

CSE 332: Data Structures and Parallelism

Fall 2022

Richard Anderson

Lecture 5: Priority Queues, Part II

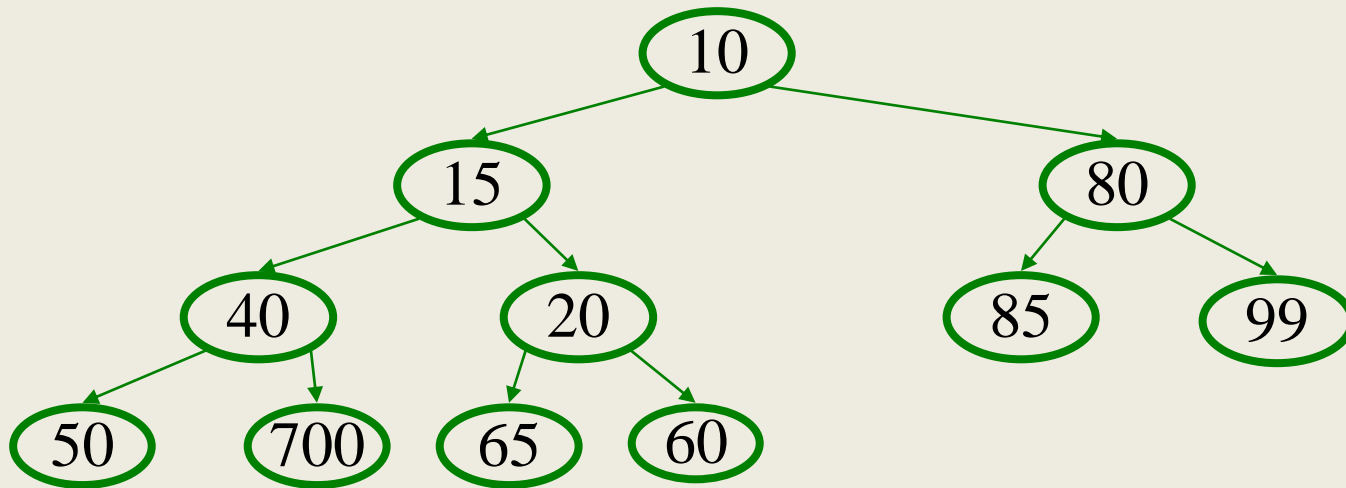
Announcements

- Reading: Weiss, for Wednesday and Friday
 - Priority Queues, 6.1-6.5
- P1 Due on Thursday, Oct 13.
- Exercise 2, due next Monday
- Longer term – beyond event horizon
 - Midterm, Friday, Nov 4
 - P2 due, Thursday, Nov 10

Priority Queues (or Heaps)

