

# CSE 332 Summer 2024

## Lecture 12: Sorting

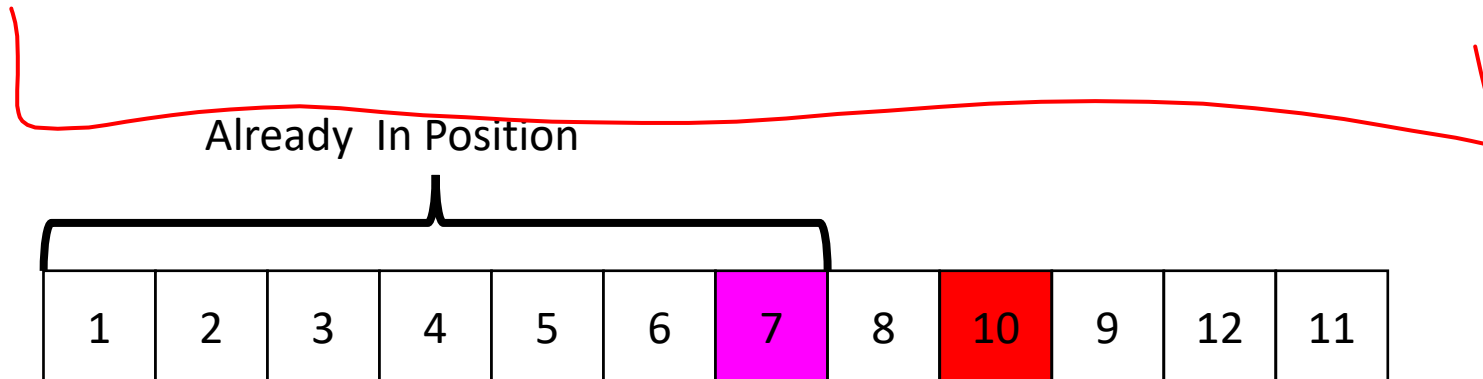
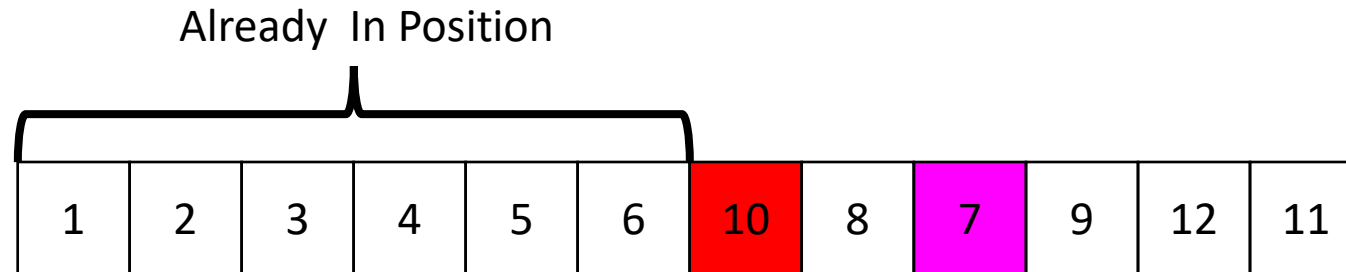
Nathan Brunelle

<http://www.cs.uw.edu/332>

# Selection Sort

*in place*

- **Idea:** Find the **next smallest** element, swap it into the **next index** in the array



# Selection Sort

- Swap the thing at index 0 with the smallest thing in the array
- Swap the thing at index 1 with the smallest thing after index 0
- ...
- Swap the thing at index  $i$  with the smallest thing after index  $i - 1$

```
for (i=0; i<a.length; i++){  
    smallest = i;  
    for (j=i; j<a.length; j++){  
        if (a[j]<a[smallest]){ smallest=j;}  
    }  
    temp = a[i];  
    a[i] = a[smallest];  
    a[smallest] = temp;  
}
```

Running Time:

Worst Case:  $\Theta(n^2)$

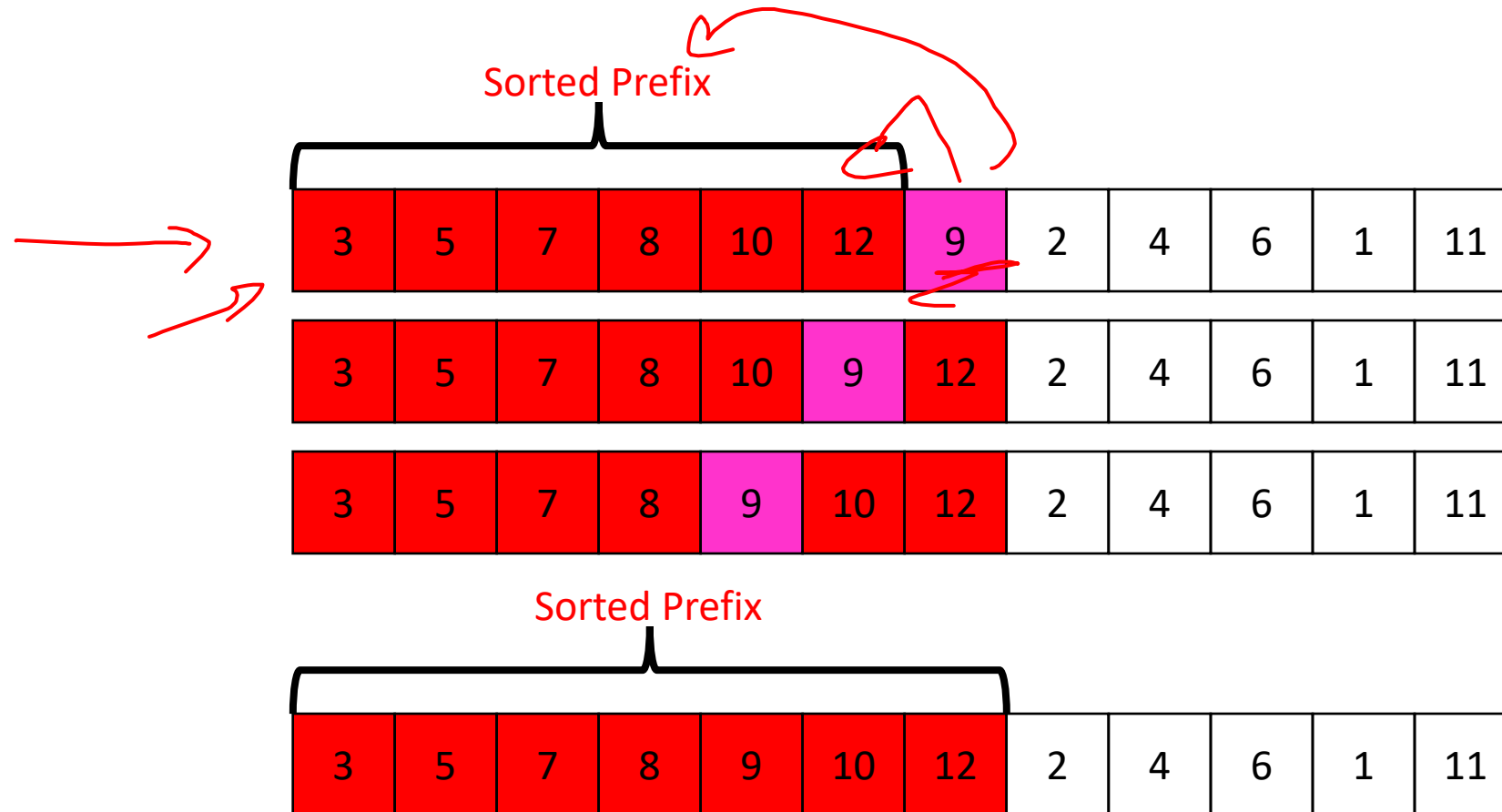
Best Case:  $\Theta(n)$



10	77	5	15	2	22	64	41	18	19	30	21	3	24	23	33
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

# Insertion Sort

- Idea: Maintain a **sorted list prefix**, extend that prefix by “inserting” the **next element**



# Insertion Sort

adaptive

- If the items at index 0 and 1 are out of order, swap them
- Keep swapping the item at index 2 with the thing to its left as long as the left thing is larger
- ...
- Keep swapping the item at index  $i$  with the thing to its left as long as the left thing is larger

```
for (i=1; i<a.length; i++){  
    prev = i-1;  
    while(a[i] < a[prev] && prev > -1){  
        temp = a[i];  
        a[i] = a[prev];  
        a[prev] = temp;  
        i--;  
        prev--;  
    }  
}
```

Running Time:

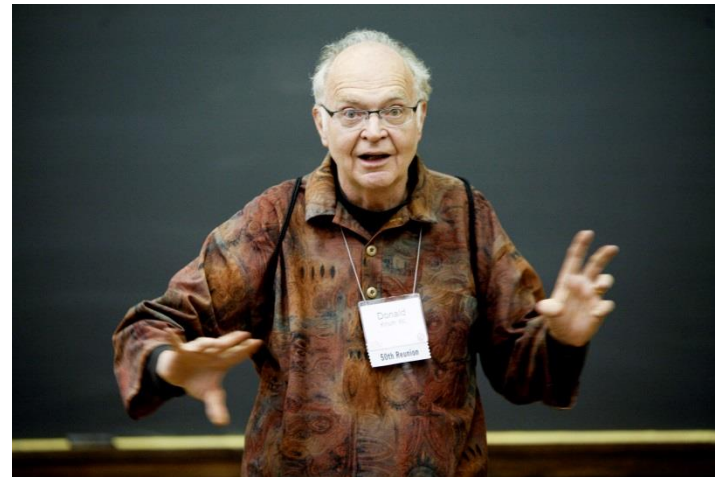
Worst Case:  $\Theta(n^2)$

Best Case:  $\Theta(n)$

10	77	5	15	2	22	64	41	18	19	30	21	3	24	23	33
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# Aside: Bubble Sort – we won't cover it

"the bubble sort seems to have nothing to recommend it, except a catchy name and the fact that it leads to some interesting theoretical problems" –Donald Knuth, The Art of Computer Programming

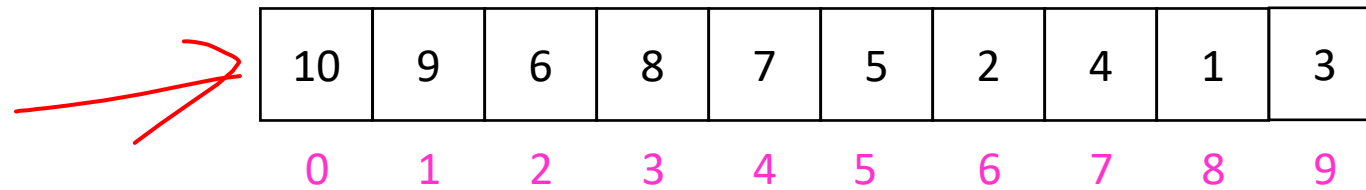


# Properties

- Worst case running time
  - $n^2$
- In place:
  - We only need to use the pre-existing array to do sorting
  - Constant extra space (only some additional variables needed)
- Adaptive
  - The running improves as the given list is closer to being sorted
  - It should be linear time for a pre-sorted list, and nearly linear time if the list is nearly sorted
- Online
  - We can start sorting before we have the entire list.

