# **CSE 332**

#### AUGUST 18<sup>TH</sup> – ALGORITHM DESIGN

• Tokens

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- If you use a token for multiple things, make it into a single document

- Course evaluations
  - Very important to this class and this department
  - Above all, they're very important to me
  - Should only take ~5 minutes, and it's very valuable feedback
  - Only 8 have filled out so far, which is only 5 away from 50% completion... a particularly low bar in my opinion

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  - Dynamic Programming

#### **LINEAR SOLVING**

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- If the decider creates a set of correct answers, find one at a time
  - Selection sort: find the lowest element at each run through
- Sometimes, the best solution
  - Find the smallest element of an unsorted array

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  - NP : Set of problems that can be verified in polynomial time
  - EXP: Set of problems that can be solved in exponential time

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  - At each move, the computer needs to approximate the best move
  - Certainty always comes at a price

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  - Board quality If you could easily rank which board layout in order of quality, chess is simply choosing the best board
  - It is very difficult, branching factor for chess is ~35
  - Look as many moves into the future as time allows to see which move yields the best outcome

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  - Does your client have a tolerance for error?
  - Can you map this problem to a similar problem?
  - "Greedy" algorithms are often approximators

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  - Las Vegas correct result in random time
  - Montecarlo estimated result in deterministic time

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  - If you haven't gotten the problem in some constrained time, just return what you have.

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- If we say a list is 90% sorted, what do we mean?
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- Analysis for these problems can be very tricky, but it's an important approach

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    - Still can be useful for some easier problems

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  - Suppose we want to have a confidence equal to α, how do we get this?

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 $(1-p)^k = \alpha$ 

 $(1-p)^{k} = \alpha$   $k*\ln(1-p) = \ln \alpha$   $k = (\ln \alpha)$   $(\ln(1-p))$   $k = \log_{(1-p)} \alpha$ 

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- Suppose P = 0.5 (we only have a 50% chance of success on any given run) and α = 0.001, we only tolerate a 0.1% error
- How many runs do we need to get this level of confidence?
  - Only 10! This is a constant multiple

 In fact, suppose we always want our error to be 0.1%, how does this change with p?

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- What does this mean?
  - Randomized algorithms don't have to be complicated, if you can create a *reasonable* guess and can verify it in a short amount of time, then you can get good performance just from running repeatedly.

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- Find the two non-empty subgraphs V<sub>1</sub> and V<sub>2</sub> such that V<sub>1</sub> U V<sub>2</sub> = V and the set of edges connecting them are minimal
- Why do we even care?
  - The min-cut is the maximum flow, if we are trying to connect two cities, the limit of traffic flow between nodes in the network
#### **Max-Flow Min-Cut Theorem**

MAX-FLOW MIN-CUT THEOREM (Ford-Fulkerson, 1956): In any network, the value of the max flow is equal to the value of the min cut.

- "Good characterization."
- Proof IOU.



#### Algorithm [edit]

Let G(V, E) be a graph, and for each edge from u to v, let c(u, v) be the capacity and f(u, v) be the flow. We want to find the maximum flow from the source s to the sink t. After every step in the algorithm the following is maintained:

Capacity  $\forall (u, v) \in E \ f(u, v) < c(u, v)$ The flow along an edge can not exceed its capacity. constraints:  $\forall (u,v) \in E \ f(u,v) = -f(v,u)$ The net flow from u to v must be the opposite of the net flow from v to u (see example). Skew symmetry:  $orall u \in V: u 
eq s ext{ and } u 
eq t \Rightarrow \sum_{w \in V} f(u,w) = 0$ That is, unless u is s or t. The net flow to a node is zero, except for the source, which Flow "produces" flow, and the sink, which "consumes" flow. conservation:  $\sum_{(s,u)\in E} f(s,u) = \sum_{(v,t)\in E} f(v,t)$ That is, the flow leaving from s must be equal to the flow arriving at t. Value(f): This means that the flow through the network is a legal flow after each round in the algorithm. We define the residual network  $G_f(V, E_f)$  to be the network with capacity  $c_f(u, v) = c(u, v) - f(u, v)$  and no flow. Notice that it can happen that a flow from v to u is allowed in the residual network, though disallowed in the

Algorithm Ford–Fulkerson

Inputs Given a Network G = (V, E) with flow capacity c, a source node s, and a sink node t

original network: if f(u, v) > 0 and c(v, u) = 0 then  $c_f(v, u) = c(v, u) - f(v, u) = f(u, v) > 0$ .

