

CSE 332: Data Structures & Parallelism Lecture 10:More Hashing

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Announcements

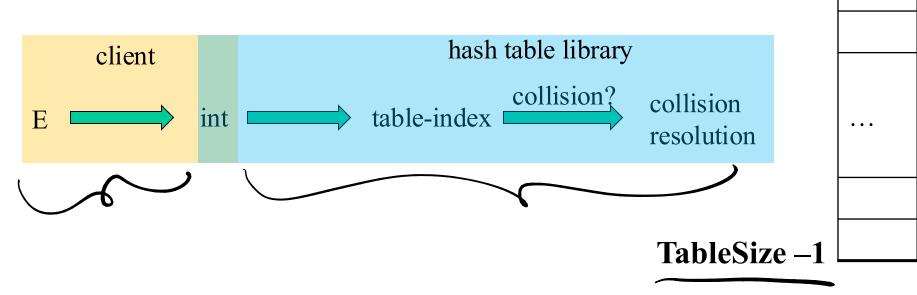
- EX04 Released
 - Start early!
- Exam 1 next Friday

Today

- Dictionaries
 - Finish Hashing

Hash Tables: Review

- Aim for constant-time (i.e., O(1)) find, insert, and delete
 - "On average" under some reasonable assumptions
- A hash table is an array of some fixed size
 - But growable as we'll see



hash table

Hashing Choices

- Choose a Hash function client
- Choose TableSize implementer
- Choose a Collision Resolution Strategy from these: implement
 - Separate Chaining
 - Open Addressing
 - Linear Probing
 - Quadratic Probing
 - Double Hashing -
- Other issues to consider:
 - deletion/actuelly remove - Deletion? -> Lazy
 - What to do when the hash table gets "too full"?

Why not use up the empty space in the table? 0 Store directly in the array cell (no linked list) How to deal with collisions? If h (key) is already full, - try (h(key) + 1) % TableSize. If full, - try (h(key) + 2) % TableSize. If full, - try (h(key) + 3) % TableSize. If full... 6 Example: insert 38, 19, 8, 8 38 9

- Another simple idea: If h (key) is already full,
 - try (h(key) + 1) % TableSize. If full,
 - try (h(key) + 2) % TableSize. If full,
 - try (h(key) + 3) % TableSize. If full...
- Example: insert 38, 19, 8, 109, 10

0	/
1	/
2	/
3	/
4	/
5	/
6	/
7	/
8	38
9	19

- Another simple idea: If h (key) is already full,
 - try (h(key) + 1) % TableSize. If full,
 - try (h(key) + 2) % TableSize. If full,
 - try (h(key) + 3) % TableSize. If full...
- Example: insert 38, 19, 8, 109, 10

0	8
1	/
2	/
3	/
4	/
5	/
6	/
7	/
8	38
9	19

- Another simple idea: If h (key) is already full,
 - try (h(key) + 1) % TableSize. If full,
 - try (h(key) + 2) % TableSize. If full,
 - try (h(key) + 3) % TableSize. If full...
- Example: insert 38, 19, 8, 109, 10

0	8
1	109
2	/
3	/
4	/
5	/
6	/
7	/
8	38
9	19

- Another simple idea: If h (key) is already full,
 - try (h(key) + 1) % TableSize. If full,
 - try (h(key) + 2) % TableSize. If full,
 - try (h(key) + 3) % TableSize. If full...
- Example: insert 38, 19, 8, 109, 10

0	8	
1	109	
2	10	
2 3	/	
4	/	
4567	/	
6	/	
7	/	
	38	
89	19	

Open addressing

Linear probing is one example of open addressing

In general, open addressing means resolving collisions by trying a sequence of other positions in the table.

Trying the *next* spot is called probing

- We just did linear probing:
 - ith probe: (h(key) + i) % TableSize
- In general have some probe function f and :
- ith probe: (h(key) + f(i)) % TableSize $qudrati(: f(i) = i^2)$

Open addressing does poorly with high load factor λ

- So want larger tables
- Too many probes means no more O(1)

Questions: Open Addressing: Linear Probing

How should **find** work? If value is in table? If not there?

Worst case scenario for find?

How should we implement delete?

How does **open addressing with linear probing** compare to **separate chaining**?



Open Addressing: Other Operations Fund (3)

insert finds an open table position using a probe function

What about find?