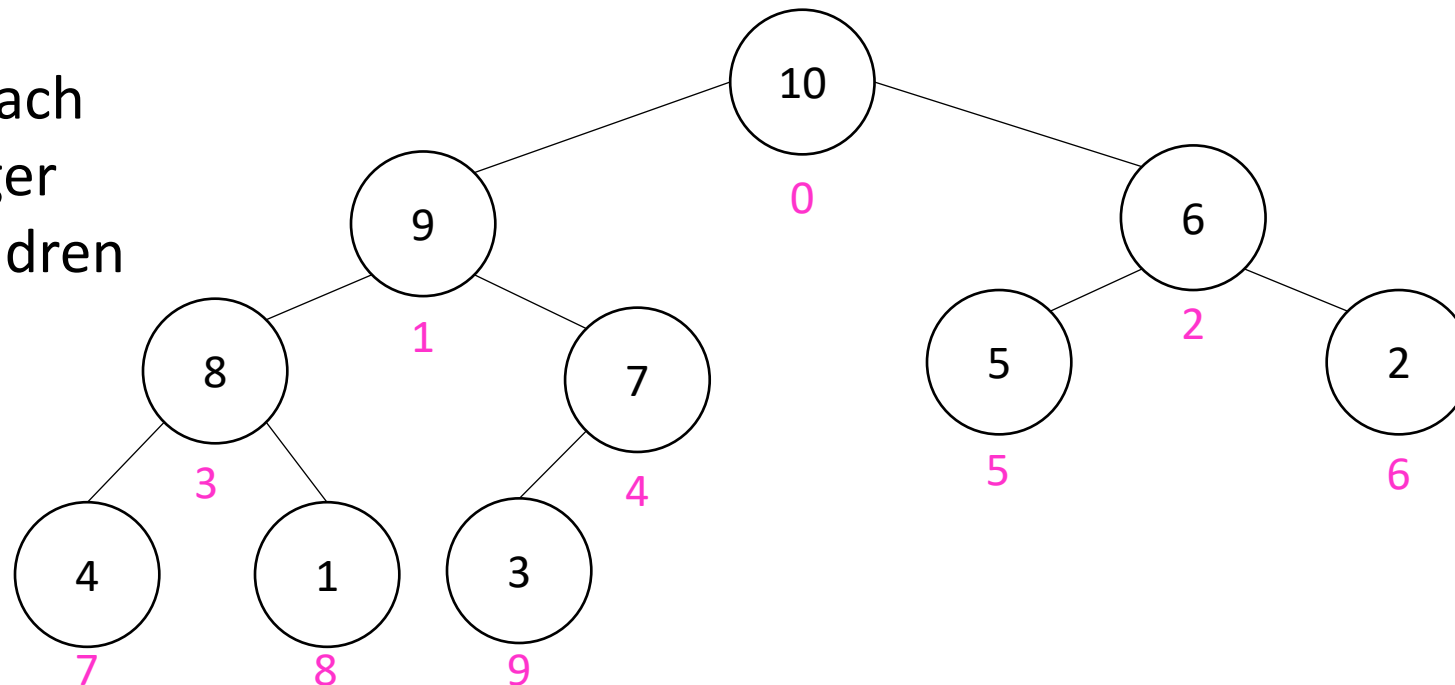
# Heap Sort

- **Idea:** Build a maxHeap, repeatedly delete the max element from the heap to build sorted list Right-to-Left



Max Heap

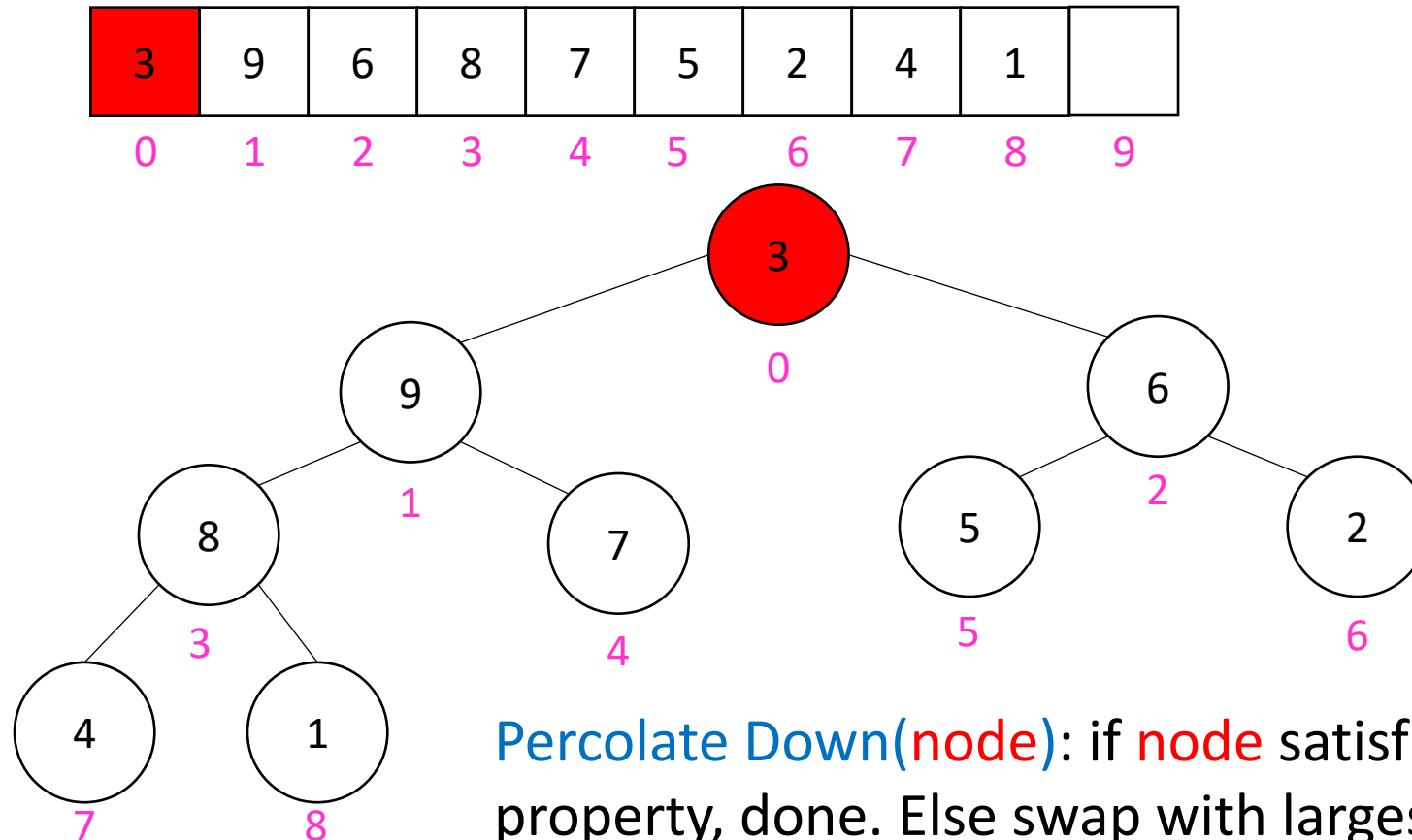
Property: Each node is larger than its children





# Heap Sort

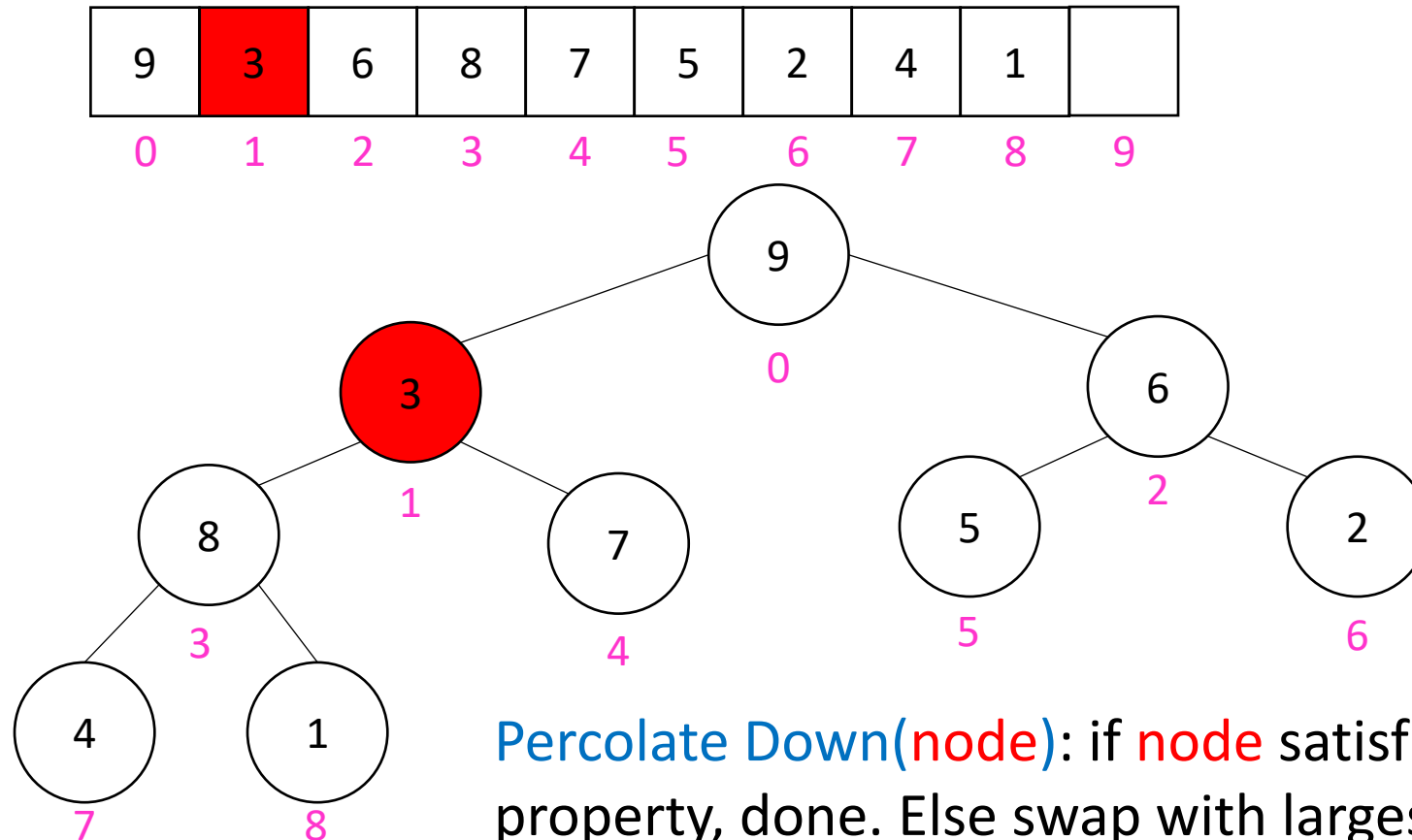
- Remove the Max element (i.e. the root) from the Heap: replace with last element, call `percolateDown(root)`



**Percolate Down(node):** if **node** satisfies heap property, done. Else swap with largest child and repeat on that subtree

