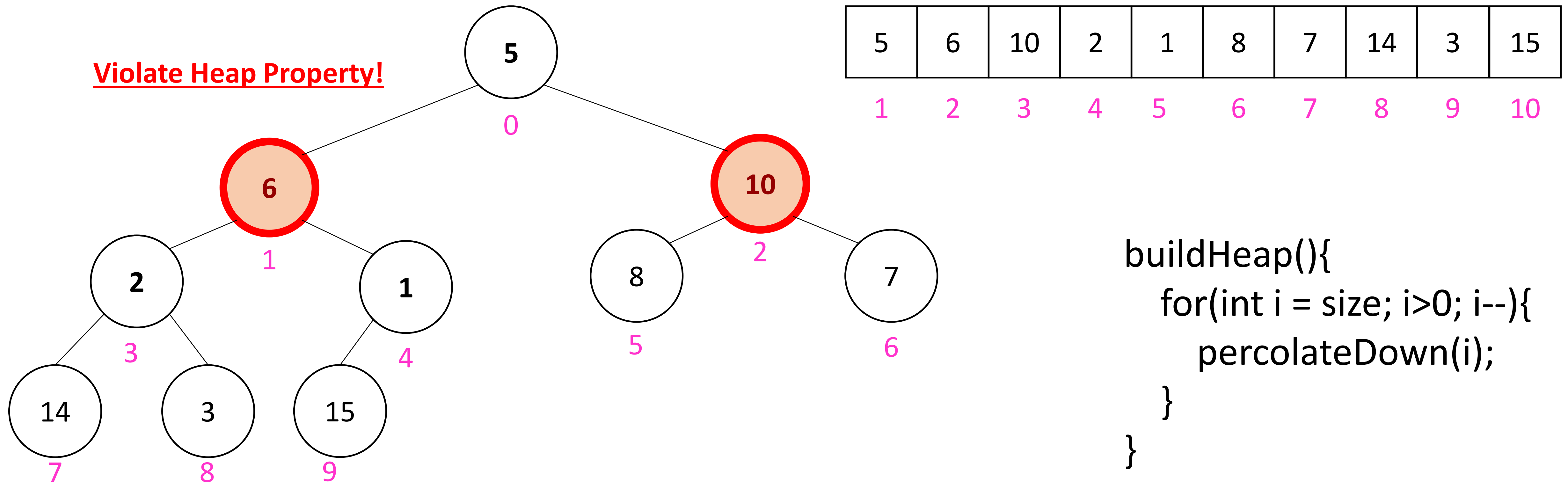


5	6	10	3	1	8	7	14	2	15
1	2	3	4	5	6	7	8	9	10

```
buildHeap(){
   for(int i = size; i>0; i--){
      percolateDown(i);
   }
}
```

Floyd's buildHeap method (Percolate 10)

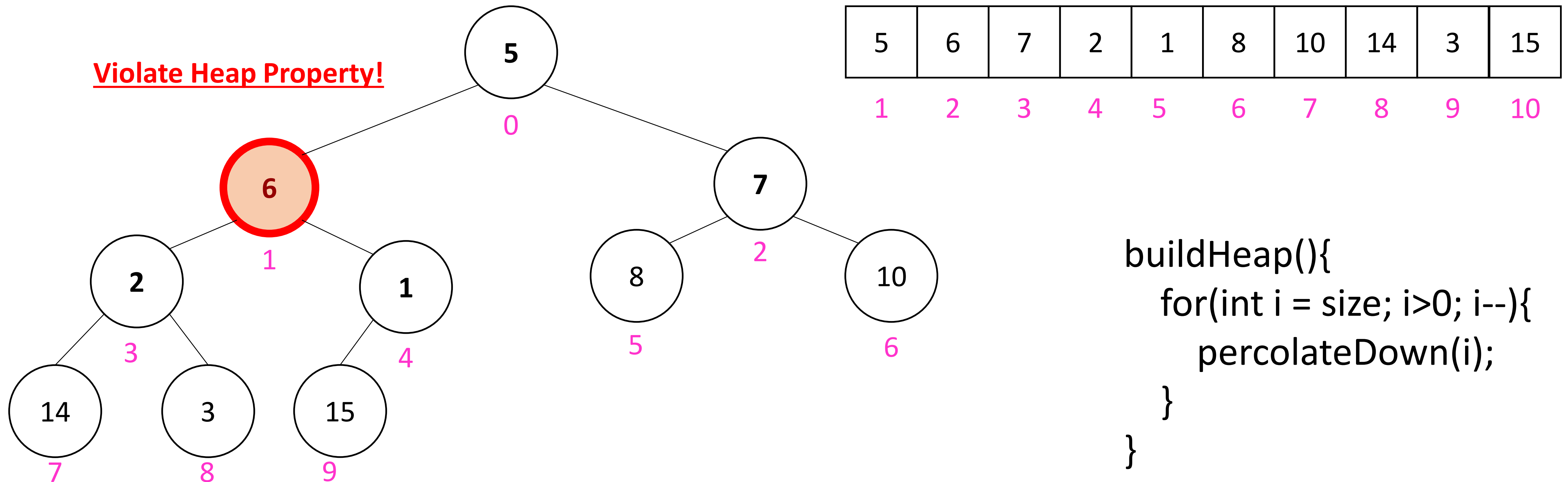
- Suppose we had n items and wanted to "heapify" them




```
buildHeap(){
    for(int i = size; i>0; i--){
        percolateDown(i);
    }
}
```

Floyd's buildHeap method (Percolate 6)

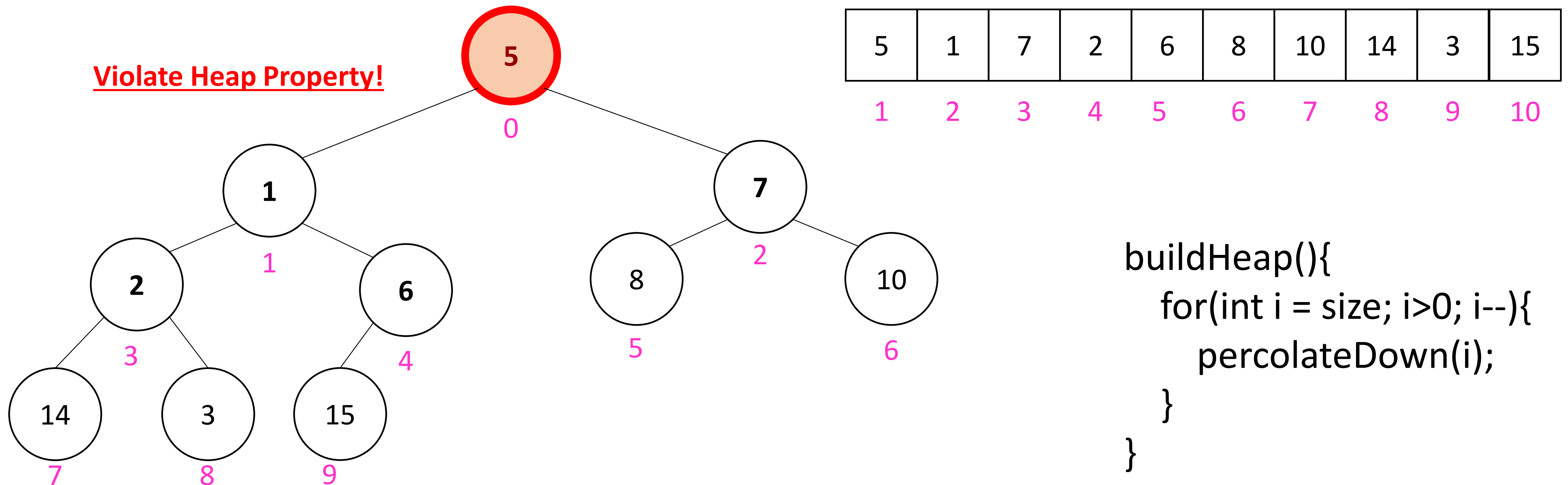
- Suppose we had n items and wanted to "heapify" them




```
buildHeap(){
   for(int i = size; i>0; i--){
      percolateDown(i);
   }
}
```

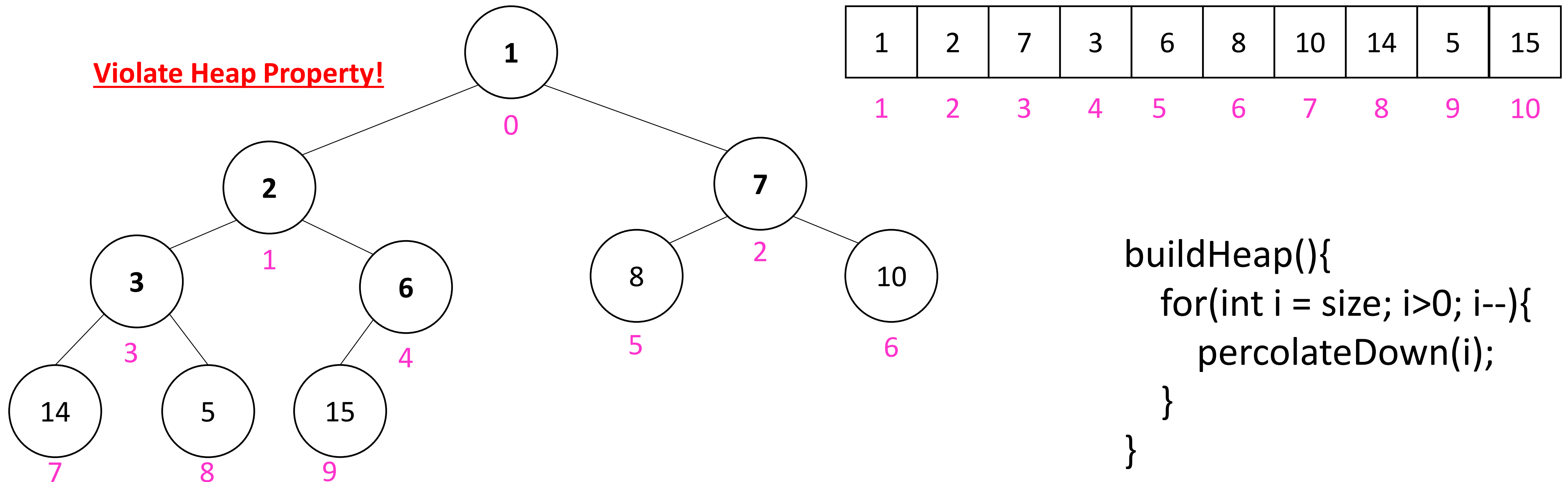
Floyd's buildHeap method (Percolate 5)

- Suppose we had n items and wanted to "heapify" them



Floyd’s buildHeap method (Done)

- Suppose we had n items and wanted to “heapify” them



How long did this take?

