

# Minimum Spanning Trees

# Problem 1

# LMNST!

# (Recall) Dijkstra's algorithm pseudocode

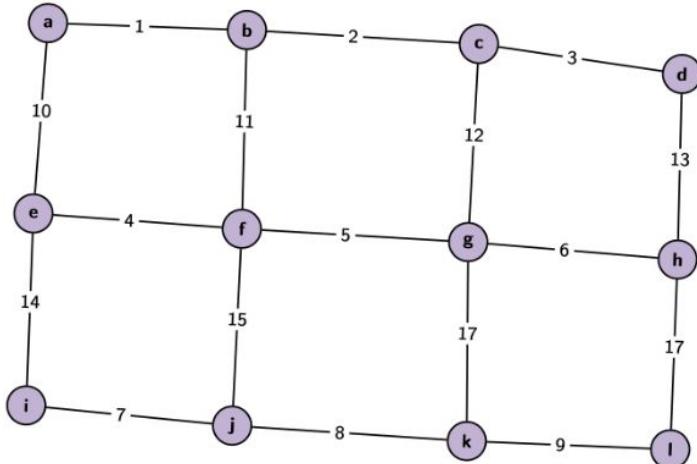
```
dijkstra(Graph G, Node source) {  
    Set<Node> processed = new HashSet<>();  
  
    for each Node n in G.nodes() { n.dist = infinity; } // initialize distances (from source) to  $\infty$   
    PriorityQueue<Node> fringe = new PriorityQueue<>(); // order by min distance  
  
    source.dist = 0 // it takes 0 step to go from source to itself  
    fringe.add(source, 0); // push source in fringe  
  
    while (!fringe.isEmpty()) {  
        Node curr = fringe.removeMin();  
        if (processed.contains(curr)) continue; // once a node is explored, its STP is settled  
        for each Edge (curr,neighbor,w) in curr.outEdges() {  
            if (!processed.contains(neighbor) && curr.dist + w < neighbor.dist) {  
                fringe.updateOrAddPriority(neighbor, curr.dist + w);  
                neighbor.predecessor = curr;  
            }  
        }  
        processed.add(curr); // mark curr node as processed  
    }  
}
```

# Prim's algorithm pseudocode

```
primMST(Graph G) {  
    Graph MST = new Graph<>();  
    Node start = any Node n in G.nodes()  
    Set<Node> processed = new HashSet<>();  
    for each Node n in G.nodes() { n.dist = infinity; } // dist here is just the cost of edge  
    PriorityQueue<Node> fringe = new PriorityQueue<>(); // order by min distance  
    start.dist = 0 // 0 weight to come to the start  
    fringe.add(start, 0); // push start in fringe  
    while (!fringe.isEmpty()) {  
        Node curr = fringe.removeMin();  
        if (processed.contains(curr)) continue; // once a node is explored, its best edge is settled and is in MST  
        if (!curr.equals(start)) MST.addEdge(curr.bestEdge);  
        for each Edge (curr,neighbor,w) in curr.outEdges() {  
            if (!processed.contains(neighbor) && w < neighbor.dist) {  
                fringe.updateOrAddPriority(neighbor, w);  
                neighbor.bestEdge = (curr,neighbor,w);  
            }  
        }  
        processed.add(curr); // mark curr node as processed  
    }}  
}
```

# Q1) LMNST!

**Problem:** Find an MST of this graph. Say which algorithm you're using and show your work. (We will use **Prim's!** We can start from any vertex but will start from a here)