- Must use same probe function to "retrace the trail" for the data
- Unsuccessful search when reach empty position

What about delete?

- Must use "lazy" deletion. Why?
 - Marker indicates "no data here, but don't stop probing"

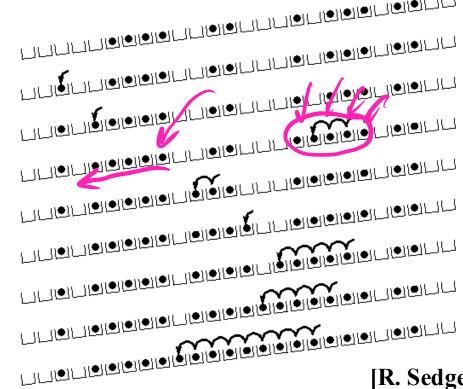
10	×	/	23	/	/	16	*	26

- As with lazy deletion on other data structures, on insert, spots marked "deleted" can be filled in.
- Note: delete with chaining is just calling delete on the bucket 2/21/2023 (e.g. linked list)

Primary Clustering

It turns out linear probing is a bad idea, even though the probe function is quick to compute (a good thing)

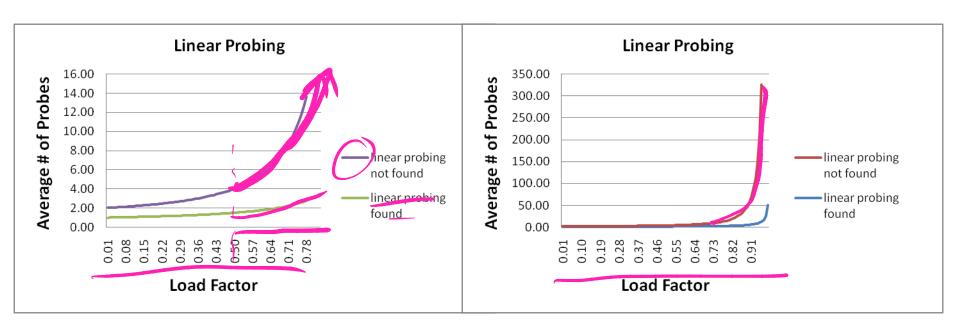
- Tends to produce clusters, which lead to long probe sequences
- Called primary clustering
- Saw the start of a cluster in our linear probing example



[R. Sedgewick]

Analysis in chart form

- Linear-probing performance degrades rapidly as table gets full
 - (Formula assumes "large table" but point remains)



 By comparison, separate chaining performance is linear in λ and has no trouble with λ>1

```
(h(key) + f(i)) % TableSize
```

– For linear probing:

$$f(i) = i$$

- So probe sequence is:
 - 0th probe: h(key) % TableSize
 - 1st probe: (h(key) + 1) % TableSize
 - 2nd probe: (h(key) + 2) % TableSize
 - 3rd probe: (h(key) + 3) % TableSize
 - •
 - ith probe: (h(key) + i) % TableSize

Open Addressing: Quadratic probing

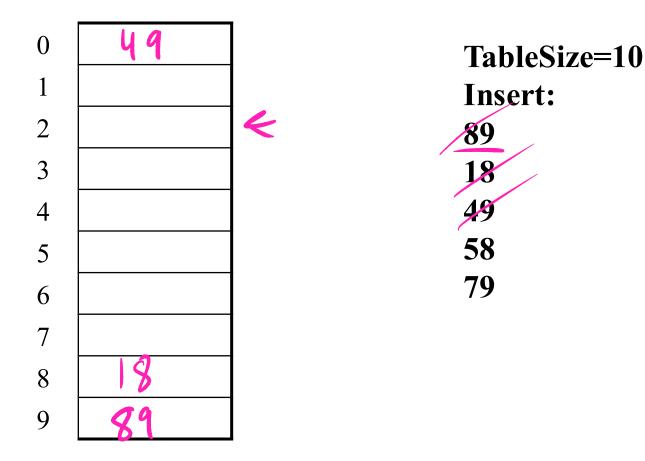
We can avoid primary clustering by changing the probe function...

```
(h(key) + f(i)) % TableSize
```