# Heap Sort

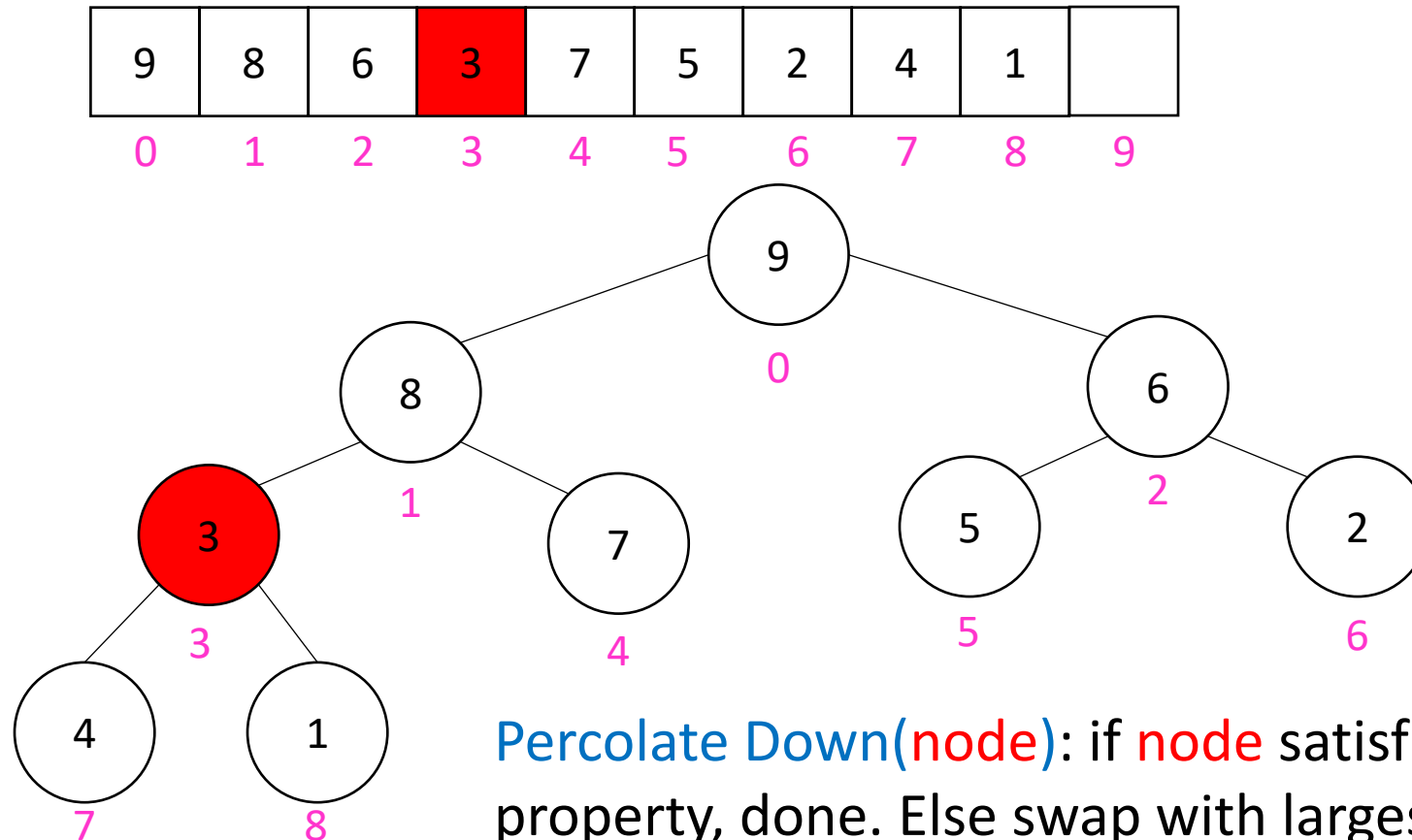
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# Heap Sort

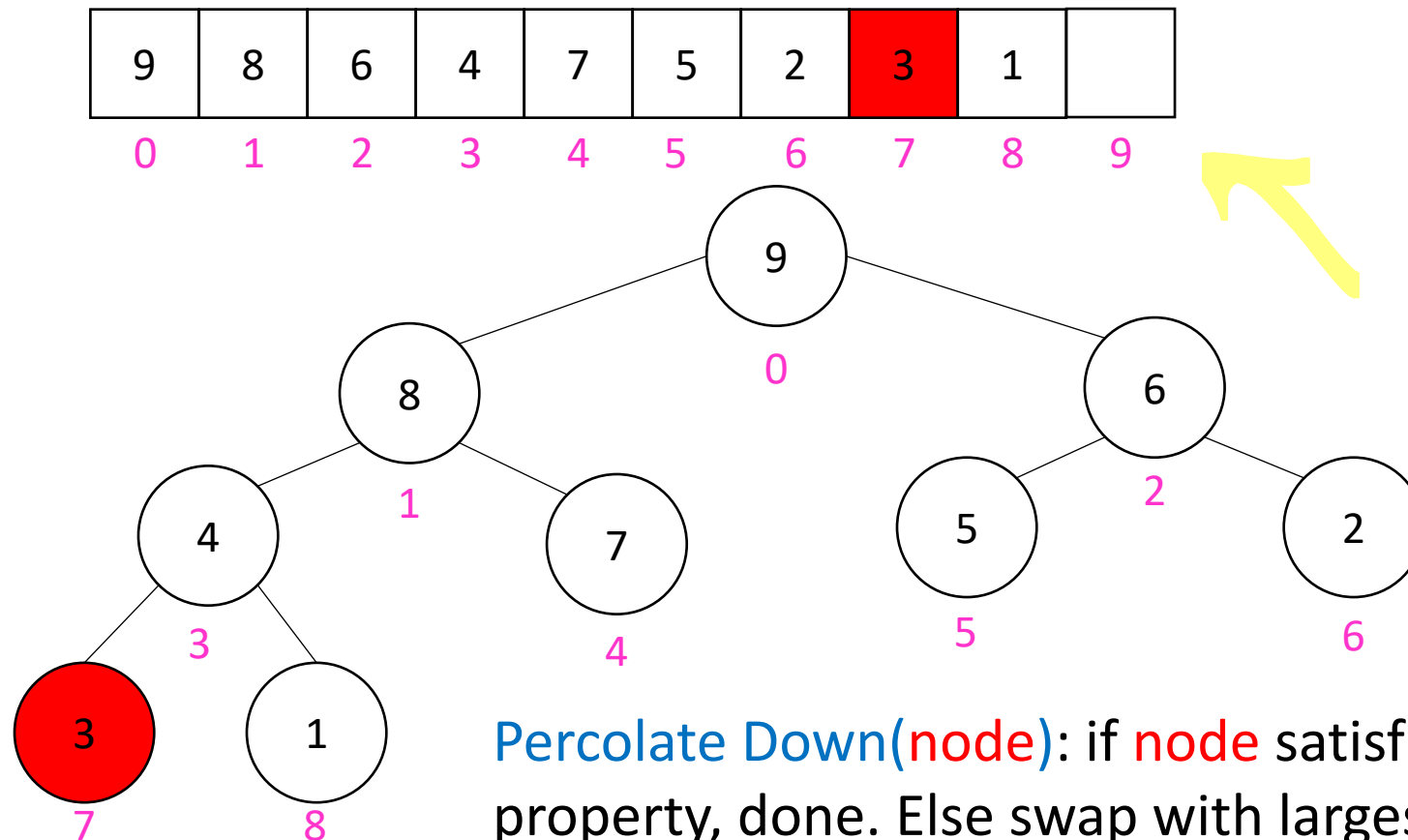
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# Heap Sort

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**Percolate Down(node):** if **node** satisfies heap property, done. Else swap with largest child and repeat on that subtree

# Heap Sort

- Build a heap
  - $O(n)$
- Call extract
  - $O(\log n)$  each
- Put that at the end of the array
  - $O(1)$

```
myHeap = buildHeap(a);  
for (int i = a.length-1; i>=0; i--){  
    item = myHeap.deleteMax();  
    a[i] = item;  
}
```

Running Time:

Worst Case:  $\Theta(n \log n)$

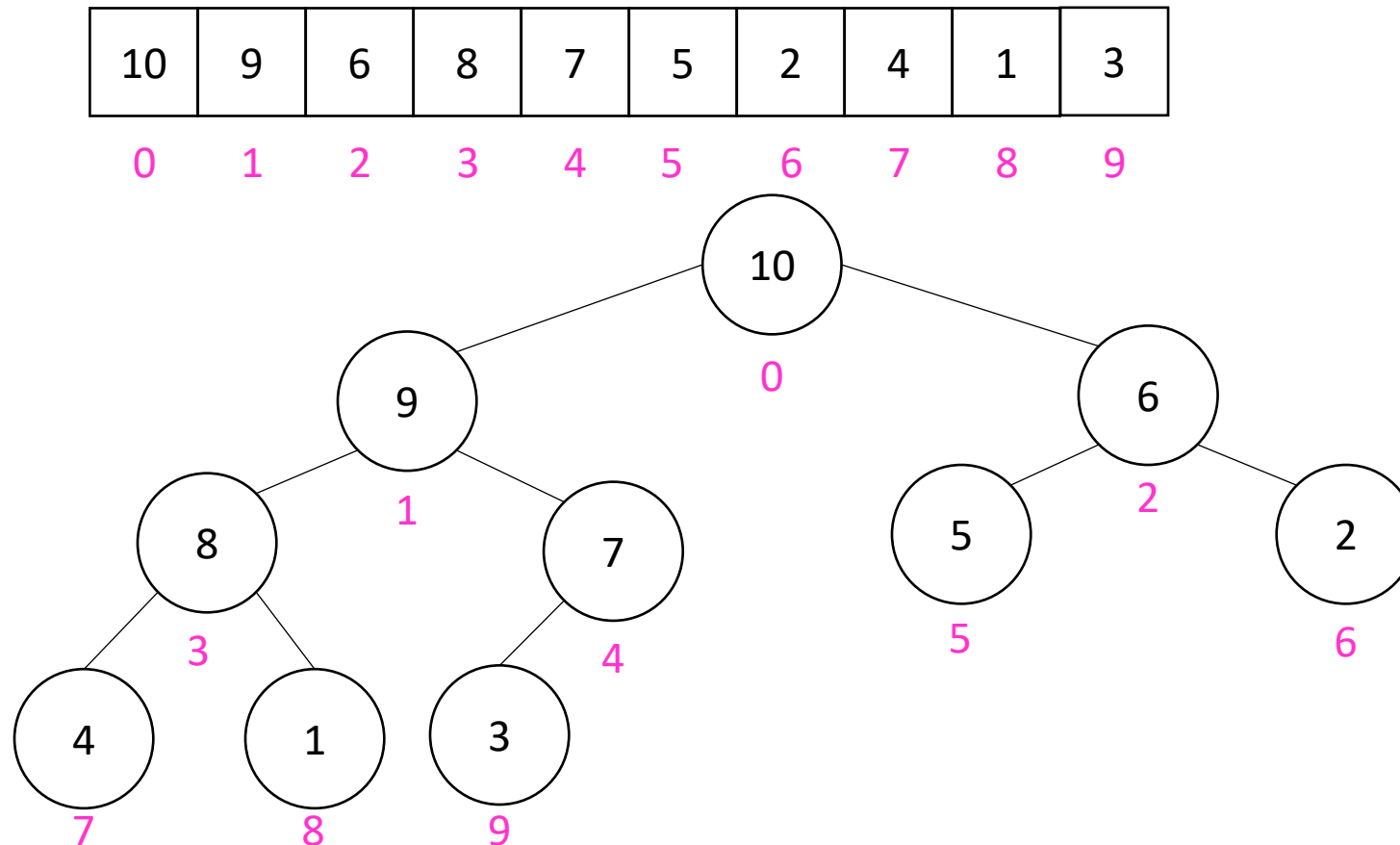
Best Case:  $\Theta(n \log n)$

# “In Place” Sorting Algorithm

- A sorting algorithm which requires no extra data structures
- Idea: It sorts items just by swapping things in the same array given
- Definition: it only uses  $\Theta(1)$  extra space
  
- Selection sort: In Place!
- Insertion sort: In Place!
- Heap sort: Not In Place!
  - But we can fix that!

