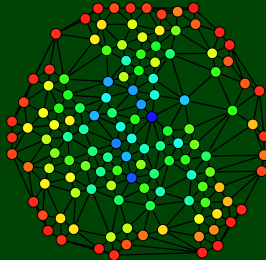


CSE 332

Data Structures and Parallelism

Graphs 4: Minimum Spanning Trees



```
1  dijkstra(G, source) {
2      dist = new Dictionary();
3      worklist = [];
4      for (v : V) {
5          if (v == source) { dist[v] = 0; }
6          else                { dist[v] = ∞; }
7          worklist.add((v, dist[v]));
8      }
9
10     while (worklist.hasWork()) {
11         v = next();
12         for (u : v.neighbors()) {
13             dist[u] = min(dist[u], dist[v] + w(v, u));
14             worklist.decreaseKey(u, dist[u]);
15         }
16     }
17
18     return dist;
19 }
```

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```

Weight of edge
from v to u.

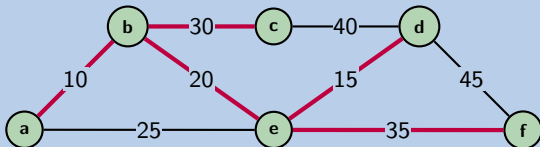
What Does ~~Dijkstra's Algorithm~~ Do Now?

Definition (Minimum Spanning Tree)

Given a graph $G = (V, E)$, find a **subgraph** $G' = (V', E')$ such that

- G' is a **tree**.
- $V = V'$ (G' is **spanning**.)
- $\sum_{e \in E'} w(e)$ is **minimized**.

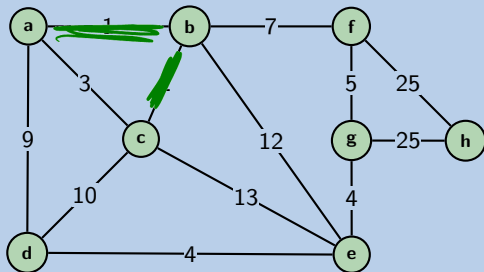
Example



- Given a layout of houses, where should we place the phone lines to minimize cost?
- How can we design circuits to minimize the amount of wire?
- Implementing efficient multiple constant multiplications
- Minimizing the number of packets transmitted across a network
- Machine learning (e.g., real-time face verification)
- Graphics (e.g., image segmentation)

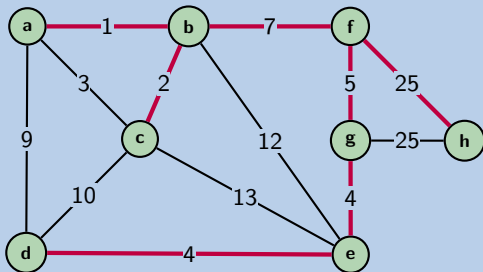
MST Example

- Find a Minimum Spanning Tree of this graph
- Are there any others?
- Come up with a simple algorithm to find MSTs



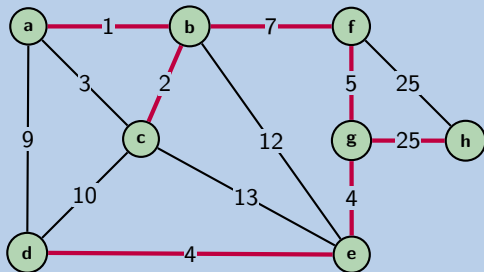
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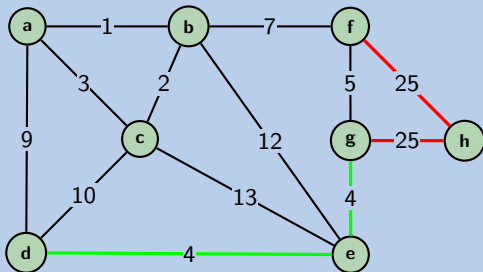
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MST Example

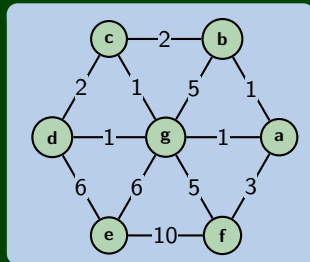
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MST Uniqueness

If a graph has all unique edges, there is a unique MST. Otherwise, there might be multiple MSTs.