- For quadratic probing:
 f(i) = i²
- So probe sequence is:
 - 0th probe: h(key) % TableSize
 - 1st probe: (h(key) + 1) % TableSize
 - 2nd probe: (h(key) + 4) % TableSize
 - 3rd probe: (h(key) + 9) % TableSize
 - ...
 - ith probe: (h(key) + i²) % TableSize
- Intuition: Probes quickly "leave the neighborhood"

ith probe: (h (key) + i²) % TableSize

Quadratic Probing Example



TableSize = 10 insert(89)

7 |

TableSize = 10

insert(89)

insert(18)

0

1

2

3

4

5

6

7

8 | 18

9 | 89

TableSize = 10

insert(89)

insert(18)

insert(49)

0 49

1 |

2

3

4

5

6

7

8 | 18

9 | 89

TableSize = 10

insert(89)

insert(18)

insert(49)

49 % 10 = 9 collision!

(49 + 1) % 10 = 0

insert(58)

0	49
1	
2	58
2	
4	
5	
6	
7	
8	18
9	89

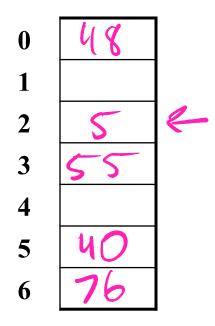
```
TableSize = 10
insert(89)
insert(18)
insert(49)
insert(58)
    58 \% 10 = 8  collision!
    (58 + 1) \% 10 = 9  collision!
    (58 + 4) \% 10 = 2
insert(79)
```

0	49
1	
2	58
3	79
4	
5	
6	
7	
8	18
9	89

```
TableSize = 10
insert(89)
insert(18)
insert(49)
insert(58)
insert(79)
    79 \% 10 = 9  collision!
    (79 + 1) \% 10 = 0 collision!
    (79 + 4) \% 10 = 3
```

ith probe: $(h (key) + i^2) % TableSize$

Another Quadratic Probing Example



TableSize = 7

Insert:

76	(76 % 7 = 6)
40	(40 % 7 = 5)
48	(48 % 7 = 6)
5	(5 % 7 = 5)
5/5	(55 % 7 = 6)
47	(47 % 7 = 5)

0

1

2

3

4

5

6 76

TableSize = 7

Insert:

76

(76 % 7 = 6)

40

(40 % 7 = 5)

48

(48 % 7 = 6)

5

(5 % 7 = 5)

55

(55 % 7 = 6)

47



1

2

3

4

5

6 | 76

40

TableSize = 7

Insert:

$$(76 \% 7 = 6)$$

$$(40 \% 7 = 5)$$

$$(48 \% 7 = 6)$$

$$(5 \% 7 = 5)$$

$$(55 \% 7 = 6)$$

$$(47 \% 7 = 5)$$

0

1

2

48

3

4

5

6 | 76

40

TableSize = 7

Insert:

76

(76 % 7 = 6)

40

(40 % 7 = 5)

48

(48 % 7 = 6)

5

(5 % 7 = 5)

55

(55 % 7 = 6)

47

0

1

2 5

48

3

4

5 | 40

6 | 76

TableSize = 7

Insert:

76

(76 % 7 = 6)

40

(40 % 7 = 5)

48

(48 % 7 = 6)

5

(5 % 7 = 5)

55

(55 % 7 = 6)

47

0

1

2 | 5

48

55

3

4

5 | 40

6 | 76

TableSize = 7

Insert:

76

(76 % 7 = 6)

40

(40 % 7 = 5)

48

(48 % 7 = 6)

5

(5 % 7 = 5)

55

(55 % 7 = 6)

47

ith probe: (h (key) + i²) % TableSize

Another Quadratic Probing Example

76

Will we ever get a 1 or

4?!?

6

TableSize = 7

Insert:

76
$$(76 \% 7 = 6)$$

$$40 (40 \% 7 = 5)$$

48
$$(48 \% 7 = 6)$$

$$5 (5 \% 7 = 5)$$

55
$$(55 \% 7 = 6)$$

47
$$(47 \% 7 = 5)$$

$$(47 + 1) \% 7 = 6$$
 collision!

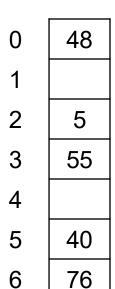
$$(47 + 4) \% 7 = 2$$
 collision!

$$(47 + 9) \% 7 = 0$$
 collision!

$$(47 + 16) \% 7 = 0$$
 collision!

$$(47 + 25) \% 7 = 2$$
 collision!

insert(47) will always fail here. Why?