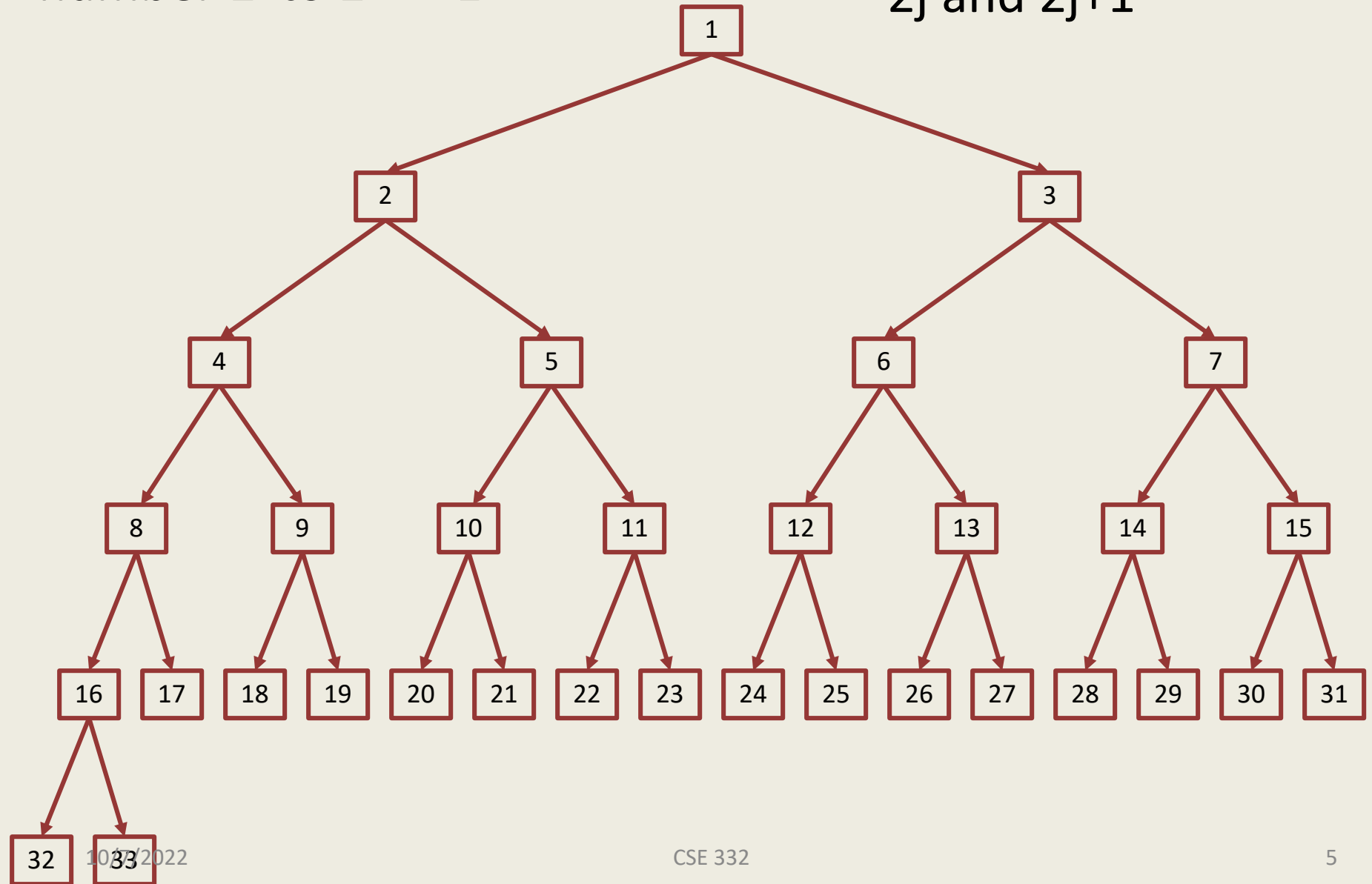
- Manage a set Insert and Delete Min
- Represent the data set as a binary tree
 - Property 1: Completeness
 - Tree is height $\lfloor \log n \rfloor$ with all leaves as far to the left as possible (for n elements in Heap)
 - Property 2: Heap Condition
 - For every non-root node X , the value of the parent of X is less than or equal to the value of X (in other words, children are bigger than their parents)