- Worst case running time of buildHeap:
- No node can percolate down more than the height of its subtree
  - When i is a leaf:
  - When i is second-from-last level:
  - When i is third-from-last level:
- Overall Running time:

```
buildHeap(){
    for(int i = size; i>0; i--){
        percolateDown(i);
    }
}
```

How long did this take? (Answers)

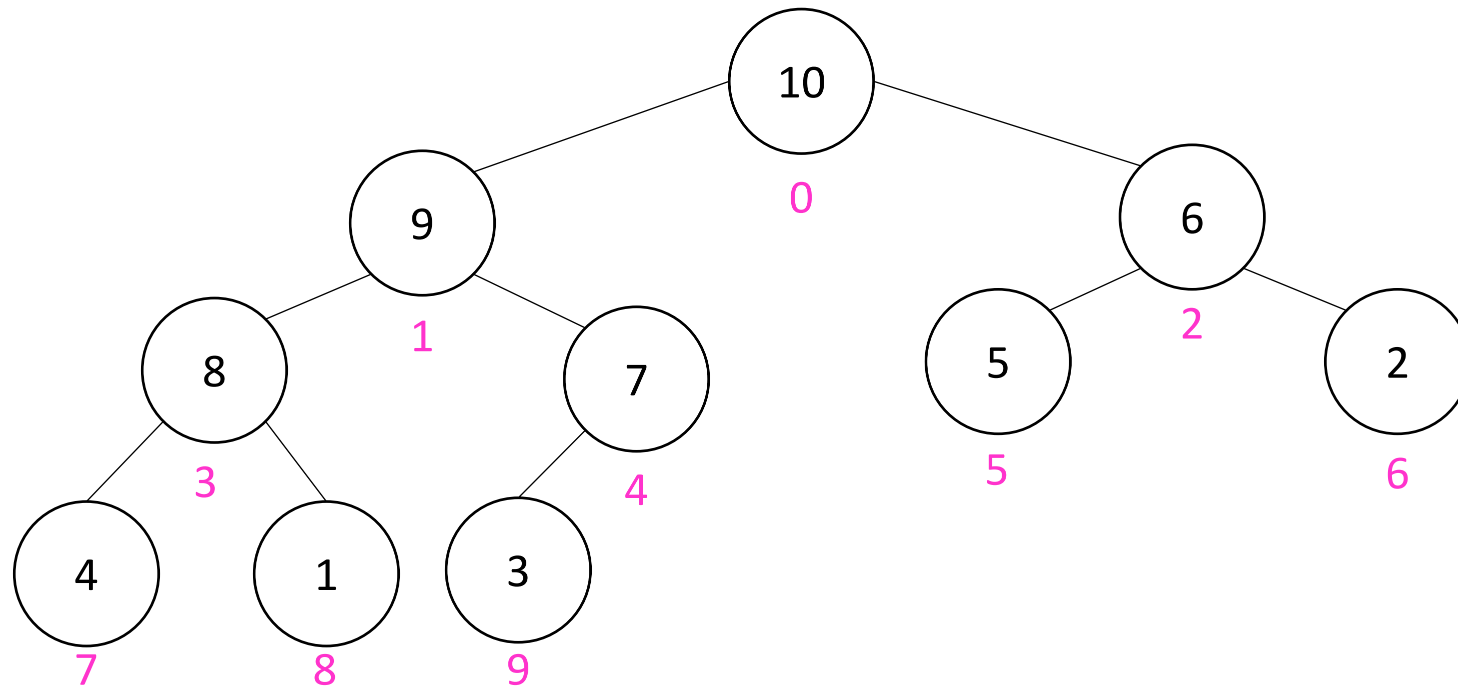
- Worst case running time of buildHeap:
- No node can percolate down more than the height of its subtree
  - When i is a leaf: 0
  - When i is second-from-last level: 1
  - When i is third-from-last level: 2
- Overall Running time:
  - $0 \cdot \frac{n}{2} + 1 \cdot \frac{n}{4} + 2 \cdot \frac{n}{8} + \cdots \log_2 n \cdot 1$
  - $\sum_{i=0}^{\log_2 n} i \cdot \frac{n}{2^{i+1}} = n \sum_{i=0}^{\log_2 n} \frac{i}{2^{i+1}} \leq n \sum_{i=0}^{\infty} \frac{i}{2^{i+1}} = 2n$
  - $\Theta(n)$

```
buildHeap(){
   for(int i = size; i>0; i--){
      percolateDown(i);
   }
}
```

Heap Sort (Example)

- Idea: Build a maxHeap, repeatedly extract the max element from the heap to build sorted list Right-to-Left

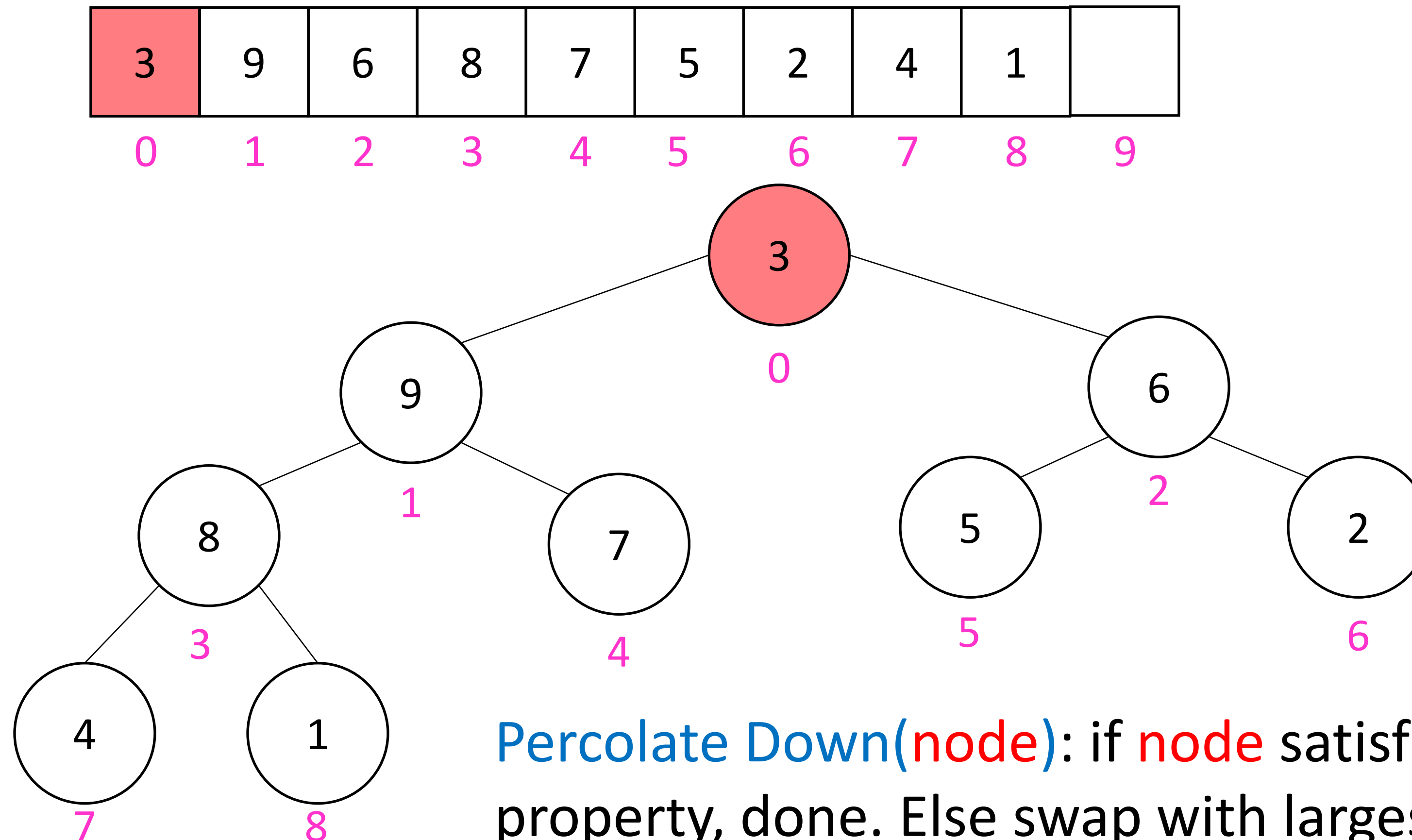
Max Heap Property: Each node is larger than its children



10	9	6	8	7	5	2	4	1	3
0	1	2	3	4	5	6	7	8	9

Heap Sort (First Extract)

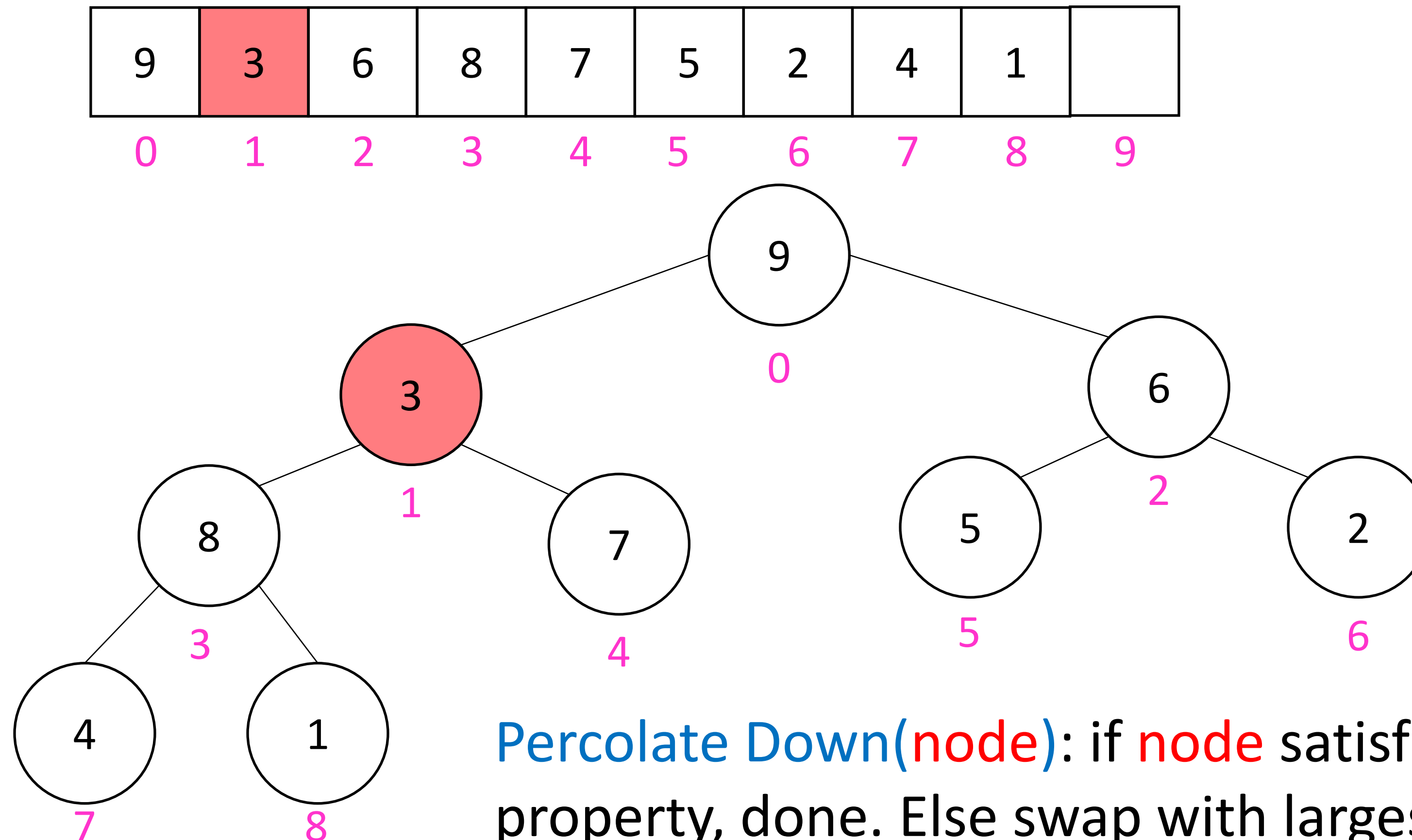
- Remove the Max element (i.e. the root) from the Heap: replace with last element, call percolateDown(root)



Percolate Down(node): if node satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort (Percolate Down, Swap 1)