Output Compute a flow f from s to t of maximum value

1. 
$$f(u,v) \leftarrow 0$$
 for all edges  $(u,v)$ 

2. While there is a path p from s to t in  $G_f$ , such that  $c_f(u,v)>0$  for all edges  $(u,v)\in p$ :

1. Find 
$$c_f(p) = \min\{c_f(u,v): (u,v) \in p\}$$

- 2. For each edge  $(u,v) \in p$ 
  - 1.  $f(u, v) \leftarrow f(u, v) + c_f(p)$  (Send flow along the path)

2. 
$$f(v,u) \leftarrow f(v,u) - c_f(p)$$
 (The flow might be "returned" later

The path in step 2 can be found with for example a breadth-first search or a depth-first search in  $G_f(V, E_f)$ . If you use the former, the algorithm is called Edmonds–Karp.

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- Contract edges at random!
  - How many edges will you contract to get two subgraphs?



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  - What might be an easy estimator?
- Contract edges at random!
  - How many edges will you contract to get two subgraphs?
  - Only |V|-2



• Does this work?

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  - Success probability of 2/|E|

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  - Run it O(E) times, and you have a bounded success rate!

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- Good for estimating difficult problems in constrained time
- Relies on the quality of the guess
- Important approach to consider in modern computing

# **EXAM FORMAT**

- Two one-hour portions
- Material before midterm and from the projects are acceptable both days
- First, Thursday 9:40 10:40
  - Parallelism and Sorting
- Second, Friday 9:40 10:40
  - Graphs and Algorithms

## **EXAM FORMAT**

- We will be our most strict grading yet, don't make any assumptions that aren't explicit
- Analysis work needs to be thorough and concrete, recurrences and summations will likely be required
- Show all of your work. Many algorithms are trivial to solve by hand. Just providing "the solution" will not earn points. Algorithms are about process.

# **EXAM FORMAT**

- A time crunch is likely
  - There are many topics that need to be covered
  - Get down things that you know, and if you don't make progress move on and come back

#### Definitions

- ADT Abstract Data Type Describes a certain set of functionality and behavior
  - e.g. PriorityQueue
- Data structure Theoretical storage method that implements an ADT.
  - e.g. Heap
- Implementation Low-level design decisions that are often language dependent
  - e.g. Using an array for the heap

#### Stacks and Queues

- LIFO and FIFO ordered storage respectively
- Can be implemented with arrays or linked lists
- Understand the desired behavior and how to implement these structures

- Priority Queues
  - Insert(key, priority)
  - findMin()
  - deleteMin()
  - changePriority(key, newPriority)

#### • Heaps

- Usually array implementations
- Heap property
- Complete trees
- Runtimes and buildHeap()

- Algorithm analysis
  - bigO, bigOmega, bigTheta
  - c and n<sub>0</sub>
  - Asymptotic behavior
  - Memory analysis
  - Recurrences
  - Summations
  - Work and Span

- Dictionary
  - ADT- insert(k,v), find(k) delete(k)
  - Many possible underlying data structures
  - Different runtimes (and support)

- Binary search trees
  - Best and worst case
  - Traversals
- Balance property AVL
  - Rotations and correctness

#### Hashtables

- Linear, quadratic, secondary hashing
- Separate chaining
- Load factor and resizing
- Primary and Secondary clustering
- Runtime and memory constraints

#### B+-trees

- Temporal and Spatial localities
- Pages and their use
- Tiered caching
- Basic rules and implementations
- Signposts and Leaves

#### Parallelism

- ForkJoinPool
- Work and Span
- Speed-up
- Debugging
- Parallel primitives

#### Synchronization

- Critical Sections
- Mutual Exclusion
- Deadlock resolution
- Course v. Fine-grained locking
- Race conditions

#### Project Material

- Minimax
- Alphabeta
- Iterators
- Debugging
- Tries
- N-grams

#### • Graphs

- Notation G(V,E)
- Traversals
- Topological Sorts
- Properties
  - Directed v. Undirected
  - Dense v. Sparse
  - Weighted v. Unweighted
  - Cyclic v. Acyclic

#### • Graphs

- Algorithms
  - Dijkstra's path finding
  - Prim's and Kruskal's Minimum spanning trees
- Know their runtimes and the data structures they rely on for those runtimes...

#### Union find

- ADT Disjoint sets
- Partitions
- Weighted Union
- Path compression
- Uptree single array representation

#### Sorting

- Insertion and Selection
- Heap, Merge and Quick
- Bucket and Radix

#### Properties

- Comparison sorts
- Stable
- In place
- Interruptible (top k)

#### Analysis

- Lower bound for comparison sorts
- Memory usages for sorting
- Best and worst case runtimes
- Work and Span for parallel algorithms

#### Algorithm Design

- How can you approach the problem?
  - Guess and check (Approximation)
  - Brute Force (Linear Work)
  - Divide and Conquer
  - Greedy algorithms (make best decision for a local sub-problem)
  - Randomization, Las Vegas and Monte Carlo
  - Preprocessing

# **FINAL WORDS**

- Great quarter!
- Stressful week
  - Nothing feels better than walking out of an exam and...
  - Filling out course evaluations!
- Course has been tough
  - But you have learned a lot
## **FINAL WORDS**

- Good luck!
- Have a nice "summer"!