For all
$$i$$
, $(5 + i^2)$ % 7 is $(0, 2, 5, \text{ or } 6)$

Proof uses induction and

$$(5 + i^2) \% 7 = (5 + (i - 7)^2) \% 7$$

In fact, for all c and k,

$$(c + i^2)$$
 % $k = (c + (i - k)^2)$ % k

From bad news to good news

Bad News:

 After Tablesize quadratic probes, we cycle through the same indices

Good News:

- If TableSize is prime and $\lambda < \frac{1}{2}$, then quadratic probing will find an empty slot in at most TableSize/2 probes
- So: If you keep $\lambda < \frac{1}{2}$ and TableSize is *prime*, no need to detect cycles
- Proof posted in lecture10.txt (slightly less detailed proof in textbook)
 For prime TableSize and 0 ≤ i, j ≤ TableSize/2 where i ≠ j,
 (h(key) + i²) % TableSize ≠ (h(key) + j²) % TableSize

That is, if **TableSize** is prime, the first **TableSize**/2 quadratic probes map to different locations (and one of those will be empty if the table is < half full).

Clustering reconsidered

- h(k)+1 h/k)+4
- Quadratic probing does not suffer from primary clustering:
 As we resolve collisions we are not merely growing "big blobs" by adding one more item to the end of a cluster, we are looking i² locations away, for the next possible spot.
- But quadratic probing does not help resolve collisions between keys that initially hash to the same index
 - Any 2 keys that initially hash to the same index will have the same series of moves after that looking for any empty spot
 - Called secondary clustering
- Can avoid secondary clustering with a probe function that depends on the key: double hashing...

Open Addressing: Double hashing

```
Idea: Given two good hash functions h and g, and two different keys k1
  and k2, it is very unlikely that: h(k1) == h(k2) and g(k1) == g(k2)
       (h(key) + f(i)) % TableSize
   – For double hashing:
                   f(i) = i*g(key)

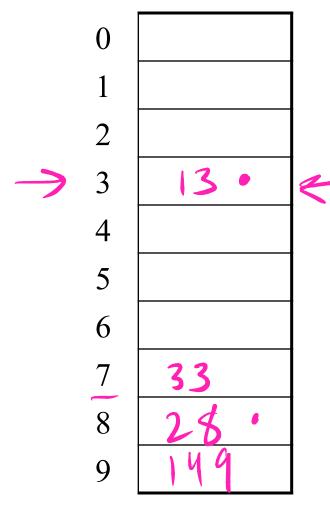
So probe sequence is:

       • 0th probe: h (key) % TableSize
       • 1st probe: (h(key) + g(key)) % TableSize
       • 2<sup>nd</sup> probe: (h(key) + 2*g(key)) % TableSize
       • 3<sup>rd</sup> probe: (h(key) + 3*g(key)) % TableSize
       • ith probe: (h(key) + i*g(key)) % TableSize
```

Detail: Make sure g (key) can't be 0

ith probe: (h(key) + i*g(key)) % TableSize

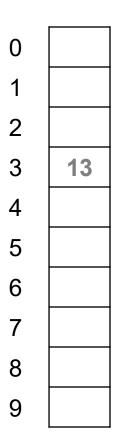
Open Addressing: Double Hashing



Insert these values into the hash table in this order. Resolve any collisions with double hashing:

13.
$$h(13) = 3$$

28. $h(28) = 8$
33. $h(33) = 3, g(33) = 4$
147. $h(147) = 7, g(147) = 6$
43. $h(143) = 3$
 $g(43) = 5$



```
T = 10 (TableSize)

<u>Hash Functions</u>:

h(key) = key mod T

g(key) = 1 + ((key/T) mod (T-1))
```

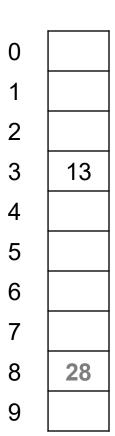
Insert these values into the hash table in this order. Resolve any collisions with double hashing:

13

28

33

147



```
T = 10 (TableSize)

Hash Functions:

h(key) = key mod T

g(key) = 1 + ((key/T) mod (T-1))
```

Insert these values into the hash table in this order. Resolve any collisions with double hashing:

13

28

33

147



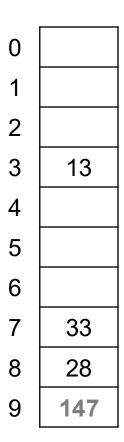
Insert these values into the hash table in this order. Resolve any collisions with double hashing:

13

28

$$33 \rightarrow g(33) = 1 + 3 \mod 9 = 4$$

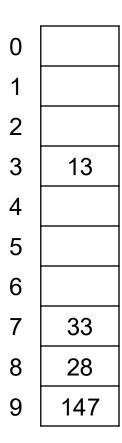
147



Insert these values into the hash table in this order. Resolve any collisions with double hashing:

- 13
- **28**
- 33

147
$$\rightarrow$$
 g(147) = 1 + 14 mod 9 = 6



Insert these values into the hash table in this order. Resolve any collisions with double hashing:

- 13
- 28
- 33

147
$$\rightarrow$$
 g(147) = 1 + 14 mod 9 = 6

43
$$\rightarrow$$
 g(43) = 1 + 4 mod 9 = 5

We have a problem:

$$3 + 0 = 3$$
 $3 + 5 = 8$

$$3 + 5 = 8$$

$$3 + 10 = 13$$

$$3 + 15 = 18$$

$$3 + 20 = 23$$

Double-hashing analysis

Intuition: Since each probe is "jumping" by **g (key)** each time, we "leave the neighborhood" and "go different places from other initial collisions"

But, as in quadratic probing, we could still have a problem where we are not "safe" due to an infinite loop despite room in table:

- No guarantee that i*g(key) will let us try all/most indices
- It is known that this cannot happen in at least one case:

For primes p and q such that
$$2 < q < p$$

$$h(key) = key \% p$$

$$g(key) = q - (key \% q)$$

Yet another reason to use a prime TableSize

- So, for double hashing
 ith probe: (h(key) + i*g(key))% TableSize
- Say g(key) divides Tablesize
 - That is, there is some integer x such that x*g(key)=Tablesize
 - After x probes, we'll be back to trying the same indices as before
- Ex:
 - Tablesize=50
 - g(key)=25
 - Probing sequence:
 - h(key)
 - h(key)+25
 - h(key)+50=h(key)
 - h(key)+75=h(key)+25
- Only 1 & itself divide a prime

Where are we?

- Separate Chaining is easy
 - find, insert, delete proportional to load factor on average if using unsorted linked list nodes
 - If using another data structure for buckets (e.g. AVL tree),
 runtime is proportional to runtime for that structure.
- Open addressing uses probing, has clustering issues as table fills
 Why use it:
 - Less memory allocation?
 - Some run-time overhead for allocating linked list (or whatever) nodes; open addressing could be faster
 - Easier data representation?
- Now:
 - Growing the table when it gets too full (aka "rehashing")

Rehashing

- As with array-based stacks/queues/lists, if table gets too full, create a bigger table and copy everything over
- With separate chaining, we get to decide what "too full" means
 - Keep load factor reasonable (e.g., < 1)?</p>
 - Consider average or max size of non-empty chains?
- For open addressing, half-full is a good rule of thumb
- New table size
 - Twice-as-big is a good idea, except, uhm, that won't be prime!
 - So go about twice-as-big
 - Can have a list of prime numbers in your code since you probably won't grow more than 20-30 times, and then calculate after that

A Generally Good hashCode()

```
int result = 17; // start at a prime
foreach field f
   int fieldHashcode =
    boolean: (f? 1: 0)
    byte, char, short, int: (int) f
    long: (int) (f ^ (f >>> 32))
    float: Float.floatToIntBits(f)
    double: Double.doubleToLongBits(f), then above
    Object: object.hashCode()
    result = 31 * result + fieldHashcode;
return result;
```

Joshua Block

Final word on hashing

- The hash table is one of the most important data structures
 - Efficient find, insert, and delete
 - Operations based on sorted order are not so <u>efficient!</u>
 - Useful in many, many real-world applications
 - Popular topic for job interview questions
- Important to use a good hash function
 - Good distribution, Uses enough of key's components
 - Not overly expensive to calculate (bit shifts good!)
- Important to keep hash table at a good size
 - Prime #)
 - Preferable λ depends on type of table
- Side-comment: hash functions have uses beyond hash tables
 - Examples: Cryptography, check-sums