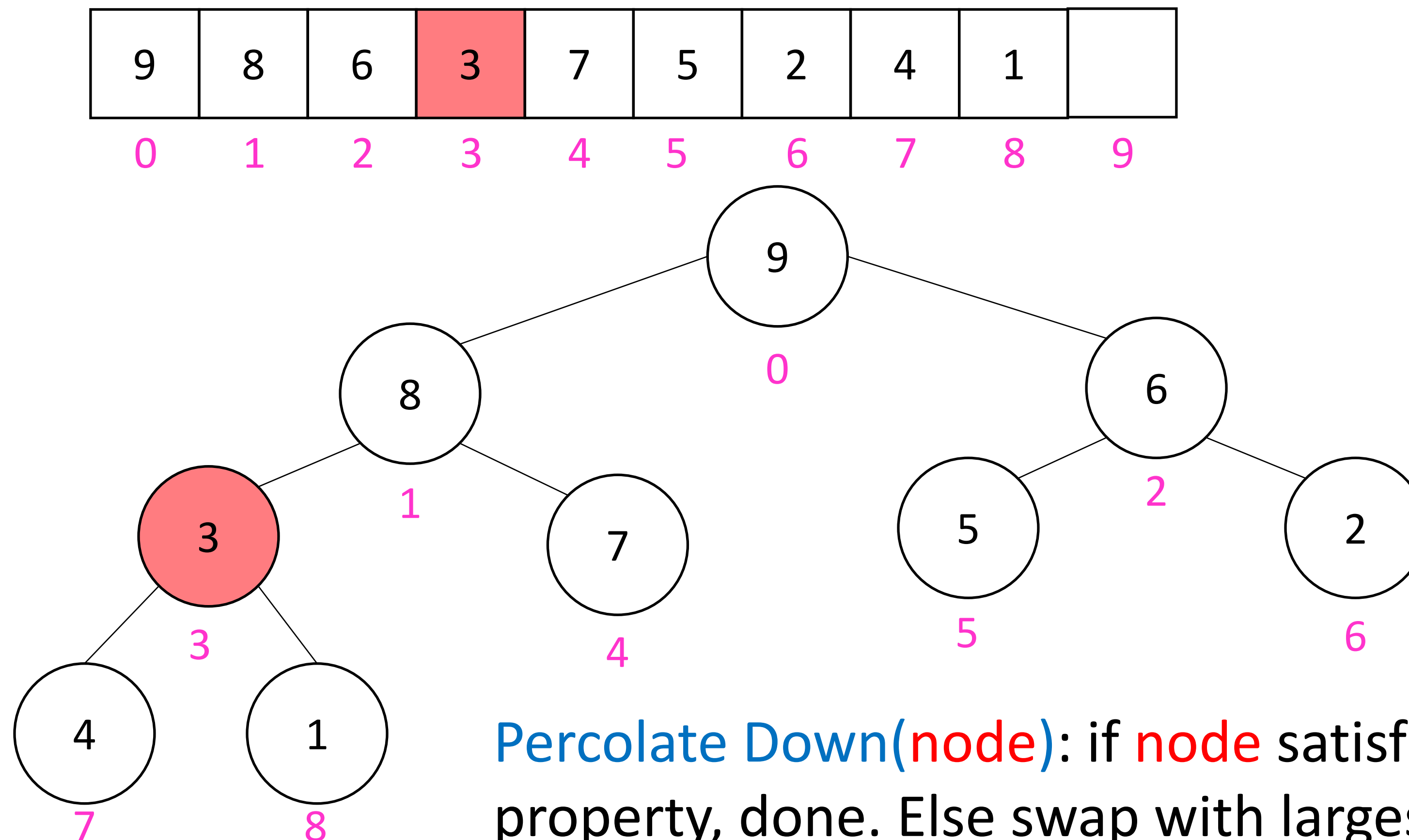
- Remove the Max element (i.e. the root) from the Heap: replace with last element, call percolateDown(root)



Percolate Down(node): if node satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort (Percolate Down, Swap 2)

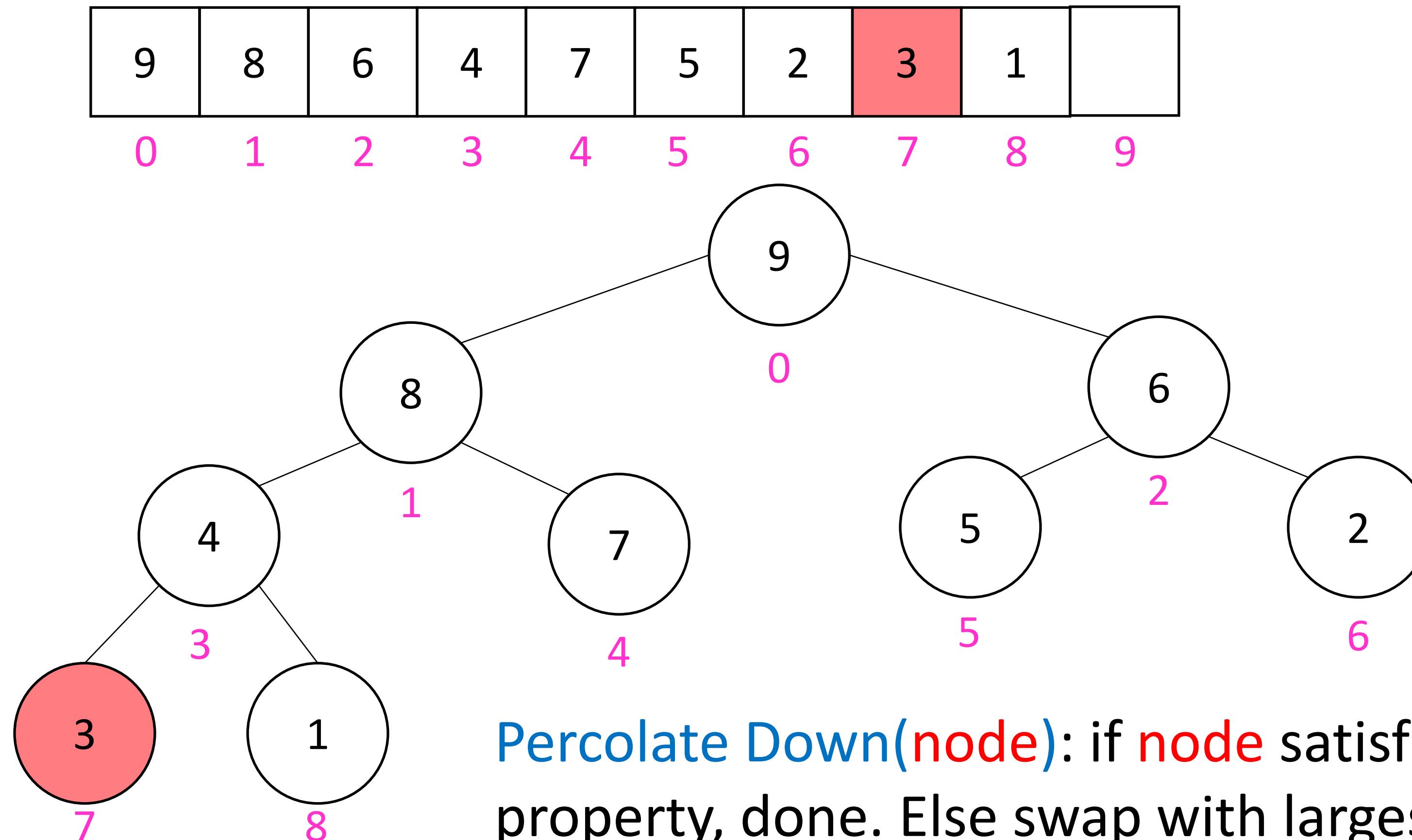
- Remove the Max element (i.e. the root) from the Heap: replace with last element, call percolateDown(root)



Percolate Down(node): if node satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort (Percolate Down, Swap 3)

- Remove the Max element (i.e. the root) from the Heap: replace with last element, call percolateDown(root)



Percolate Down(node): if node satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort - Summary

- Build a max heap
- Call extract
- Put that at the end of the array

```
myHeap = buildMaxHeap(a);
for (int i = a.length-1; i>=0; i--){
	item = myHeap.extract();
	a[i] = item;
}
```

Running Time:

Worst Case: $\Theta(n \log n)$

Best Case: $\Theta(n \log n)$

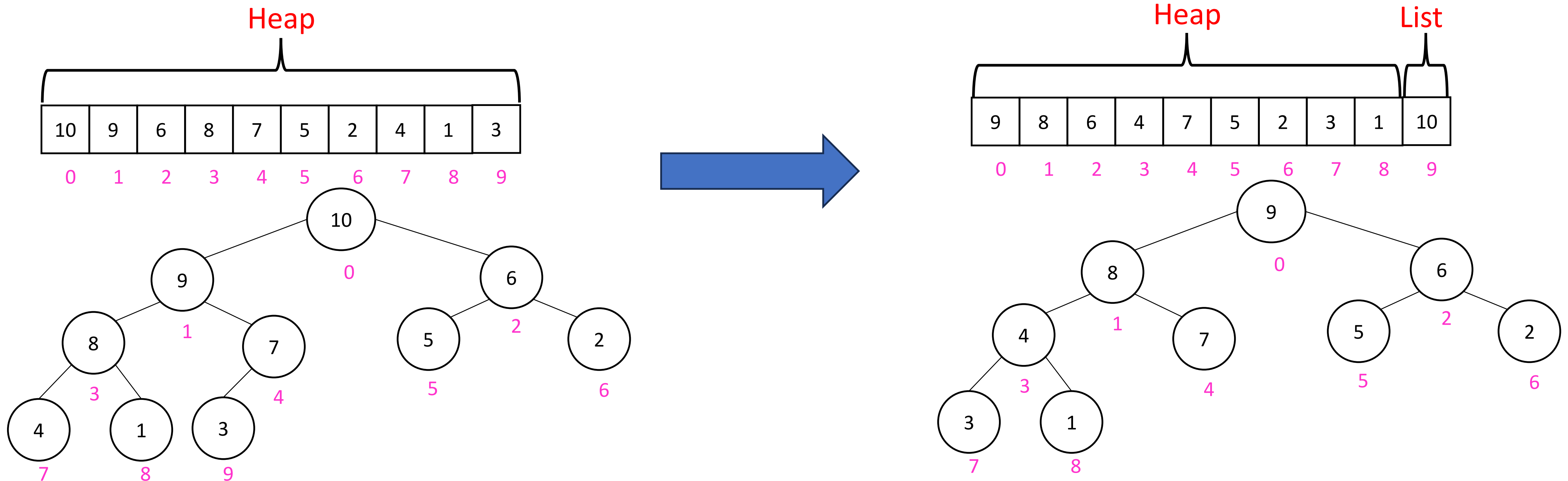
“In Place” Sorting Algorithm

- A sorting algorithm which requires no extra data structures
- Idea: It sorts items just by swapping things in the same array given
- Definition: it only uses $\Theta(1)$ extra space

- Insertion sort: In Place!
- Heap sort: Not In Place!
  - But we can fix that!

