

CSE 332 Summer 2024

Lecture 10: Hashing 2

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Next topic: Hash Tables

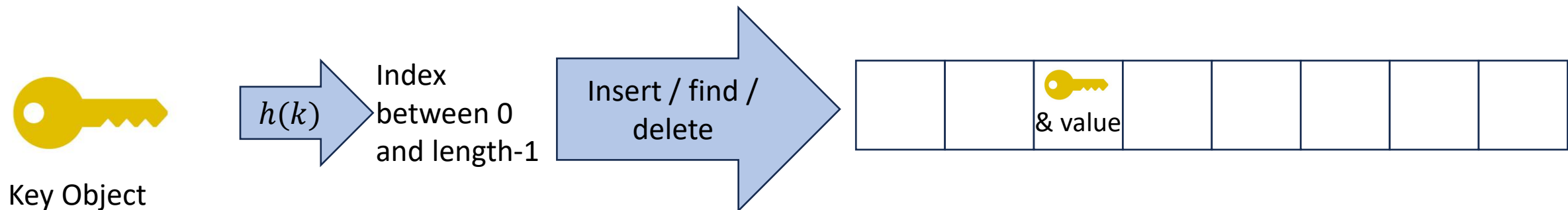
Data Structure	Time to insert	Time to find	Time to delete
Unsorted Array	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Unsorted Linked List	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Sorted Array	$\Theta(n)$	$\Theta(\log n)$	$\Theta(n)$
Sorted Linked List	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Binary Search Tree	$\Theta(\text{height})$	$\Theta(\text{height})$	$\Theta(\text{height})$
AVL Tree	$\Theta(\log n)$	$\Theta(\log n)$	$\Theta(\log n)$
Hash Table (Worst case)	$\Theta(n)$	$\Theta(n)$	$\Theta(n)$
Hash Table (Expected and amortized)	$\Theta(1)$	$\Theta(1)$	$\Theta(1)$

Dictionary (Map) ADT

- Contents:
 - Sets of key+value pairs
 - ~~Keys must be comparable~~
- Operations:
 - insert(key, value)
 - Adds the (key,value) pair into the dictionary
 - If the key already has a value, overwrite the old value
 - Consequence: Keys cannot be repeated
 - find(key)
 - Returns the value associated with the given key
 - delete(key)
 - Remove the key (and its associated value)

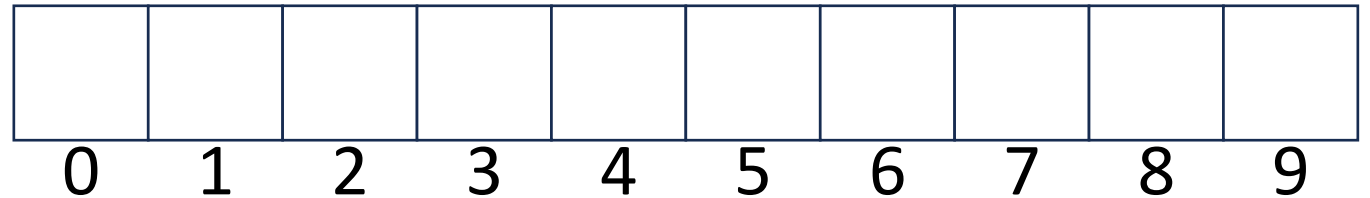
Hash Tables

- Idea:
 - Have a small array to store information
 - Use a **hash function** to convert the key into an index
 - Hash function should “scatter” the keys, behave as if it randomly assigned keys to indices
 - Store key at the index given by the hash function
 - Do something if two keys map to the same place (should be very rare)
 - Collision resolution



Collision Resolution

- A Collision occurs when we want to insert something into an already-occupied position in the hash table
- 2 main strategies:
 - Separate Chaining
 - Use a secondary data structure to contain the items
 - E.g. each index in the hash table is itself a linked list
 - Open Addressing
 - Use a different spot in the table instead
 - Linear Probing
 - Quadratic Probing
 - Double Hashing



Rehashing

- If your load factor λ gets too large, copy everything over to a larger hash table
 - To do this: make a new, larger array
 - Re-insert all items into the new hash table by reapplying the hash function
 - We need to reapply the hash function because items should map to a different index
 - New array should be “roughly” double the length (but probably still want it to be prime)
- What does “too large” mean?
 - For separate chaining, typically we want $\lambda < 2$
 - For open addressing, typically we want $\lambda < \frac{1}{2}$

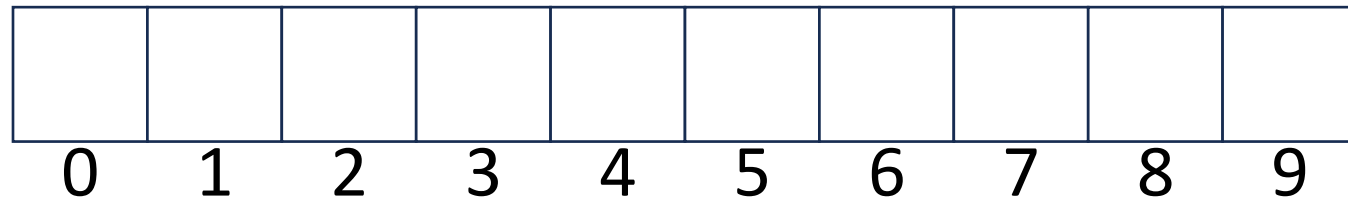
Linear Probing: Insert Procedure

- To insert k, v
 - Calculate $i = h(k) \% \text{length}$
 - If $table[i]$ is occupied then try $(i + 1) \% \text{length}$
 - If that is occupied try $(i + 2) \% \text{length}$
 - If that is occupied try $(i + 3) \% \text{length}$
 - ...
 - $h(k) = k \% 10$

		2	32	24	62	54			
0	1	2	3	4	5	6	7	8	9

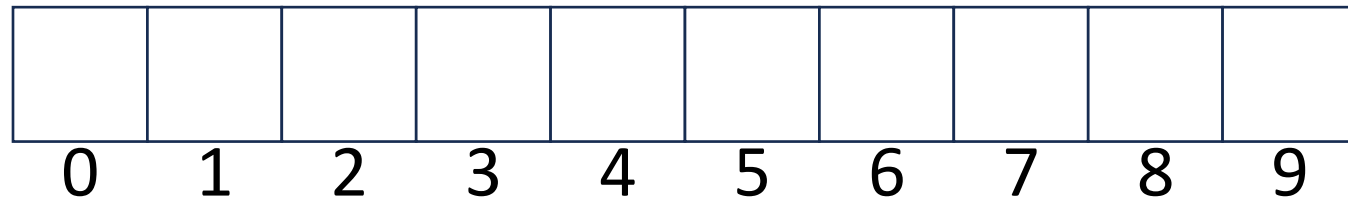
Linear Probing: Find

- To find key k
 - Calculate $i = h(k) \% length$
 - If $table[i]$ is occupied and does not contain k then look at $(i + 1) \% length$
 - If that is occupied and does not contain k then look at $(i + 2) \% length$
 - If that is occupied and does not contain k then look at $(i + 3) \% length$
 - Repeat until you either find k or else you reach an empty cell in the table



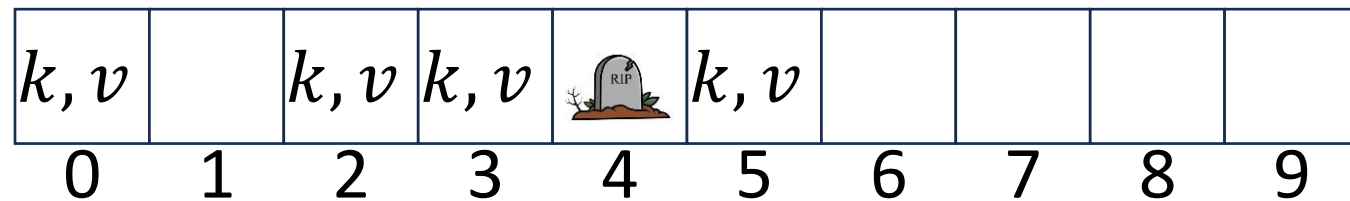
Linear Probing: Delete

- To delete key k , where $h(k) = i$
 - Assume it is present
- Beginning at index i , probe until we find k (call this location index j)
- Mark j as empty (e.g. null), then continue probing while doing the following until you find another empty index
 - If you come across a key which hashes to a value $\leq j$ then move that item to index j and update j .



