CSE 332: Data Structures \& Parallelism Lecture 10:Hashing

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Winter 2023

## Today

- Dictionaries
- Hashing


## Motivating Hash Tables

For dictionary with $n$ key/value pairs

- Unsorted linked-list
- Unsorted array
- Sorted linked list
- Sorted array
- Balanced tree

| insert | find | delete |
| :---: | :--- | :--- |
| $O(n)^{*}$ | $O(n)$ | $O(n)$ |
| $O(n)^{*}$ | $O(n)$ | $O(n)$ |
| $O(n)$ | $O(n)$ | $O(n)$ |
| $O(n)$ | $O(\log n)$ | $O(n)$ |
| $O(\log n)$ | $O(\log n)$ | $O(\log n)$ |

* Assuming we must check to see if the key has already been inserted. Cost becomes cost of a find operation, inserting itself is $\mathrm{O}(1)$.


## Hash Tables

- Aim for constant-time (i.e., $O(1)$ ) find, insert, and delete
- "On average" under some reasonable assumptions
- A hash table is an array of some fixed size
- Basic idea:

key space (e.g., integers, strings)


## Aside: Hash Tables vs. Balanced Trees

- In terms of a Dictionary ADT for just insert, find, delete, hash tables and balanced trees are just different data structures
- Hash tables $O(1)$ on average (assuming few collisions)
- Balanced trees $O(\log n)$ worst-case
- Constant-time is better, right?
- Yes, but you need "hashing to behave" (must avoid collisions)
- Yes, but what if we want to findMin, findMax, predecessor, and successor, printSorted?
- Hashtables are not designed to efficiently implement these operations
- Your textbook considers Hash tables to be a different ADT
- Not so important to argue over the definitions


## Hash Tables

- There are $m$ possible keys ( $m$ typically large, even infinite)
- We expect our table to have only $n$ items
- $n$ is much less than $m$ (often written $n \ll m$ )

Many dictionaries have this property

- Compiler: All possible identifiers allowed by the language vs. those used in some file of one program
- Database: All possible student names vs. students enrolled
- Al: All possible chess-board configurations vs. those considered by the current player


## Hash Functions

An ideal hash function:

- Is fast to compute
- "Rarely" hashes two "used" keys to the same index
- Often impossible in theory; easy in practice
- Will handle collisions a bit later

key space (e.g., integers, strings)



## Who hashes what?

- Hash tables can be generic
- To store keys of type $\mathbf{E}$, we just need to be able to:

1. Test equality: are you the $\mathbf{E}$ I'm looking for?
2. Hashable: convert any E to an int

- When hash tables are a reusable library, the division of responsibility generally breaks down into two roles:

- We will learn both roles, but most programmers "in the real world" spend more time as clients while understanding the library


## More on roles

Some ambiguity in terminology on which parts are "hashing"


Two roles must both contribute to minimizing collisions (heuristically)

- Client should aim for different ints for expected items
- Avoid "wasting" any part of E or the 32 bits of the int
- Library should aim for putting "similar" ints in different indices
- conversion to index is almost always "mod table-size"
- using prime numbers for table-size is common


## What to hash?

- We will focus on two most common things to hash: ints and strings
- If you have objects with several fields, it is usually best to have most of the "identifying fields" contribute to the hash to avoid collisions
- Example:

```
class Person {
    String first; String middle; String last;
        Date birthdate;
}
```

- An inherent trade-off: hashing-time vs. collision-avoidance
- Use all the fields?
- Use only the birthdate?
- Admittedly, what-to-hash is often an unprincipled guess $:^{\circ}$


## Hashing integers

key space = integers
Simple hash function:
$\mathrm{h}($ key $)=$ key $\%$ TableSize

- Client: $\mathbf{f}(\mathbf{x})=\mathbf{x}$
- Library $g(x)=f(x) \%$ TableSize
- Fairly fast and natural


## Example:

- TableSize = 10
- Insert 7, 18, 41, 34, 10
- (As usual, ignoring corresponding data)



## Hashing integers (Soln)

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## Collision-avoidance

- With "x \% TableSize" the number of collisions depends on
- the ints inserted (obviously)
- TableSize
- Larger table-size tends to help, but not always
- Example: 70, 24, 56, 43, 10 with TableSize $=10$ and TableSize $=60$
- Technique: Pick table size to be prime. Why?
- Real-life data tends to have a pattern
- "Multiples of 61" are probably less likely than "multiples of 60 "
- We'll see some collision strategies do better with prime size


## More arguments for a prime table size

If TableSize is 60 and...

- Lots of keys are multiples of 5 , wasting $80 \%$ of table
- Lots of keys are multiples of 10 , wasting $90 \%$ of table
- Lots of keys are multiples of 2, wasting $50 \%$ of table

If TableSize is 61...