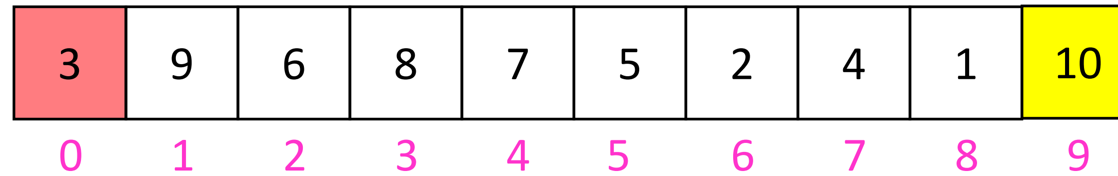
In Place Heap Sort

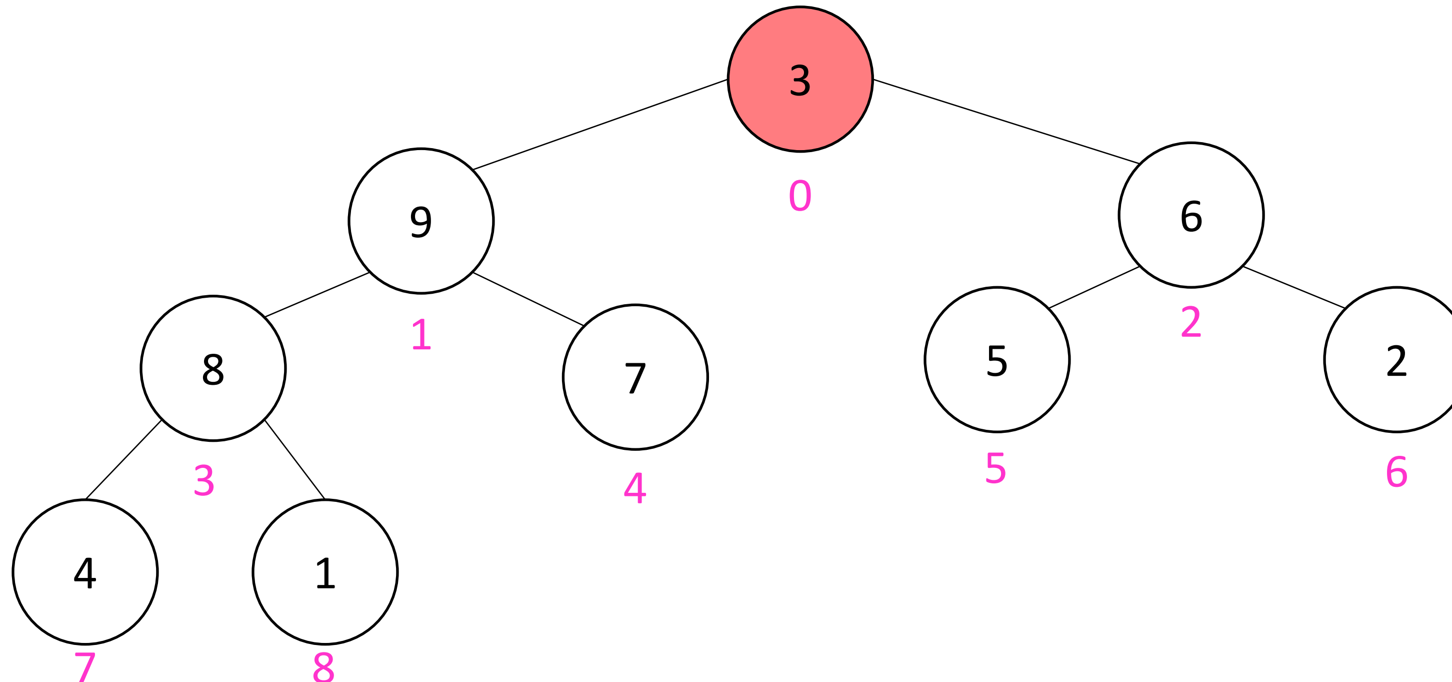
- Idea: Insert all items into a max heap, extract the largest one-by-one to fill sorted list from end to beginning, all the while the heap and sorted list share the same array



In Place Heap Sort (First Extract)

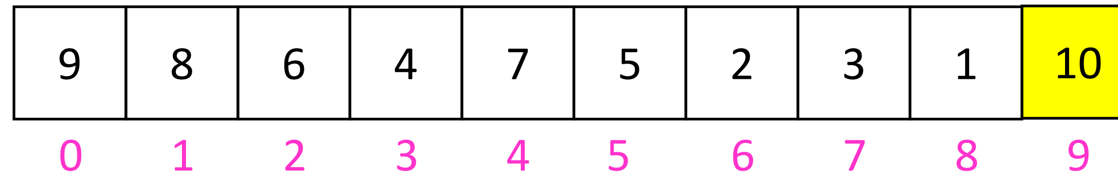
- Idea: When extracting an element from the heap, swap it with the last item of the heap then "pretend" the heap is one item shorter

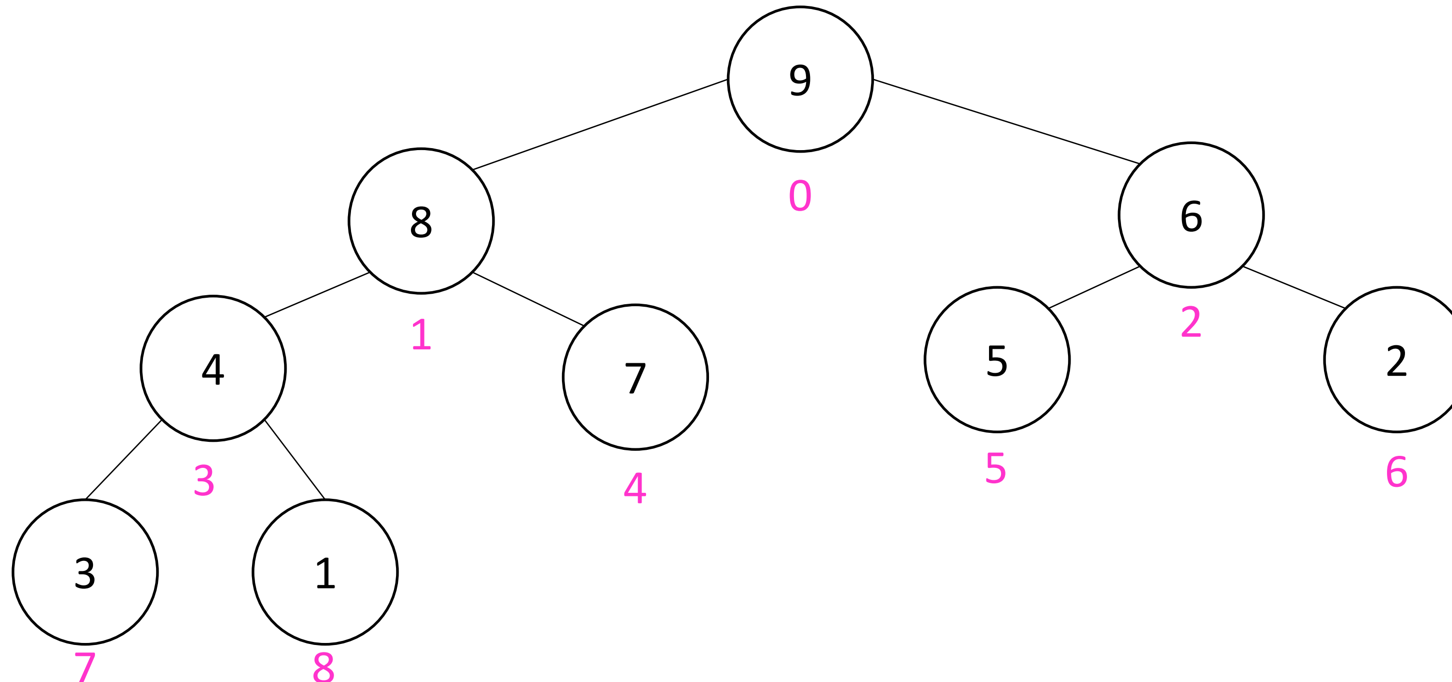




In Place Heap Sort (First Percolate Down)

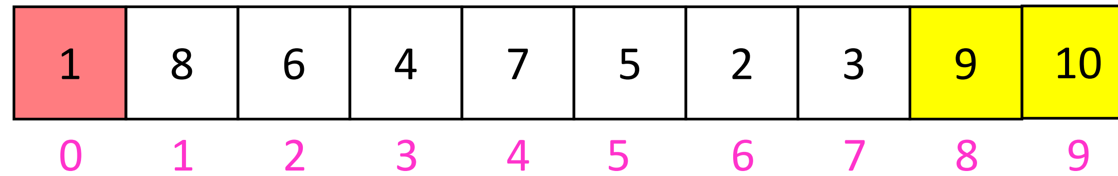
- Idea: When extracting an element from the heap, swap it with the last item of the heap then "pretend" the heap is one item shorter

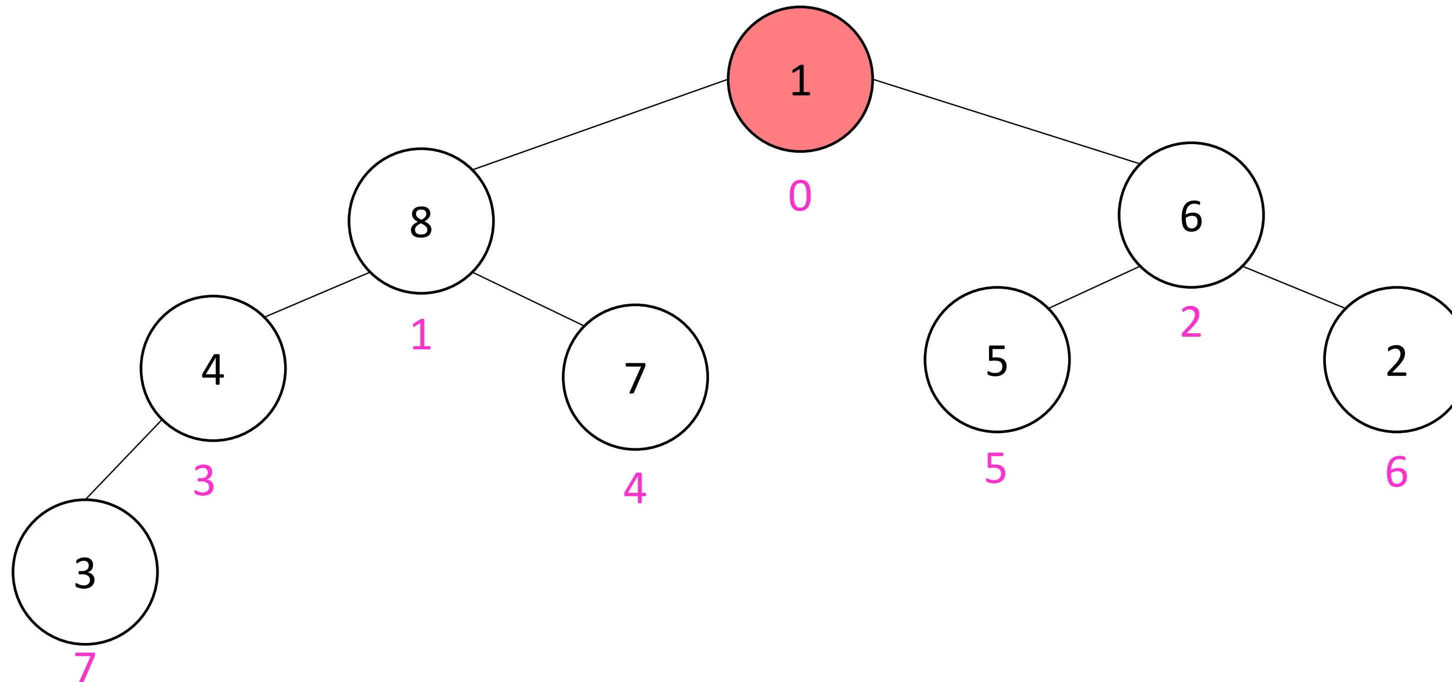




In Place Heap Sort (Second Extract)

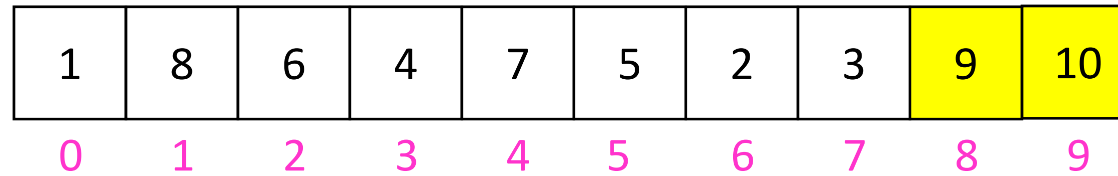
- Idea: When extracting an element from the heap, swap it with the last item of the heap then "pretend" the heap is one item shorter