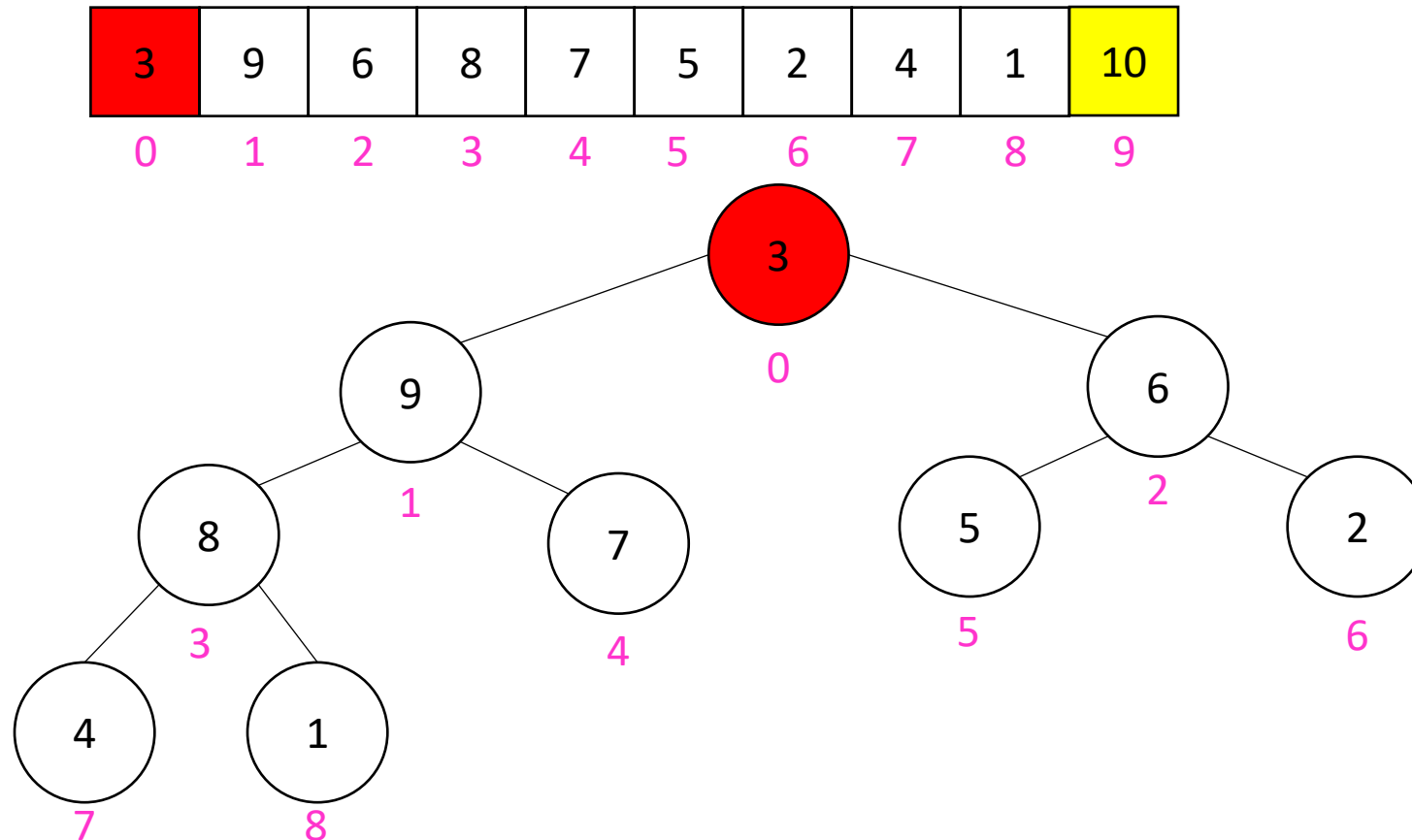
# In Place Heap Sort

- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter



# Heap Sort

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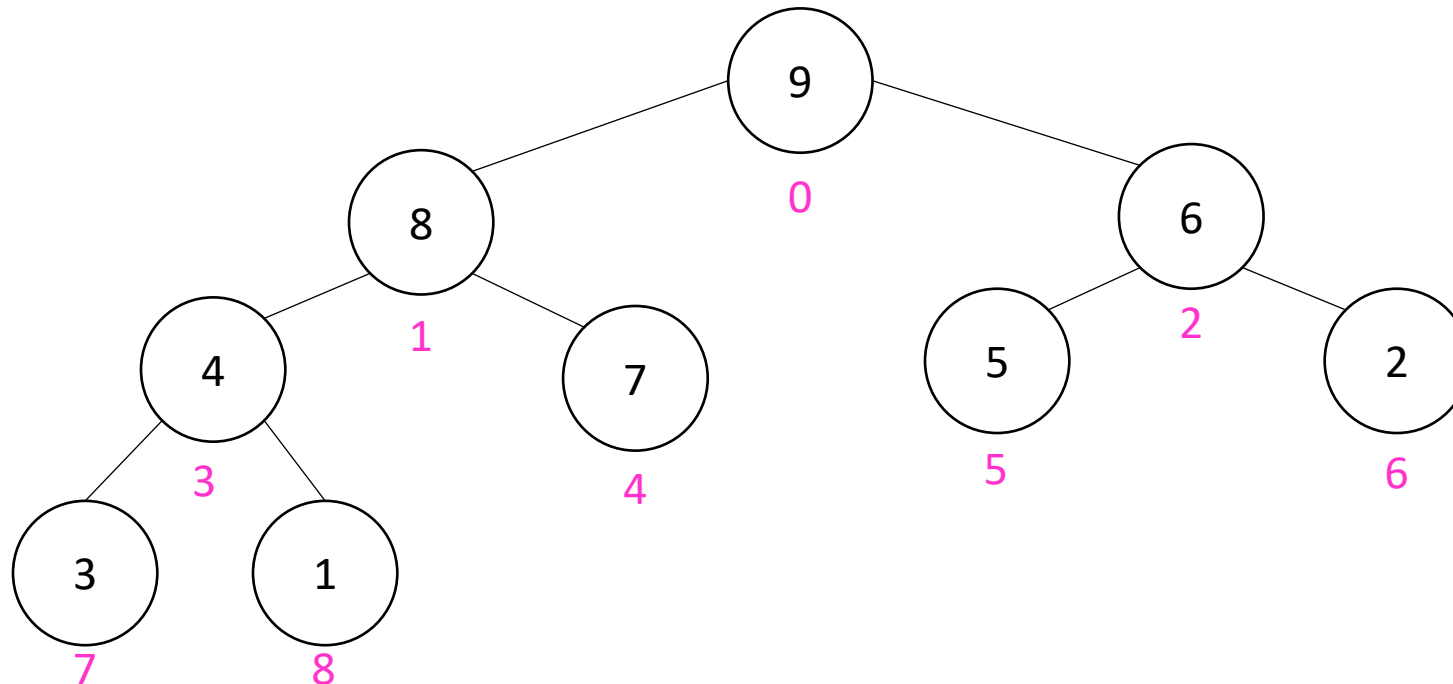




# Heap Sort

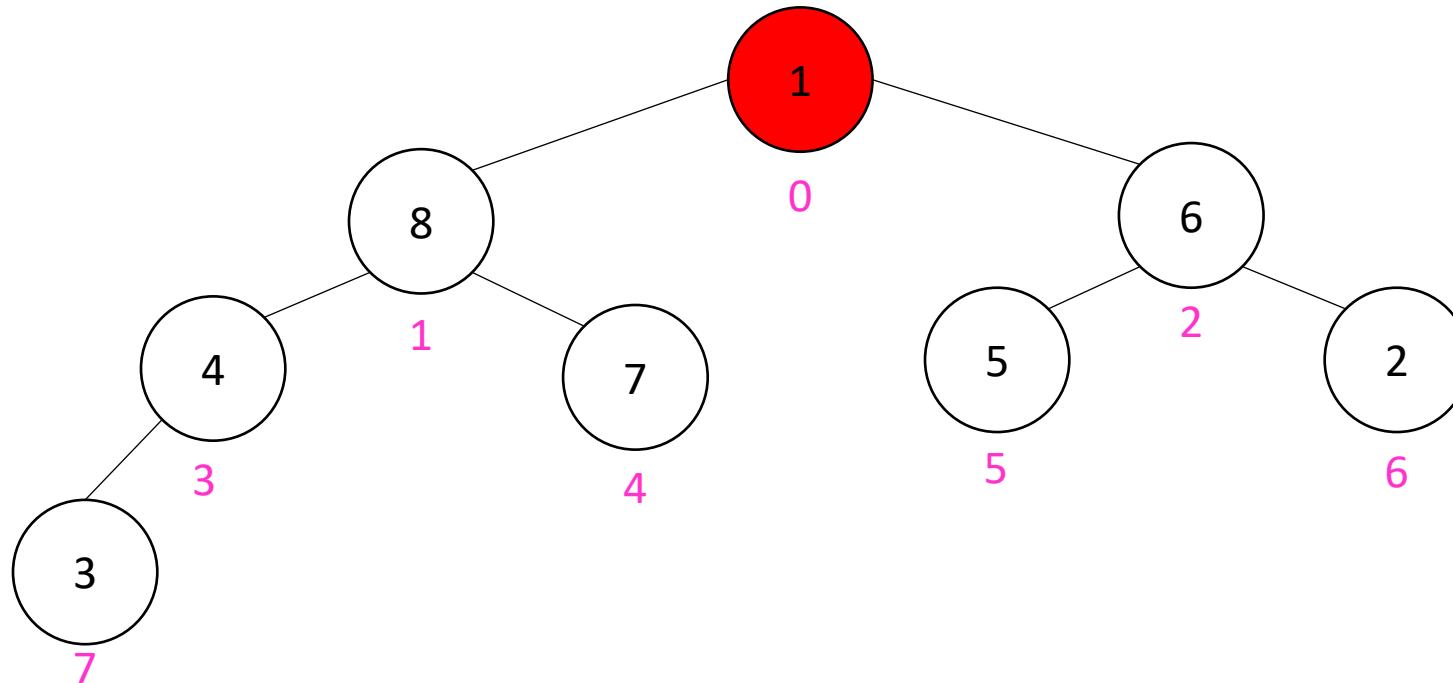
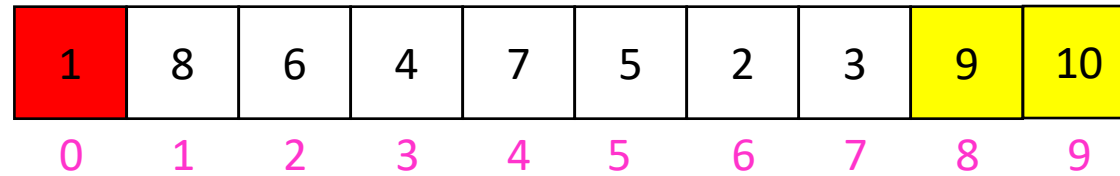
- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

