CSE 332: Data Structures and Parallelism

Fall 2022 Richard Anderson Lecture 5: Priority Queues, Part II

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Announcements

- Reading: Weiss, for Wednesday and Friday
 - Priority Queues, 6.1-6.5
- P1 Due on Thursday, Oct 13.
- Exercise 2, due next Monday
- Longer term beyond event horizon
 - Midterm, Friday, Nov 4
 - P2 due, Thursday, Nov 10

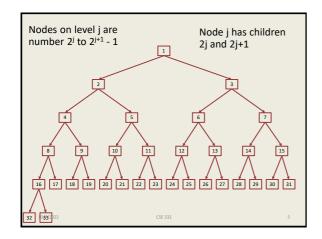
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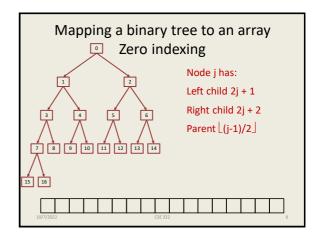
Priority Queues (or Heaps)

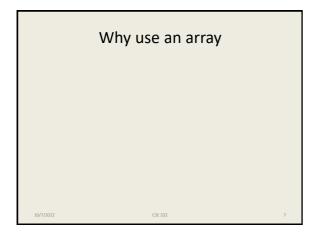
- Manage a set Insert and Delete Min
- Represent the data set as a binary tree
 - Property 1: Completeness
 - Tree is height log n with all leaves as far to the left as possible (for n elements in Heap)
 - Property 2: Heap Condition
 - For every non-root node X, the value of the parent of X is less than or equal to the value of X (in other words, children are bigger than their parents)

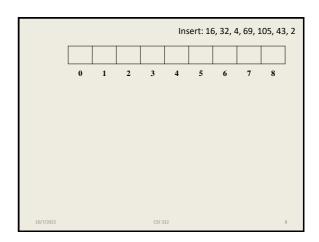
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Heap operations, O(log n) time 10 15 88 85 99







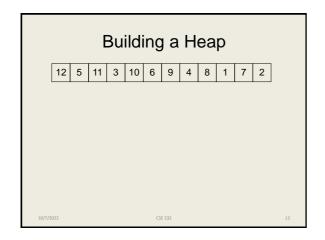


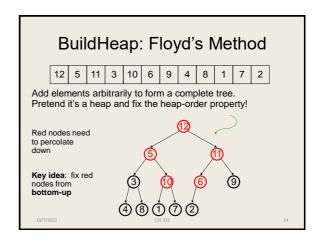
void insert(int v) { assert(!isFull()); size++; newPos = percolateUp(size,v); Heap[newPos] = v; } int percolateUp(int hole, int val) { while (hole > 0 && val < Heap[(hole-1)/2]) Heap[hole] = Heap[(hole-1)/2]; hole = (hole-1)/2; return hole; } int percolateUp(int hole, int val) { val < Heap[(hole-1)/2]; hole = (hole-1)/2; return hole; }</pre>

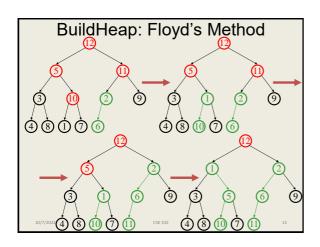
```
DeleteMin Code
                                int deleteMin() {
  assert(!isEmpty());
                                while (2*hole <= size) {
  returnVal = Heap[0];
                                    left = 2*hole + 1;
right = left + 1;
if (right ≤ size &&
                                      Heap[right] < Heap[left])
target = right;</pre>
  newPos =
    percolateDown(0,
                                    else
target = left;
        Heap[size + 1]);
  Heap[newPos] =
                                    if (Heap[target] < val) {
  Heap[hole] = Heap[target];
  hole = target;</pre>
    Heap[size + 1];
  return returnVal;
                                      break;
                                  return hole;
```

More Priority Queue Operations decreaseKey(nodePtr, amount): given a pointer to a node in the queue, reduce its key value Binary heap: change priority of node and ______ increaseKey(nodePtr, amount): given a pointer to a node in the queue, increase its key value Binary heap: change priority of node and ______

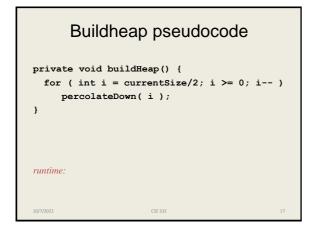
Still More Priority Queue Operations		
remove(objPtr): given a pointer to an object in the queue, remove it		
Binary heap: _		
findMax(): Find the object with the highest value in the queue		
Binary heap:		
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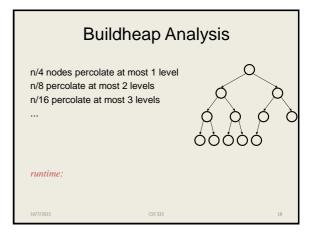












The Math:

$$\sum_{i>1} \frac{i}{2^i} = 2$$

$$\frac{n}{4} + \frac{2n}{8} + \frac{3n}{16} + \frac{4n}{32} + \dots = \frac{n}{2} \left[\frac{1}{2} + \frac{2}{4} + \frac{3}{8} + \frac{4}{16} + \dots \right] = \frac{n}{2} \sum_{i \ge 1} \frac{i}{2^i}$$

$$\begin{split} S &= \sum_{i \geq 1} \frac{i}{2^i} &= \sum_{i \geq 1} \frac{1}{2^i} + \sum_{i \geq 1} \frac{i-1}{2^i} = 1 + \sum_{i \geq 1} \frac{i-1}{2^i} = 1 + \frac{1}{2} \sum_{i \geq 1} \frac{i-1}{2^{i-1}} \\ &= 1 + \frac{1}{2} \sum_{i \geq 0} \frac{i}{2^i} = 1 + \sum_{i \geq 1} \frac{i}{2^i} = 1 + \frac{S}{2} \end{split}$$

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Heap Sort

```
HeapSort(int[] A) {
    BuildHeap(A);
    for (int i = A.Length - 1; i >= 0; i--) {
        A[i] = DeleteMin(A);
    }
}
```

This version sorts in decreasing order – for increasing order, either reverse the result, or use a MaxHeap.

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Why Heapsort is great

- · Relatively easy to code
- O(n log n) worst case runtime
- In place
- Elegant use of space to store results as heap shrinks

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