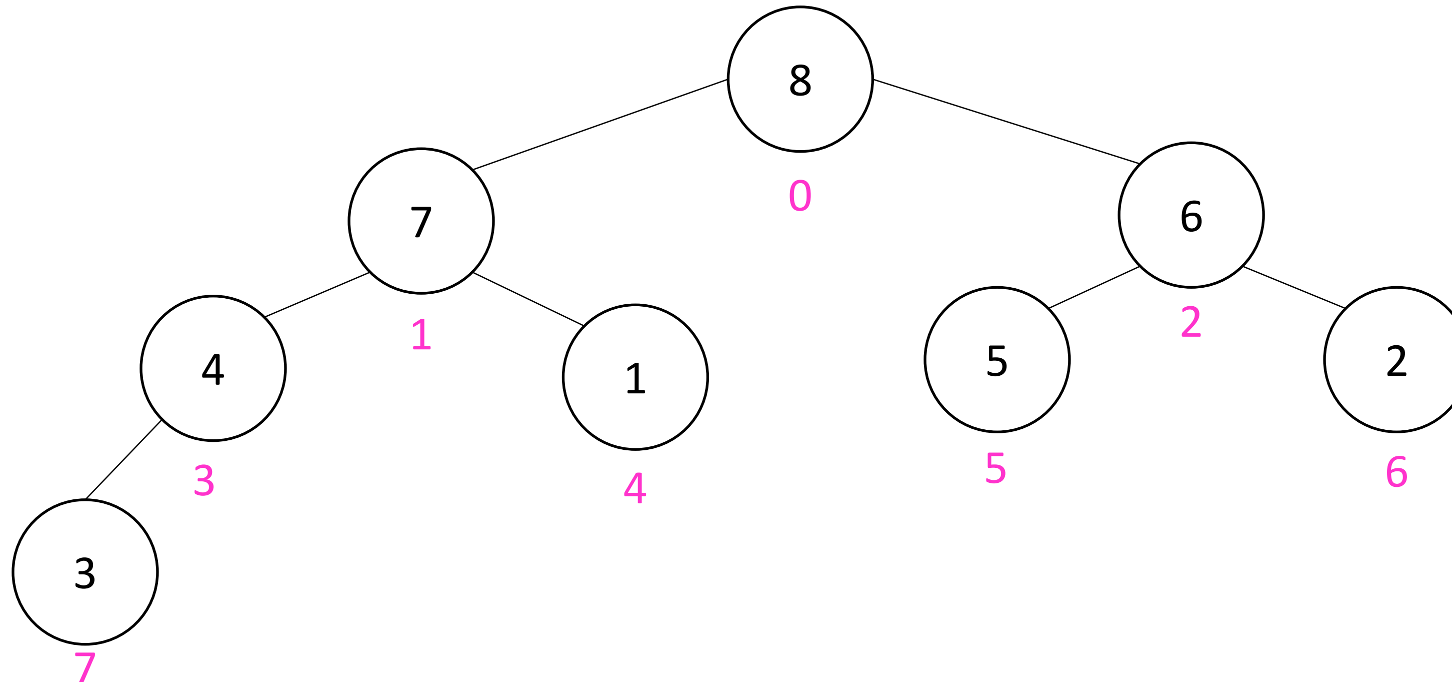




In Place Heap Sort (Second Percolate Down)

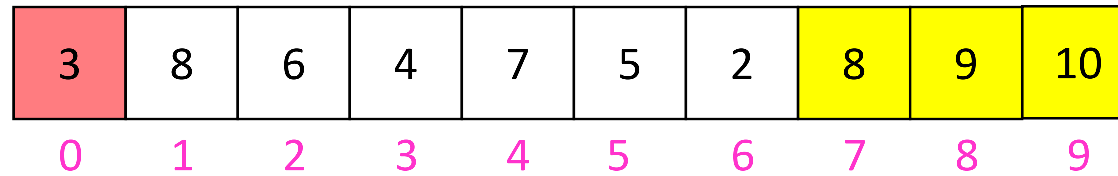
- Idea: When extracting an element from the heap, swap it with the last item of the heap then "pretend" the heap is one item shorter

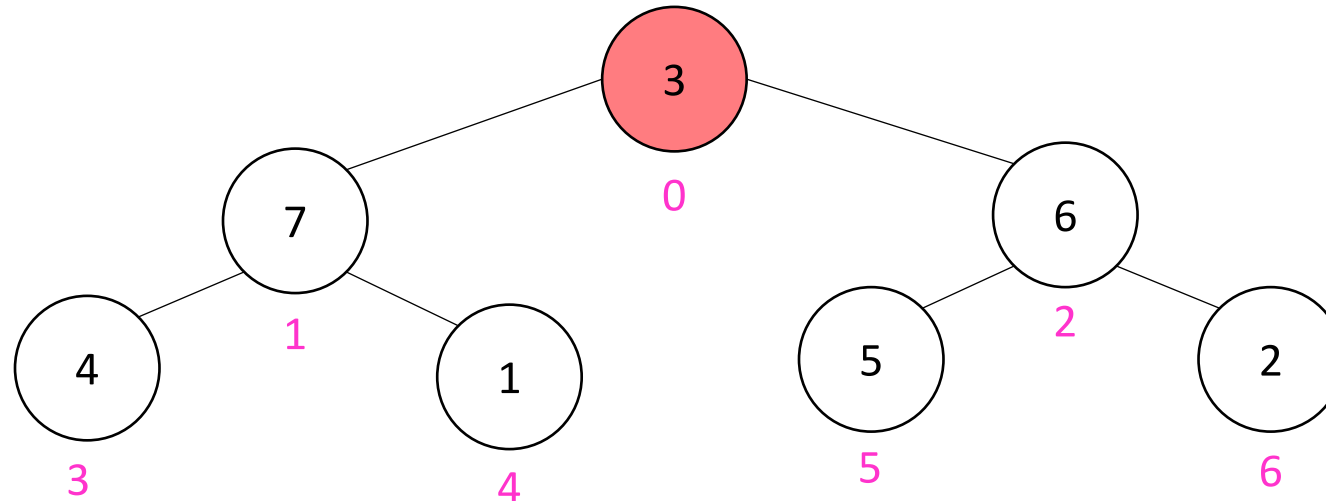




In Place Heap Sort (Third Extract)

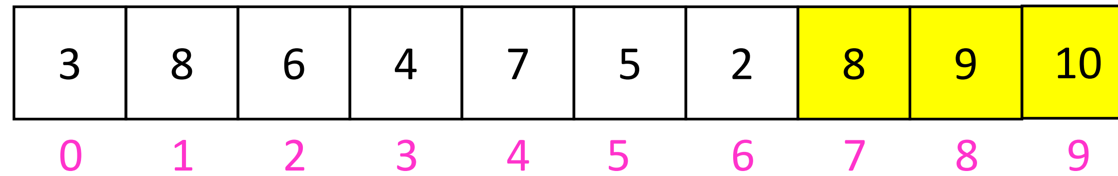
- Idea: When extracting an element from the heap, swap it with the last item of the heap then "pretend" the heap is one item shorter



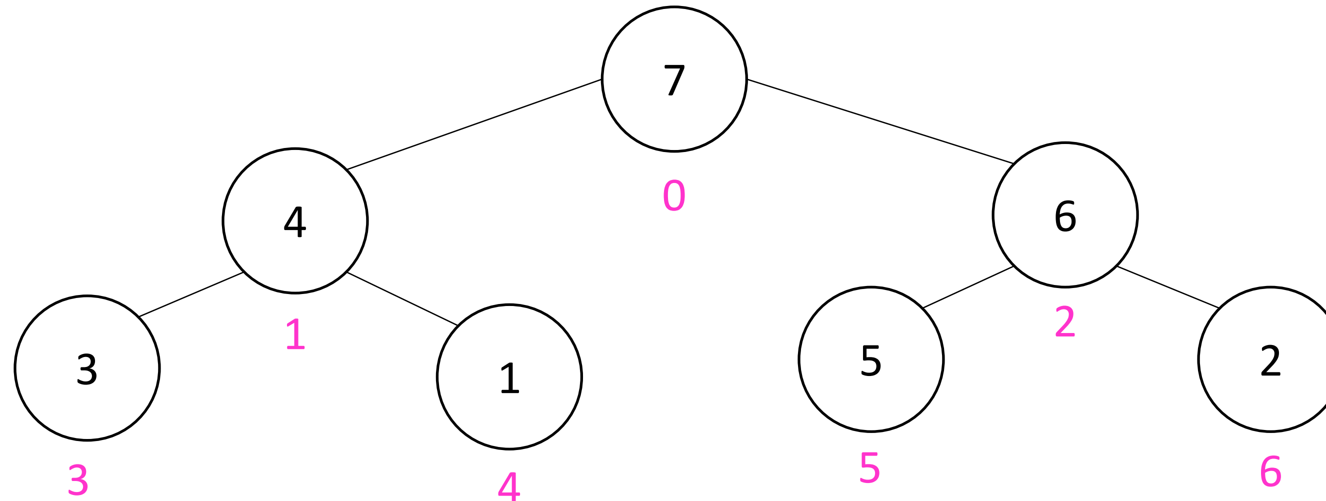


In Place Heap Sort (Third Percolate Down)

- Idea: When extracting an element from the heap, swap it with the last item of the heap then "pretend" the heap is one item shorter



3	8	6	4	7	5	2	8	9	10
0	1	2	3	4	5	6	7	8	9



In Place Heap Sort - Summary

- Build a heap using the same array (Floyd’s build heap algorithm works)
- Call extract
- Put that at the end of the array

```
buildHeap(a);
for (int i = a.length-1; i>=0; i--){
	temp=a[i]
	a[i] = a[0];
	a[0] = temp;
	percolateDown(0);
}
```

Running Time:

Worst Case: $\Theta(n \log n)$

Best Case: $\Theta(n \log n)$

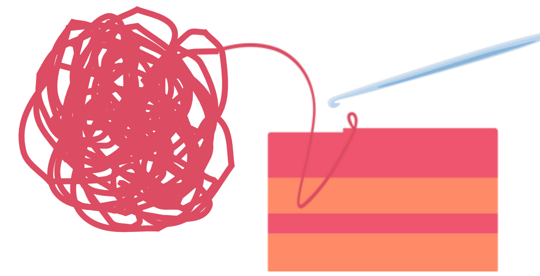
Heap Sort Properties

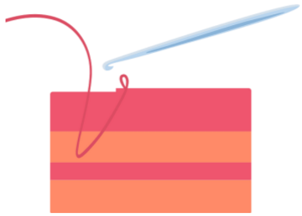
- Worst case running time
  - $\Theta(n \log n)$
- In place:
  - YES!
  - We only swap items within the given array
- Adaptive
  - NO!
  - Running time is the same regardless of original list's order
- Online
  - NO!
  - We need all elements in the heap before we can start extracting
- Stable
  - NO!
  - Question on Exercise 6

Divide And Conquer Sorting

- Divide and Conquer:
  - Recursive algorithm design technique
  - Solve a large problem by breaking it up into smaller versions of the same problem