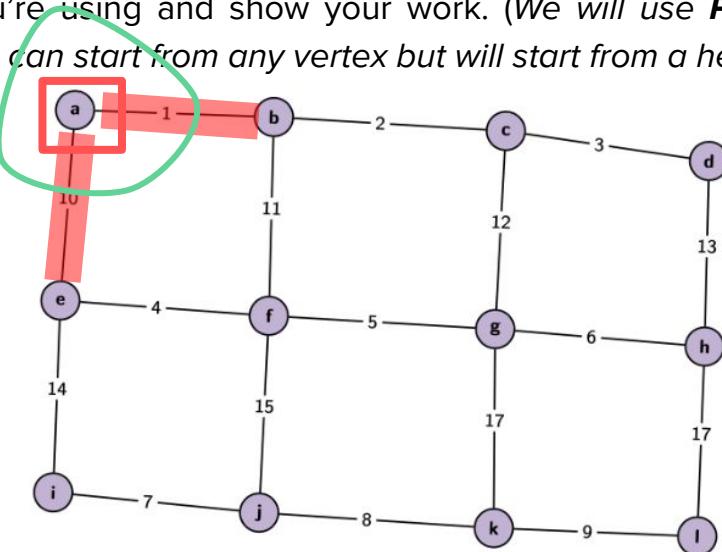
Vertex	Processed?	Cost of Edge	Best Edge
a	N	0	-
b	N	$\infty$	
c	N	$\infty$	
d	N	$\infty$	
e	N	$\infty$	
f	N	$\infty$	
g	N	$\infty$	
h	N	$\infty$	
i	N	$\infty$	
j	N	$\infty$	
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)							

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Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N	$\infty$ 1	(a,b)
c	N	$\infty$	
d	N	$\infty$	
e	N	$\infty$ 10	(a,e)
f	N	$\infty$	
g	N	$\infty$	
h	N	$\infty$	
i	N	$\infty$	
j	N	$\infty$	
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)	(b,1)	(e,10)				

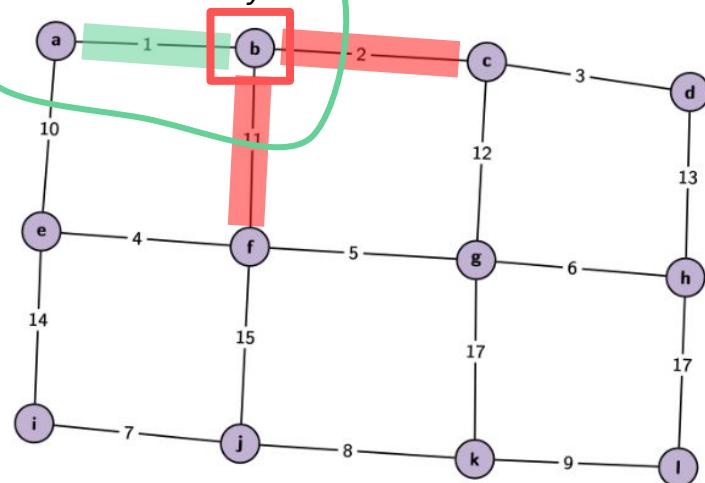
Add/Update priority

No need to update priority

Pop the node and settle the best edge coming into it

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Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
c	N	$\infty$ 2	(b,c)
d	N	$\infty$	
e	N	$\infty$ 10	(a,e)
f	N	$\infty$ 11	(b,f)
g	N	$\infty$	
h	N	$\infty$	
i	N	$\infty$	
j	N	$\infty$	
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,11)			

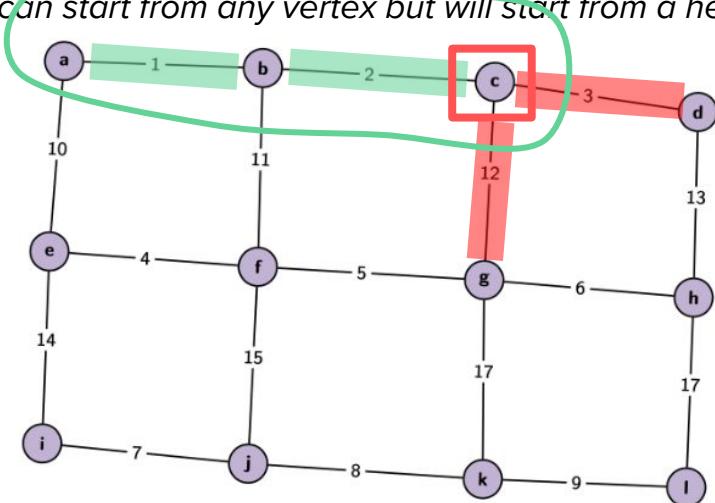
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c	N Y	$\infty$ 2	(b,c)
d	N	$\infty$ 3	(c,d)
e	N	$\infty$ 10	(a,e)
f	N	$\infty$ 11	(b,f)
g	N	$\infty$ 12	(c,g)
h	N	$\infty$	
i	N	$\infty$	
j	N	$\infty$	
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,11)	(d,3)	(g,12)	