9	8	6	4	7	5	2	3	1	10
0	1	2	3	4	5	6	7	8	9



# Heap Sort

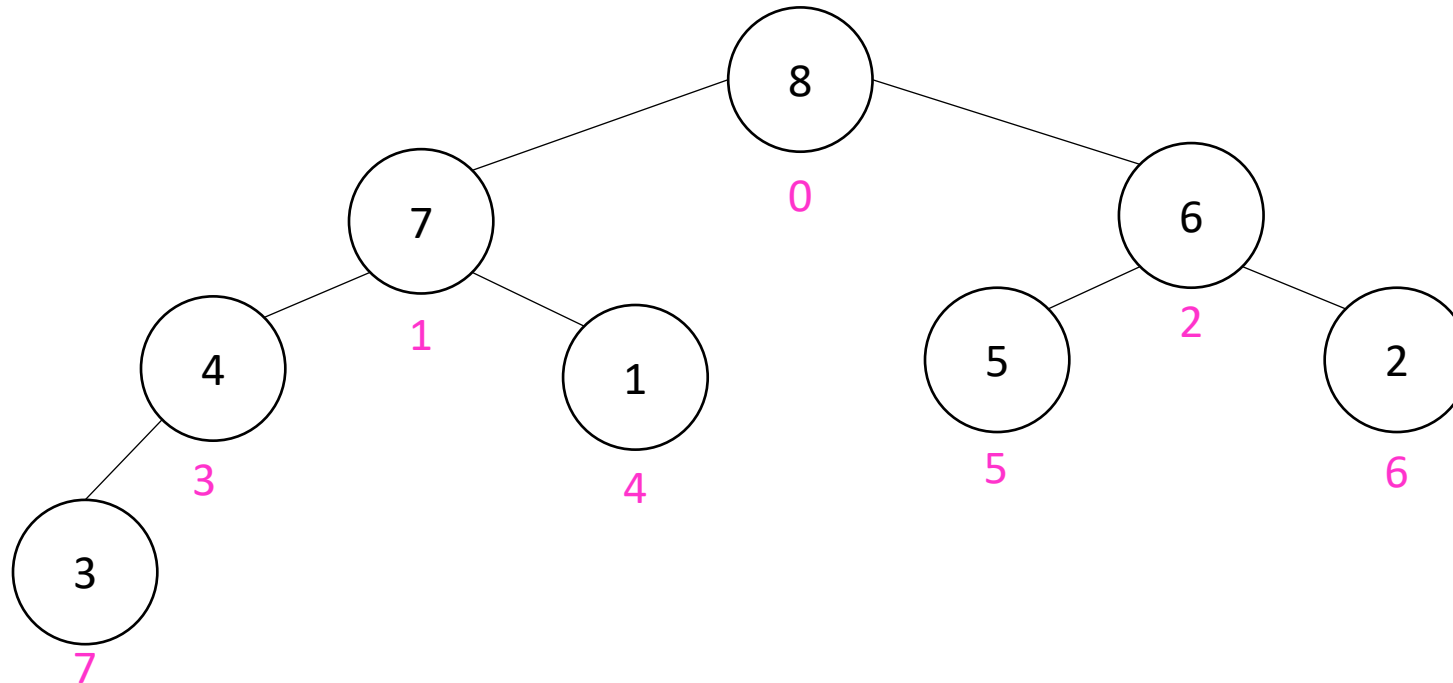
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# Heap Sort

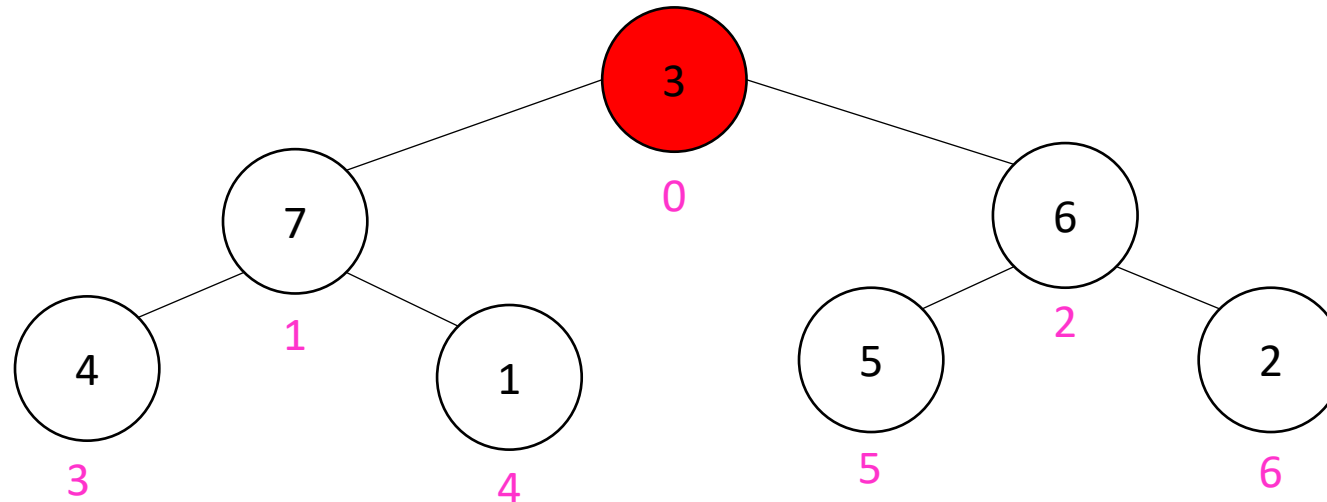
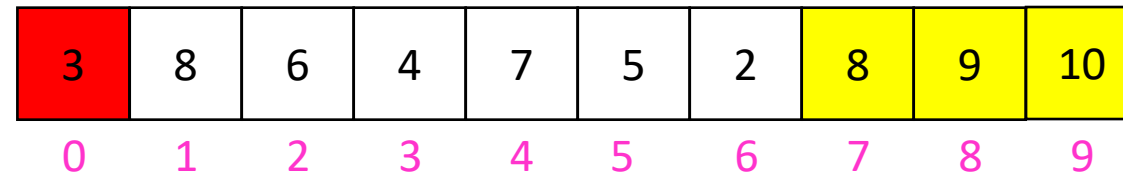
- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

1	8	6	4	7	5	2	3	9	10
0	1	2	3	4	5	6	7	8	9



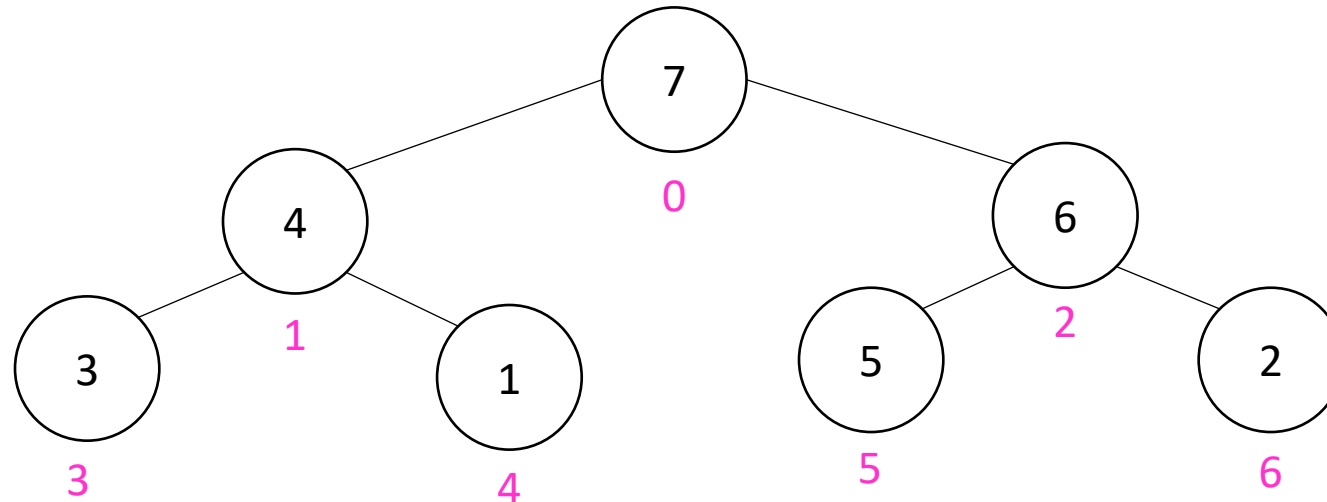
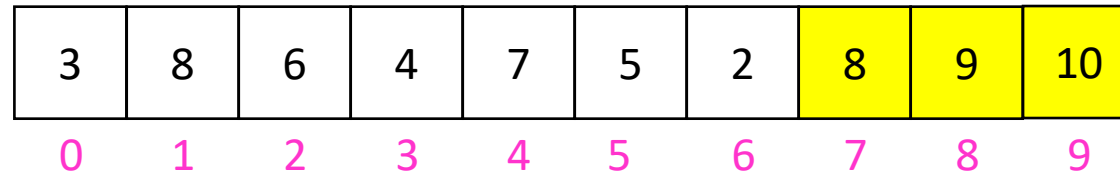
# Heap Sort

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# Heap Sort

- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter



# In Place Heap Sort

- Build a heap using the same array (Floyd's build heap algorithm works)
- Call deleteMax
- Put that at the end of the array

```
buildHeap(a);  
for (int i = a.length-1; i>=0; i--){  
    temp=a[i]  
    a[i] = a[0];  
    a[0] = temp;  
    percolateDown(0);  
}
```

Running Time:

Worst Case:  $\Theta(n \log n)$

Best Case:  $\Theta(n \log n)$

# Floyd's buildHeap method

- Working towards the root, one row at a time, percolate down

```
buildHeap(){  
    for(int i = size; i>0; i--){  
        percolateDown(i);  
    }  
}
```

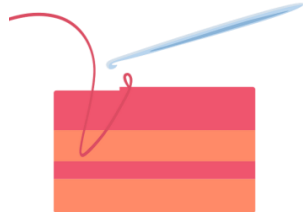
# Divide And Conquer Sorting

- Divide and Conquer:

- Recursive algorithm design technique
- Solve a large problem by breaking it up into smaller versions of the same problem

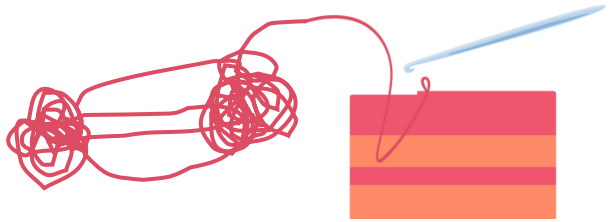


# Divide and Conquer



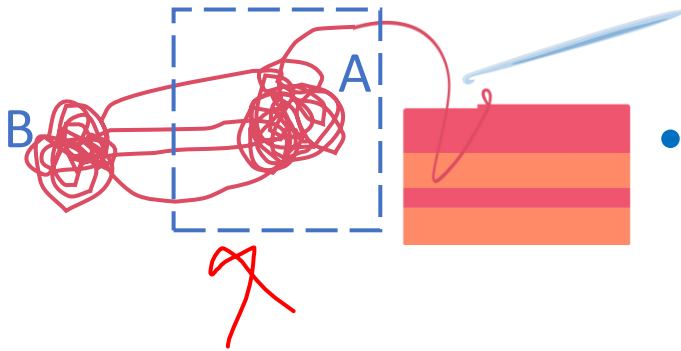
- **Base Case:**

- If the problem is “small” then solve directly and return



- **Divide:**

- Break the problem into subproblem(s), each smaller instances





- **Conquer:**

- Solve subproblem(s) recursively

- **Combine:**

- Use solutions to subproblems to solve original problem

# Divide and Conquer Template Pseudocode

```
def my_DandC(problem){  
  // Base Case   
  if (problem.size() <= small_value){  
    return solve(problem); // directly solve (e.g., brute force)  
  }  
  // Divide  
  List subproblems = divide(problem);  
  
  // Conquer  
  solutions = new List();  
  for (sub : subproblems){  
    subsolution = my_DandC(sub);  
    solutions.add(subsolution);  
  }  
  // Combine  
  return combine(solutions);   
}
```

# Merge Sort

5	8	2	9	4	1
---	---	---	---	---	---

5
---

- **Base Case:**

- If the list is of length 1 or 0, it's already sorted, so just return it

5	8	2	9	4	1
---	---	---	---	---	---

- **Divide:**

- Split the list into two "sublists" of (roughly) equal length

2	5	8	1	4	9
---	---	---	---	---	---

- **Conquer:**

- Sort both lists recursively

2	5	8	1	4	9
---	---	---	---	---	---

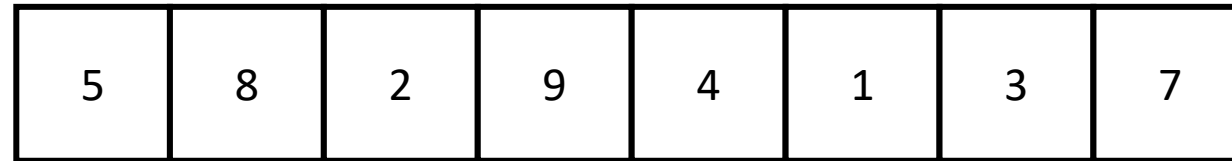
- **Combine:**

- Merge sorted sublists into one sorted list

1	2	4	5	8	9
---	---	---	---	---	---

# Merge Sort In Action!

Sort between indices *low* and *high*

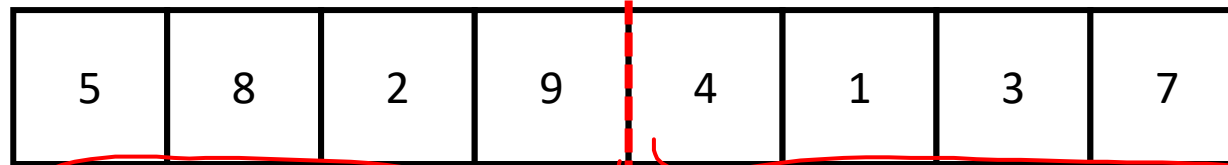


*low*

*high*

Base Case: if *low* == *high* then that range is already sorted!

