

buildHeap;

Algorithm Analysis II: Amortization

CSE 332 Spring 2020

Instructor: Hannah C. Tang

Teaching Assistants:

Annie Mao

Howard Xiao

Lucy Jiang

Chris Choi

Jade Watkins





Nathan Lipiarski

Ethan Knutson

Khushi Chaudhari

Richard Jiang

Announcements

- ❖ Tell us how Quiz #1 went!
 - **rn:**   pollev.com/cse332  
 - Later/more details: cse332-staff@cs or anonymous feedback
- ❖ Exercises 2-4 due on Monday @ midnight
- ❖ Project 1 due on Tuesday @ midnight
 - If you're struggling with your partnership, please reach out!
 - If you're struggling with the project, schedule 1:1 time!
 - Don't forget to check your pipelines for failures (we do!)

Learning Objectives

- ❖ Implement Floyd's algorithm for building heaps and reason about its runtime
- ❖ Be able to formally prove a big-O runtime bound
- ❖ Intuit, but not necessarily prove, amortized analysis
- ❖ Explain the different axes of case complexity, and how it relates to complexity bounds

Lecture Outline

- ❖ Heaps, cont.
 - **$O(1)$ average case insert**
 - Floyd's `buildHeap` Algorithm
 - Farewell to Heaps ...
- ❖ Algorithm Analysis II
 - Proof example
 - Amortized bounds
 - Where We've Come / Where We're Going

$O(1)$ average-case `add()`?! (1 of 2)

- ❖ Yes, `add`'s worst case is $O(\log n)$
 - It all depends on the order the items are inserted
 - What is the worst case order?
- ❖ Empirical studies of randomly ordered inputs shows:
 - Average 2.607 comparisons per insert (# of percolation passes)
 - An element usually moves up 1.607 levels
- ❖ If we define “average” as a *single operation with random input, occurring after a sequence of similarly randomized operations*:
 - `add`'s *average case* is $O(1)$
 - `deleteMin`'s average case is still $O(\log n)$
 - Moving a leaf to the root usually requires re-percolating that priority back to the bottom

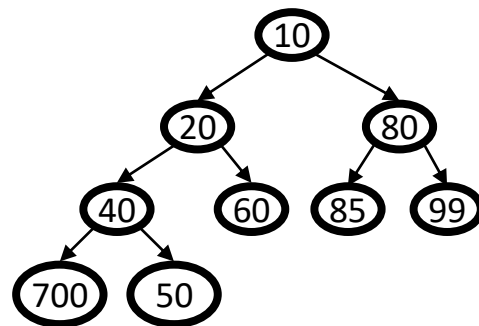
$O(1)$ average-case $\text{add}()$?! (2 of 2)

❖ In a complete binary tree, each row has 2x nodes of its parent row

- Bottom level has $\sim 1/2$ of all nodes
- Second to bottom has $\sim 1/4$ of all nodes
- ...

❖ Intuition:

- When inserting a *random* priority, likely not to have highest nor lowest value; somewhere in middle
- Given a random distribution of priorities in the heap:
 - Bottom level should have the upper $\frac{1}{2}$ of priorities
 - Second to bottom, next $\frac{1}{4}$
 - ...
- Expect to only percolate up 1-2 levels



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One Final Operation: buildHeap

- ❖ `buildHeap()` takes an array of size N and applies the heap-ordering principle to it
- ❖ Naïve implementation:
 - Start with an empty array (representing an empty binary heap)
 - Call `add()` N times
 - Runtime: ??
- ❖ Can we do better?
 - If we only have `add` and `deleteMin` operations, **NO**
 - There is a faster way -- $O(n)$ -- but requires the ADT to have a specialized `buildHeap` operation
 - **Is it convenient? Efficient? Simple?**

Floyd's buildHeap Method

- ❖ Recall our general strategy for working with the heap:
 - Preserve structure property
 - (Break and) Restore heap ordering property
- ❖ Floyd's buildHeap:
 - Create a complete tree by putting the n items in an array
 - *Structure property!*
 - Treat the array as a binary heap and fix the heap-order property
 - *Order property!*
 - Exactly how we do this is where we gain efficiency

Reminder: a priority queue contains *priorities* and *values*; an *item* or *data* refers to the (priority, value) pair