Linear Probing: Delete

- Option 1: Fill in with items that hashed to before the empty slot
- Option 2: “Tombstone” deletion. Leave a special object that indicates an object was deleted from there
 - The tombstone does not act as an open space when finding (so keep looking after its reached)
 - When inserting you can replace a tombstone with a new item

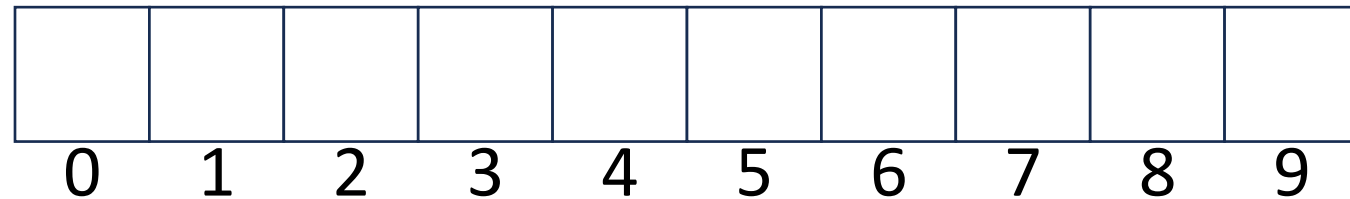


Downsides of Linear Probing

- What happens when λ approaches 1?
 - Get longer and longer contiguous blocks
 - A collision is guaranteed to grow a block
 - Larger blocks experience more collisions
 - Feedback loop!
- What happens when λ exceeds 1?
 - Impossible!
 - You can't insert more stuff

Quadratic Probing: Insert Procedure

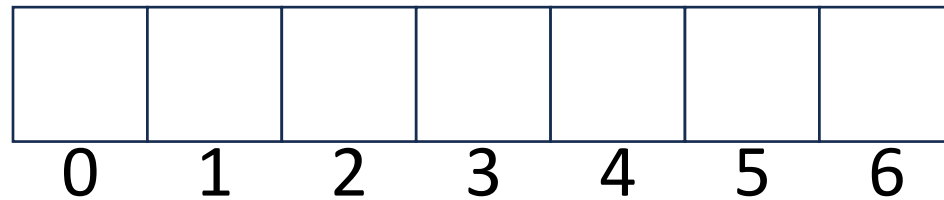
- To insert k, v
 - Calculate $i = h(k) \% size$
 - If $table[i]$ is occupied then try $(i + 1^2) \% size$
 - If that is occupied try $(i + 2^2) \% size$
 - If that is occupied try $(i + 3^2) \% size$
 - If that is occupied try $(i + 4^2) \% size$
 - ...



Quadratic Probing: Example

- Insert:

- 76
- 40
- 48
- 5
- 55
- 47

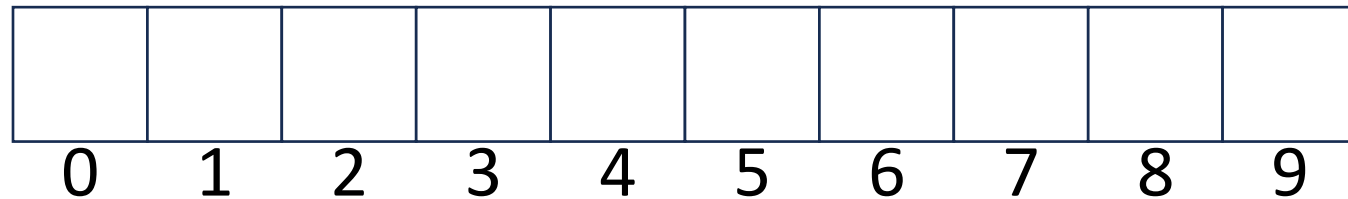


Using Quadratic Probing

- If you probe *tablesize* times, you start repeating the same indices
- If *tablesize* is prime and $\lambda < \frac{1}{2}$ then you're guaranteed to find an open spot in at most $tablesize/2$ probes
- Helps with the clustering problem of linear probing, but does not help if many things hash to the same value

Double Hashing: Insert Procedure

- Given h and g are both good hash functions
- To insert k, v
 - Calculate $i = h(k) \% size$
 - If $table[i]$ is occupied then try $(i + g(k)) \% size$
 - If that is occupied try $(i + 2 \cdot g(k)) \% size$
 - If that is occupied try $(i + 3 \cdot g(k)) \% size$
 - If that is occupied try $(i + 4 \cdot g(k)) \% size$
 - ...



Sorting

- Rearrangement of items into some defined sequence
 - Usually: reordering a list from smallest to largest according to some metric
- Why sort things?

More Formal Definition

- Input:

- An array A of items
- A comparison function for these items
 - Given two items x and y , we can determine whether $x < y$, $x > y$, or $x = y$

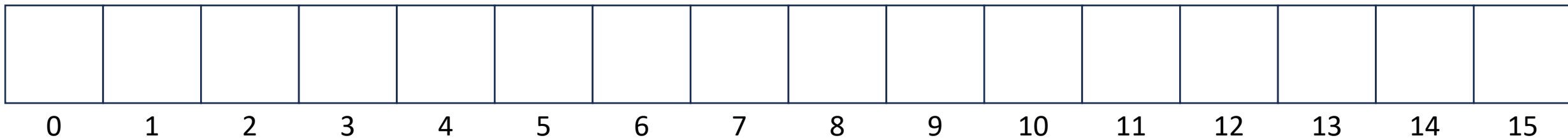
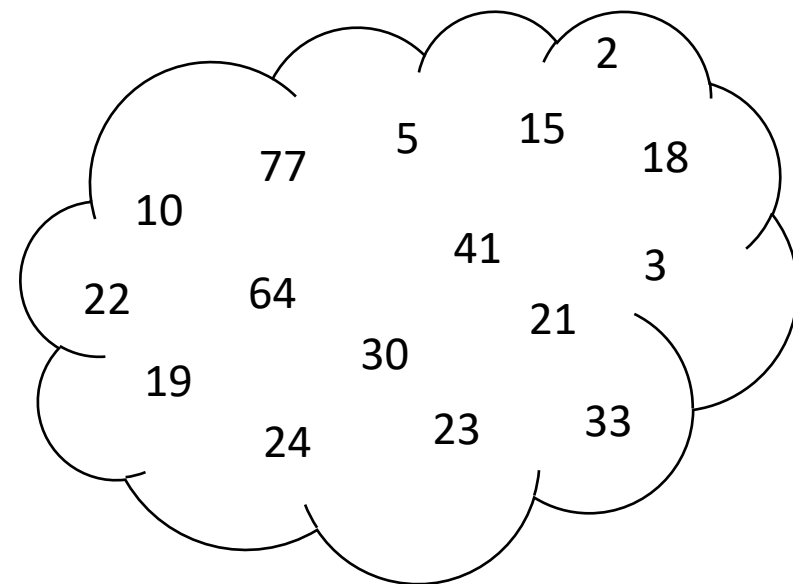
- Output:

- A permutation of A such that if $i \leq j$ then $A[i] \leq A[j]$
- Permutation: a sequence of the same items but perhaps in a different order

Sorting “Landscape”

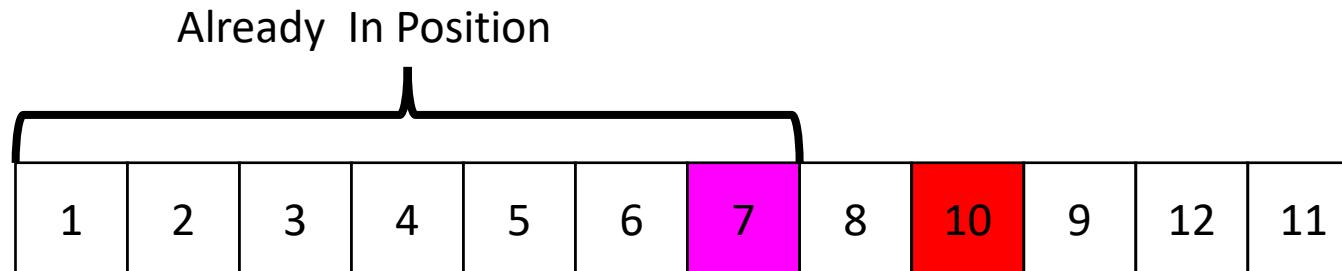
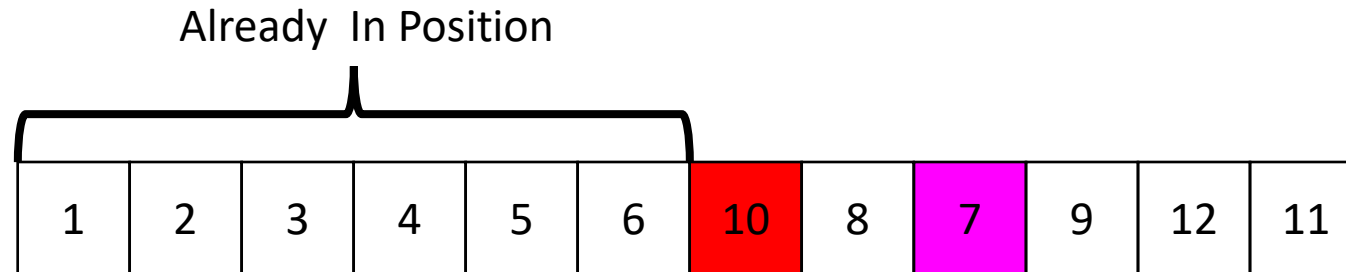
- There is no singular best algorithm for sorting
- Some are faster, some are slower
- Some use more memory, some use less
- Some are super extra fast if your data matches particular assumptions
- Some have other special properties that make them valuable
- No sorting algorithm can have only all the “best” attributes