Divide and Conquer: Otherwise call mergesort on ranges  $(low, \frac{low+high}{2})$  and  $(\frac{low+high}{2} + 1, high)$



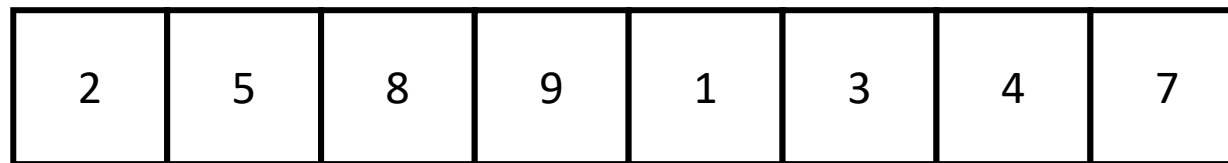
*low*

$\frac{low+high}{2}$

$\frac{low+high}{2} + 1$

*high*

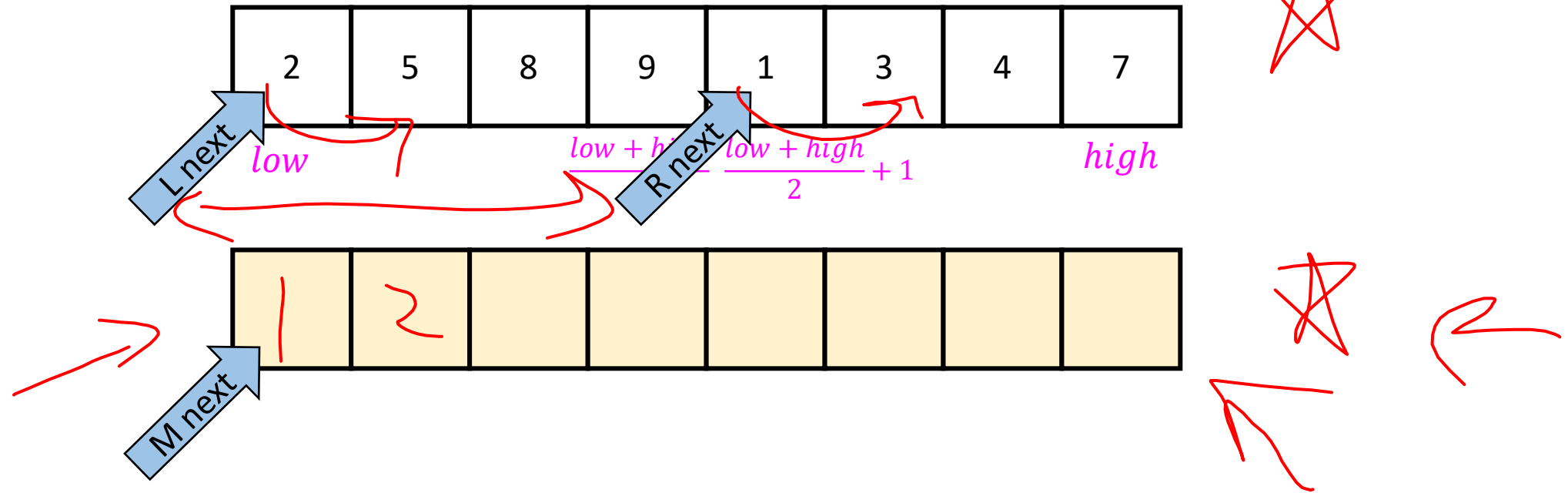
After Recursion:



*low*

*high*

# Merge (the combine part)



Create a **new array to merge into**, and 3 pointers/indices:

- **L\_next**: the smallest “unmerged” thing on the left
- **R\_next**: the smallest “unmerged” thing on the right
- **M\_next**: where the next smallest thing goes in the merged array

One-by-one: put the smallest of **L\_next** and **R\_next** into **M\_next**, then advance both **M\_next** and whichever of **L/R** was used.

# Merge Sort Pseudocode

```
void mergesort(myArray){
    ms_helper(myArray, 0, myArray.length());
}

void mshelper(myArray, low, high){
    if (low == high){return;} // Base Case
    mid = (low+high)/2;
    ms_helper(low, mid);
    ms_helper(mid+1, high);
    merge(myArray, low, mid, high);
}
```

# Merge Pseudocode

```
void merge(myArray, low, mid, high){
    merged = new int[high-low+1]; // or whatever type is in myArray
    l_next = low;
    r_next = high;
    m_next = 0;
    while (l_next <= mid && r_next <= high){
        if (myArray[l_next] <= myArray[r_next]){
            merged[m_next++] = myArray[l_next++];
        }
        else{
            merged[m_next++] = myArray[r_next++];
        }
    }
    while (l_next <= mid){ merged[m_next++] = myArray[l_next++]; }
    while (r_next <= high){ merged[m_next++] = myArray[r_next++]; }
    for(i=0; i<=merged.length; i++){ myArray[i+low] = merged[i];}
}
```

# Analyzing Merge Sort

$$T(n) = aT\left(\frac{n}{b}\right) + f(n)$$
$$= 2T\left(\frac{n}{2}\right) +$$

1. Identify time required to Divide and Combine
2. Identify all subproblems and their sizes
3. Use recurrence relation to express recursive running time
4. Solve and express running time asymptotically

• **Divide:** 0 comparisons

• **Conquer:** recursively sort two lists of size  $\frac{n}{2}$

• **Combine:**  ~~$n$  comparisons~~

• **Recurrence:**

$$T(n) = 0 + T\left(\frac{n}{2}\right) + T\left(\frac{n}{2}\right) + n$$

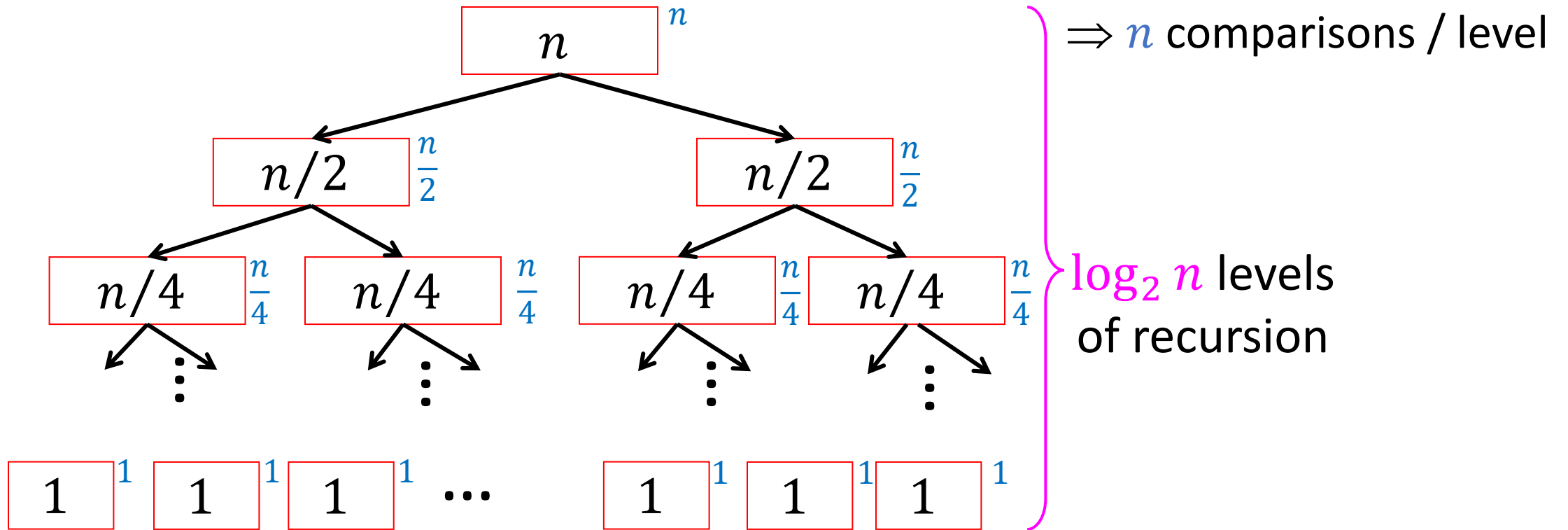
$$\rightarrow T(n) = 2T\left(\frac{n}{2}\right) + n$$



Red box represents a problem instance

Blue value represents time spent at that level of recursion

$$T(n) = 2T\left(\frac{n}{2}\right) + n$$



$$T(n) = \sum_{i=1}^{\log_2 n} n = n \log_2 n$$

# Properties of Merge Sort

- Worst Case Running time:
  - $\Theta(n \log n)$
- In-Place?
  - No!
- Adaptive?
  - No!
- Stable?
  - Yes!
  - As long as in a tie you always pick `l_next`

# Quicksort

- Like Mergesort:
  - Divide and conquer
  - $O(n \log n)$  run time (kind of...)
- Unlike Mergesort:
  - Divide step is the “hard” part
  - *Typically* faster than Mergesort

# Quicksort

Idea: pick a **pivot** element, recursively sort two sublists around that element

- **Divide:** select **pivot** element  $p$ , **Partition( $p$ )**
- **Conquer:** recursively sort left and right sublists
- **Combine:** Nothing!