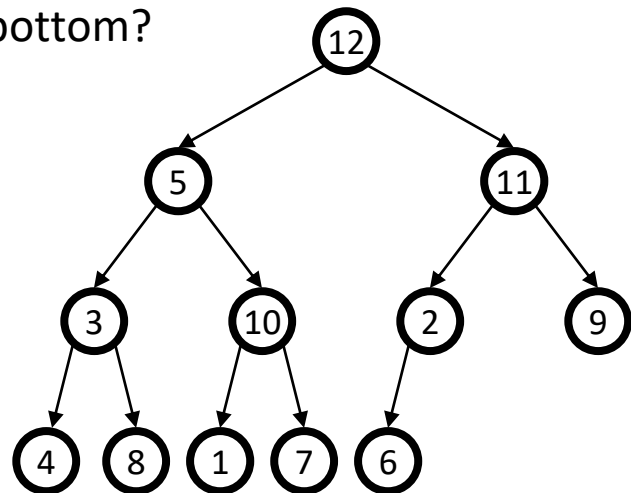
Thinking about buildHeap

❖ Say we start with this array: [12,5,11,3,10,2,9,4,8,1,7,6]

❖ Where should we start? Top vs bottom?

❖ To “fix” the ordering can we use:

- percolateUp?
- percolateDown?



Floyd's buildHeap Method

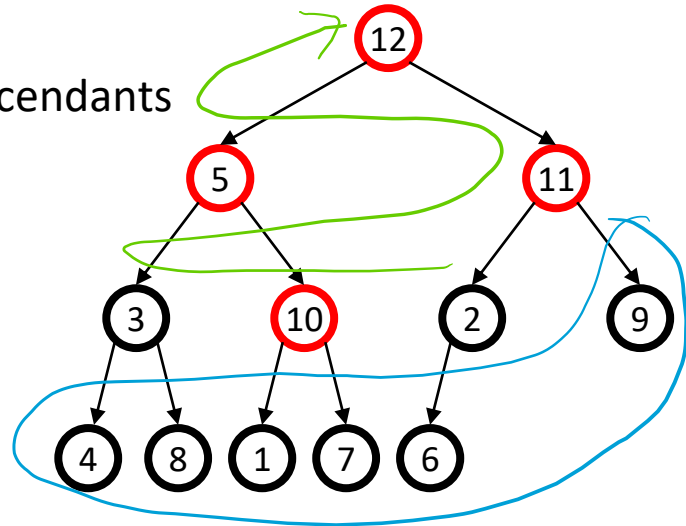
❖ Bottom-up:

- Leaves are already in heap order
- Work up toward the root one level at a time

```
void buildHeap(arr) {  
    n = arr.length  
    for (i = n/2; i>0; i--) {  
        val = arr[i];  
        hole = percolateDown(i, val);  
        arr[hole] = val;  
    }  
}
```

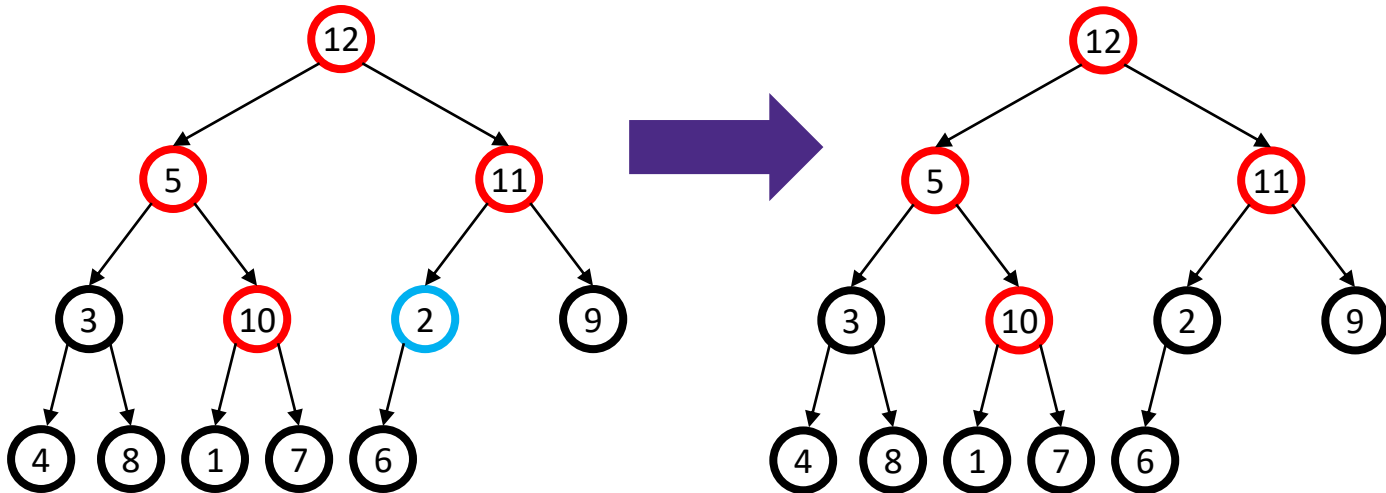
buildHeap Example

- ❖ Say we start with this array: [12,5,11,3,10,2,9,4,8,1,7,6]
 - In tree form for readability
- ❖ **Red** for node not less than descendants
 - Ie, heap-order problem
 - Notice no leaves are **red**!