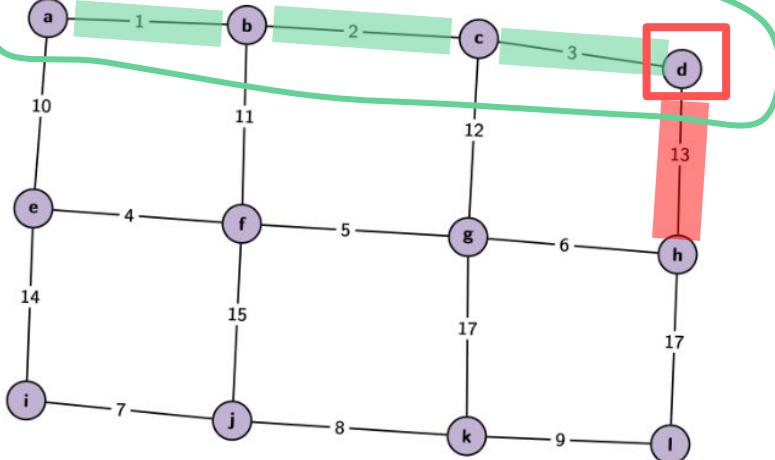
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d	N Y	$\infty$ 3	(c,d)
e	N	$\infty$ 10	(a,e)
f	N	$\infty$ 11	(b,f)
g	N	$\infty$ 12	(c,g)
h	N	$\infty$ 13	(d,h)
i	N	$\infty$	
j	N	$\infty$	
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,11)	(d,3)	(g,12)	(h,13)

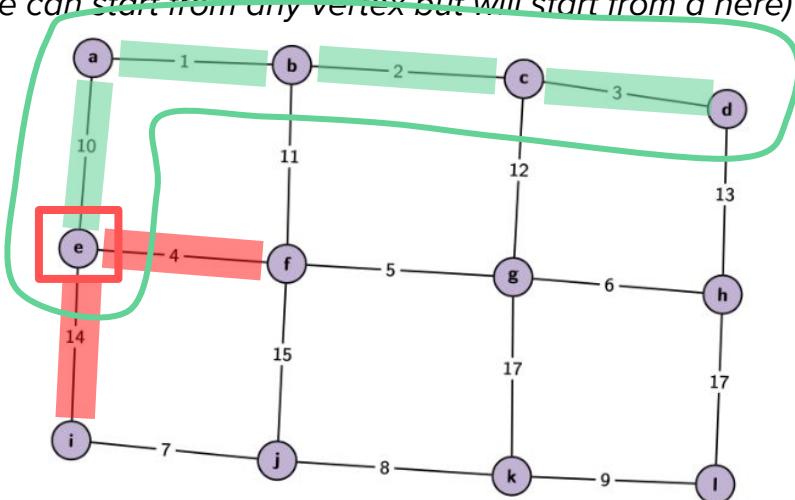
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c	N Y	$\infty$ 2	(b,c)
d	N Y	$\infty$ 3	(c,d)
e	N Y	$\infty$ 10	(a,e)
f	N	$\infty$ 4	(b,f) (e,f)
g	N	$\infty$ 12	(c,g)
h	N	$\infty$ 13	(d,h)
i	N	$\infty$ 14	(e,i)
j	N	$\infty$	
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)	(b,1)	(e,10)	(e,2)	(f,4)	(d,3)	(g,12)	(h,13)
(i,14)							