# Partition (Divide step)

Given: a list, a pivot  $p$

Start: unordered list

8	5	7	3	12	10	1	2	4	9	6	11
---	---	---	---	----	----	---	---	---	---	---	----

Goal: All elements  $< p$  on left, all  $> p$  on right

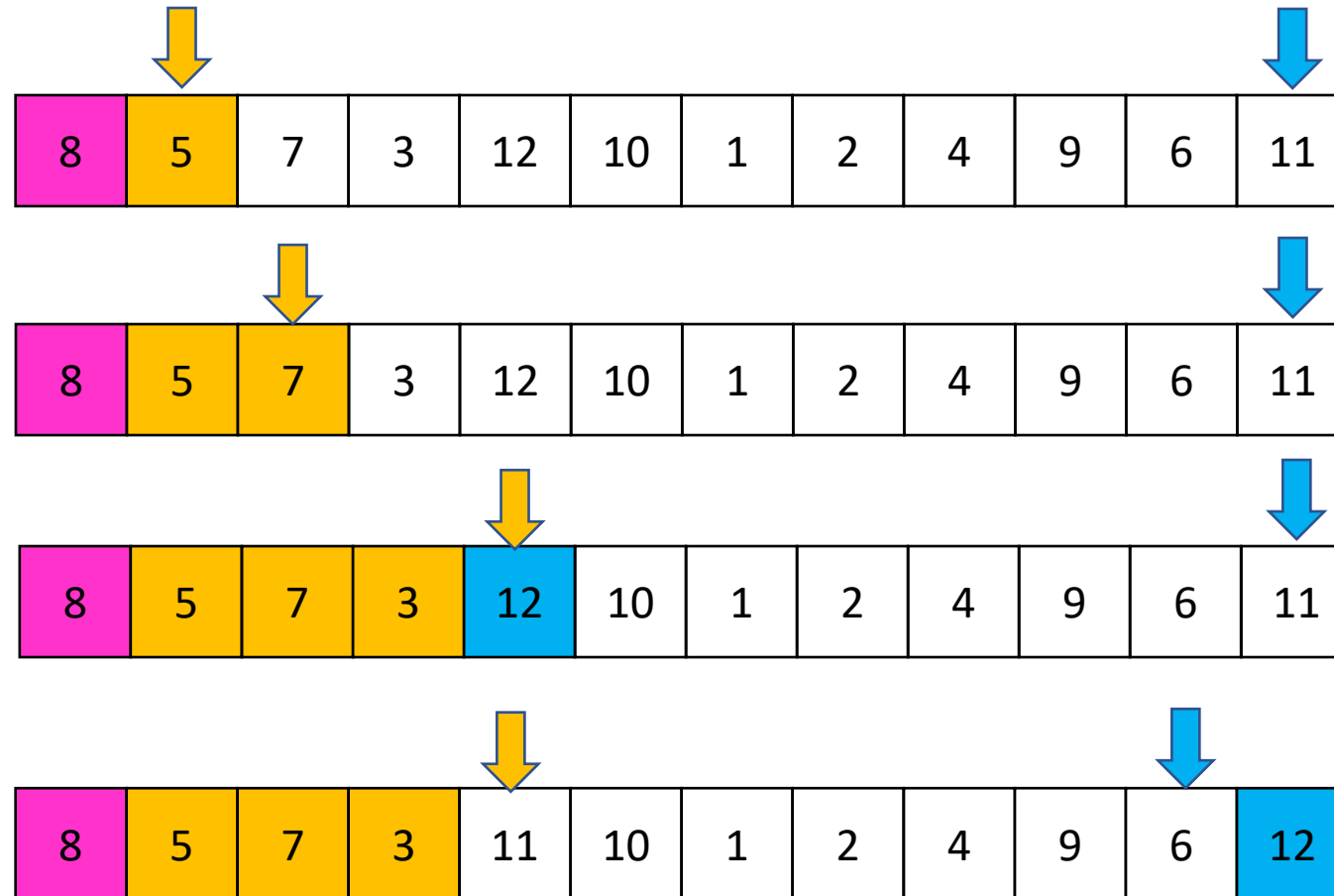
5	7	3	1	2	4	6	8	12	10	9	11
---	---	---	---	---	---	---	---	----	----	---	----

# Partition, Procedure

If **Begin** value  $< p$ , move **Begin** right

Else swap **Begin** value with **End** value, move **End** Left

Done when **Begin** = **End**

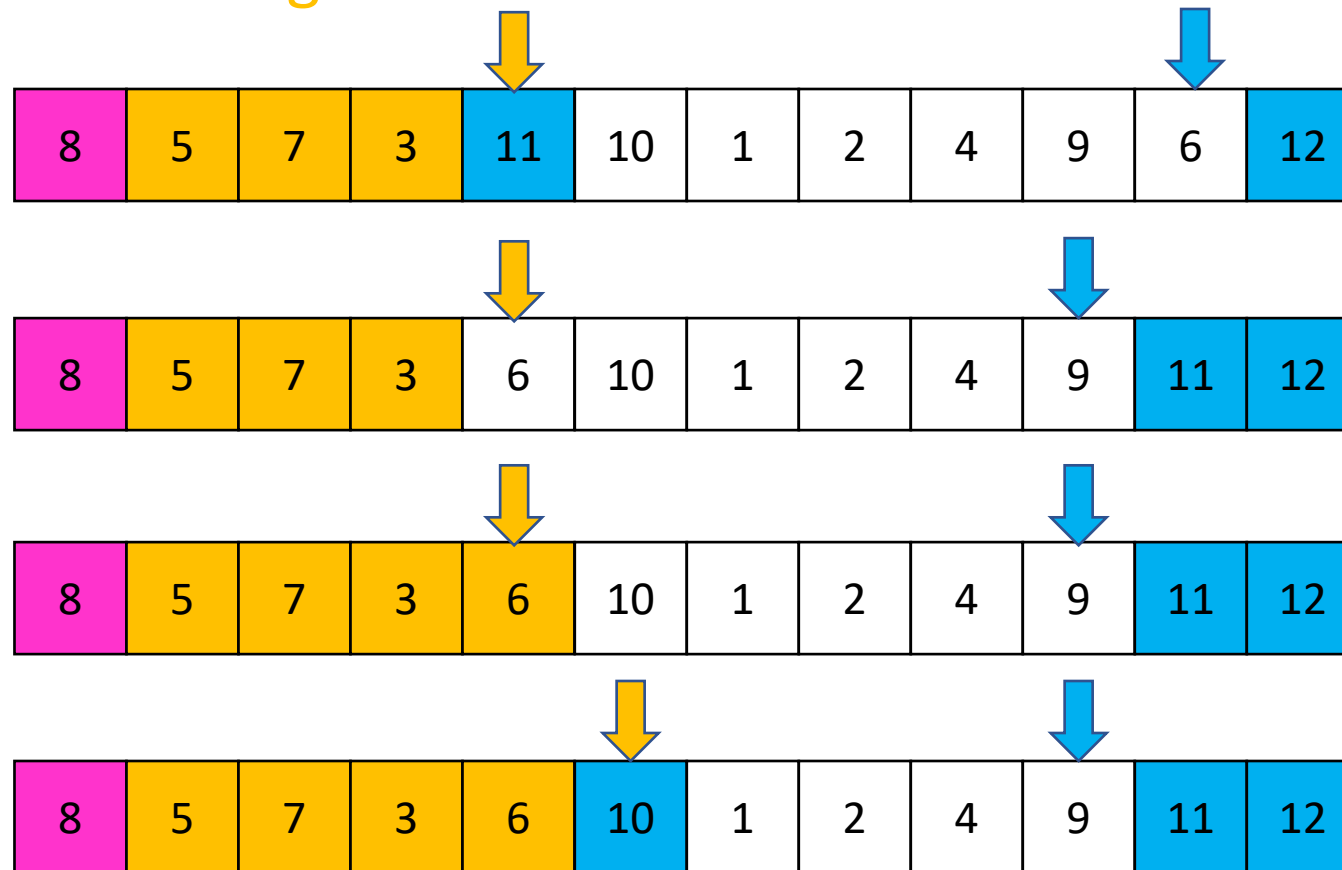


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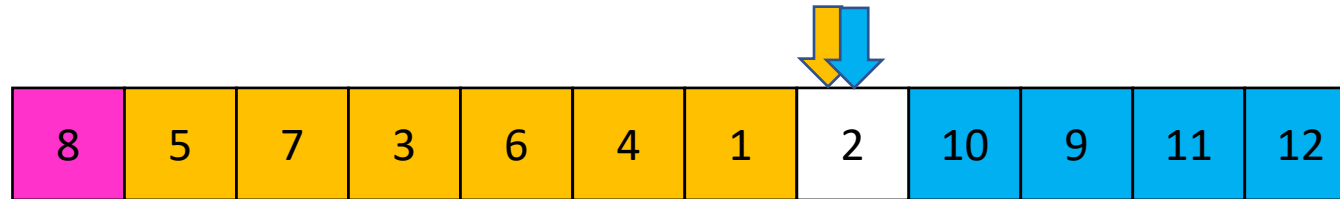


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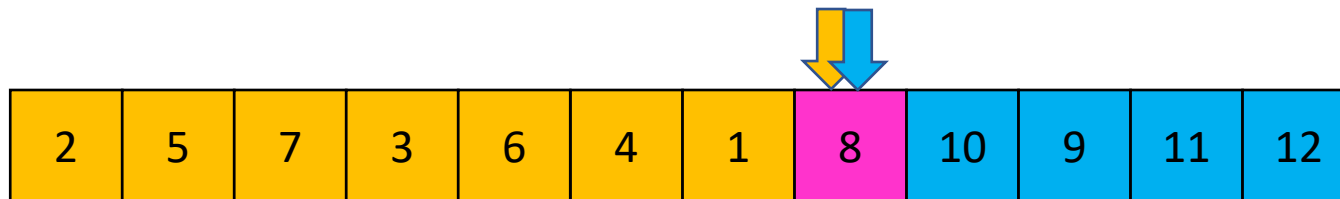
Else swap **Begin** value with **End** value, move **End** Left

Done when **Begin** = **End**



Case 1: meet at element  $< p$

Swap  $p$  with **pointer position** (2 in this case)



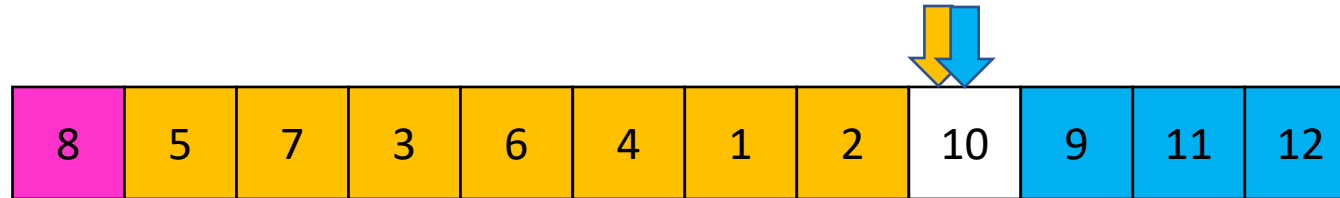


# Partition, Procedure

If **Begin** value  $< p$ , move **Begin** right

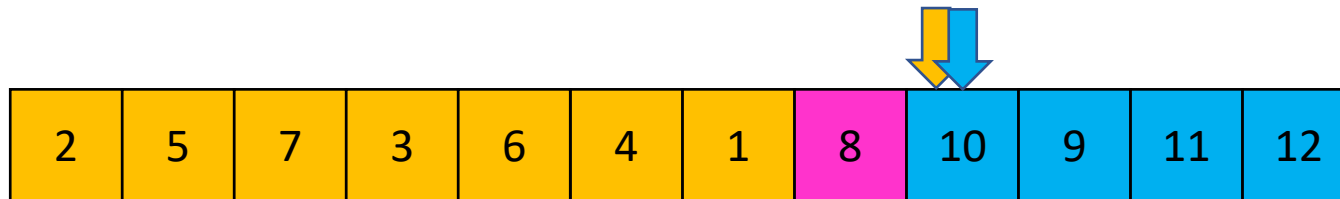
Else swap **Begin** value with **End** value, move **End** Left

Done when **Begin** = **End**



Case 2: meet at element  $> p$

Swap  $p$  with **value to the left** (2 in this case)