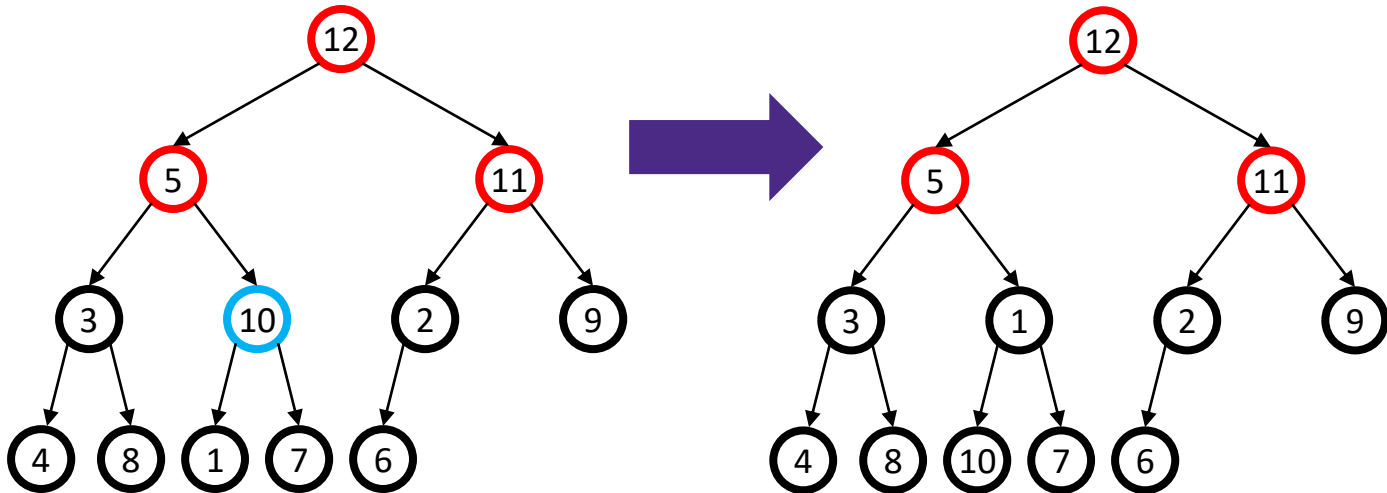
buildHeap Example: Step 1

- ❖ Happens to already be less than child



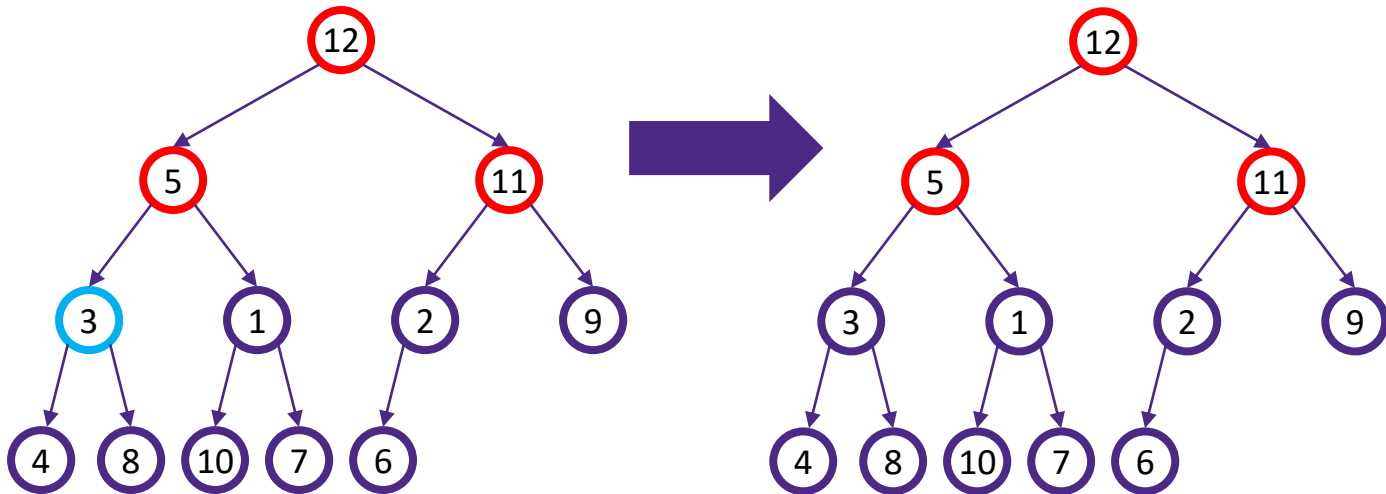
buildHeap Example: Step 2

- ❖ Percolate down (notice that moves 1 up)



