

CSE 332: Data Structures and Parallelism

Spring 2022

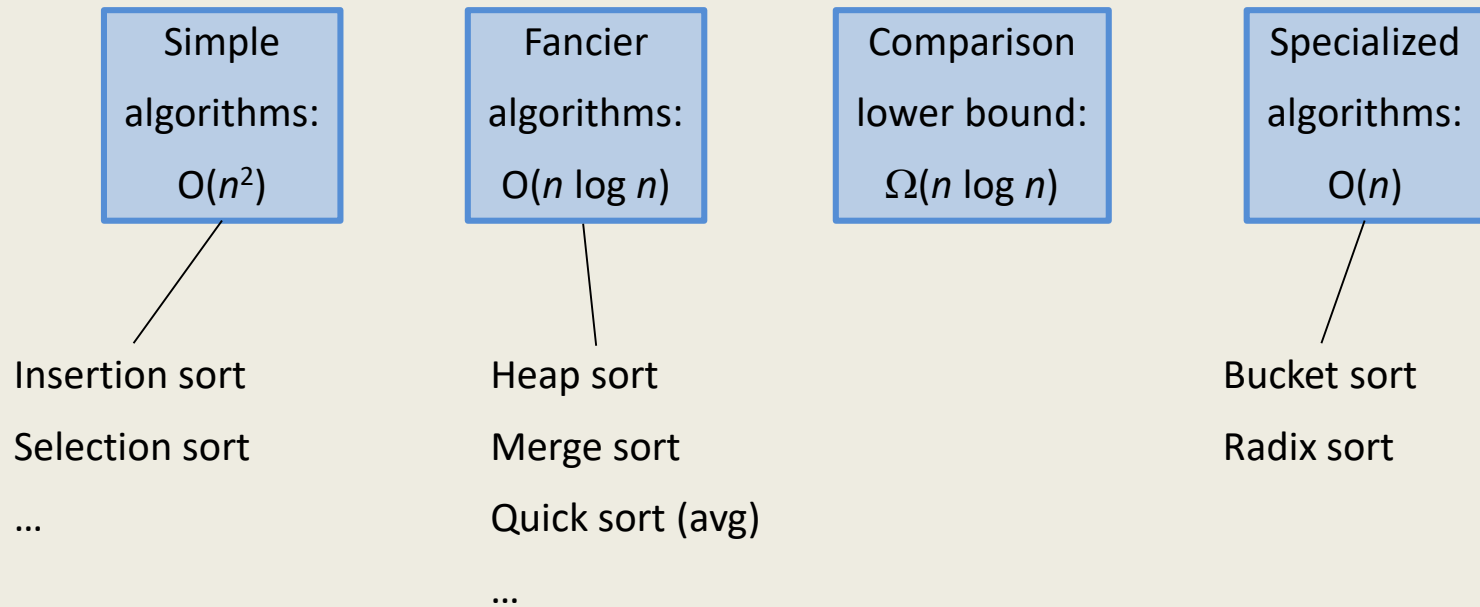
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Lecture 14: Sorting II

Announcements

- Midterm, Friday, November 4
 - In class
 - No notes, no calculators
 - Coverage: up to, and including Sorting
 - Review session, Tuesday, Nov 1, CSE2 G01
- Lecture on Wed, Nov 2 will end at 1:10 pm

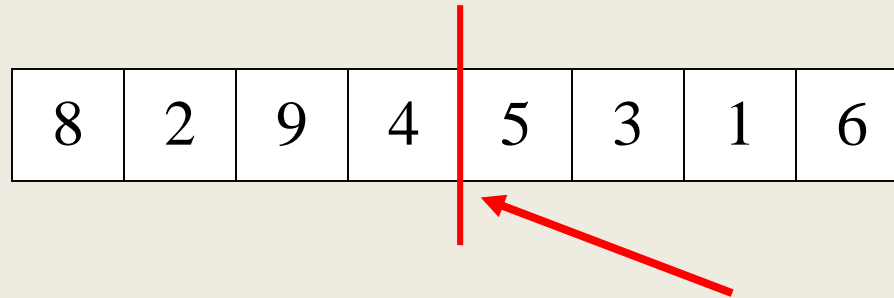
Sorting: *The Big Picture*



“Divide and Conquer”