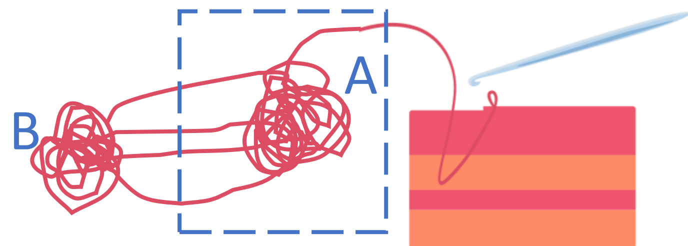
Divide and Conquer





- **Base Case**:
  - If the problem is “small” then solve directly and return

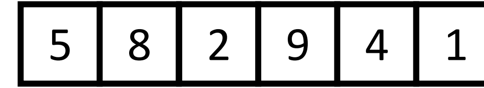
- **Divide**:
  - Break the problem into subproblem(s), each smaller instances



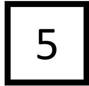
- **Conquer**:
  - Solve subproblem(s) recursively
- **Combine**:
  - Use solutions to subproblems to solve original problem

Divide and Conquer Template Pseudocode

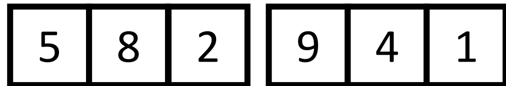
```
def my_DandC(problem){
   // Base Case
   if (problem.size() <= small_value){
      return solve(problem);  // directly solve (e.g., brute force)
   }
   // Divide
   List subproblems = divide(problem);

   // Conquer
   solutions = new List();
   for (sub : subproblems){
      subsolution = my_DandC(sub);
      solutions.add(subsolution);
   }
   // Combine
   return combine(solutions);
}
```



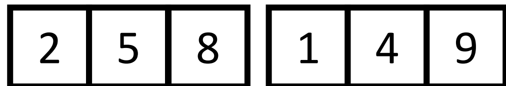
Merge Sort



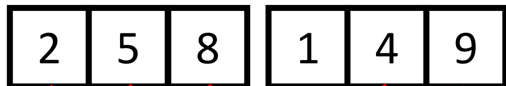
- **Base Case:**
  - If the list is of length 1 or 0, it's already sorted, so just return it

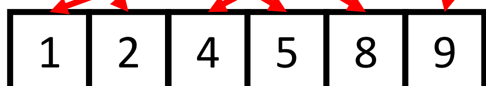


- **Divide:**
  - Split the list into two "sublists" of (roughly) equal length



- **Conquer:**
  - Sort both lists recursively

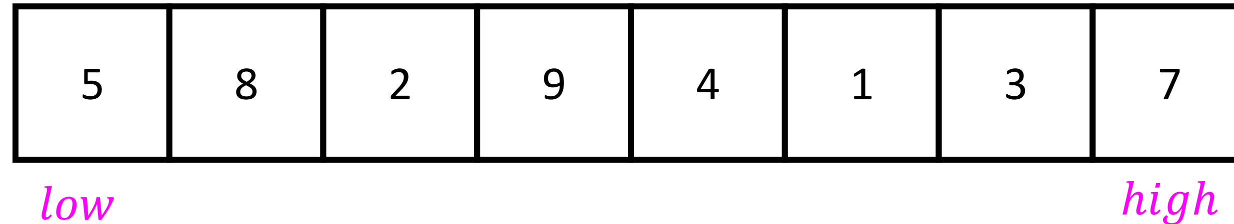




- **Combine:**
  - **Merge** sorted sublists into one sorted list

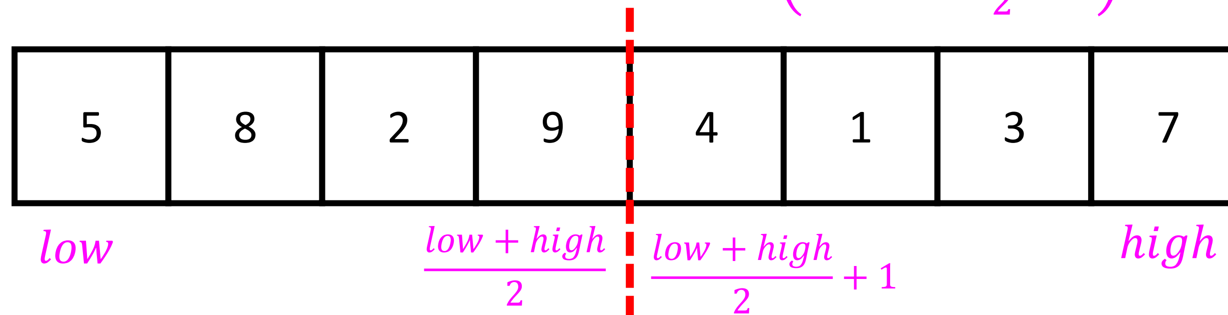
Merge Sort In Action!

Sort between indices low and $high$

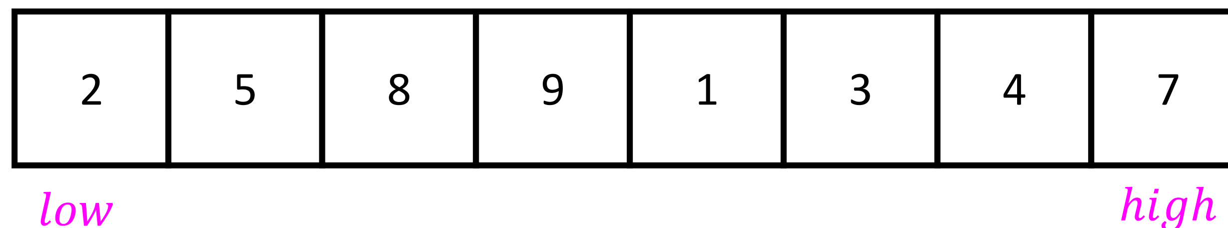


Base Case: if low == $high$ then that range is already sorted!

Divide and Conquer: Otherwise call mergesort on ranges $\left(low, \frac{low+high}{2}\right)$ and $\left(\frac{low+high}{2}+1, high\right)$



After Recursion:

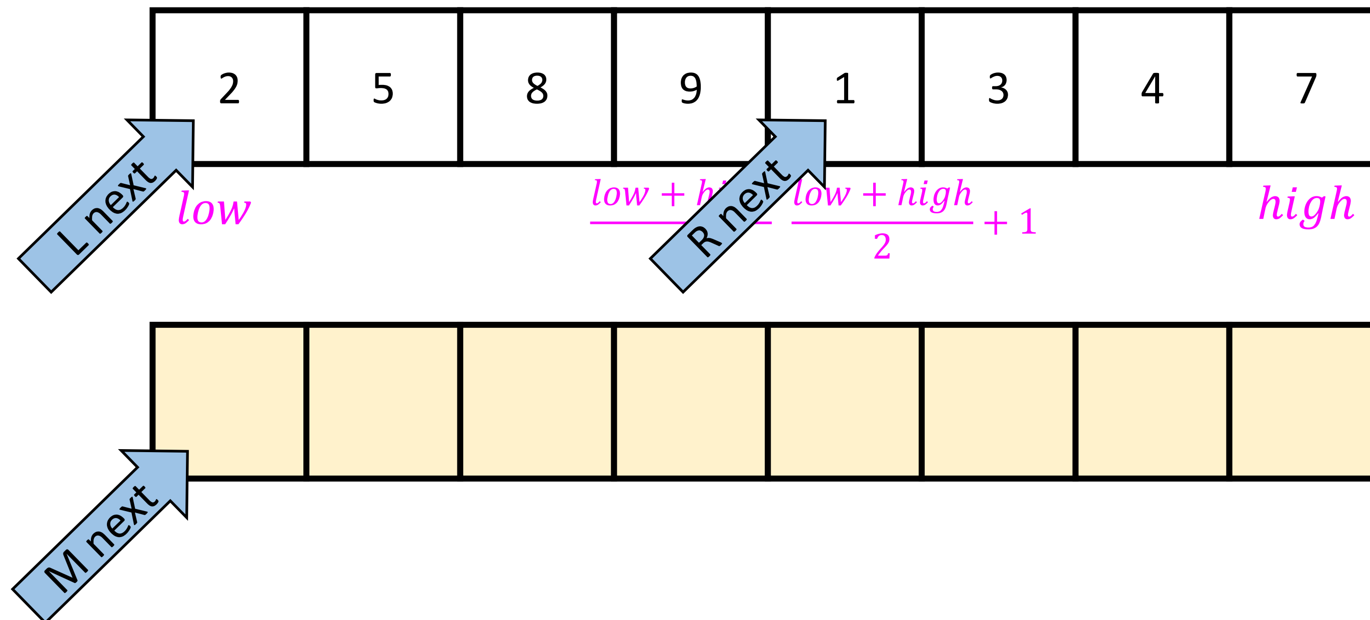


Merge (the combine part)

Create a new array to merge into, and 3 pointers/indices:

- L_next: the smallest "unmerged" thing on the left
- R_next: the smallest "unmerged" thing on the right
- M_next: where the next smallest thing goes in the merged array

One-by-one: put the smallest of L_next and R_next into M_next, then advance both M_next and whichever of L/R was used.



Merge Sort Pseudocode

```
void mergesort(myArray){
        ms_helper(myArray, 0, myArray.length());
}
void mshelper(myArray, low, high){
        if (low == high){return;}  // Base Case
        mid = (low+high)/2;
        ms_helper(low, mid);
        ms_helper(mid+1, high);
        merge(myArray, low, mid, high);
}
```

Merge Pseudocode

```
void merge(myArray, low, mid, high){
        merged = new int[high-low+1]; // or whatever type is in myArray
        l_next = low;
        r_next = high;
        m_next = 0;
        while (l_next <= mid && r_next <= high){
                if (myArray[l_next] <= myArray[r_next]){
                        merged[m_next++] = myArray[l_next++];
                }
                else{
                        merged[m_next++] = myArray[r_next++];
                }
        }
        while (l_next <= mid){ merged[m_next++] = myArray[l_next++]; }
        while (r_next <= high){  merged[m_next++] = myArray[r_next++]; }
        for(i=0; i<=merged.length; i++){ myArray[i+low] = merged[i];}
}
```