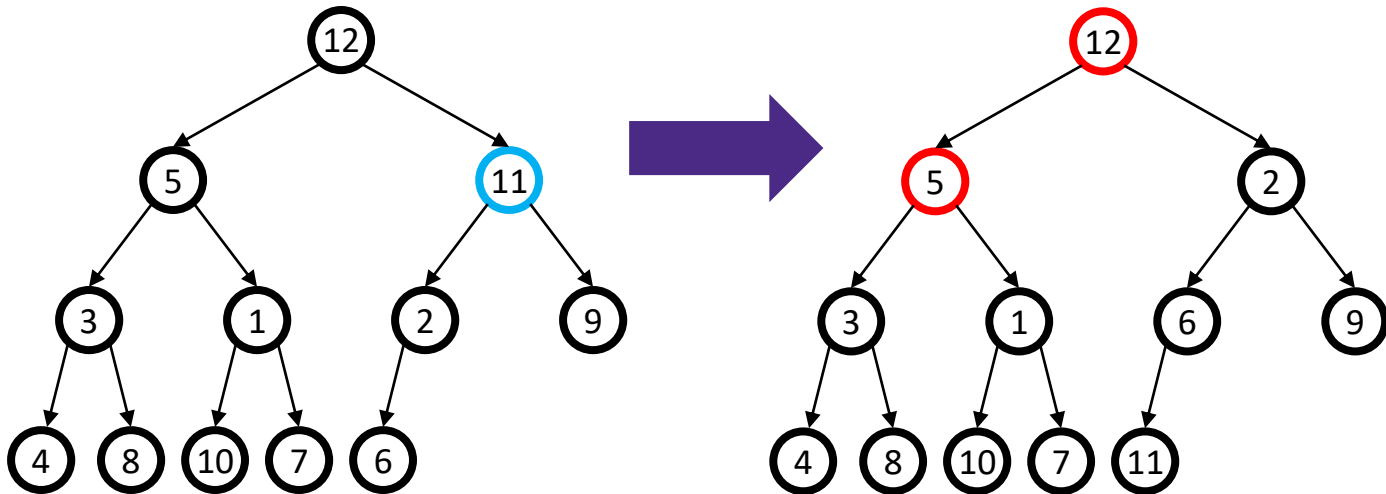
buildHeap Example: Step 3

- ❖ Another nothing-to-do step



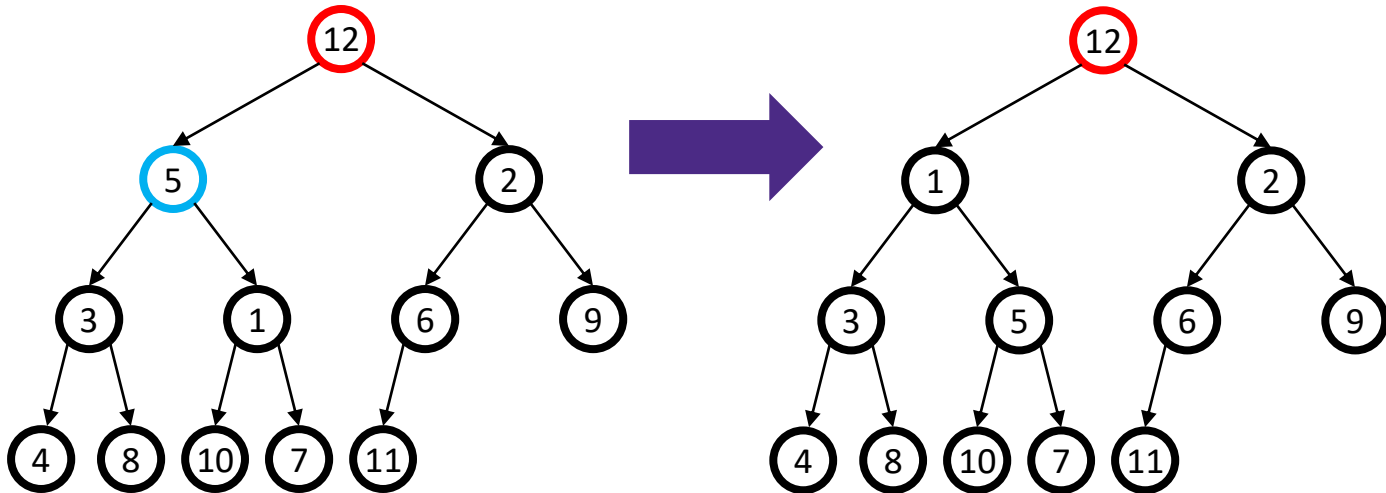
buildHeap Example: Step 4

- ❖ Percolate down as necessary



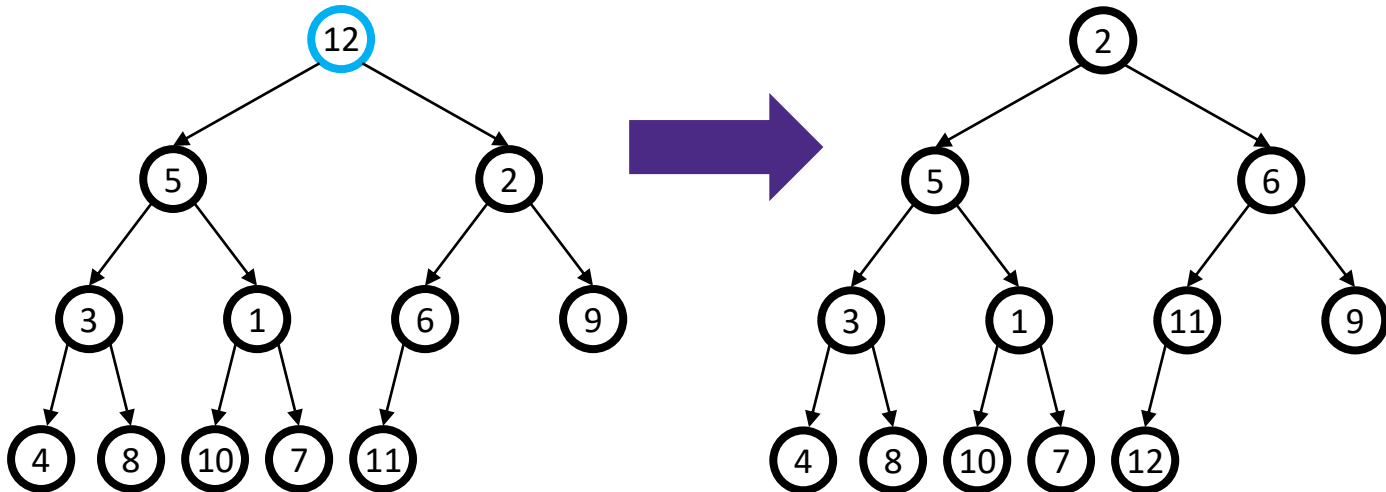
buildHeap Example: Step 5

- ❖ Again, percolate down as necessary



buildHeap Example: Step 6

- ❖ Lastly, percolate down as necessary



But is it right?

- ❖ “Seems to work”
 - Let’s *prove* it restores the heap property (correctness)
 - Then let’s *prove* its running time (efficiency)

```
void buildHeap(arr) {  
    n = arr.length  
    for(i = n/2; i>0; i--) {  
        val = arr[i];  
        hole = percolateDown(i, val);  
        arr[hole] = val;  
    }  
}
```

Floyd's buildHeap: Correctness

❖ **Loop Invariant:** For all $j > i$, `arr[j]` is less than its children

