CSE 332: Data Structures & Parallelism Lecture 16: Graph Traversals

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Administrative

EX06 – On Sorting: Due Fri Nov 7

EX07 – On Graphs: programming, coming soon

Resources!

- Conceptual Office Hours: 11:30 Tues (Connor) and 11:30 Wed (Samarth) both in CSE1 006. A space to ask about course content and topics only as opposed to direct help with exercises.
- <u>1-on-1 Meeting Requests</u> Request a meeting with a staff member if you cannot make it to regularly scheduled office hours, or feel like you have an issue that requires a more in depth discussion.

What do we do with graphs

So many things!

-That's why we said graphs are more general than a single ADT---they don't have a standard set of operations.

As a starting point---how could we process the entire graph? Examine every vertex and every edge?

Called a "search" of the graph or a "traversal"

Two algorithms (with different purposes)

BFS

Start somewhere...

For every vertex (in some order)

Do whatever you want on that vertex

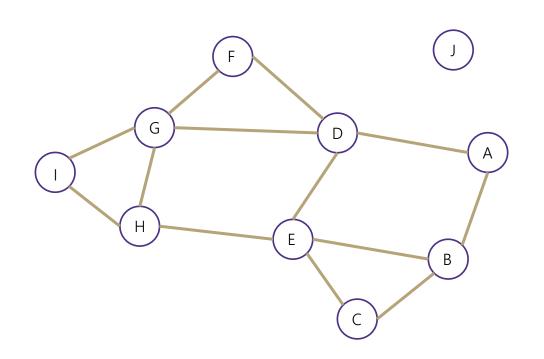
- -Sometimes, record some information, store something in there, etc.
- -At least, we'll mark it as having been "visited"

You need to process all of its neighbors...store them in some data structure to process them. Then back to the top of the loop.

If you use a Queue for your storage structure, you get BFS.

Breadth First Search

```
search (graph)
   toVisit.enqueue(first vertex)
     mark first vertex as visited
   while (to Visit is not empty)
      current = toVisit.dequeue()
      for (V : current.neighbors())
         if (v is not visited)
            toVisit.enqueue(v)
                 mark v as visited
      finished.add(current)
```



Current node:

Queue:

Finished:

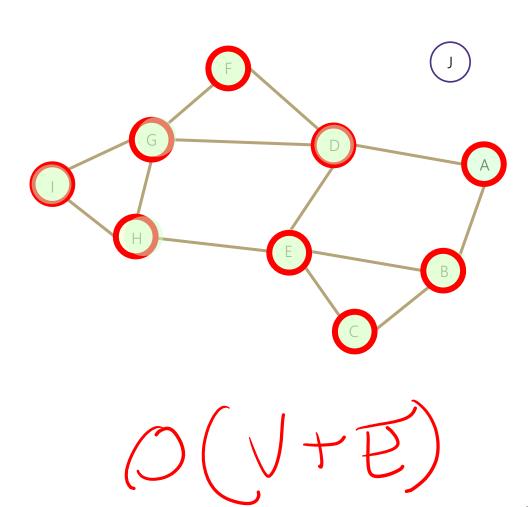
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```

Current node:

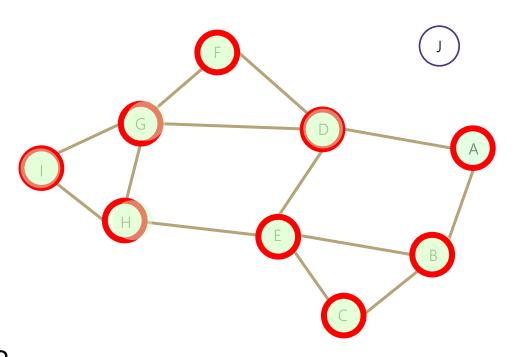
Queue: BDECFGHI

Finished: A B D E C F G H I



Breadth First Search

```
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      for (V : current.neighbors())
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```



What's the running time of this algorithm?

We visit each vertex at most twice, and each edge at most once:

$$O(|V| + |E|)$$

Depth First Search (DFS)

BFS uses a queue to order which vertex we move to next

Gives us a growing "frontier" movement across graph

Can you move in a different pattern? What if you used a stack instead?

```
bfs(graph)
                                     dfs(graph, curr)
   toVisit.enqueue(first vertex)
                                        mark curr as visited
     mark first vertex as visited
                                        for(v : curr.neighbors()){
   while (to Visit is not empty)
                                           if(v is not visited) {
                                              dfs(graph, v)
      current = toVisit.dequeue()
      for (V : current.neighbors())
         if (v is not visited)
            toVisit.enqueue(v)
                                       mark curr as "done"
                  mark v as visited
      finished.add(current)
```

Depth First Search

```
dfs (graph, curr)
   mark curr as visited
  for(v : curr.neighbors()){
      if(v is not visited) {
         dfs(graph, v)
   mark curr as "done"
 Finished:
                                               Call Stack
```

Depth First Search