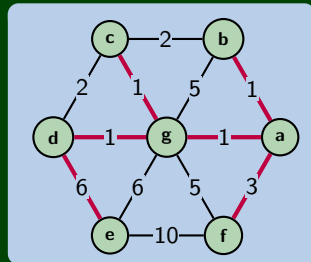
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1 prim(G) {
2   conns = new Dictionary();
3   worklist = [];
4   for (v : V) {
5     conns[v] = null;
6     worklist.add((v, ∞));
7   }
8   while (worklist.hasWork()) {
9     v = next();
10    for (u : v.neighbors()) {
11      if (w(v, u) < w(conns[u], u)) {
12        conns[u] = v;
13        worklist.decreaseKey(
14          u, w(v, u)
15        );
16      }
17    }
18  }
19  return conns;
20 }
```



This really is almost identical to Dijkstra's Algorithm! We build up an MST by **adding vertices** to a "done set" and keeping track of what edge got us there.

Do we have to use vertices? Can we use edges instead?

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Simple MST

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1 findMST(G) {  
2   mst = {};  
3   for ((v, w) ∈ sorted(E)) {  
4     foundV = foundW = false;  
5     for ((a, b) ∈ mst) {  
6       foundV |= (a == v) || (b == v);  
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8     }  
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Some Questions!

- How many edges is the MST?
- What is the runtime of this algorithm?
- What is the slow operation of this algorithm?

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$|E| \log |E|$

$|V| |E|$

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Every MST will have $|V| - 1$ edges; one edge to include each vertex
- What is the runtime of this algorithm?
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- What is the slow operation of this algorithm? Checking if a vertex is already in our MST is very slow here. Can we do better?

A **disjoint sets** data structure keeps track of multiple sets which do not share any elements. Here's the ADT:

UnionFind ADT

<code>find(x)</code>	Returns a number representing the set that <code>x</code> is in.
<code>union(x, y)</code>	Updates the sets so whatever sets <code>x</code> and <code>y</code> were in are now considered the same sets.

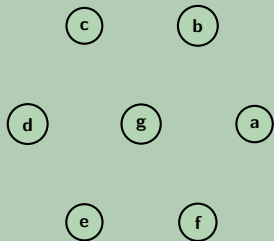
Example