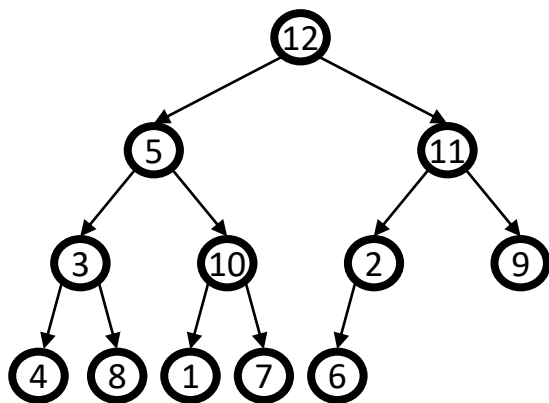
- True initially: If $j > \text{size}/2$, then j is a leaf
 - Otherwise its left child would be at position $> \text{size}$

- True after one iteration: loop body and `percolateDown` make `arr[i]` less than children without breaking the property for any descendants

❖ Therefore, after loop terminates, ***all nodes are less than their children***

```
void buildHeap(arr) {
    n = arr.length
    for(i = n/2; i>0; i--) {
        val = arr[i];
        hole = percolateDown(i, val);
        arr[hole] = val;
    }
}
```

Floyd's buildHeap: Correctness Example



```
void buildHeap(arr) {  
    n = arr.length  
    for(i = n/2; i>0; i--) {  
        val = arr[i];  
        hole = percolateDown(i, val);  
        arr[hole] = val;  
    }  
}
```