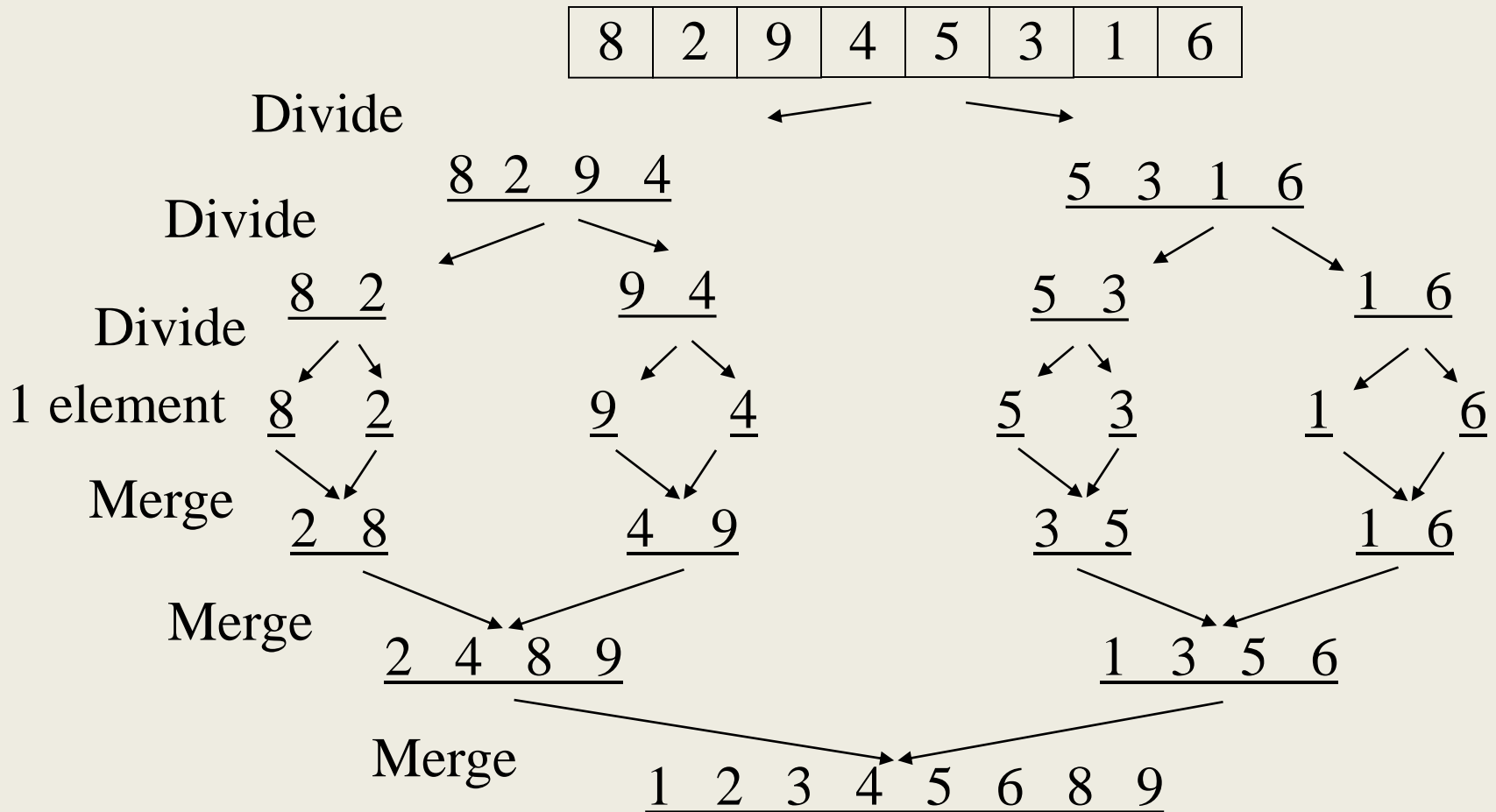
- Very important strategy in computer science:
 - Divide problem into smaller parts
 - Independently solve the parts
 - Combine these solutions to get overall solution
- **Idea 1:** Divide array in half, *recursively* sort left and right halves, then *merge* two halves
→ known as **Mergesort**
- **Idea 2 :** Partition array into small items and large items, then recursively sort the two sets
→ known as **Quicksort**