“Moving Day” Sorting Algorithm



Selection Sort

- **Idea:** Find the **next smallest** element, swap it into the **next index** in the array



Selection Sort

- Swap the thing at index 0 with the smallest thing in the array
- Swap the thing at index 1 with the smallest thing after index 0
- ...
- Swap the thing at index i with the smallest thing after index $i - 1$

```
for (i=0; i<a.length; i++){  
    smallest = i;  
    for (j=i; j<a.length; j++){  
        if (a[j]<a[smallest]){ smallest=j;}  
    }  
    temp = a[i];  
    a[i] = a[smallest];  
    a[smallest] = temp;  
}
```

Running Time:

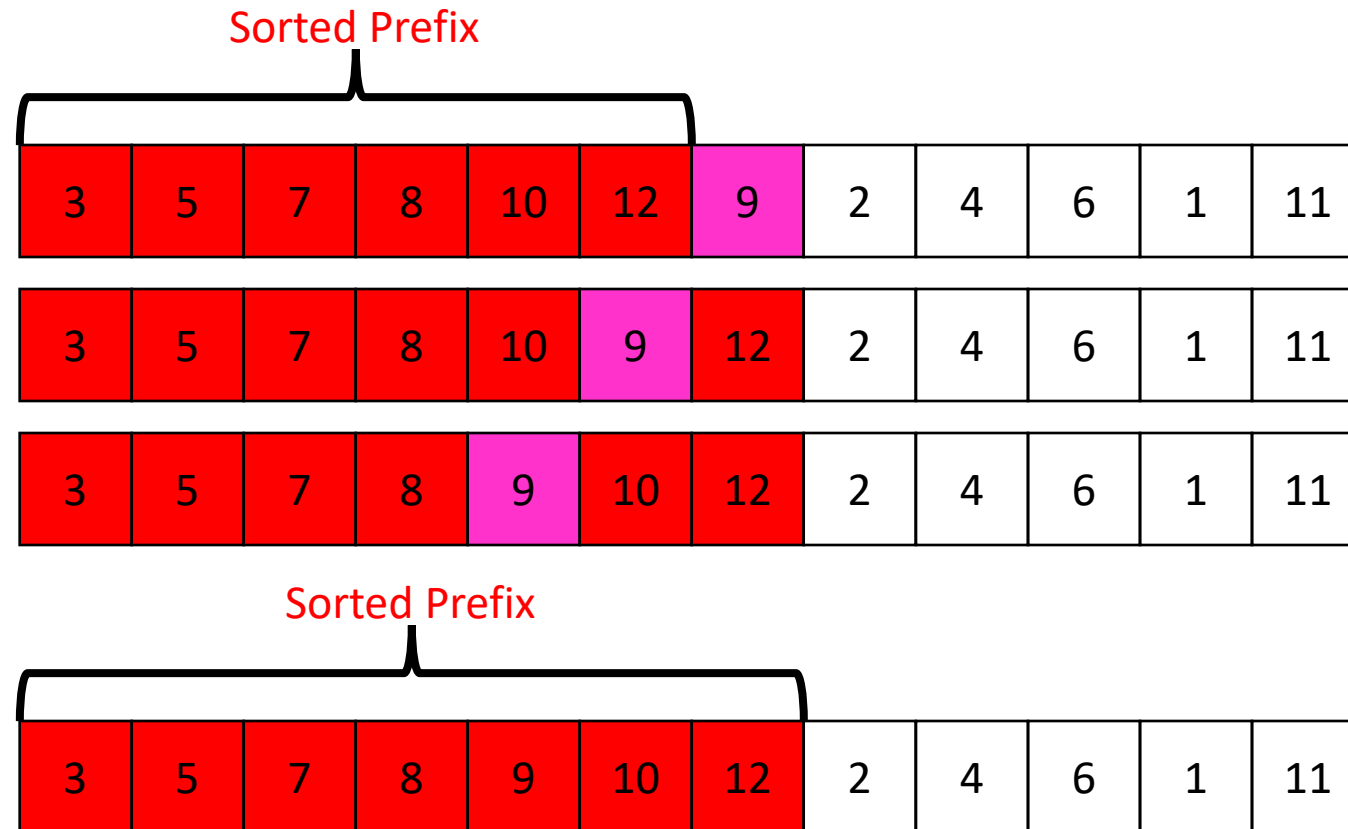
Worst Case: $\Theta(n^2)$

Best Case: $\Theta(n^2)$

10	77	5	15	2	22	64	41	18	19	30	21	3	24	23	33
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15

Insertion Sort

- Idea: Maintain a **sorted list prefix**, extend that prefix by “inserting” the **next element**



Insertion Sort

- If the items at index 0 and 1 are out of order, swap them
- Keep swapping the item at index 2 with the thing to its left as long as the left thing is larger
- ...
- Keep swapping the item at index i with the thing to its left as long as the left thing is larger

```
for (i=1; i<a.length; i++){  
  prev = i-1;  
  while(a[i] < a[prev] && prev > -1){  
    temp = a[i];  
    a[i] = a[prev];  
    a[prev] = temp;  
    i--;  
    prev--;  
  }  
}
```

Running Time:

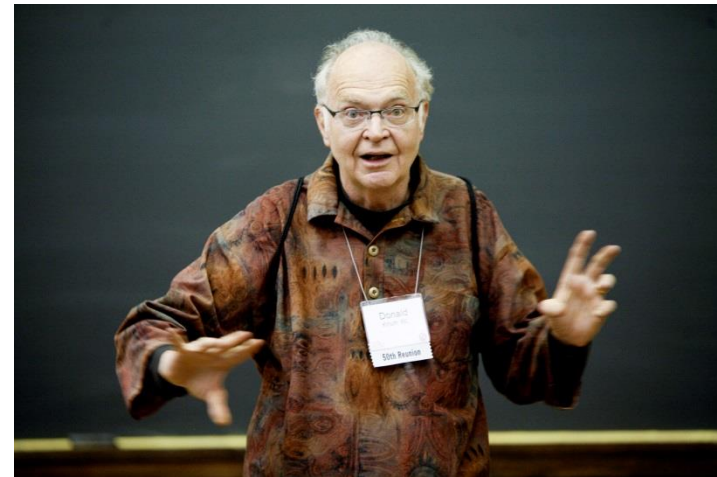
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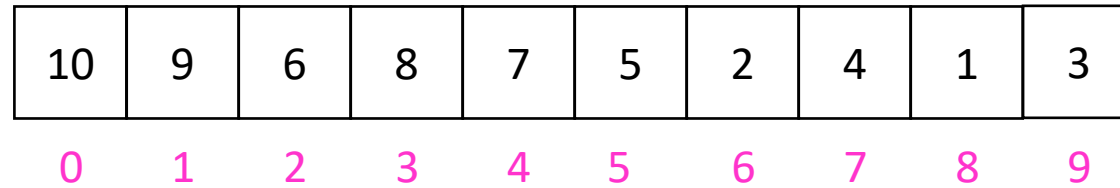
Aside: Bubble Sort – we won't cover it

"the bubble sort seems to have nothing to recommend it, except a catchy name and the fact that it leads to some interesting theoretical problems" –Donald Knuth, The Art of Computer Programming