	12	5	11	3	10	2	9	4	8	1	7	6
0	1	2	3	4	5	6	7	8	9	10	11	12

Note: Exercises and P1 start counting from 0

Floyd's buildHeap: Efficiency (1 of 2)

- ❖ Easy argument: `buildHeap` is $O(n \log n)$ where n is array size
 - $n/2$ loop iterations
 - Each iteration does one `percolateDown`, which are $O(\log n)$ each
 - So Floyd's `buildHeap` is $n/2 * \log n = O(n \log n)$
- ❖ This is correct, but there is a more precise (“tighter”) analysis

```
void buildHeap() {  
    for(i = size/2; i>0; i--) {  
        val = arr[i];  
        hole = percolateDown(i, val);  
        arr[hole] = val;  
    }  
}
```

Floyd's buildHeap: Efficiency (2 of 2)

❖ Better argument: buildHeap is $O(n)$ where n is array size

■ $n/2$ total loop iterations: $O(n)$

- 1/2 of the loop iterations percolate at most **1 step**
- 1/4 of the loop iterations percolate at most **2 steps**
- 1/8 of the loop iterations percolate at most **3 steps**
- ... etc ...

Actual runtime:

$$\frac{n}{2} \sum_{i=0}^{\lfloor \log n \rfloor} \frac{1}{2^i} i$$

■ But we know $(1 + (1/2) + (2/4) + (3/8) + \dots) = 2$

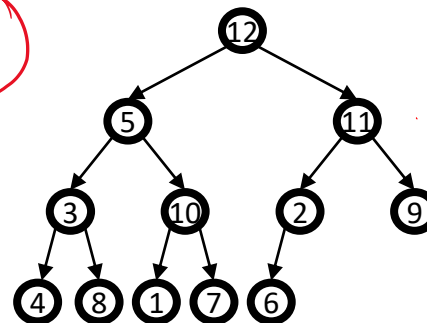
- See page 4 of Weiss
- Also see Weiss 6.3.4, sum of heights of nodes in a perfect tree

We know:

$$\sum_{i=0}^{\infty} \frac{1}{2^i} i$$

■ So Floyd's buildHeap is $n/2 * 2 = O(n)$

We know $\frac{n}{2} \left(\sum_{i=0}^{\lfloor \log n \rfloor} \frac{1}{2^i} i \right) < \frac{n}{2} \left(\sum_{i=0}^{\infty} \frac{1}{2^i} i \right) < \frac{n}{2} \cdot 2$
 \therefore Runtime is $O(n)$



Lessons from `buildHeap`

- ❖ Without `buildHeap`, our ADT let clients implement their own in $\Theta(n \log n)$ worst case
 - Worst case is inserting lower priorities later
- ❖ By providing a specialized operation (with access to the internal data structure), we can do $O(n)$ worst case
 - Intuition: Most items are near a leaf, so better to percolate down
- ❖ Can analyze this algorithm for:
 - Correctness: Non-trivial inductive proof using loop invariant
 - Efficiency:
 - First analysis easily proved it was $O(n \log n)$
 - A “tighter” analysis shows same algorithm is $O(n)$

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What we're skipping (see text if curious)

- ❖ *d-heaps*: have d children instead of 2 (Weiss 6.5)
 - Makes heaps shallower, useful for heaps too big for memory
 - How does this affect the asymptotic run-time (for small d 's)?
- ❖ *Leftist heaps, skew heaps, binomial queues* (Weiss 6.6-6.8)
 - Different data structures for priority queues that support a logarithmic time merge operation (impossible with binary heaps)
 - `merge`: given two priority queues, make one priority queue
 - `add` & `deleteMin` defined in terms of `merge` (!!)
- ❖ **Aside: How might you merge binary heaps:**
 - If one heap is much smaller than the other?
 - If both are about the same size?

Other Operations

- ❖ **decreasePriority**: given pointer to object in priority queue (e.g., its array index), lower its priority by p
 - Change priority and percolate up
- ❖ **increasePriority**: given pointer to object in priority queue (e.g., its array index), raise its priority by p
 - Change priority and percolate down
- ❖ **remove**: given pointer to object in priority queue (e.g., its array index), remove it from the queue
 - `decreaseKey` with $p = \infty$, then `deleteMin`
- ❖ Running time for all these operations?

Priority Queue Summary

- ❖ Without `buildHeap`, our ADT already let clients implement their own in $\theta(n \log n)$ worst case
 - Worst case is inserting lower priorities later
- ❖ By providing a specialized operation internally (with access to the data structure), we can do $O(n)$ worst case
 - Intuition: Most items are near a leaf, so better to percolate down
- ❖ Can analyze this algorithm for:
 - Correctness: Non-trivial inductive proof using loop invariant
 - Efficiency:
 - First analysis easily proved it was $O(n \log n)$
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👉👉👉 Heap-y Birthday, Kenny! 👉👉👉



Lots of 🍷 and 🗨️ for an awesome year ahead!