Analyzing Merge Sort

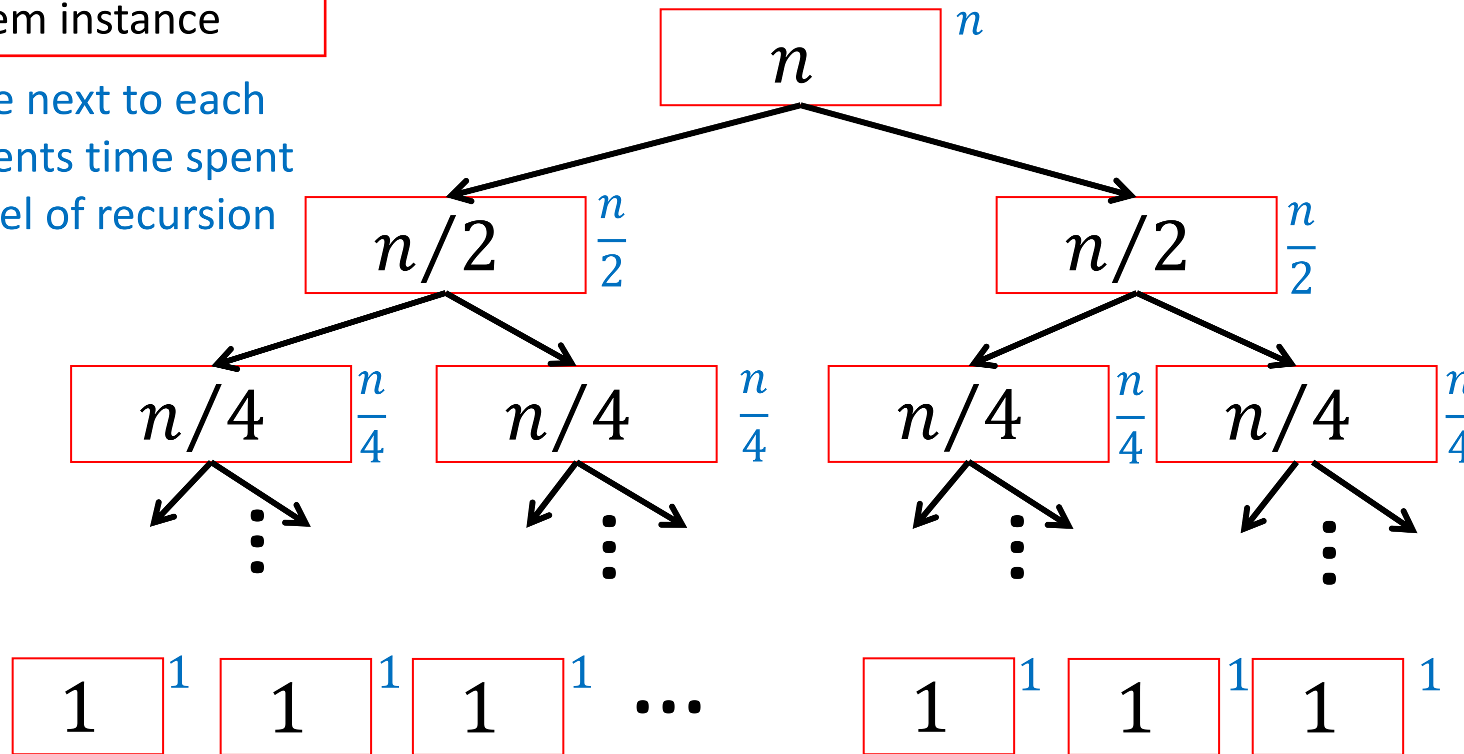
1. Identify time required to Divide and Combine
2. Identify all subproblems and their sizes
3. Use recurrence relation to express recursive running time
4. Solve and express running time asymptotically

- **Divide**: 0 comparisons
- **Conquer**: recursively sort two lists of size $\frac{n}{2}$
- **Combine**: n comparisons
- **Recurrence:**

$$T(n) = 0 + T\left(\frac{n}{2}\right) + T\left(\frac{n}{2}\right) + n$$

$$T(n) = 2T\left(\frac{n}{2}\right) + n$$

Tree Method $T(n) = 2T\left(\frac{n}{2}\right) + n$



$\Rightarrow n$ work per level

$\log_2 n$ levels of recursion

$$T(n) = \sum_{i=0}^{\log_2 n} n = \Theta(n \log n)$$

Merge Sort Properties

- Worst case running time
  - $\Theta(n \log n)$
- In place:
  - NO!
  - We need a second array to merge into
- Adaptive
  - NO!
  - Running time is the same regardless of original list’s order
- Online
  - NO!
  - We need all elements before we can divide
- Stable
  - YES!
  - When merging, and there’s a tie, choose the element from the left

Quicksort Vs. Mergesort

- Like Mergesort:
  - Divide and conquer
  - $O(n \log n)$ run time (kind of…)
- Unlike Mergesort:
  - Divide step is the “hard” part
  - *Typically* faster than Mergesort

Quicksort Overview

Idea: pick a pivot element, recursively sort two sublists around that element

- Divide: select pivot element p, Partition(p)
- Conquer: recursively sort left and right sublists
- Combine: Nothing!

Partition (Divide step)

Given: a list, a pivot p

Start: unordered list

8	5	7	3	12	10	1	2	4	9	6	11

Goal: All elements $< p$ on left, all $> p$ on right

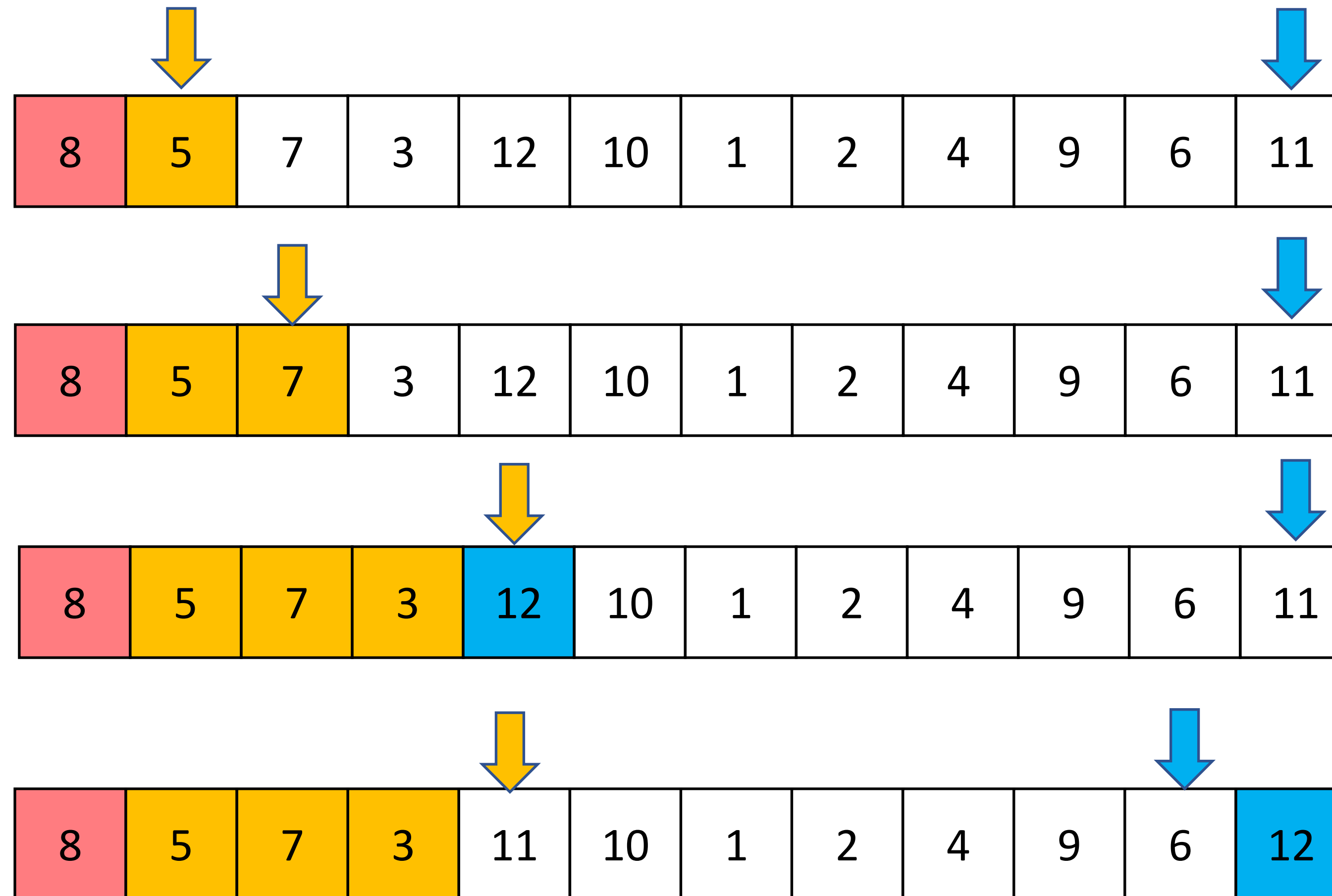
5	7	3	1	2	4	6	8	12	10	9	11

Partition Procedure (Slide 1 of 2)

If Begin value $< p$, move Begin right

Else swap Begin value with End value, move End Left

Done when Begin = End

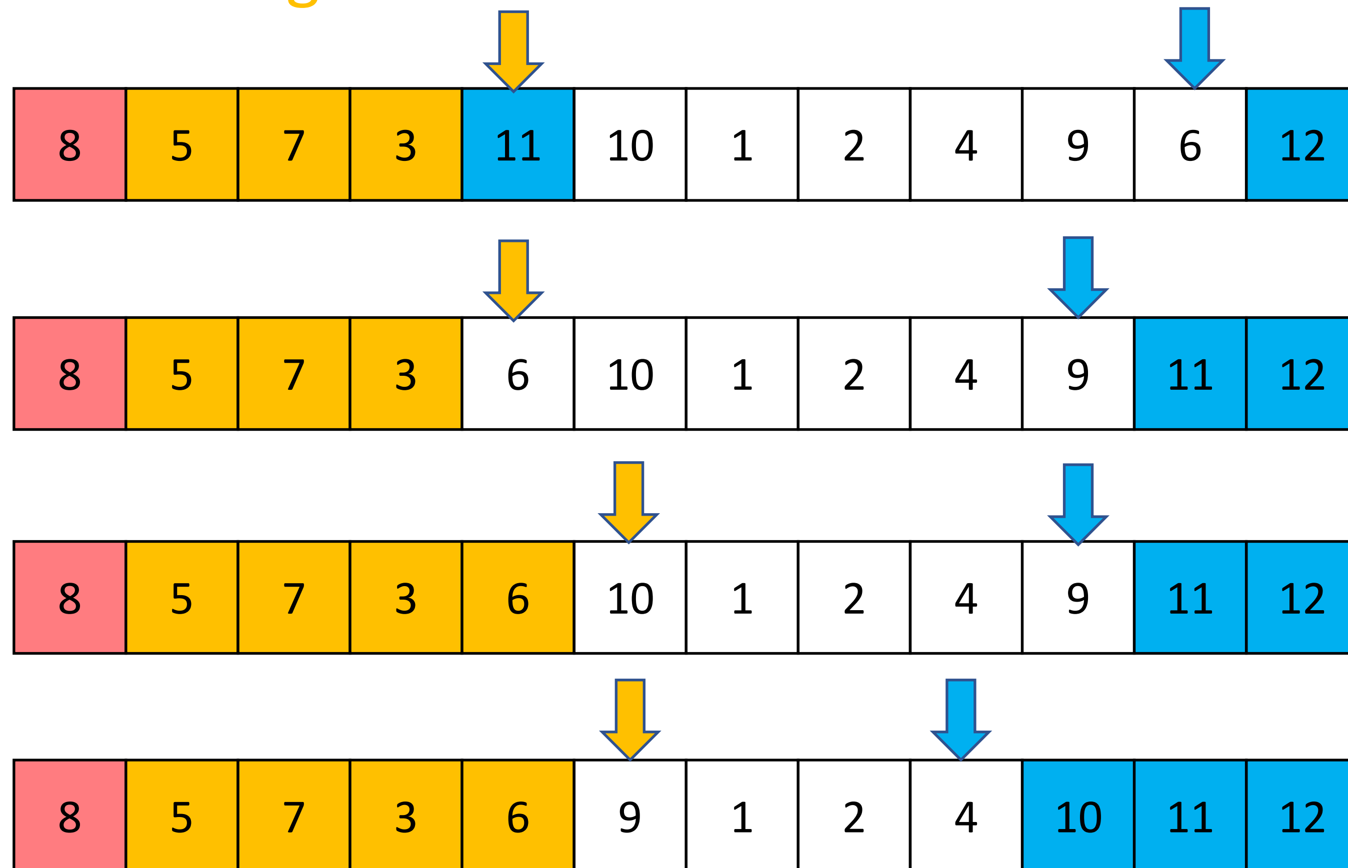


Partition Procedure (Slide 2 of 2)