Heap operations, $O(\log n)$ time



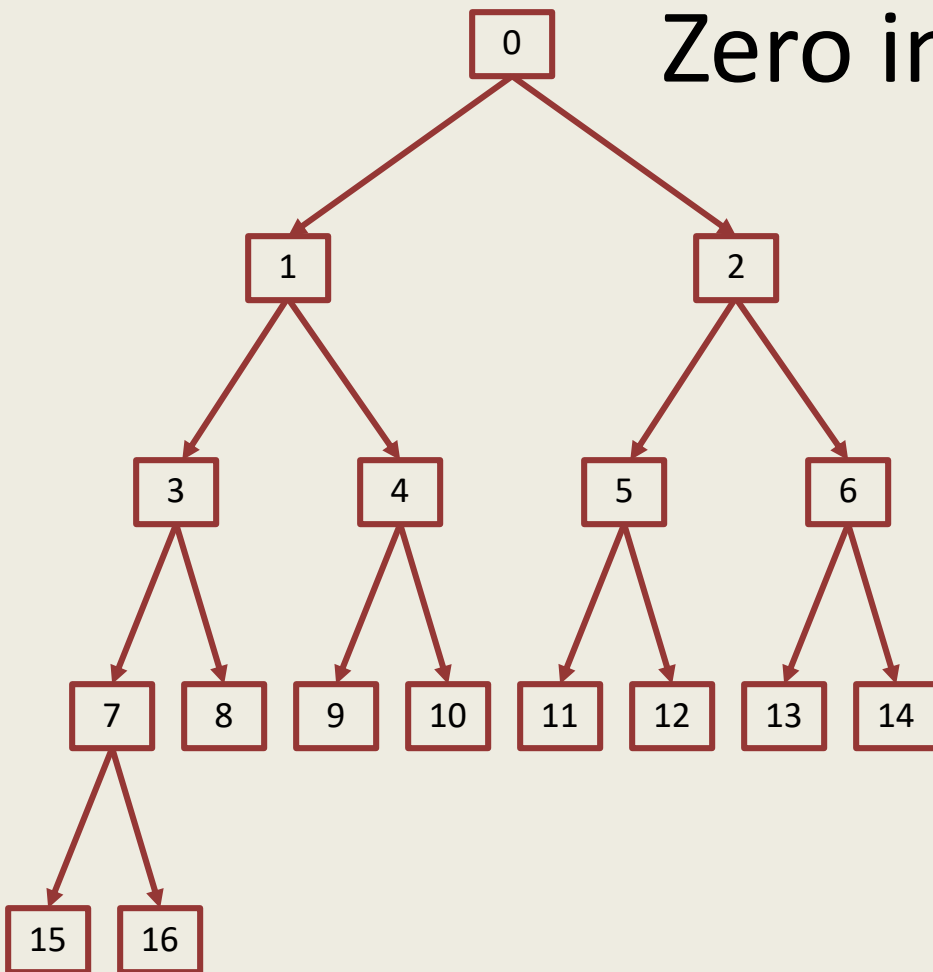
Nodes on level j are
number 2^j to $2^{j+1} - 1$

Node j has children
 $2j$ and $2j+1$



Mapping a binary tree to an array

Zero indexing



Node j has:

Left child $2j + 1$

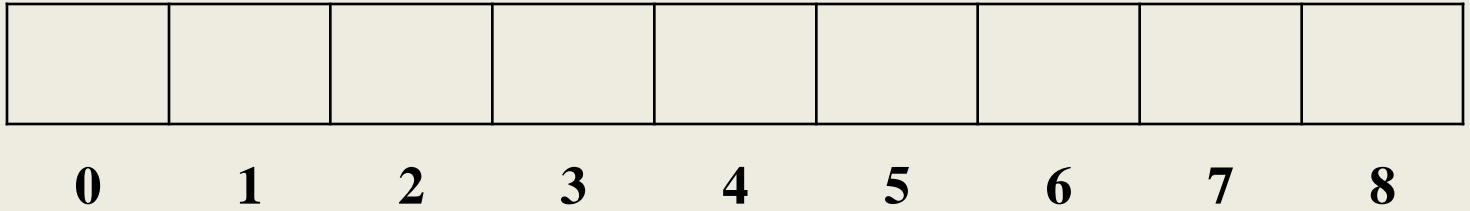
Right child $2j + 2$

Parent $\lfloor (j-1)/2 \rfloor$



Why use an array

Insert: 16, 32, 4, 69, 105, 43, 2



Insert Code

```
void insert(int v) {
    assert(!isFull());
    size++;
    newPos =
        percolateUp(size, v);
    Heap[newPos] = v;
}

int percolateUp(int hole,
                int val) {
    while (hole > 0 &&
           val < Heap[(hole-1)/2])
        Heap[hole] = Heap[(hole-1)/2];
        hole = (hole-1)/2;
    }
    return hole;
}
```