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The Proof is in the Practice

$$c > 0 \\ n_0 \geq 1 \text{ (natural)}$$

- ❖ Prove $g(n)$ is in $O(f(n))$ by picking a c large enough to “cover the constant factors” and n_0 large enough to “cover the lower-order terms”
 - Let $g(n) = 4n^2 + 3n + 4$, and $f(n) = n^3$

$$4n^2 \leq 4n^3$$

$$3n \leq 3n^3$$

$$4 \leq 4n^3$$

$$4n^2 + 3n + 4 \leq \underbrace{11}_c n^3$$

$$\text{Let } c = 11, \\ n_0 = 1$$

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Linear Search: Best vs Worst Case

Find an integer in a *sorted* array

2	3	5	16	37	50	73	75	126
---	---	---	----	----	----	----	----	-----

```
// requires array is sorted
// returns whether k is in array
boolean find(int[] arr, int k) {
    for (int i=0; i < arr.length; ++i)
        if(arr[i] == k)
            return true;
    return false;
}
```

Best case: **find(2)**

Worst case: **find(126)**

Complexity Cases

- ❖ We started with two cases:
 - **Worst-case complexity:** *maximum* number of steps algorithm takes on “most challenging” input of size N
 - **Best-case complexity:** *minimum* number of steps algorithm takes on “easiest” input of size N

- ❖ We punted on one case: **Average-case complexity**
 - Sometimes: relies on distribution of inputs
 - Eg, binary heap’s $O(1)$ insert
 - See CSE312 and STAT391
 - Sometimes: uses randomization in the algorithm
 - Will see an example with sorting; also see CSE312

- ❖ We’ve mentioned, but not defined, one *category* of cases:
 - **Amortized-case complexity**

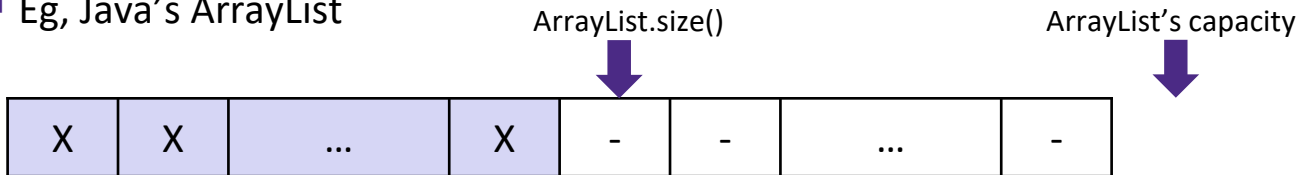
Amortized Analyses = Multiple Executions

Single Execution	Multiple Executions
Worst Case	Amortized Worst Case
Best Case	Amortized Best Case
<i>Average Case</i>	<i>Amortized Average Case</i>

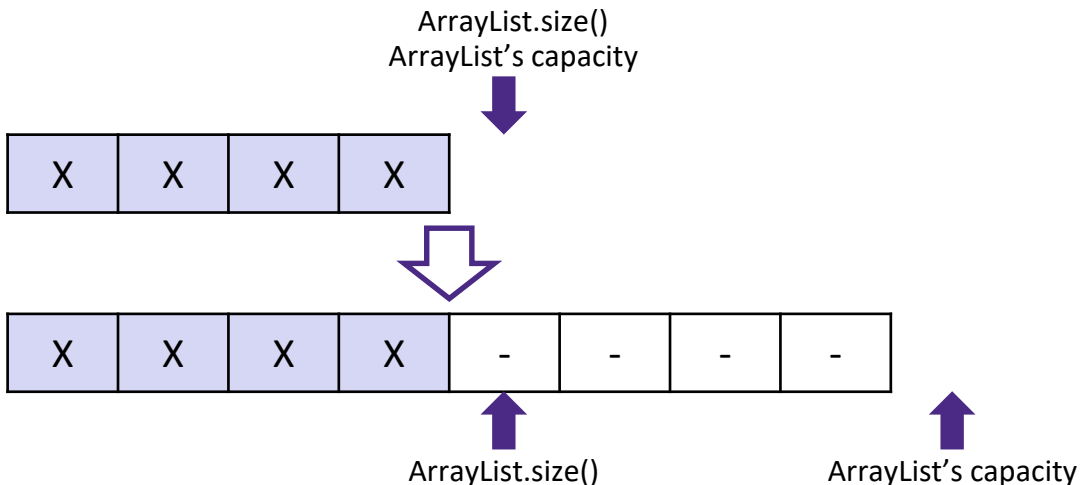
Amortized Analysis: `ArrayList.add()`

- ❖ Consider adding an element to an array-backed structure

- Eg, Java's `ArrayList`



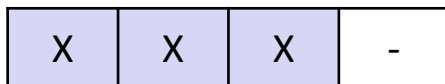
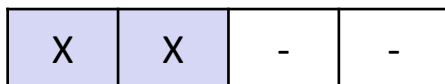
- ❖ When the underlying array fills, we allocate and copy contents