```
1 list = [1, 2, 3, 4, 5, 6];
2 UF uf = new UF(list); // State: {1}, {2}, {3}, {4}, {5}, {6}
3 uf.find(1);           // Returns 1
4 uf.find(2);           // Returns 2
5 uf.union(1, 2);       // State: {1, 2}, {3}, {4}, {5}, {6}
6 uf.find(1);           // Returns 1
7 uf.find(2);           // Returns 1
8 uf.union(3, 5);       // State: {1, 2}, {3, 5}, {4}, {6}
9 uf.union(1, 3);       // State: {1, 2, 3, 5}, {4}, {6}
10 uf.find(3);           // Returns 1
11 uf.find(6);           // Returns 6
```

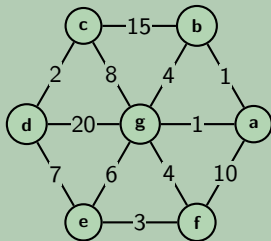
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Forest



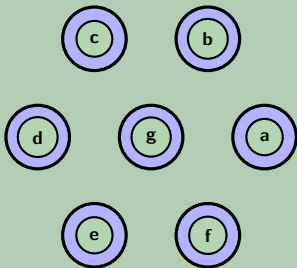
Graph



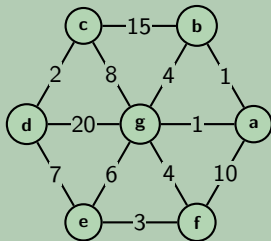
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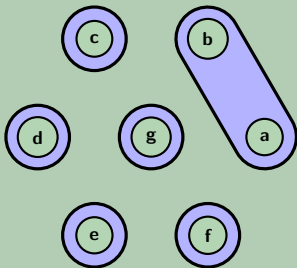
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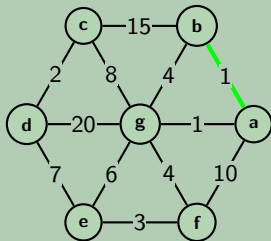
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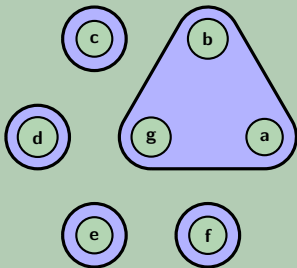
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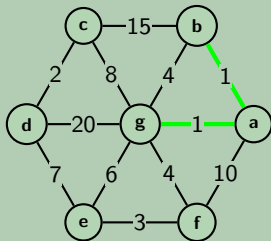
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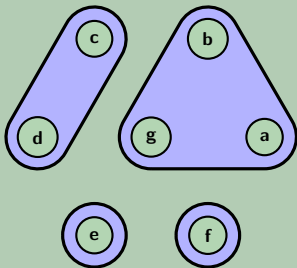
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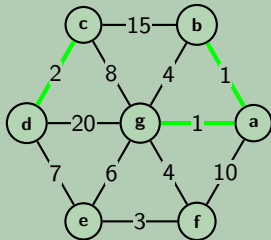
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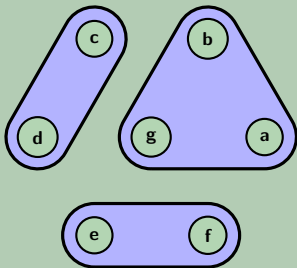
Graph



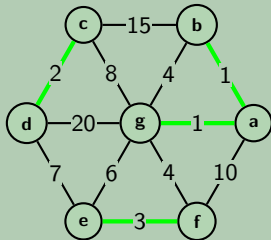
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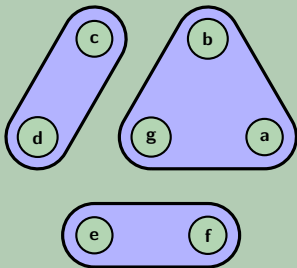
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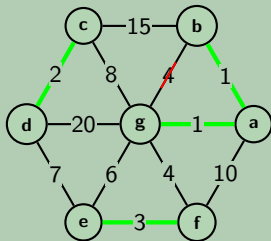
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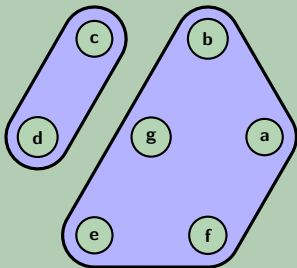
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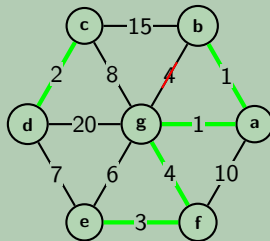
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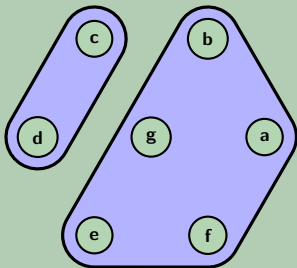
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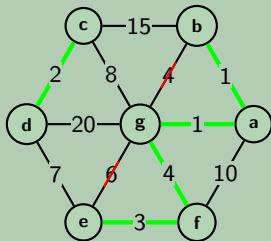
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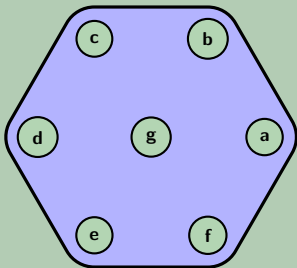
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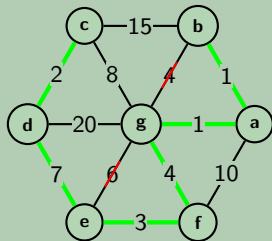
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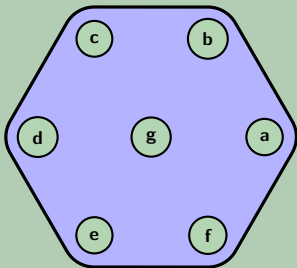
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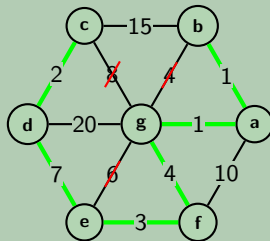
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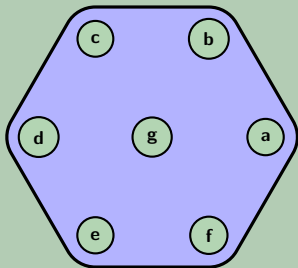