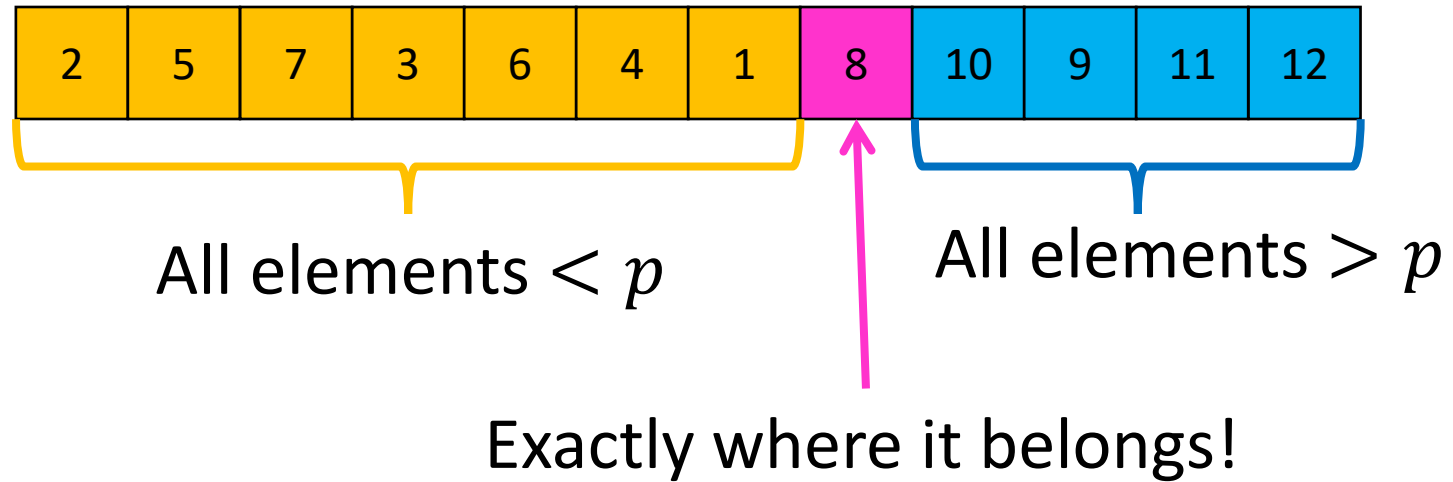


# Partition Summary

1. Put  $p$  at beginning of list
2. Put a pointer (**Begin**) just after  $p$ , and a pointer (**End**) at the end of the list
3. While **Begin** < **End**:
  1. If **Begin** value <  $p$ , move **Begin** right
  2. Else swap **Begin** value with **End** value, move **End** Left
4. If pointers meet at element <  $p$ : Swap  $p$  with **pointer position**
5. Else If pointers meet at element >  $p$ : Swap  $p$  with **value to the left**

Run time?  $O(n)$

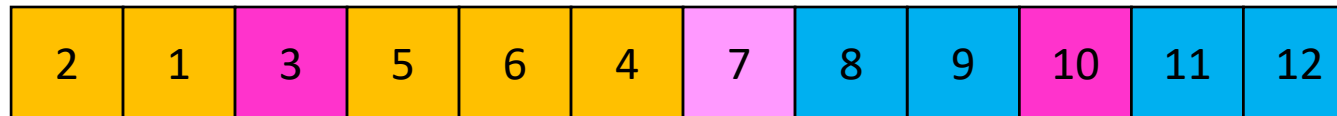
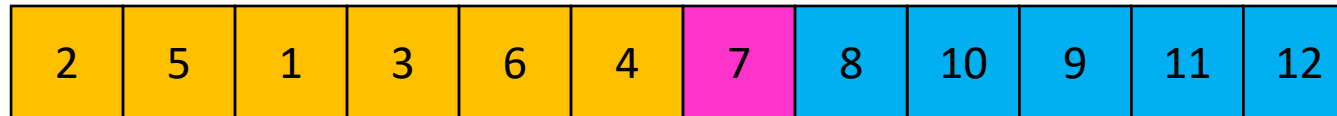
# Conquer



Recursively sort **Left** and **Right** sublists

# Quicksort Run Time (Best)

If the **pivot** is always the median:



Then we divide in half each time

$$T(n) = 2T\left(\frac{n}{2}\right) + n$$

$$T(n) = O(n \log n)$$

# Quicksort Run Time (Worst)

If the pivot is always at the extreme:



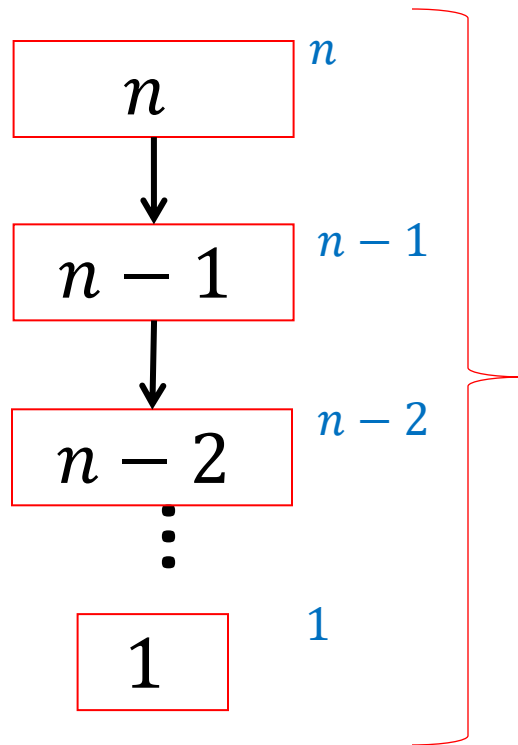
Then we shorten by 1 each time

$$T(n) = T(n - 1) + n$$

$$T(n) = O(n^2)$$

# Quicksort Run Time (Worst)

$$T(n) = T(n - 1) + n$$



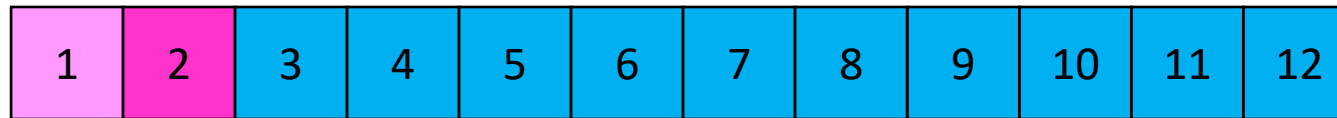
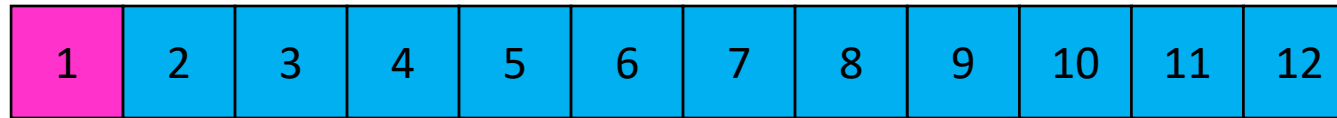
$$T(n) = 1 + 2 + 3 + \dots + n$$

$$T(n) = \frac{n(n + 1)}{2}$$

$$T(n) = O(n^2)$$

# Quicksort on a (nearly) Sorted List

First element always yields unbalanced pivot



So we shorten by 1 each time

$$T(n) = T(n - 1) + n$$

$$T(n) = O(n^2)$$

# Good Pivot

- What makes a good Pivot?
  - Roughly even split between left and right
  - Ideally: median
- There are ways to find the median in linear time, but it's complicated and slow and you're better off using mergesort
- In Practice:
  - Pick a random value as a pivot
  - Pick the middle of 3 random values as the pivot



# Properties of Quick Sort

- Worst Case Running time:
  - $\Theta(n^2)$
  - But  $\Theta(n \log n)$  average! And typically faster than mergesort!
- In-Place?
  - ....Debatable
- Adaptive?
  - No!
- Stable?
  - No!

# Improving Running time

- Recall our definition of the sorting problem:
  - Input:
    - An array  $A$  of items
    - A comparison function for these items
      - Given two items  $x$  and  $y$ , we can determine whether  $x < y$ ,  $x > y$ , or  $x = y$
  - Output:
    - A permutation of  $A$  such that if  $i \leq j$  then  $A[i] \leq A[j]$
- Under this definition, it is impossible to write an algorithm faster than  $n \log n$  asymptotically.
- Observation:
  - Sometimes there might be ways to determine the position of values without comparisons!

# “Linear Time” Sorting Algorithms

- Useable when you are able to make additional assumptions about the contents of your list (beyond the ability to compare)
  - Examples:
    - The list contains only positive integers less than  $k$
    - The number of distinct values in the list is much smaller than the length of the list
- The running time expression will always have a term other than the list's length to account for this assumption
  - Examples:
    - Running time might be  $\Theta(k \cdot n)$  where  $k$  is the range/count of values



# BucketSort Running Time

- Create array of  $k$  buckets
  - Either  $\Theta(k)$  or  $\Theta(1)$  depending on some things...
- Insert all  $n$  things into buckets
  - $\Theta(n)$
- Empty buckets into an array
  - $\Theta(n + k)$
- Overall:
  - $\Theta(n + k)$
- When is this better than mergesort?

# Properties of BucketSort

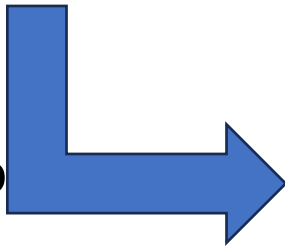
- In-Place?
  - No
- Adaptive?
  - No
- Stable?
  - Yes!

# RadixSort

- Radix: The base of a number system
  - We'll use base 10, most implementations will use larger bases
- Idea:
  - BucketSort by each digit, one at a time, from least significant to most significant

103	801	401	323	255	823	999	101	113	901	555	512	245	800	018	121
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

Place each element into a "bucket" according to its 1's place



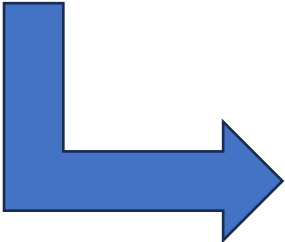
800	801 401 101 901 121	512	103 323 823 113		255 555 245			018	999
0	1	2	3	4	5	6	7	8	9

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	801		103		255				
800	401	512	323		555			018	999
	101		823		245				
	901		113						
	121								
0	1	2	3	4	5	6	7	8	9

Place each element into a "bucket" according to its 10's place



800									
801	512	121							
401	113	323		245	255				999
101	018	823			555				
901									
103									
0	1	2	3	4	5	6	7	8	9

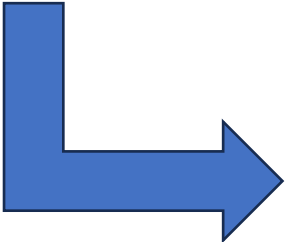


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800									
801									
401	512	121			255				999
101	113	323		245	555				
901	018	823							
103									
0	1	2	3	4	5	6	7	8	9

Place each element into a "bucket" according to its 100's place

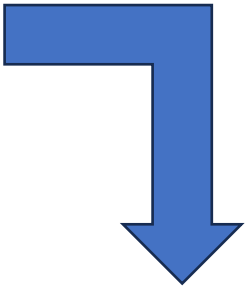


	101							800	
	103							801	901
018	113	245	323	401	512			823	999
	121	255			555				
0	1	2	3	4	5	6	7	8	9

# RadixSort

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018	101 103 113 121	245 255	323	401	512 555			800 801 823	901 999
0	1	2	3	4	5	6	7	8	9



Convert back into an array

018	811	103	113	121	245	255	323	401	512	555	800	801	823	901	999
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

# RadixSort Running Time

- Suppose largest value is  $m$
- Choose a radix (base of representation)  $b$
- BucketSort all  $n$  things using  $b$  buckets
  - $\Theta(n + k)$
- Repeat once per each digit
  - $\log_b m$  iterations
- Overall:
  - $\Theta(n \log_b m + b \log_b m)$
- In practice, you can select the value of  $b$  to optimize running time
- When is this better than mergesort?