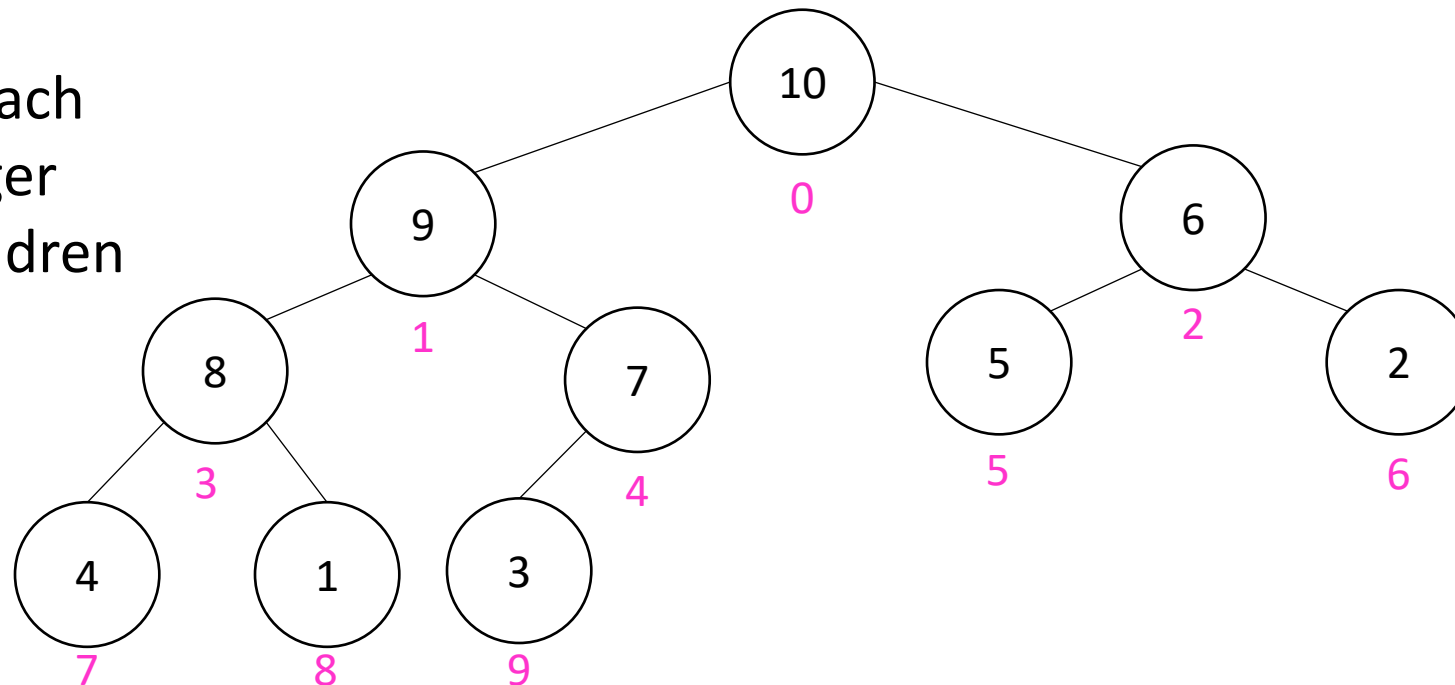
Heap Sort

- **Idea:** Build a maxHeap, repeatedly delete the max element from the heap to build sorted list Right-to-Left