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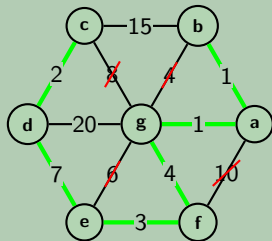
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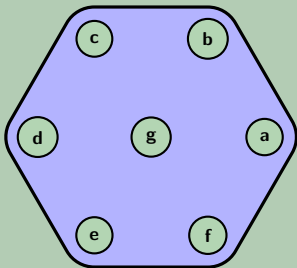
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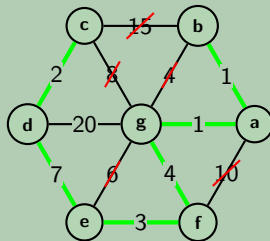
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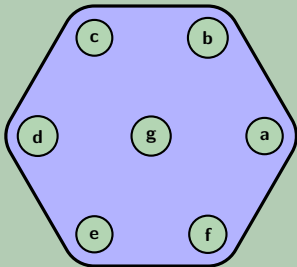
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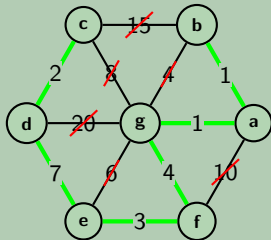
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Proving Correctness

To prove that Kruskal's Algorithm is correct, we must prove:

- 1 The output is some spanning tree
- 2 The output has minimum weight

Kruskal's Algorithm Outputs **SOME** Spanning Tree

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- It's acyclic because we check before adding an edge.
- Connected?

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- 1 The output is some spanning tree
- 2 The output has minimum weight

Kruskal's Algorithm Outputs **SOME** Spanning Tree

We must show that the output, G' is spanning, connected, and acyclic.

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- It's acyclic because we check before adding an edge.
- Connected?
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Since there is a path between every u and v in the graph in G' , G' is connected by definition.

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Proof: We go by induction.

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- If $e_{i+1} \in T_i$, then we choose $T_{i+1} = T_i$, and we're done.
- Otherwise. . .

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- So, $w(T_i - e' + e_{i+1}) = w(T_i) + w(e_{i+1}) - w(e') \leq w(T_i)$

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So, choose $T_{i+1} = T_i - e' + e_{i+1}$ since its weight is no more than any MST!

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- Note that e connects the same nodes as e' ; so, it's also a spanning tree.

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That's it! For each i , we found an MST that extends the previous one. So, the last one must also be an MST!

- Sort takes $\mathcal{O}(n \lg n)$
- We don't know how `UnionFind` works, but if we know...
 - `find` is $\mathcal{O}(\lg n)$
 - `union` takes $\mathcal{O}(\lg n)$ time

The runtime is $\mathcal{O}(|E| \lg(|E|) + |E| \lg(|V|))$

Due to time constraints, we won't explore how union-find works, but you can do some very interesting amortized analysis with it. . .