- Collisions can still happen, but $5,10,15,20, \ldots$ will fill table
- Collisions can still happen but 10, 20, 30, 40, ... will fill table
- Collisions can still happen but $2,4,6,8, \ldots$ will fill table

In general, if $\mathbf{x}$ and y are "co-prime" (means $\operatorname{gcd}(\mathbf{x}, \mathrm{y})==1$ ), then
$(a * x) \% y=(b * x) \% y$ if and only if $a \% y==b \% y$

- Given table size $y$ and keys as multiples of $x$, we'll get a decent distribution if $x \& y$ are co-prime
- So good to have a TableSize that has no common factors 1/30/2023 with any "likely pattern" x


## What if the key is not an int?

- If keys aren't ints, the client must convert to an int
- Trade-off: speed and distinct keys hashing to distinct ints
- Common and important example: Strings
- Key space $\mathrm{K}=\mathrm{s}_{0} \mathrm{~s}_{1} \mathrm{~s}_{2} \ldots \mathrm{~s}_{\mathrm{m}-1}$
- where $\mathrm{s}_{\mathrm{i}}$ are chars: $\mathrm{s}_{\mathrm{i}} \in[0,256]$
- Some choices: Which avoid collisions best?

1. $h(K)=s_{0}$
2. $\mathrm{h}(\mathrm{K})=\left(\sum_{i=0}^{m-1} s_{i}\right)$
3. $\mathrm{h}(\mathrm{K})=\left(\sum_{i=0}^{m-1} s_{i} \cdot 37^{i}\right)$

Then on the library side we typically mod by Tablesize to find index into the table

## Specializing hash functions

How might you hash differently if all your strings were web addresses (URLs)?

## Aside: Combining hash functions

A few rules of thumb / tricks:

1. Use all 32 bits (careful, that includes negative numbers)
2. Use different overlapping bits for different parts of the hash

- This is why a factor of $37^{i}$ works better than $256^{i}$

3. When smashing two hashes into one hash, use bitwise-xor

- bitwise-and produces too many 0 bits
- bitwise-or produces too many 1 bits

4. Rely on expertise of others; consult books and other resources
5. If keys are known ahead of time, choose a perfect hash

## Collision resolution

Collision:
When two keys map to the same location in the hash table

We try to avoid it, but number-of-possible-keys exceeds table size

So hash tables should support collision resolution

- Ideas?


## Flavors of Collision Resolution

Separate Chaining

Open Addressing

- Linear Probing
- Quadratic Probing
- Double Hashing


## Separate Chaining

| 0 | / |
| :---: | :---: |
| 1 | / |
| 2 | / |
| 3 | / |
| 4 | / |
| 5 | / |
| 6 | / |
| 7 | / |
| 8 | / |
| 9 | / |

Chaining: All keys that map to the same table location are kept in a list (a.k.a. a "chain" or "bucket")

As easy as it sounds

Example: insert 10, 22, 107, 12, 42 with mod hashing and TableSize $=10$

## Separate Chaining

|  | $\rightarrow 10$ / |
| :---: | :---: |
| 1 |  |
| 1 |  |
| 1 |  |
| 1 |  |
| 1 |  |
| 1 |  |
| 1 |  |
| 1 |  |
| / |  |

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## Separate Chaining

|  | $\rightarrow 10$ / |
| :---: | :---: |
| / |  |
| - | $\rightarrow 22 /$ |
| 1 |  |
| / |  |
| 1 |  |
| 1 |  |
| 1 |  |
| 1 |  |
| / |  |

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$22 \mid$
As easy as it sounds

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Worst case time for find?

## Thoughts on separate chaining

Worst-case time for find?

- Linear
- But only with really bad luck or bad hash function
- So not worth avoiding (e.g., with balanced trees at each bucket)
- Keep \# of items in each bucket small
- Overhead of AVL tree, etc. not worth it if small \# items per bucket

Beyond asymptotic complexity, some "data-structure engineering" can improve constant factors

- Linked list vs. array or a hybrid of the two
- Move-to-front (part of Project 2)
- Leave room for 1 element (or 2?) in the table itself, to optimize constant factors for the common case
- A time-space trade-off...


## Time vs. space

(only makes a difference in constant factors)


## More rigorous separate chaining analysis

Definition: The load factor, $\lambda$, of a hash table is

$$
\lambda=\frac{\mathrm{N}}{\text { TableSize }} \leftarrow \text { number of elements }
$$

Under chaining, the average number of elements per bucket is $\qquad$

So if some inserts are followed by random finds, then on average:

- Each unsuccessful find compares against $\qquad$ items
- Each successful find compares against $\qquad$ items
- How big should TableSize be??


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Definition: The load factor, $\lambda$, of a hash table is

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$$

Under chaining, the average number of elements per bucket is $\lambda$

So if some inserts are followed by random finds, then on average:

- Each unsuccessful find compares against $\lambda$ items
- Each successful find compares against $\lambda / 2$ items
- If $\lambda$ is low, find \& insert likely to be $\mathrm{O}(1)$
- We like to keep $\boldsymbol{\lambda}$ around 1 for separate chaining


## Load Factor?



## Load Factor?



## Load Factor?



## Load Factor?



## Separate Chaining Deletion?

## Separate Chaining Deletion

- Not too bad
- Find in table
- Delete from bucket
- Say, delete 12
- Similar run-time as insert