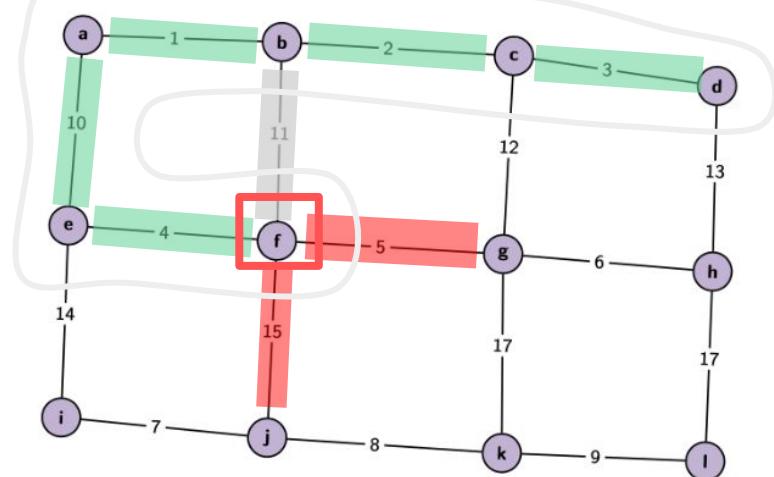
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d	N Y	$\infty$ 3	(c,d)
e	N Y	$\infty$ 10	(a,e)
f	N Y	$\infty$ 4	(b,f) (e,f)
g	N	$\infty$ 5	(e,g) (f,g)
h	N	$\infty$ 13	(d,h)
i	N	$\infty$ 14	(e,i)
j	N	$\infty$ 15	(f,j)
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)	(b,1)	(e,10)	(e,2)	(f,4)	(d,3)	(g,5)	(h,13)
(i,14)	(j,15)						

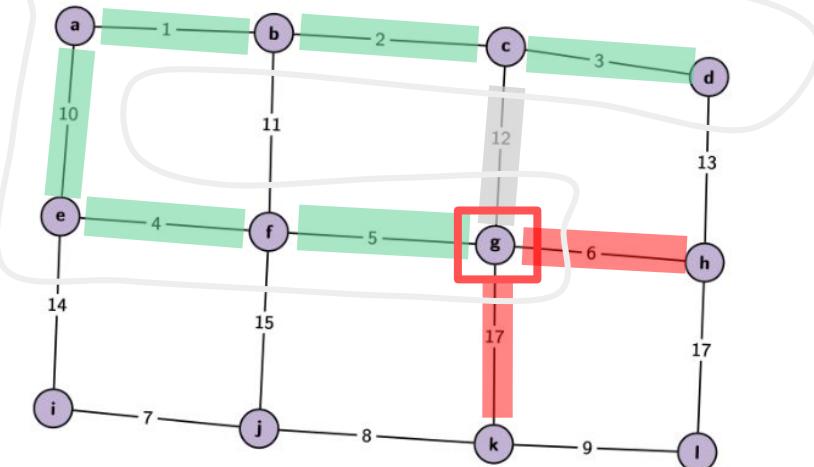
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Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,4)	(d,3)	(g,5)	(h,6)
(i,14)	(j,15)	(k,17)					

Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
c	N Y	$\infty$ 2	(b,c)
d	N Y	$\infty$ 3	(c,d)
e	N Y	$\infty$ 10	(a,e)
f	N Y	$\infty$ 14 4	(b,f) (e,f)
g	N Y	$\infty$ 12 5	(e,g) (f,g)
h	N	$\infty$ 13 6	(d,h) (g,h)
i	N	$\infty$ 14	(e,i)
j	N	$\infty$ 15	(f,j)
k	N	$\infty$ 17	(g,k)
l	N	$\infty$	

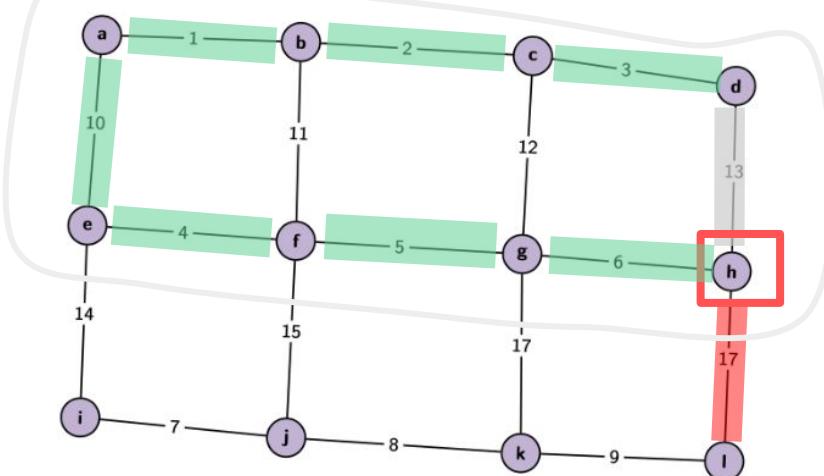
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h	N Y	$\infty$ 13 6	(d,h) (g,h)
i	N	$\infty$ 14	(e,i)
j	N	$\infty$ 15	(f,j)
k	N	$\infty$ 17	(g,k)
l	N	$\infty$ 17	(h,l)

Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,4)	(d,3)	(g,5)	(h,6)
(i,14)	(j,15)	(k,17)	(l,17)				

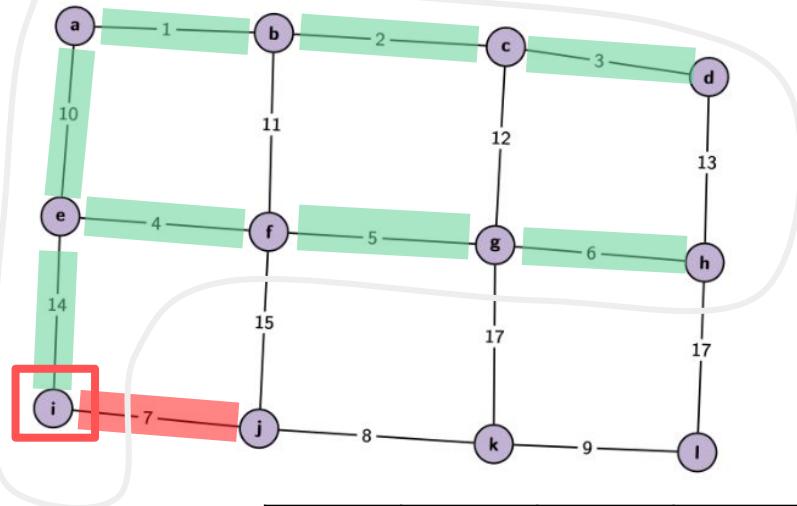
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Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,4)	(d,3)	(g,5)	(h,6)
(i,14)	(j,7)	(k,17)	(l,17)				

Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
c	N Y	$\infty$ 2	(b,c)
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k	N	$\infty$ 17	(g,k)
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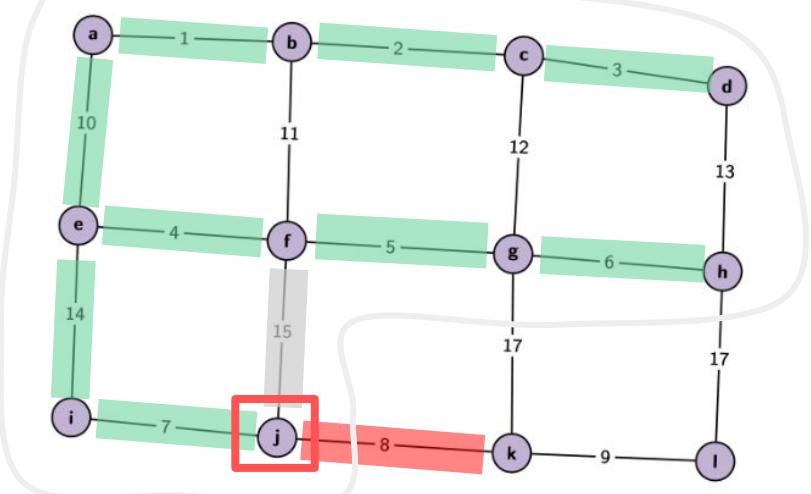
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Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,4)	(d,3)	(g,5)	(h,6)
(i,14)	(j,7)	(k,8)	(l,17)				

Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
c	N Y	$\infty$ 2	(b,c)
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e	N Y	$\infty$ 10	(a,e)
f	N Y	$\infty$ 14	(b,f) (e,f)
g	N Y	$\infty$ 12	(c,g) (f,g)
h	N Y	$\infty$ 13	(d,h) (g,h)
i	N Y	$\infty$ 14	(e,i)
j	N Y	$\infty$ 15	(f,j) (i,j)
k	N	$\infty$ 17	(g,k) (j,k)
l	N	$\infty$ 17	(h,l)