Mergesort



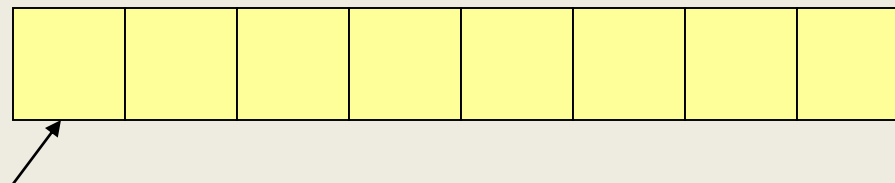
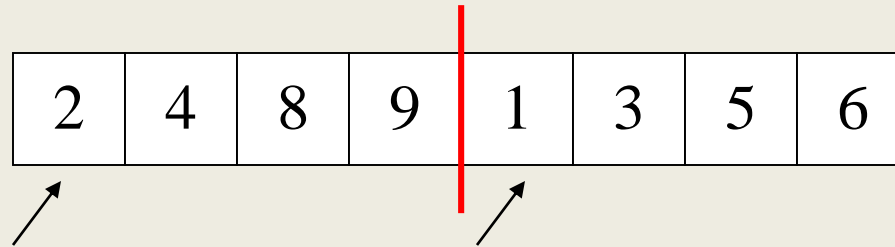
- Divide it in two at the midpoint
- Sort each half (recursively)
- Merge two halves together

Mergesort Example



Merging: Two Pointer Method

Merge using an auxiliary array



Auxiliary array

Merging

```
Merge(A[], Temp[], left, mid, right) {
    int i, j, k, l, target
    i = left
    j = mid + 1
    target = left
    while (i  $\leq$  mid && j  $\leq$  right) {
        if (A[i]  $\leq$  A[j])
            Temp[target] = A[i++]
        else
            Temp[target] = A[j++]
        target++
    }
    if (i > mid) //left completed
        for (k = left to target-1)
            A[k] = Temp[k];
    if (j > right) //right completed
        k = mid
        l = right
        while (k  $\geq$  i)
            A[l--] = A[k--]
        for (k = left to target-1)
            A[k] = Temp[k]
}
```