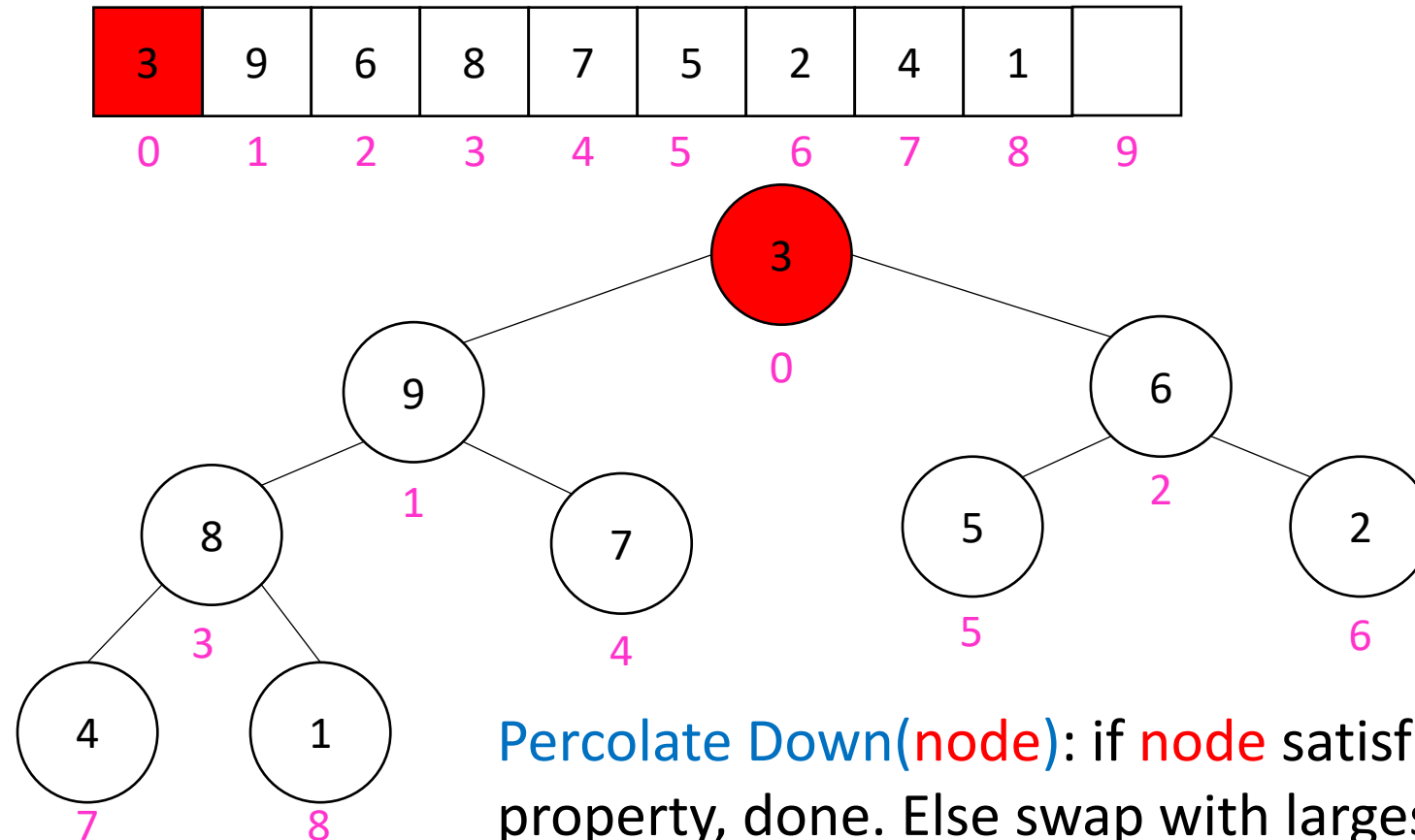
Max Heap

Property: Each node is larger than its children



Heap Sort

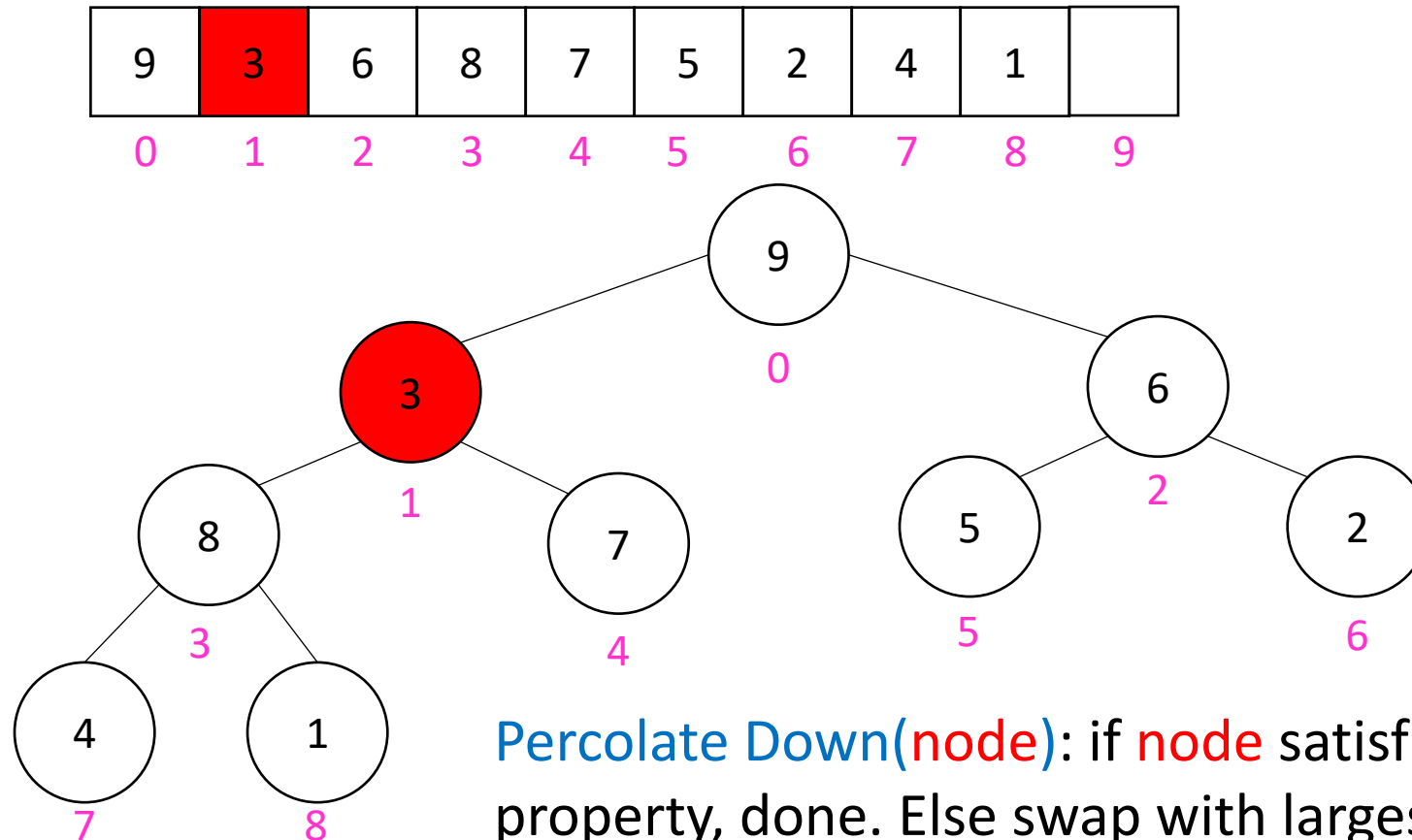
- Remove the Max element (i.e. the root) from the Heap: replace with last element, call `percolateDown(root)`



Percolate Down(node): if **node** satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort

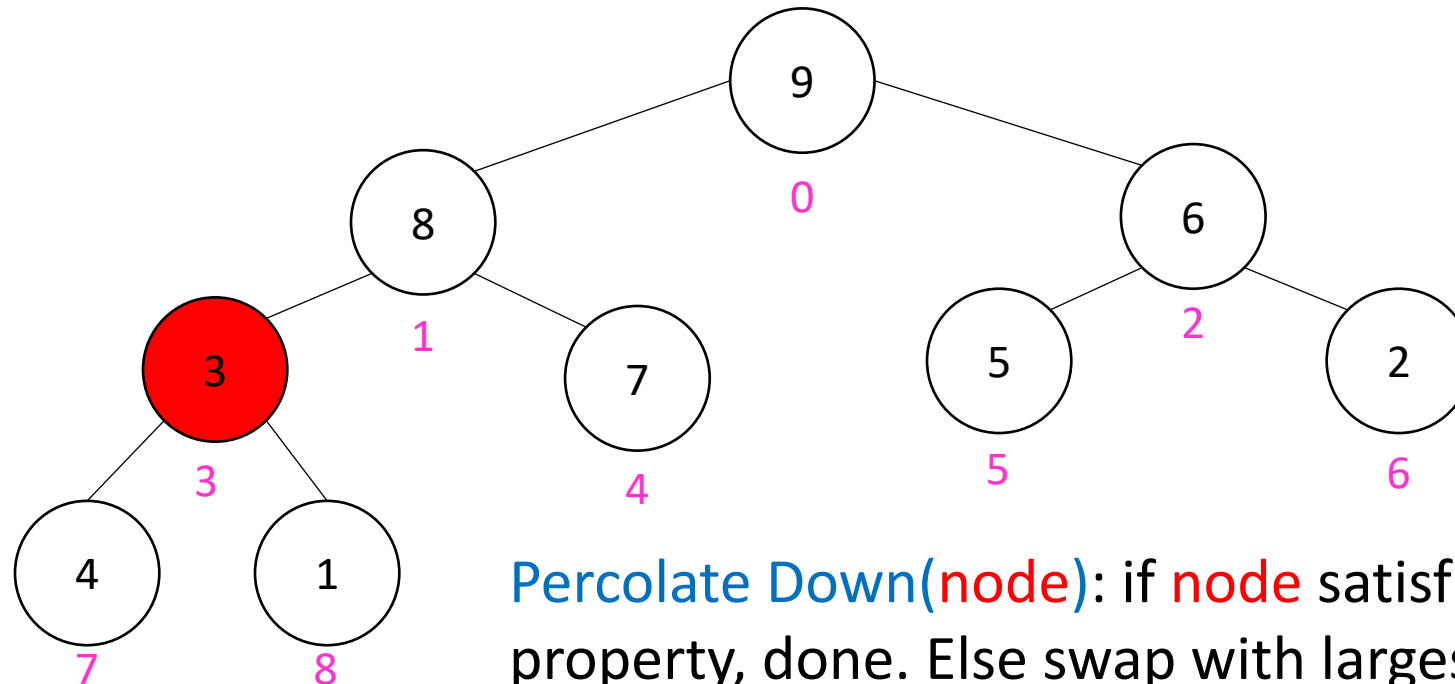
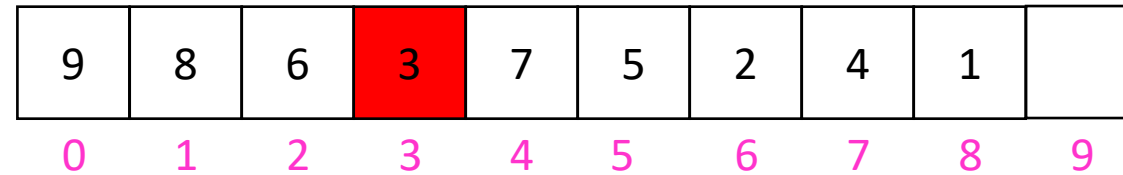
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Heap Sort

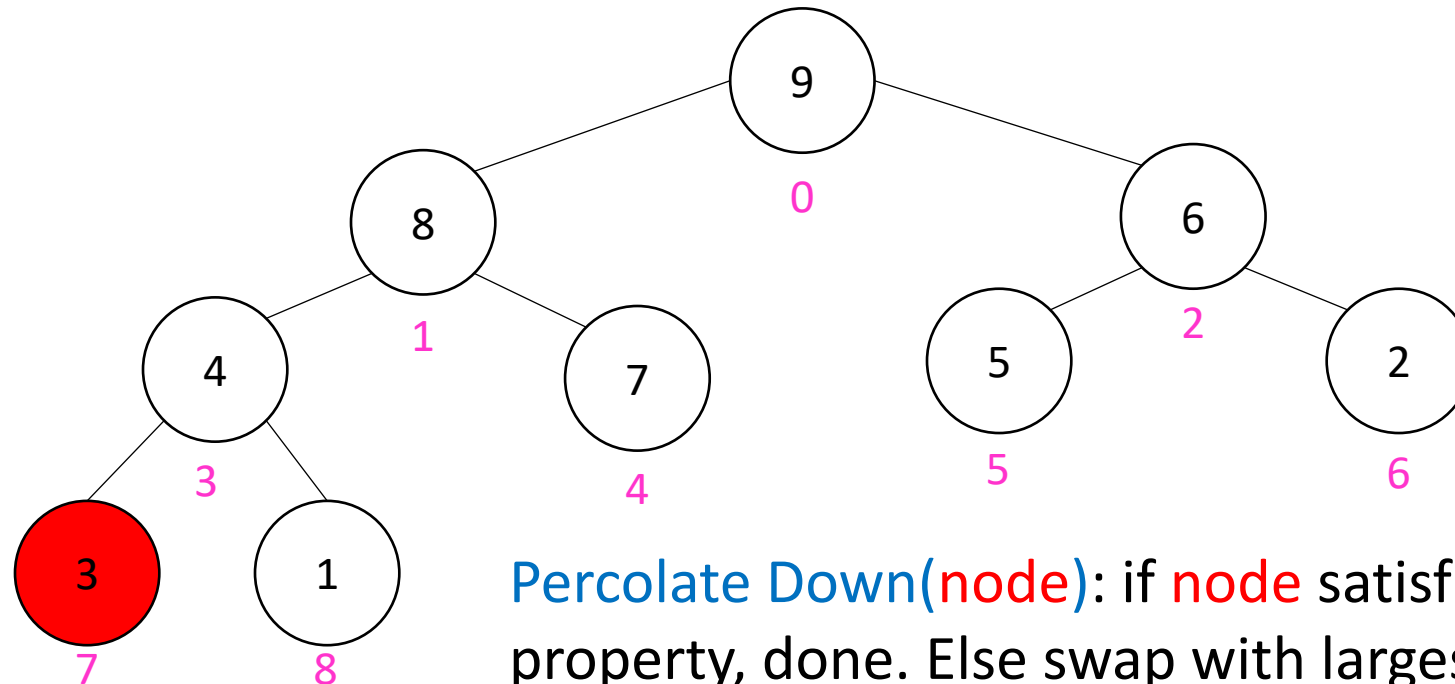
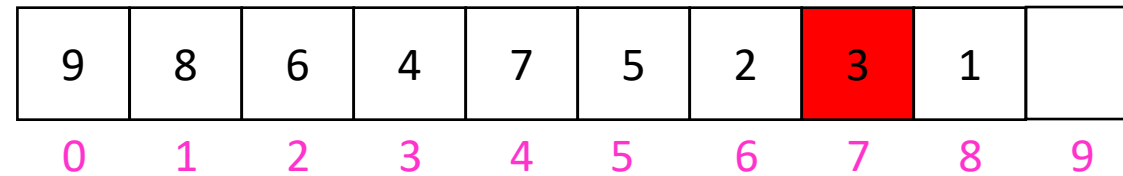
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Heap Sort