```
dfs(graph, curr)
---mark curr as visited
   for(v : curr.neighbors()){
      if(v is not visited) {
         dfs(graph, v)
   mark curr as "done"
 Finished: FDGHECBA
                                              Call Stack
```

H;(H,G) E;(E,H) C;(C,E)B;(B,C) A; (A,B)

DFS

Running time?

-Same as BFS: $\Theta(|V| + |E|)$

You can rewrite DFS to be an iterative method (that explicitly uses a stack data structure). Use that in place of the call stack.

Getting the details right is actually pretty annoying/subtle.

Next: Using BFS, DFS and other algorithms to solve problems!

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DFS for applications

Applications for DFS (and BFS) are often:

Run [D/B]FS, and do some extra bookkeeping.

-Many applications work (easily) with only one ordering.

For DFS, it's common to classify based on "start" and "finish" times When vertices go on the (call) stack, and when they come off.

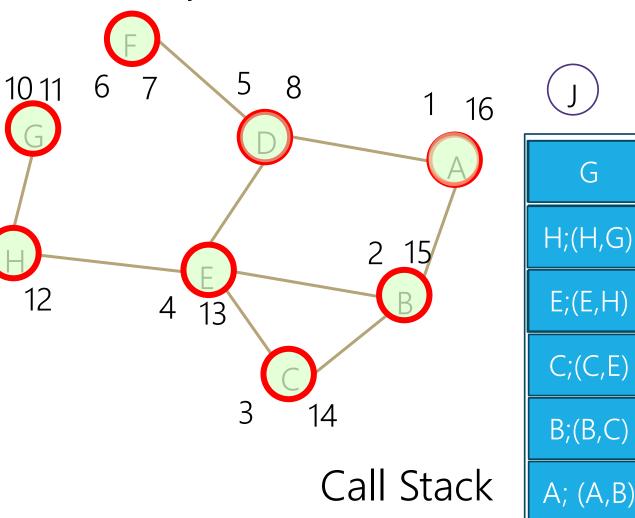
Depth First Search

```
dfs(graph, curr)
   mark curr as visited
  record curr.start
   for(v : curr.neighbors()){
      if(v is not visited) {
         dfs(graph, v)
   mark curr as "done"
   record curr.end
```

Finished: FDGHECBA

(A,B), (B,C), (C,E) cause a new vertex to go on the stack.

(E,B) goes "back" to an edge that's already on the stack, but not finished.



Saving the path

Our graph traversals can answer the "reachability question":

-" *Is there* a path from node x to node y?"

Q: But what if we want to <u>output the actual path</u>?

-Like getting driving directions rather than just knowing it's possible to get there!

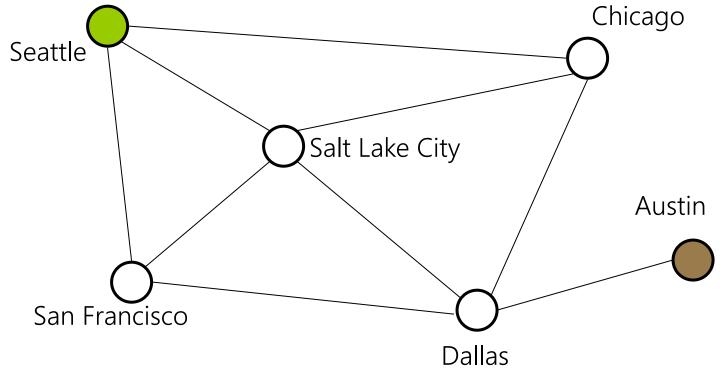
A: Like this:

- -Instead of just "marking" a node, store the <u>previous node</u> along the path (when processing $\bf u$ causes us to add $\bf v$ to the search, set $\bf v.pred$ field to be $\bf u$)
- -When you reach the goal, follow **pred** fields backwards to where you started (and then reverse the answer)
- If just wanted path length, could put the integer distance at each node instead

Example using BFS

What is a path from Seattle to Austin

- Remember marked nodes are not re-enqueued
- Note shortest paths may not be unique



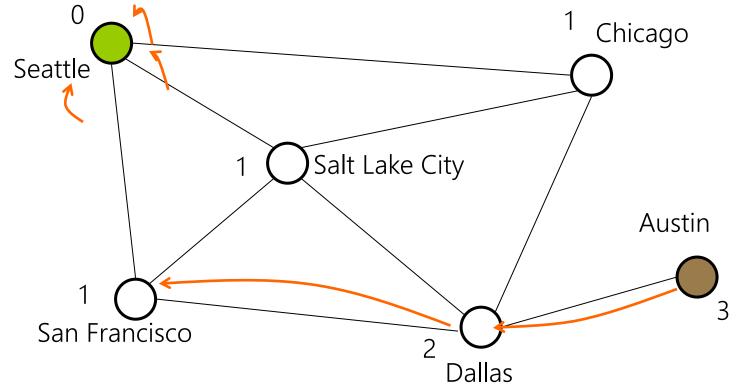
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Example using BFS

What is a path from Seattle to Austin

- Remember marked nodes are not re-enqueued
- Note shortest paths may not be unique



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