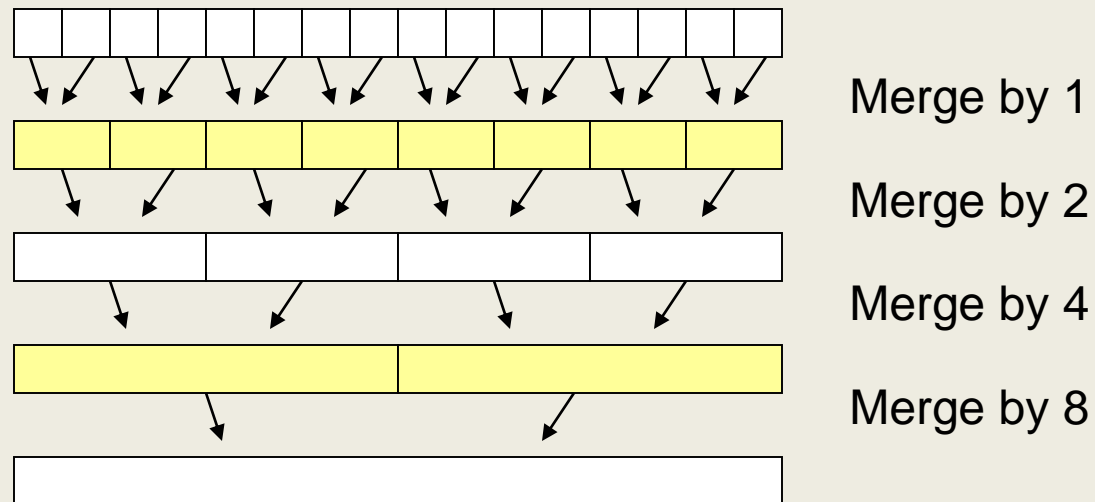

Recursive Mergesort

```
MainMergesort(A[1..n], n) {  
    Array Temp[1..n]  
    Mergesort[A, Temp, 1, n]  
}  
  
Mergesort(A[], Temp[], left, right) {  
    if (left < right) {  
        mid = (left + right)/2  
        Mergesort(A, Temp, left, mid)  
        Mergesort(A, Temp, mid+1, right)  
        Merge(A, Temp, left, mid, right)  
    }  
}
```

What is the recurrence relation?

Mergesort: Complexity

Iterative Mergesort



Properties of Mergesort

- In-place?
- Sorted list complexity?
- Nicely extends to handle linked lists.
- Multi-way merge is basis of big data sorting.
- Java uses Mergesort on Collections and on Arrays of Objects.

Recurrences

General form:

$$T(N) = S(N) + \sum_i a_i T(f_i(N)); \quad T(1) = c;$$

Important recurrences

$$T(N) = T(N-1) + f(N)$$

$$T(N) = T(aN) + cN, \quad a < 1$$

$$T(N) = aT(N/b) + Nc$$

$$T(N) = T(N-1) + N^2; \quad T(1) = 0$$

$$T(N) = T(N/2) + N; \quad T(1) = 1$$

$$T(N) = 4 T(N/4) + N; \quad T(1) = 1$$

Quicksort

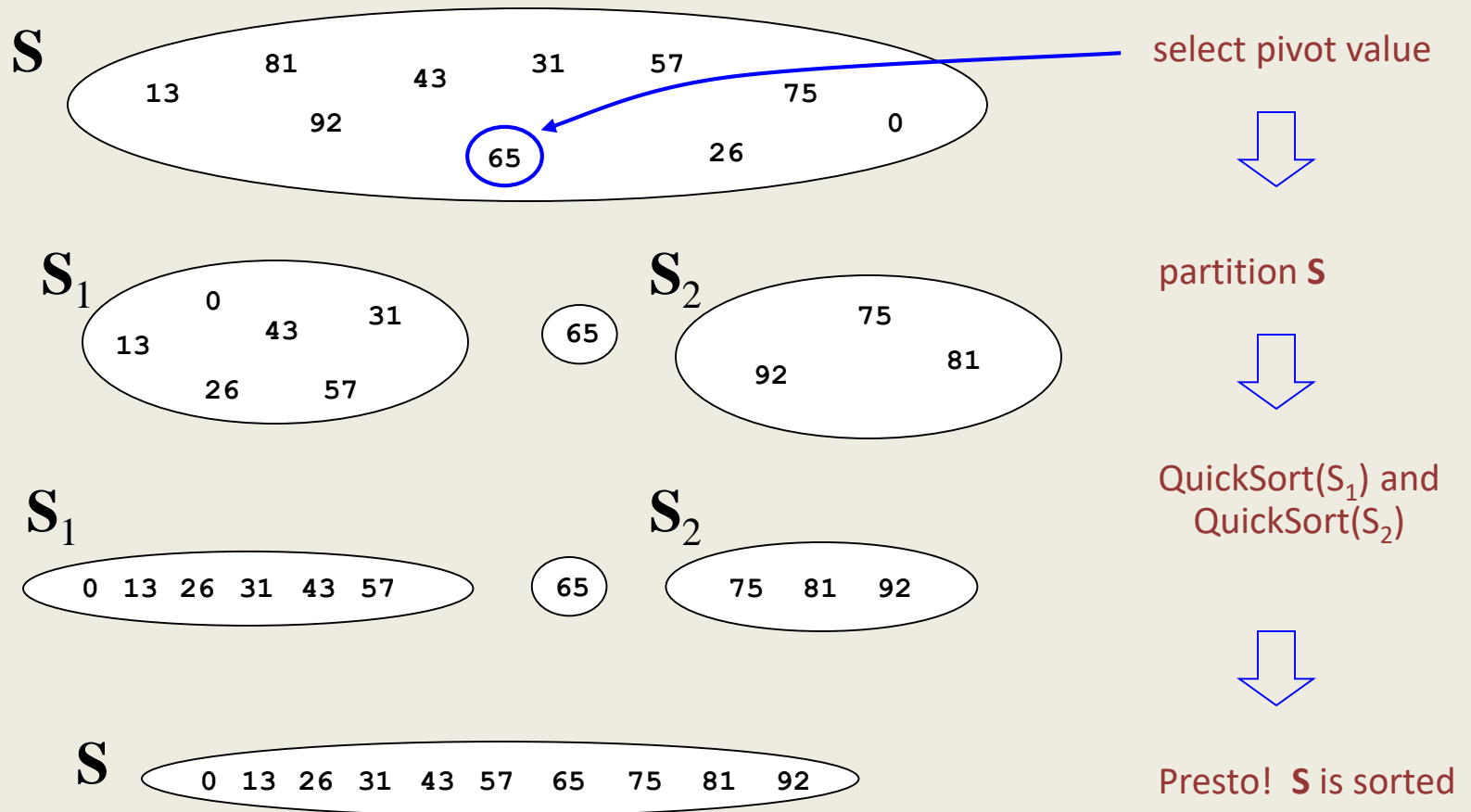
Quicksort uses a divide and conquer strategy, but does not require the $O(N)$ extra space that MergeSort does.