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Percolate Down(node): if **node** satisfies heap property, done. Else swap with largest child and repeat on that subtree

Heap Sort

- Build a heap
- Call deleteMax
- Put that at the end of the array

```
myHeap = buildHeap(a);  
for (int i = a.length-1; i>=0; i--){  
    item = myHeap.deleteMax();  
    a[i] = item;  
}
```

Running Time:

Worst Case: $\Theta(\cdot)$

Best Case: $\Theta(\cdot)$

“In Place” Sorting Algorithm

- A sorting algorithm which requires no extra data structures
- Idea: It sorts items just by swapping things in the same array given
- Definition: it only uses $\Theta(1)$ extra space

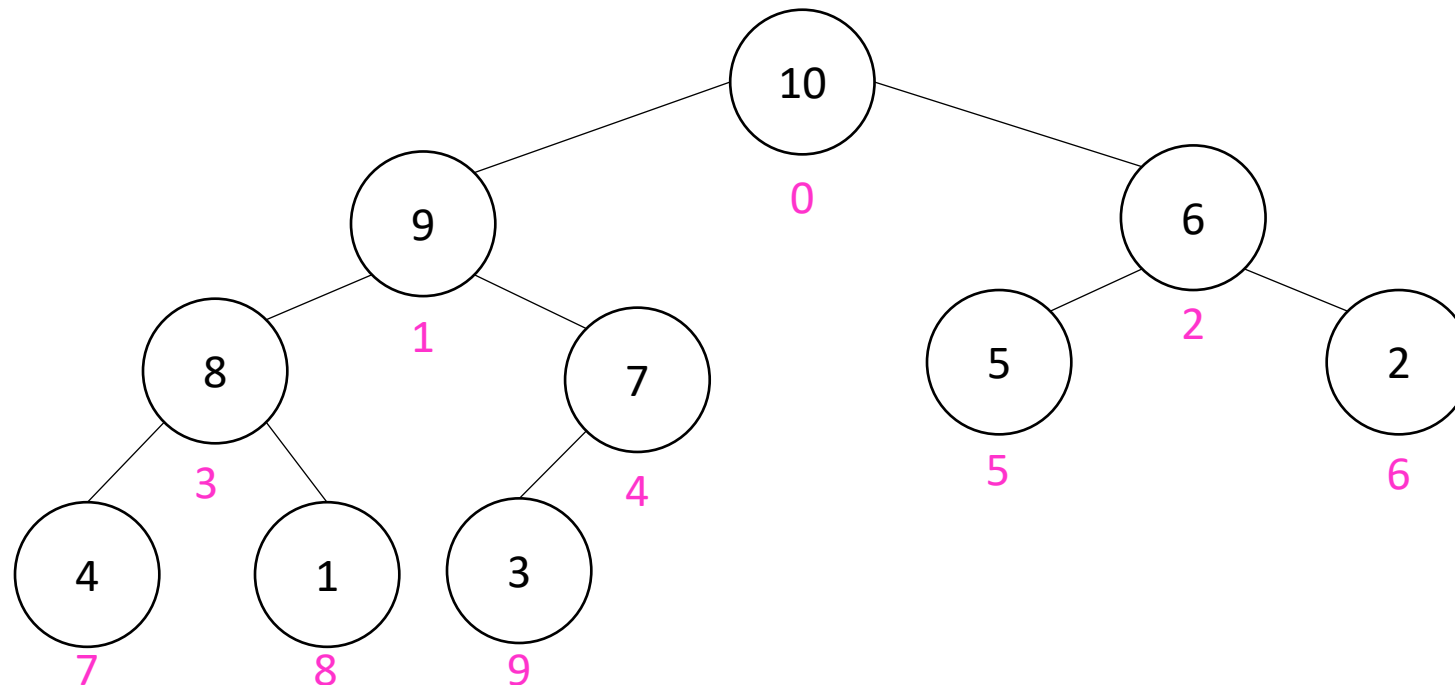
- Selection sort: In Place!
- Insertion sort: In Place!
- Heap sort: Not In Place!
 - But we can fix that!

In Place Heap Sort

- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

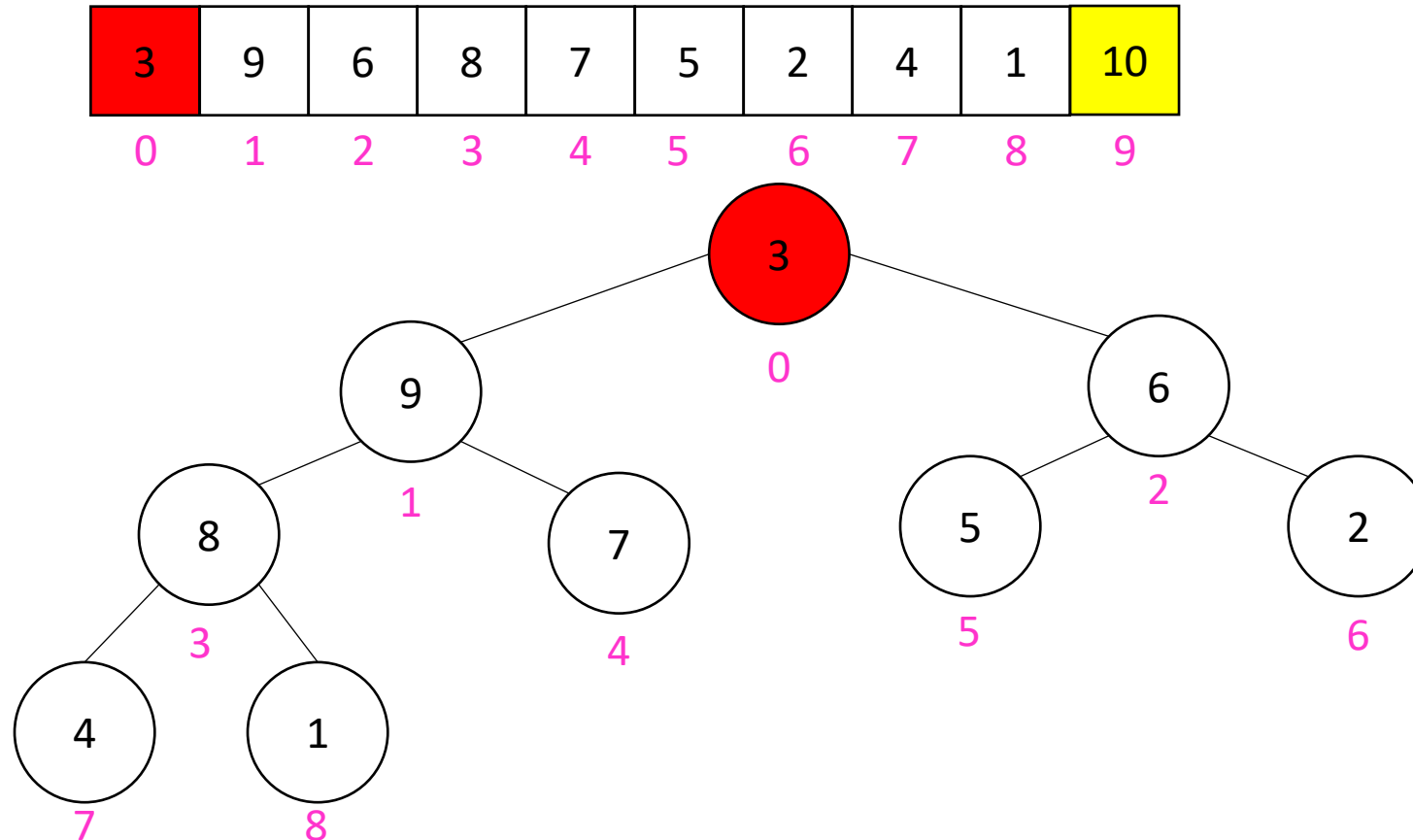
10	9	6	8	7	5	2	4	1	3
----	---	---	---	---	---	---	---	---	---