ArrayList.add() Runtime (1 of 2)

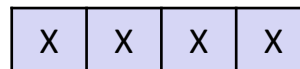
- ❖ We know that copying a single element and allocating arrays are both constant-time operations
 - Let's call their runtimes 'c' and 'd', respectively

Most of the time



Runtime: $c \in O(1)$

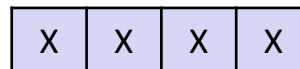
Worst case



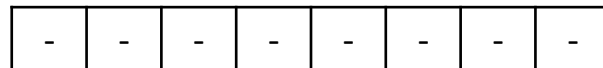
Runtime:

$$d + c(n-1) + c$$

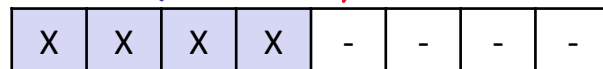
$$d + cn \in O(n)$$



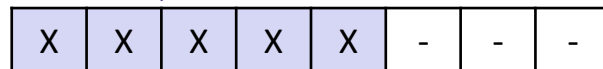
d



$c(n-1)$



e



ArrayList.add() Runtime (2 of 2)

Single Execution	Multiple Executions
Worst Case: $O(n)$	Amortized Worst Case:
Best Case: $O(1)$	Amortized Best Case:

- ❖ Some applications *cannot tolerate* the “occasional $O(n)$ behavior”
- ❖ Other applications *can tolerate* “occasional $O(n)$ behavior” if we can show that it’s “not too bad” / “not too common”

ArrayList.add(): Best-Case Aggregate Runtime



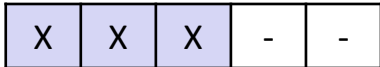
add(X)



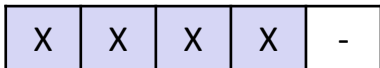
add(X)



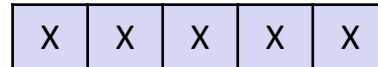
add(X)



add(X)



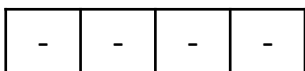
add(X)



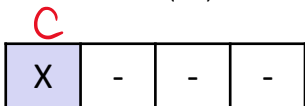
Best-case Aggregate Runtime:

*c*_n

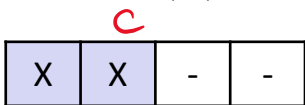
ArrayList.add(): Worst-Case Aggregate Runtime



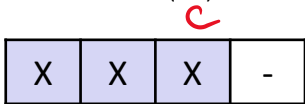
add(X)



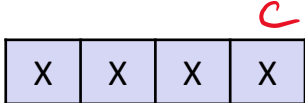
add(X)



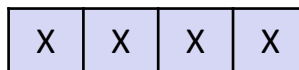
add(X)



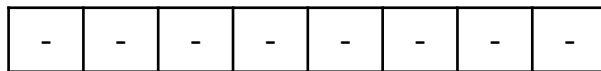
add(X)



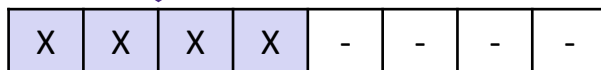
add(X)



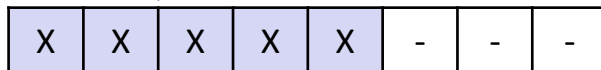
d



c(n-1)



c



Worst-case Aggregate Runtime:
 $c(n-1) + d + c(n-1) + c$
 $= 2cn + d - c$

Amortized Analysis Intuition

- ❖ See Weiss, ch 11, for formal methods
- ❖ But the intuition is: if our client is willing to tolerate it, we will “smooth” the *aggregate cost of n operations* over n itself

Single Execution	Multiple Executions
Worst Case: $O(n)$	Amortized Worst Case: $\frac{2cn+d-c}{n} \in O(1)$
Best Case: $O(1)$	Amortized Best Case: $\frac{cn}{n} \in O(1)$

- ❖ Note: we increased our array size by a factor of n (eg, $2n$, $3n$, etc). What if we increased it by a constant factor (eg, 1 , 100 , 1000) instead?