Here's the idea for sorting array \mathbf{S} :

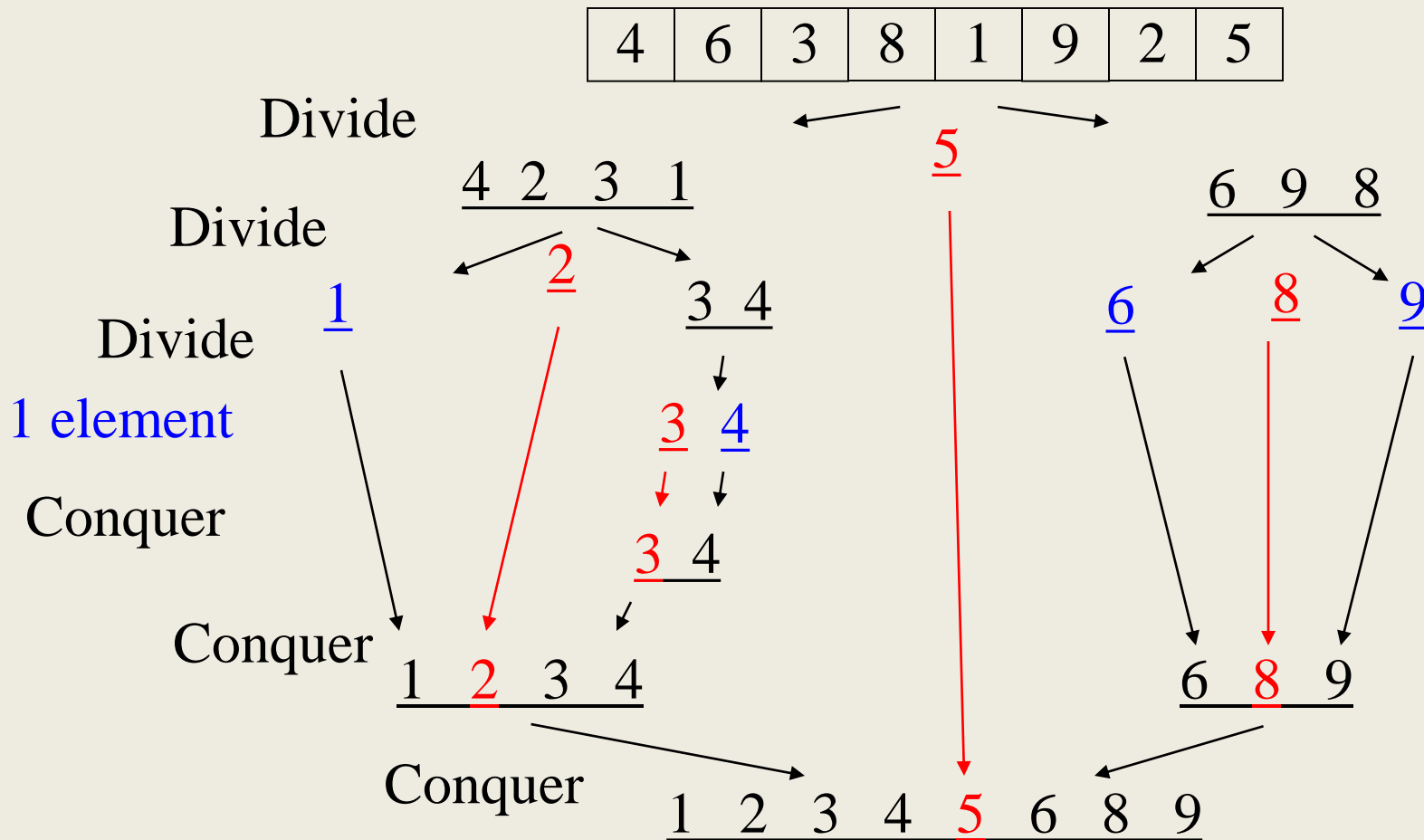
1. Pick an element v in \mathbf{S} . This is the *pivot* value.
2. Partition $\mathbf{S}-\{v\}$ into two disjoint subsets, \mathbf{S}_1 and \mathbf{S}_2 such that:
 - elements in \mathbf{S}_1 are all $\leq v$
 - elements in \mathbf{S}_2 are all $\geq v$
3. Return concatenation of $\text{QuickSort}(\mathbf{S}_1)$, v , $\text{QuickSort}(\mathbf{S}_2)$