DeleteMin Code

```
int deleteMin() {
    assert(!isEmpty());
    returnVal = Heap[0];
    size--;
    newPos =
        percolateDown(0,
            Heap[size + 1]);
    Heap[newPos] =
        Heap[size + 1];
    return returnVal;
}
```

```
int percolateDown(int hole,
                  int val) {
    while (2*hole <= size) {
        left = 2*hole + 1;
        right = left + 1;
        if (right <= size &&
            Heap[right] < Heap[left])
            target = right;
        else
            target = left;

        if (Heap[target] < val) {
            Heap[hole] = Heap[target];
            hole = target;
        }
        else
            break;
    }
    return hole;
}
```

More Priority Queue Operations

`decreaseKey(nodePtr, amount):`

given a pointer to a node in the queue, reduce its key value

Binary heap: change priority of node and _____

`increaseKey(nodePtr, amount):`

given a pointer to a node in the queue, increase its key value

Binary heap: change priority of node and _____

Still More Priority Queue Operations

`remove(objPtr):`

given a pointer to an object in the queue, remove it

Binary heap: _____

`findMax():`

Find the object with the highest value in the queue

Binary heap: _____

Building a Heap

12	5	11	3	10	6	9	4	8	1	7	2
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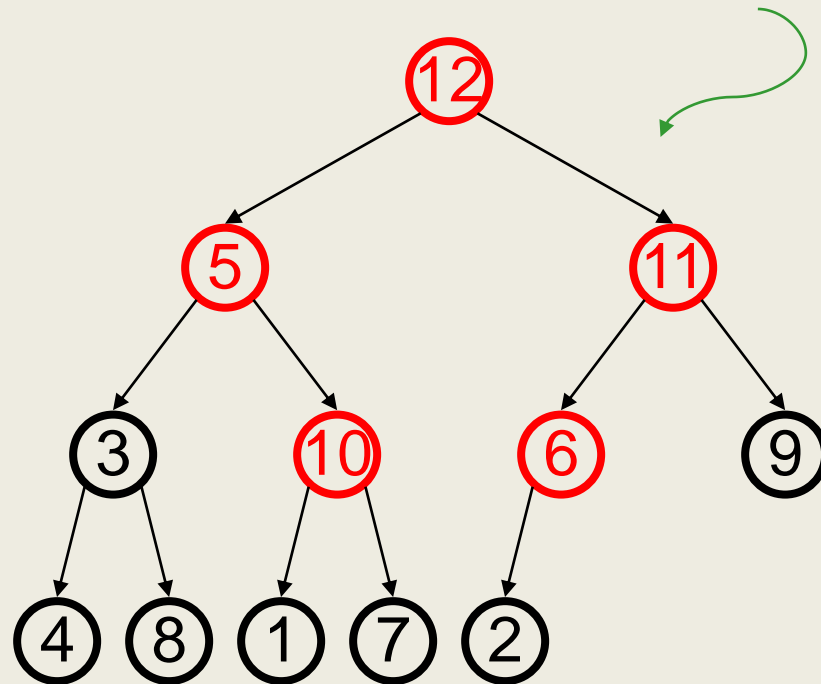
BuildHeap: Floyd's Method