If Begin value < p, move Begin right

Else swap Begin value with End value, move End Left

Done when Begin = End

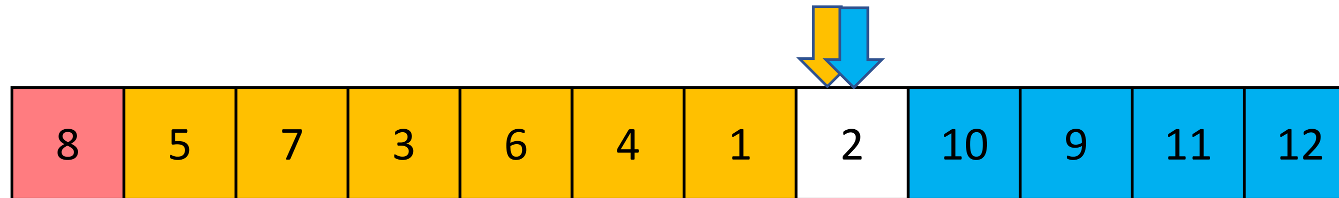


Partition – Begin Meets End (Case 1)

If Begin value $<\ p$, move Begin right

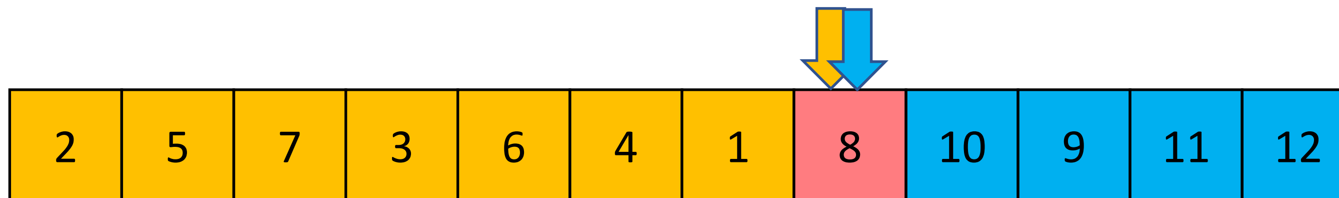
Else swap Begin value with End value, move End Left

Done when Begin = End



Case 1: meet at element $< p$

Swap p with pointer position (2 in this case)

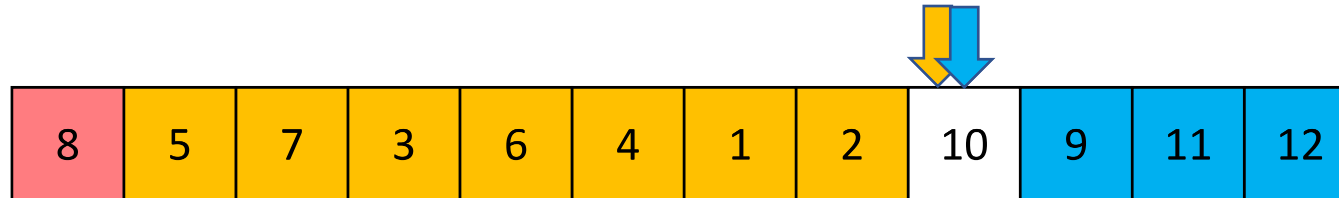


Partition – Begin Meets End (Case 2)

If Begin value $<$ p, move Begin right

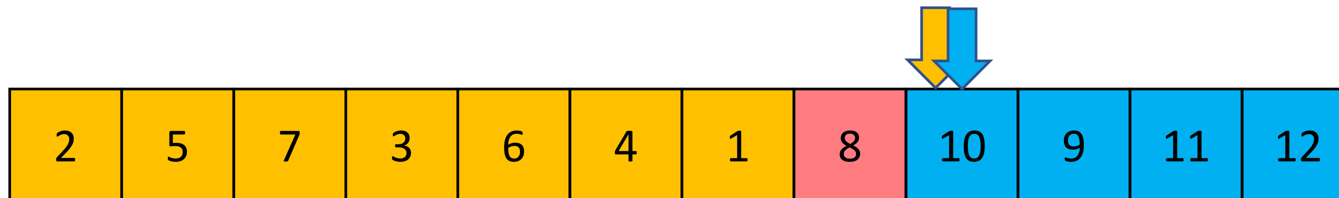
Else swap Begin value with End value, move End Left

Done when Begin = End



Case 2: meet at element $> p$

Swap p with value to the left (2 in this case)

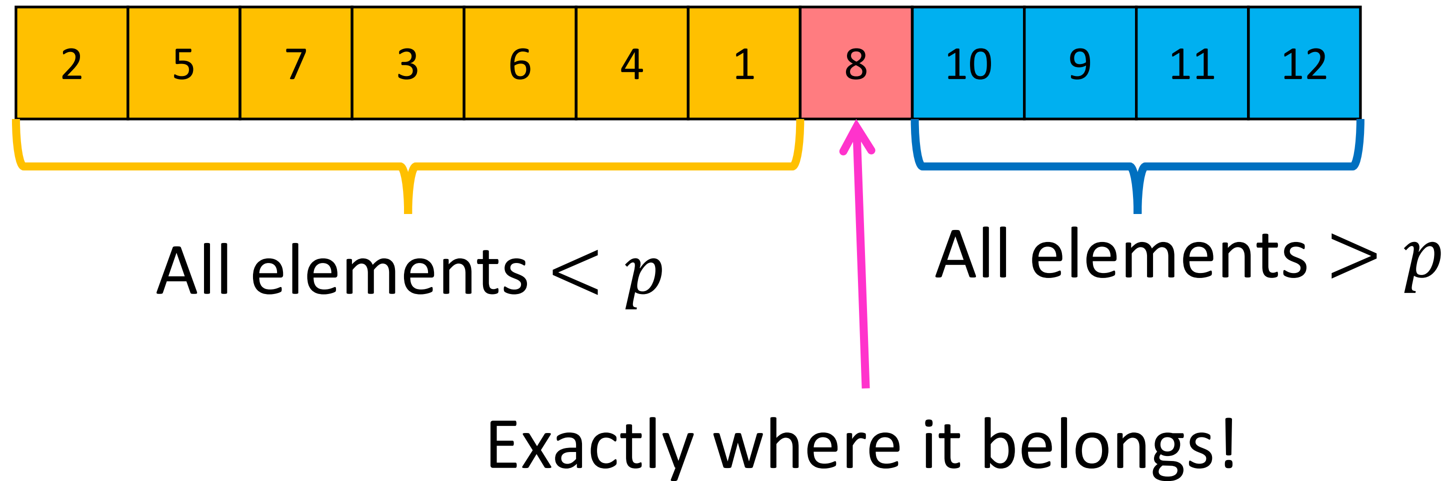


Partition Summary

1. Put p at beginning of list
2. Put a pointer (Begin) just after p, and a pointer (End) at the end of the list
3. While Begin < End:
   1. If Begin value $< p$, move Begin right
   2. Else swap Begin value with End value, move End Left
4. If pointers meet at element $< p$: Swap p with pointer position
5. Else If pointers meet at element $> p$: Swap p with value to the left

Run time? $O(n)$

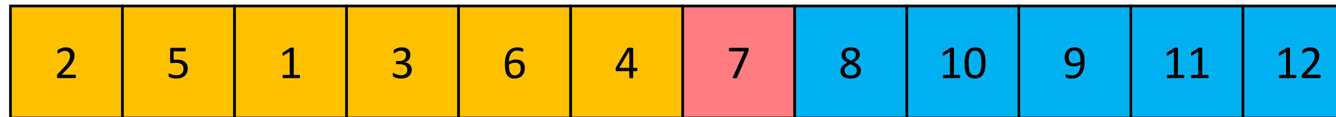
Conquer

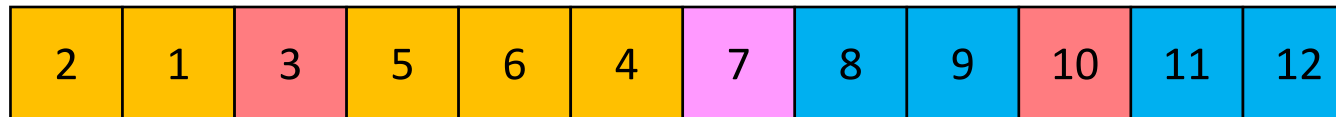


Recursively sort Left and Right sublists

Quicksort Run Time (Best)

If the pivot is always the median:





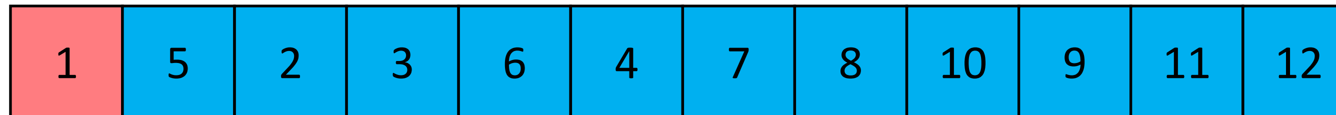
Then we divide in half each time

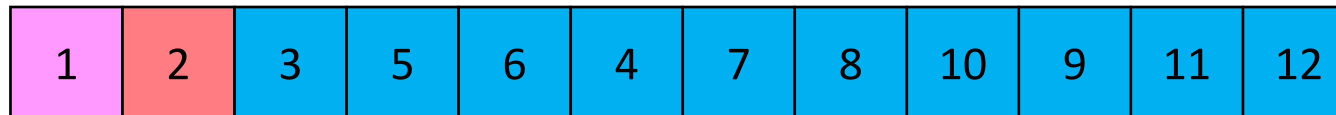
$$T(n) = 2T\left(\frac{n}{2}\right) + n$$

$$T(n) = O(n \log n)$$

Quicksort Run Time (Worst)

If the pivot is always at the extreme:





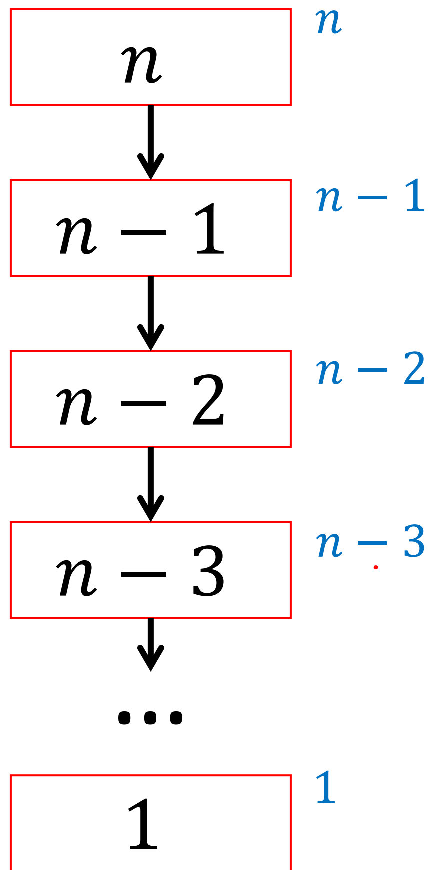
Then we shorten by 1 each time

$$T(n) = T(n-1) + n$$

$$T(n) = O(n^2)$$

Quicksort Worst Case Tree Method

$T(n) = T(n-1) + n$



n levels of recursion

$$T(n) = \sum_{i=0}^{n-1} n - i = \sum_{i=1}^{n} i = \frac{n(n+1)}{2}$$

$$= \Theta(n^2)$$

Good Pivot

- What makes a good Pivot?
  - Roughly even split between left and right
  - Ideally: median
- There are ways to find the median in linear time, but it’s complicated and slow and you’re better off using mergesort
- In Practice:
  - Pick a random value as a pivot
  - Pick the middle of 3 random values as the pivot

Quick Sort Properties

- Worst case running time
  - $\Theta(n^2)$, but “almost always” $\Theta(n \log n)$ in practice
  - Better constants than merge sort
- In place:
  - Kinda…
  - We swap within the given array, but do so using recursion, so we need space for the stack frames
  - Different textbooks disagree on whether call-stack space “counts”
- Adaptive
  - NO!
- Online
  - NO!
  - We need all elements before we can divide
- Stable
  - NO!
  - Partition procedure may rearrange tied elements