# CSE 332 Data Structures & Parallelism

Priority Queues 2

Melissa Winstanley Spring 2024

#### **Types of Trees**

Binary tree: Every node has ≤2 children

n-ary tree: Every node has ≤n children

Perfect tree: Every row is completely full

Complete tree: All rows except possibly the bottom are completely full, and it is filled from left to right



## Properties of a Binary Min-Heap

More commonly known as a binary heap or simply a heap

- Structure Property
  - A complete [binary] tree
- Heap Property
  - Every non-root node has a priority value larger than (or possibly equal to) the priority of its parent

How is this different from a binary search tree?

#### Properties of a Binary Min-Heap

More commonly known as a binary heap or simply a heap

- Structure Property
  - A complete [binary] tree
- Heap Property
  - Every non-root node has a priority value larger than (or possibly equal to) the priority of its parent





Is this a binary min heap? yes/no

#### Today - Priority Queues / Heaps

- What is a Priority Queue?
- Introduction to the heap
- Heap operations
- Heap implementation
- Building a heap



## **Heap Operations**

- findMin
- insert(val): percolate up
- deleteMin: percolate down



#### **Operations:** basic idea

• findMin:

return root.data

- deleteMin:
  - 1. answer = root.data
  - 2. Move right-most node in last row to root to restore structure property
  - 3. "Percolate down" to restore heap order property
- insert:
  - 1. Put new node in next position on bottom row to restore structure property
  - 2. "Percolate up" to restore heap order property



#### Overall strategy:

- Preserve complete tree structure property
- This may break heap order property
- Percolate to restore heap order property

#### A Clever Trick for Storing the Heap

- Clearly, insert and deleteMin are worst-case O(log n)
  - But we promised average-case O(1) insert (how??)
- Insert requires access to the "next to use" position in the tree
  - Walking the tree from root to leaf requires O(log n) steps
  - insert and deleteMin would have to update the "next to use" reference each time:
     O(log n)
- We should only pay for the functionality we need!!
  - Why have we insisted the tree be complete? ③
- All complete trees of size n contain the same edges
  - So why are we even representing the edges?

#### Here comes the really clever bit about implementing heaps!!!



- We skip index 0 to make the math simpler
- Actually, it can be a good place to store the current size of the heap

#### Today - Priority Queues / Heaps

- What is a Priority Queue?
- Introduction to the heap
- Heap operations
- Heap implementation
- Building a heap

#### Pseudocode: insert



#### Pseudocode: deleteMin

```
int deleteMin() {
    if(isEmpty()) throw...
    ans = arr[1];
    hole = percolateDown
                         (1,arr[size]);
    arr[hole] = arr[size];
    size--;
    return ans;
}
```



int percolateDown(int hole, int val) { while(2\*hole <= size) {</pre> left = 2\*hole; right = left + 1;if(arr[left] < arr[right]</pre> | right > size)  $\rightarrow$  target = left; else  $\rightarrow$  target = right; if(arr[target] < val) {</pre> arr[hole] = arr[target]; hole = target; } else break; } return hole;

700

8

50

9

65

10

11

12

13



#### **Other Operations**

- **decreaseKey**: given pointer to object in priority queue (e.g., its array index), lower its priority value by p
  - Change priority and percolate up
- **increaseKey**: given pointer to object in priority queue (e.g., its array index), raise its priority value by p
  - Change priority and percolate down
- remove: given pointer to object in priority queue (e.g., its array index), remove it from the queue
  - decreaseKey with  $p = \infty$ , then deleteMin
- Running time for all these operations?

## So why O(1) average-case insert?

- Yes, insert's worst case is O(log n)
- The trick is that it all depends on the order the items are inserted (What is the worst case order?)
- Experimental studies of randomly ordered inputs shows the following:
  - Average<u>2.607 c</u>omparisons per insert (# of percolation passes)
  - An element usually moves up 1.607 levels
- deleteMin is average O(log n)
  - Moving a leaf to the root usually requires re-percolating that value back to the bottom

#### Intuition for O(1) runtime average case

- Insert: Place in next spot, percUp
- How high do we expect it to go?
- Aside: Complete Binary Tree
  - Each full row has 2x nodes of parent row
  - Bottom level has ~1/2 of all nodes
  - Second to bottom has ~1/4 of all nodes
- PercUp Intuition:
  - $\circ$   $\quad$  Move up if value is less than parent
  - Inserting a random value, likely to have value not near highest, nor lowest; somewhere in middle
  - Given a random distribution of values in the heap, bottom row should have the upper half of values, 2nd from bottom row, next 1/4
  - Expect to only raise a level or 2, even if h is large
- Worst case: still O(logn)
- Expected case: O(1)
- Of course, there's no guarantee; it may percUp to the root



#### Today - Priority Queues / Heaps

- What is a Priority Queue?
- Introduction to the heap
- Heap operations
- Heap implementation
- Building a heap

#### **Building a Heap**

Suppose you have n items you want to put in a new priority queue

- A sequence of n <u>insert</u> operations works
- Runtime? O(rlogn)

Can we do better?

- If we only have access to **insert** and **deleteMin** operations, then NO.
- There is a faster way O(n), but that requires the ADT to have a specialized **buildHeap** operation

Important issue in ADT design: how many specialized operations?

• Tradeoff: Convenience, Efficiency, Simplicity

#### Floyd's buildHeap Method

Recall our general strategy for working with the heap:

- Preserve structure property
- Break and restore heap ordering property

Floyd's buildHeap:

- 1. Create a complete tree by putting the n items in array indices 1, ... n
- 2. Treat the array as a heap and fix the heap-order property
  - Exactly how we do this is where we gain efficiency

#### Thinking about **buildHeap**

• Say we start with this array:

[12,5,11,3,10,2,9,4,8,1,7,6]

- To "fix" the ordering can we use:
  - o percolateUp?
  - o percolateDown?



#### Floyd's buildHeap Method

Bottom-up:

- Leaves are already in heap order
- Work up toward the root one level at a time

```
void buildHeap() {
  for(i = size/2; i>0; i--) {
    val = arr[i];
    hole = percolateDown(i,val);
    arr[hole] = val;
  }
}
```

#### Thinking about **buildHeap**

• Say we start with this array:

[12,5,11,3,10,2,9,4,8,1,7,6]

- In tree form for readability
   Red for node out of place
- Notice no leaves are red
- Check/fix each non-leaf, bottom-up (6 steps here)















#### buildHeap Efficiency

Easy argument: **buildHeap** is O(n log n) where n is size

- size/2 loop iterations
- Each iteration does one percolateDown, each is O(log n)

This is correct, but there is a more precise ("tighter") analysis of the algorithm...

void buildHeap() { for(i = size/2; i>0; i--) { val = arr[i]; ( hole = percolateDown(i,val); arr[hole] = val;

#### buildHeap Efficiency

- No node can percolate down more than the height of its subtree
  - When i is a leaf: 0
  - When i is second-from-last level: 1
  - When i is third-from-last level: 2
- Overall Running time:

k=0

k = height of tree = log n
but it's actually easier
math if we say that it's
infinity

$$egin{aligned} &0\left(rac{n}{2}
ight)+1\left(rac{n}{4}
ight)+2\left(rac{n}{8}
ight)....+k\left(rac{n}{2^{k+1}}
ight)\ &\sum_{k=1}^{\infty}rac{kn}{2^{k+1}}=n\sum_{k=1}^{\infty}rac{k}{2^{k+1}}=n imes 1=n \end{aligned}$$

k=0