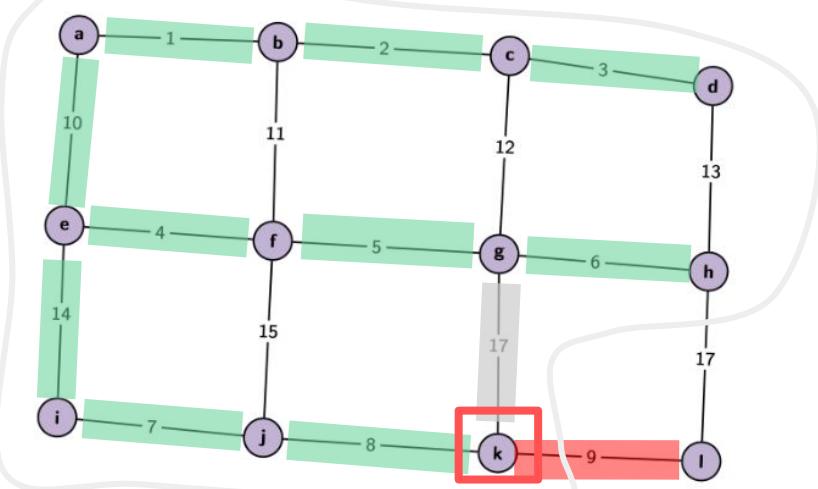
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Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,4)	(d,3)	(g,5)	(h,6)
(i,14)	(j,7)	(k,8)	(l,9)				

Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
c	N Y	$\infty$ 2	(b,c)
d	N Y	$\infty$ 3	(c,d)
e	N Y	$\infty$ 10	(a,e)
f	N Y	$\infty$ 14	(b,f) (e,f)
g	N Y	$\infty$ 12	(c,g) (f,g)
h	N Y	$\infty$ 13	(d,h) (g,h)
i	N Y	$\infty$ 14	(e,i)
j	N Y	$\infty$ 15	(f,j) (i,j)
k	N Y	$\infty$ 17	(g,k) (j,k)
l	N	$\infty$ 17	(h,l) (k,l)

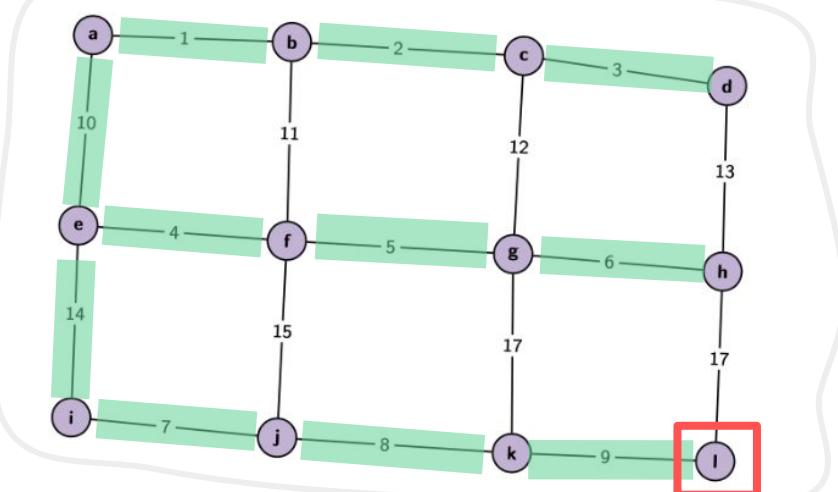
Add/Update priority

No need to update priority

Pop the node and settle the best edge coming into it

# Q1) LMNST!

**Problem:** Find an MST of this graph. Say which algorithm you're using and show your work. (We will use **Prim's!** We can start from any vertex but will start from a here)



Priority Queue:

(a,0)	(b,1)	(e,10)	(c,2)	(f,4)	(d,3)	(g,5)	(h,6)
(i,14)	(j,7)	(k,8)	(l,9)				

Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
c	N Y	$\infty$ 2	(b,c)
d	N Y	$\infty$ 3	(c,d)
e	N Y	$\infty$ 10	(a,e)
f	N Y	$\infty$ 14 4	(b,f) (e,f)
g	N Y	$\infty$ 12 5	(c,g) (f,g)
h	N Y	$\infty$ 13 6	(d,h) (g,h)
i	N Y	$\infty$ 14	(e,i)
j	N Y	$\infty$ 15 7	(f,j) (i,j)
k	N Y	$\infty$ 17 8	(g,k) (j,k)
l	N Y	$\infty$ 17 9	(h,l) (k,l)