0 1 2 3 4 5 6 7 8 9



Heap Sort

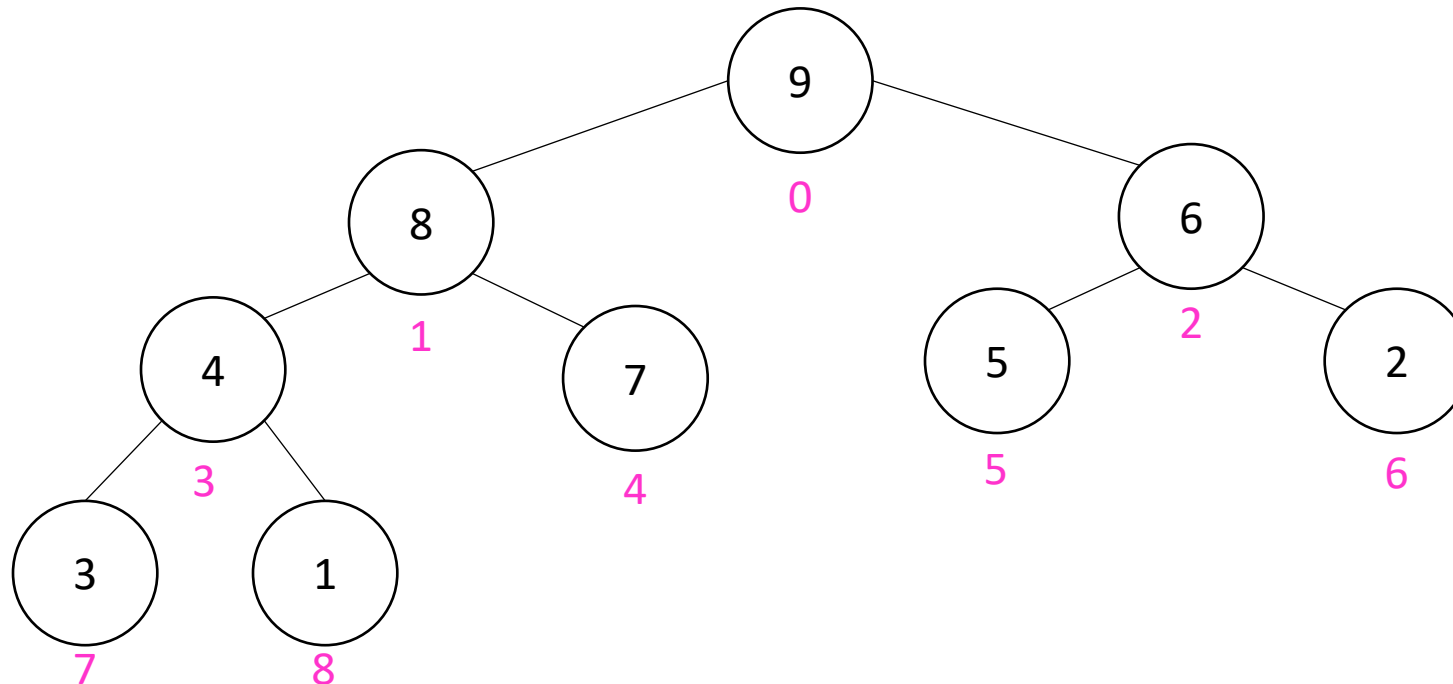
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Heap Sort

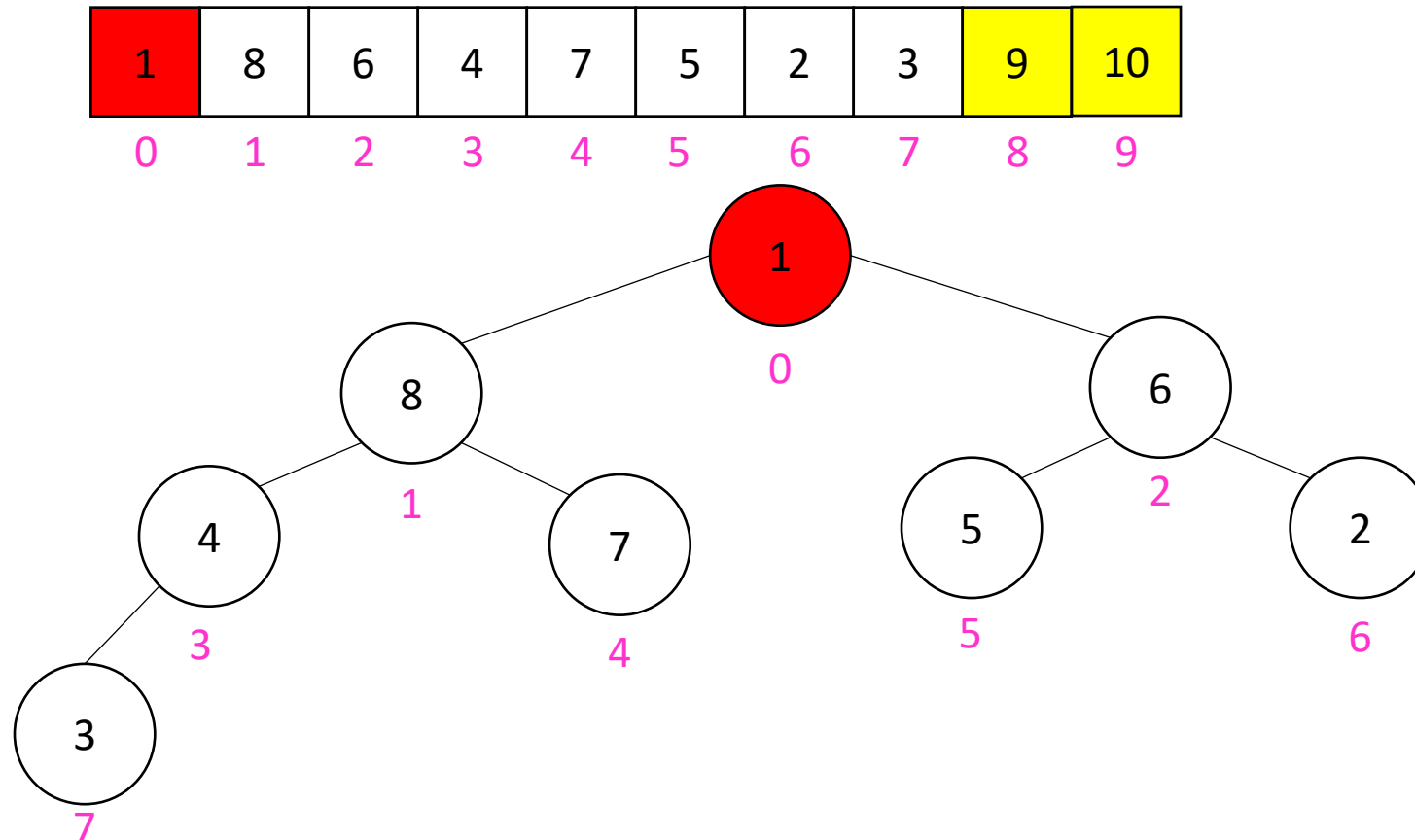
- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