12	5	11	3	10	6	9	4	8	1	7	2
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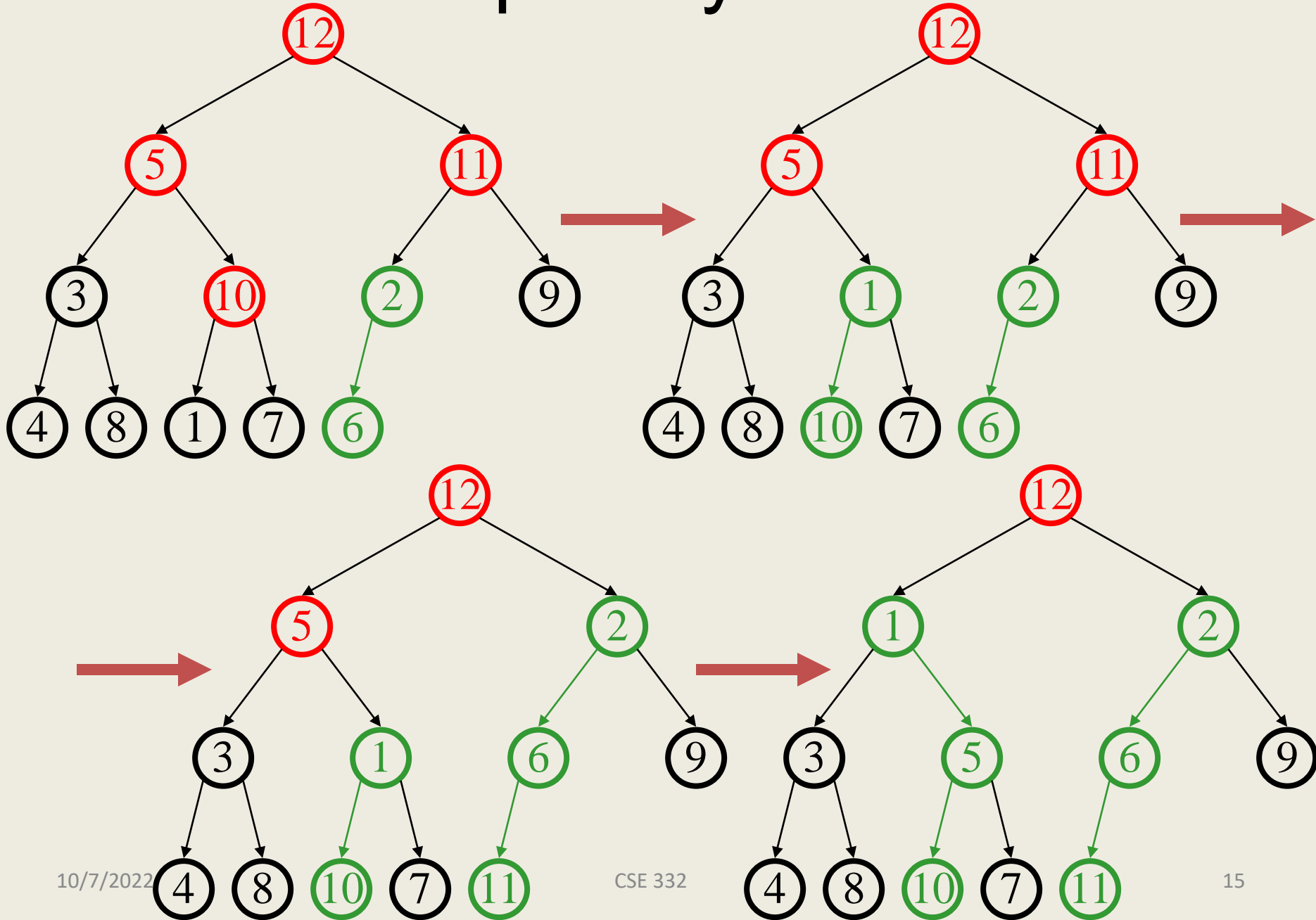
Add elements arbitrarily to form a complete tree.
Pretend it's a heap and fix the heap-order property!