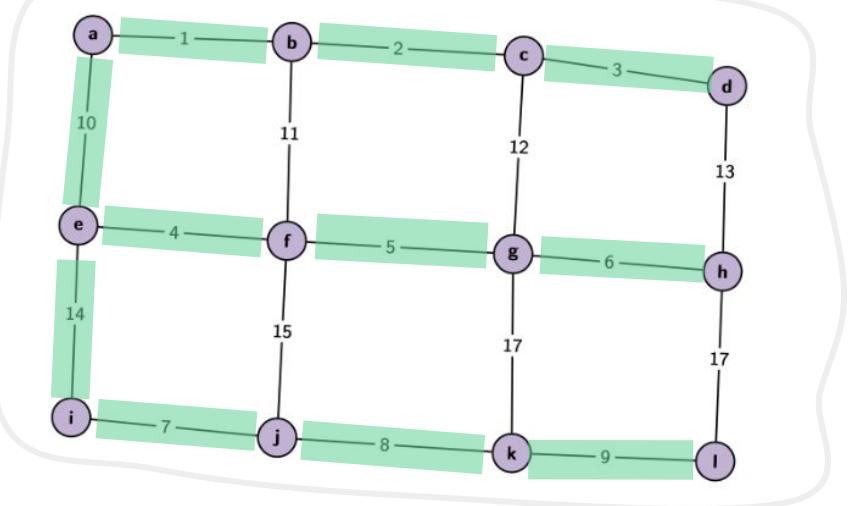
Add/Update priority

No need to update priority

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# Q1) LMNST!

**Problem:** Find an MST of this graph. Say which algorithm you're using and show your work. (We will use **Prim's!** We can start from any vertex but will start from a here)

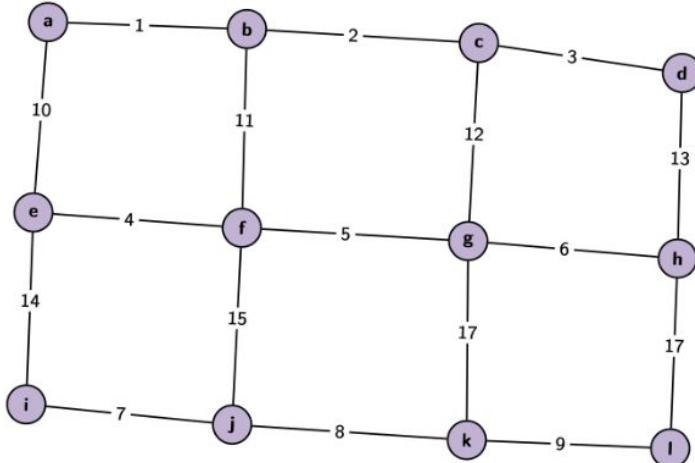


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a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
c	N Y	$\infty$ 2	(b,c)
d	N Y	$\infty$ 3	(c,d)
e	N Y	$\infty$ 10	(a,e)
f	N Y	$\infty$ 14	<del>(b,f)</del> (e,f)
g	N Y	$\infty$ 12	<del>(c,g)</del> (f,g)
h	N Y	$\infty$ 13	<del>(d,h)</del> (g,h)
i	N Y	$\infty$ 14	(e,i)
j	N Y	$\infty$ 15	<del>(f,j)</del> (i,j)
k	N Y	$\infty$ 17	<del>(g,k)</del> (j,k)
l	N Y	$\infty$ 17	<del>(h,l)</del> (k,l)

Total Weight of the MST:  $1 + 2 + 3 + 10 + 4 + 5 + 6 + 14 + 7 + 8 + 9 = 69$

# Q1) LMNST! - Breakout 1

**Problem:** Find an MST of this graph. Say which algorithm you're using and show your work. (We will use **Prim's!** We can start from any vertex but will start from a here)