Recursion ends if $\text{QuickSort}()$ receives an array of length 0 or 1.

The steps of Quicksort



Quicksort Example



Pivot Picking and Partitioning

The tricky parts are:

- **Picking the pivot**
 - Goal: pick a pivot value so that $|S_1|$ and $|S_2|$ are roughly equal in size.
- **Partitioning**
 - Preferably in-place
 - Dealing with duplicates

Picking the pivot

- Choose the first element in the subarray
- Choose a value that might be close to the middle
 - Median of three
- Choose a random element

Quicksort Partitioning

- Partition the array into left and right sub-arrays such that:
 - elements in left sub-array are \leq pivot
 - elements in right sub-array are \geq pivot
- Can be done in-place with another “two pointer method”
 - Sounds like mergesort, but here we are *partitioning*, not sorting...
 - ...and we can do it in-place.
- Lots of work has been invested in engineering quicksort

Quicksort Pseudocode

Putting the pieces together:

```
Quicksort(A[], left, right) {
  if (left < right) {
    medianOf3Pivot(A, left, right);
    pivotIndex = Partition(A, left+1, right-1);

    Quicksort(A, left, pivotIndex - 1);
    Quicksort(A, pivotIndex + 1, right);
  }
}
```

Important Tweak

Insertion sort is actually better than quicksort on small arrays. Thus, a better version of quicksort:

```
Quicksort(A[], left, right) {  
    if (right - left  $\geq$  CUTOFF) {  
        medianOf3Pivot(A, left, right);  
        pivotIndex = Partition(A, left+1, right-1);  
  
        Quicksort(A, left, pivotIndex - 1);  
        Quicksort(A, pivotIndex + 1, right);  
  
    } else {  
        InsertionSort(A, left, right);  
    }  
}
```

CUTOFF = 16 is reasonable.

Quicksort run time

- What is the best case behavior?

Worst case run time

- What is the bad case for partitioning?
- Design a bad case input (assume first element is chosen as pivot)

Average case performance

- Assume all permutations of the data are equally likely
 - Or equivalently, a random pivot is chosen
- The math gets messy, but doable

Properties of Quicksort

- $O(N^2)$ worst case performance, but $O(N \log N)$ average case performance.
- Pure quicksort not good for small arrays.
- No iterative version (without using a stack).
- “In-place,” but uses auxiliary storage because of recursive calls.
- Used by Java for sorting arrays of primitive types.