Red nodes need
to percolate
down

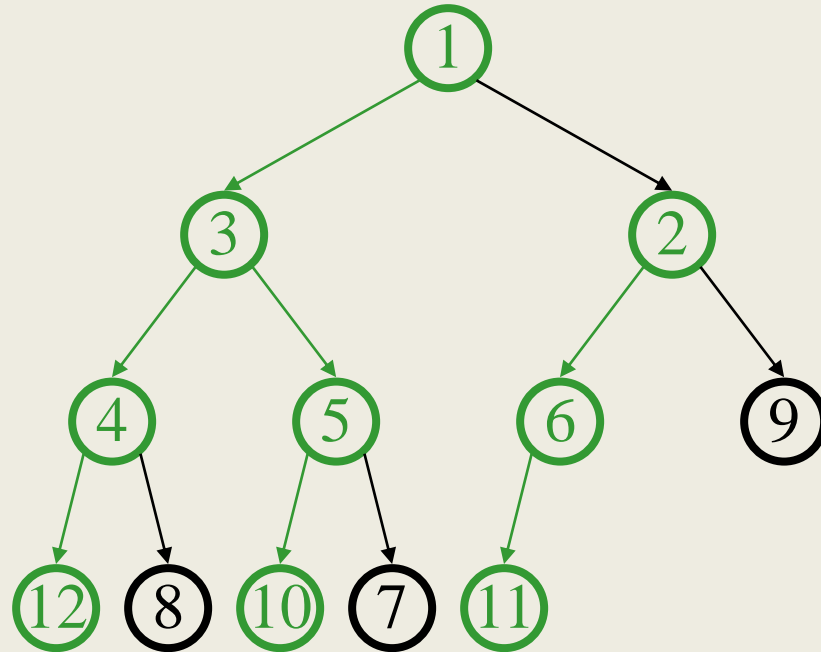
Key idea: fix red
nodes from
bottom-up



BuildHeap: Floyd's Method



Finally . . .



Buildheap pseudocode

```
private void buildHeap() {  
    for ( int i = currentSize/2; i >= 0; i-- )  
        percolateDown( i );  
}
```

runtime:

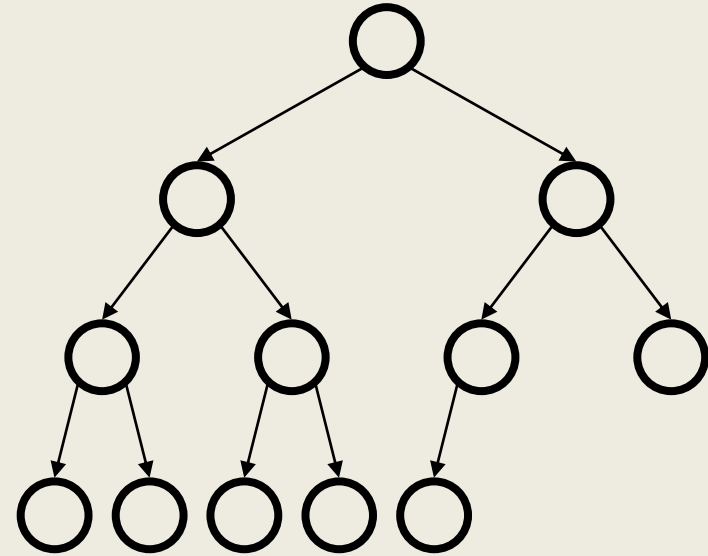
Buildheap Analysis

$n/4$ nodes percolate at most 1 level

$n/8$ percolate at most 2 levels

$n/16$ percolate at most 3 levels

...



runtime:

The Math:

$$\sum_{i \geq 1} \frac{i}{2^i} = 2$$

$$\frac{n}{4} + \frac{2n}{8} + \frac{3n}{16} + \frac{4n}{32} + \dots = \frac{n}{2} \left[\frac{1}{2} + \frac{2}{4} + \frac{3}{8} + \frac{4}{16} + \dots \right] = \frac{n}{2} \sum_{i \geq 1} \frac{i}{2^i}$$

$$\begin{aligned} S &= \sum_{i \geq 1} \frac{i}{2^i} = \sum_{i \geq 1} \frac{1}{2^i} + \sum_{i \geq 1} \frac{i-1}{2^i} = 1 + \sum_{i \geq 1} \frac{i-1}{2^i} = 1 + \frac{1}{2} \sum_{i \geq 1} \frac{i-1}{2^{i-1}} \\ &= 1 + \frac{1}{2} \sum_{i \geq 0} \frac{i}{2^i} = 1 + \sum_{i \geq 1} \frac{i}{2^i} = 1 + \frac{S}{2} \end{aligned}$$

Heap Sort

```
HeapSort(int[] A) {  
    BuildHeap(A);  
    for (int i = A.Length - 1; i >= 0; i--) {  
        A[i] = DeleteMin(A);  
    }  
}
```

This version sorts in decreasing order – for increasing order, either reverse the result, or use a MaxHeap.

Why Heapsort is great

- Relatively easy to code
- $O(n \log n)$ worst case runtime
- In place
- Elegant use of space to store results as heap shrinks