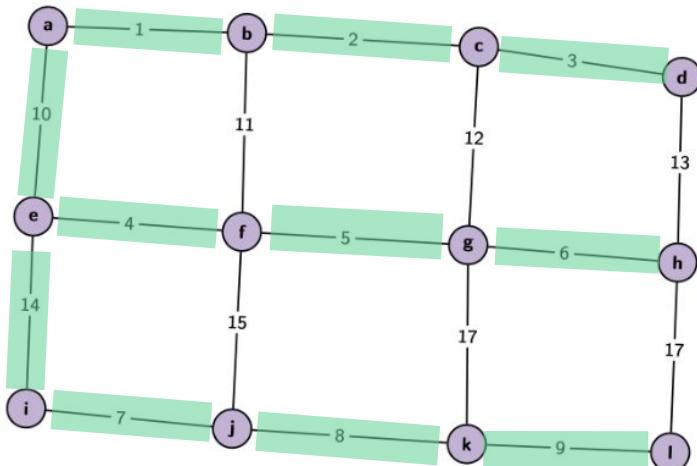
Vertex	Processed?	Cost of Edge	Best Edge
a	N	0	-
b	N	$\infty$	
c	N	$\infty$	
d	N	$\infty$	
e	N	$\infty$	
f	N	$\infty$	
g	N	$\infty$	
h	N	$\infty$	
i	N	$\infty$	
j	N	$\infty$	
k	N	$\infty$	
l	N	$\infty$	

Priority Queue:

(a,0)							

## Q1b) LMNST!

b) Using just the graph, how can you determine if it's possible that there are multiple MSTs of the graph? Does this graph have multiple MSTs?

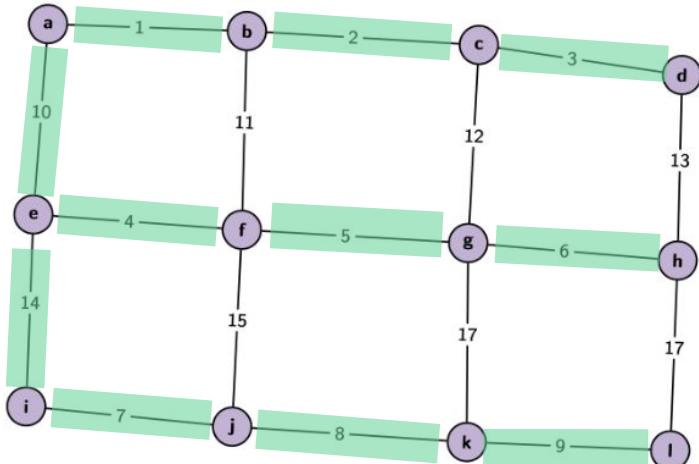


Vertex	Processed?	Cost of Edge	Best Edge
a	N Y	0	-
b	N Y	$\infty$ 1	(a,b)
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g	N Y	$\infty$ 12 5	<del>(c,g)</del> (f,g)
h	N Y	$\infty$ 13 6	<del>(d,h)</del> (g,h)
i	N Y	$\infty$ 14	(e,i)
j	N Y	$\infty$ 15 7	<del>(f,j)</del> (i,j)
k	N Y	$\infty$ 17 8	<del>(g,k)</del> (j,k)
l	N Y	$\infty$ 17 9	<del>(h,l)</del> (k,l)

A graph can only have multiple MSTs if it has **multiple edges of the same weight**. This graph has two 17's, but neither of them are used in the MST. So, there's only one MST here.

# Q1c) LMNST!

c) What is the asymptotic runtime of the algorithms that you used to compute the MSTs?



Vertex	Processed?	Cost of Edge	Best Edge
a	No	0	-
b	No	$\infty$ 1	(a,b)
c	No	$\infty$ 2	(b,c)
d	No	$\infty$ 3	(c,d)
e	No	$\infty$ 10	(a,e)
f	No	$\infty$ 11 4	(b,f) (e,f)
g	No	$\infty$ 12 5	(c,g) (f,g)
h	No	$\infty$ 13 6	(d,h) (g,h)
i	No	$\infty$ 14	(e,i)
j	No	$\infty$ 15 7	(f,j) (i,j)
k	No	$\infty$ 17 8	(g,k) (j,k)
l	No	$\infty$ 17 9	(h,l) (k,l)

Prim's algorithm - similar to Dijkstra's, it takes  $O(|V| \log |V| + |E| \log |V|)$

Kruskal's algorithm - sort edges by weights and use union-find to detect cycle while adding edges into MST. It takes  $O(|E| \log |E| + E * O(\log^*(|V|)) + V * O(\log^*(|V|))) \approx O(|E| \log |E|)$ , assuming path-compression UF is used.