9	8	6	4	7	5	2	3	1	10
0	1	2	3	4	5	6	7	8	9



Heap Sort

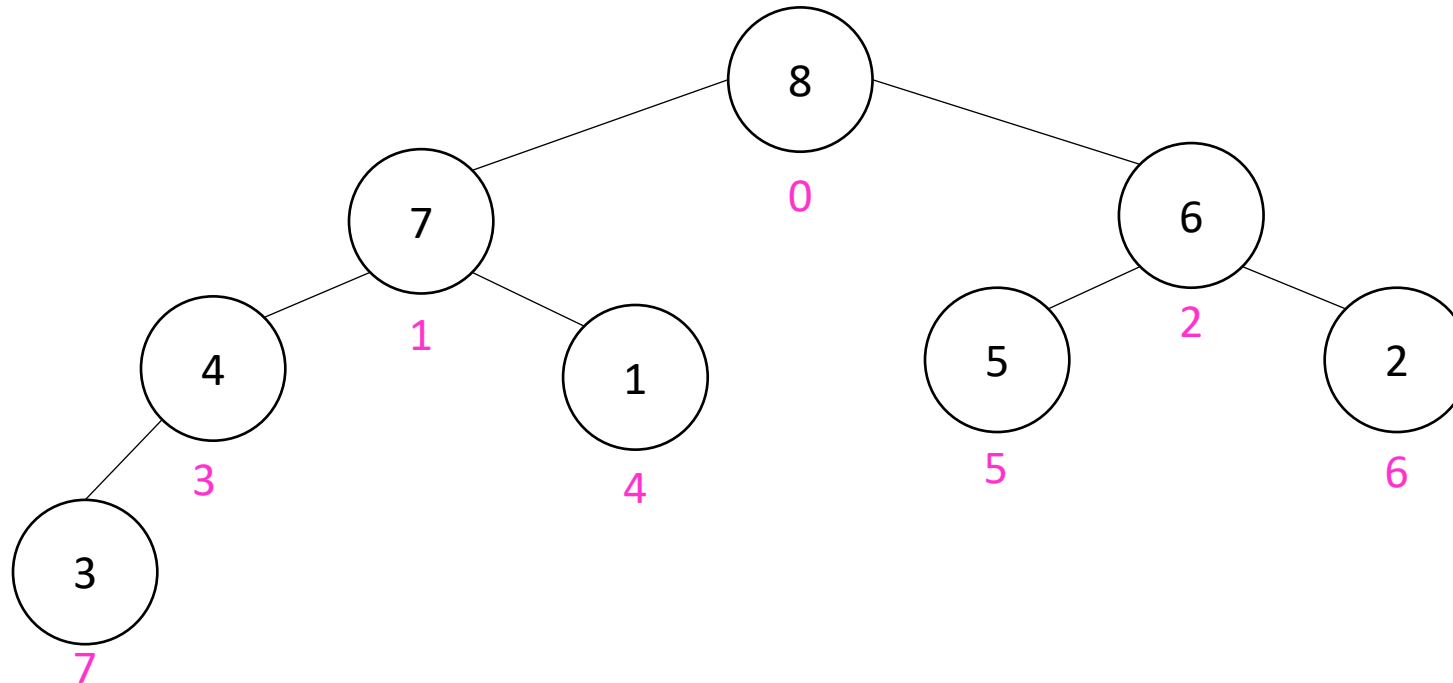
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Heap Sort

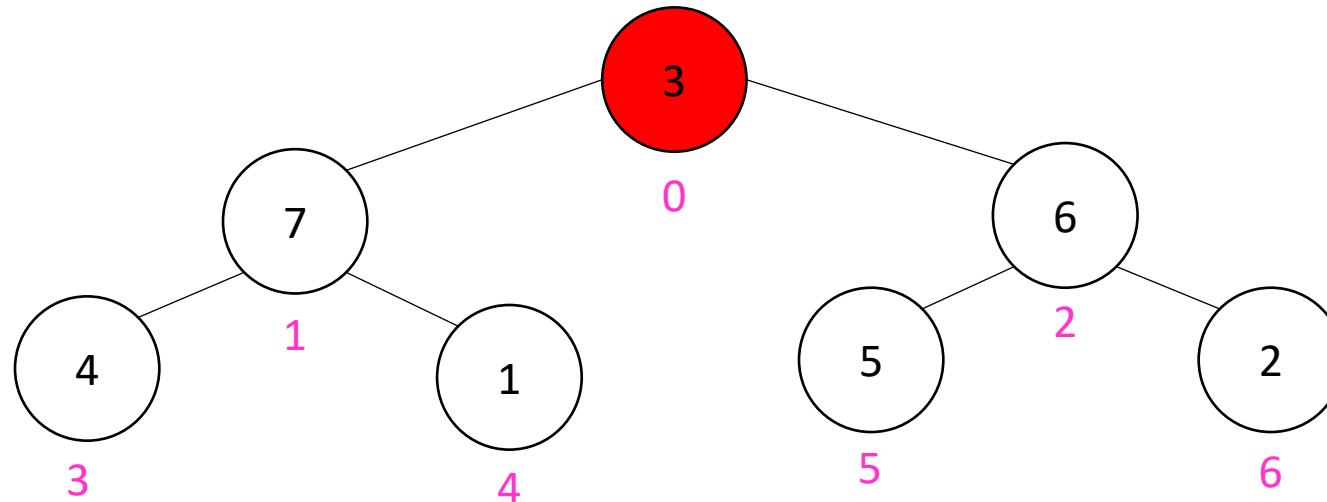
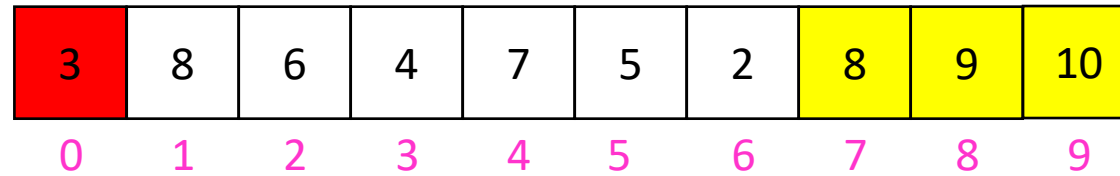
- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

1	8	6	4	7	5	2	3	9	10
0	1	2	3	4	5	6	7	8	9



Heap Sort

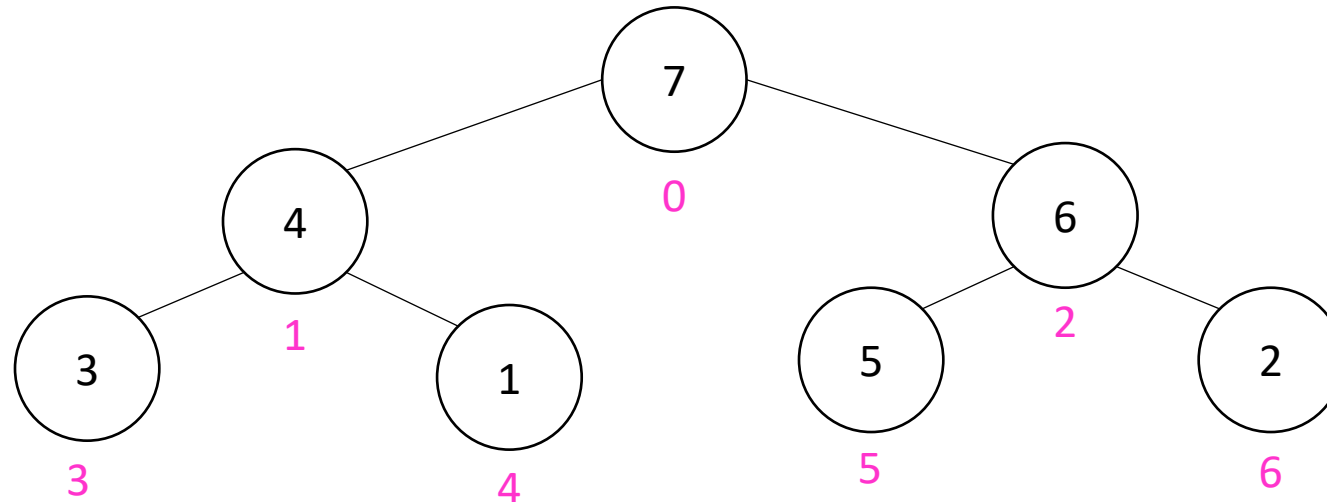
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Heap Sort

- **Idea:** When “removing” an element from the heap, swap it with the last item of the heap then “pretend” the heap is one item shorter

3	8	6	4	7	5	2	8	9	10
0	1	2	3	4	5	6	7	8	9



In Place Heap Sort

- Build a heap using the same array (Floyd's build heap algorithm works)
- Call deleteMax
- Put that at the end of the array

```
buildHeap(a);  
for (int i = a.length-1; i>=0; i--){  
    temp=a[i]  
    a[i] = a[0];  
    a[0] = temp;  
    percolateDown(0);  
}
```

Running Time:

Worst Case: $\Theta(\cdot)$

Best Case: $\Theta(\cdot)$

Floyd's buildHeap method

- Working towards the root, one row at a time, percolate down

```
buildHeap(){  
    for(int i = size; i>0; i--){  
        percolateDown(i);  
    }  
}
```