

CSE 332: Data Structures

Priority Queues – Binary Heaps

Richard Anderson

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Recall Queues

- **FIFO: First-In, First-Out**
 - Print jobs
 - File serving
 - Phone calls and operators
 - Lines at the Department of Licensing...

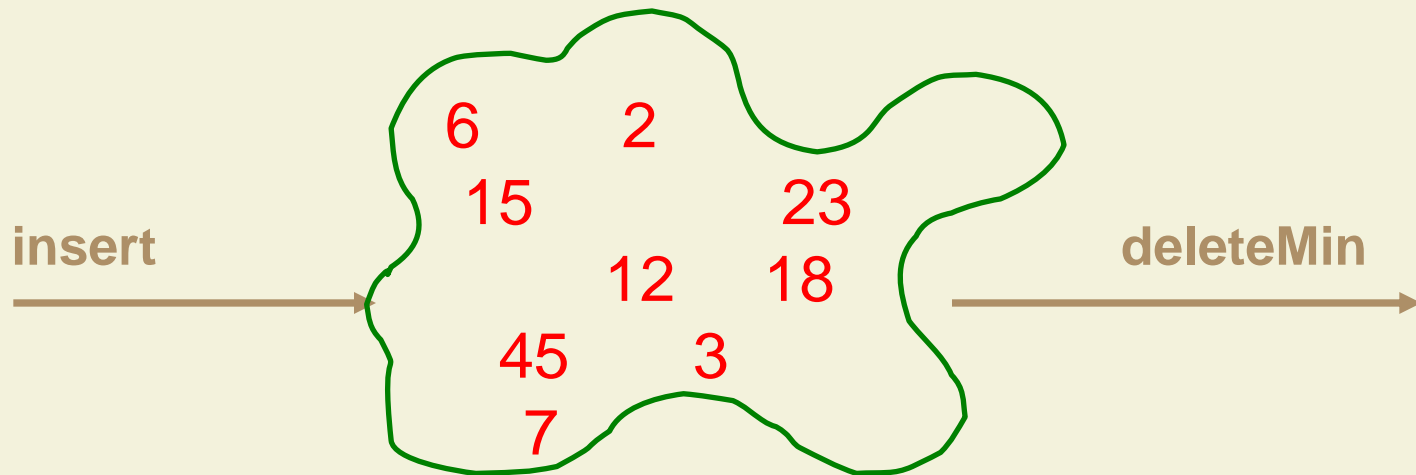
Priority Queues

Prioritize who goes first – a **priority queue**:

- treat ER patients in order of **severity**
- route network packets in order of **urgency**
- operating system can favor jobs of shorter **duration** or those tagged as having higher **importance**
- Greedy optimization: “**best first**” problem solving

Priority Queue ADT

- Need a new ADT
- Operations: Insert an Item,
Remove the “Best” Item



Priority Queue ADT

1. **PQueue data** : collection of data with **priority**
2. **PQueue operations**
 - insert
 - deleteMin(also: create, destroy, is_empty)
3. **PQueue property**: if x has **lower** **priority** than y , x will be deleted before y

Potential implementations

	insert	deleteMin
Unsorted list (Array)		
Unsorted list (Linked-List)		
Sorted list (Array)		
Sorted list (Linked-List)		
Binary Search Tree (BST)		

Binary Heap data structure

- **binary heap** (a kind of binary tree) for priority queues:
 - $O(\log n)$ **worst case** for both insert and deleteMin
 - $O(1)$ **average** insert
- It's optimized for priority queues. Lousy for other types of operations (e.g., searching, sorting)

Tree Review

root(T): A

leaves(T): D-F, I-N

children(B): D-F

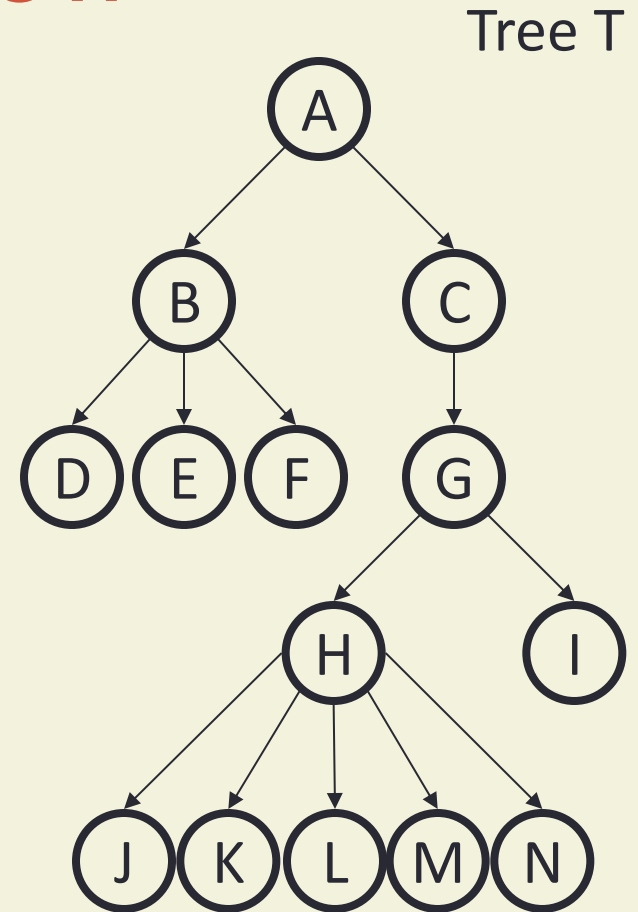
parent(H): G

siblings(E): D,F

ancestors(F):

descendants(G):

subtree(C):



More Tree Terminology

depth(B):

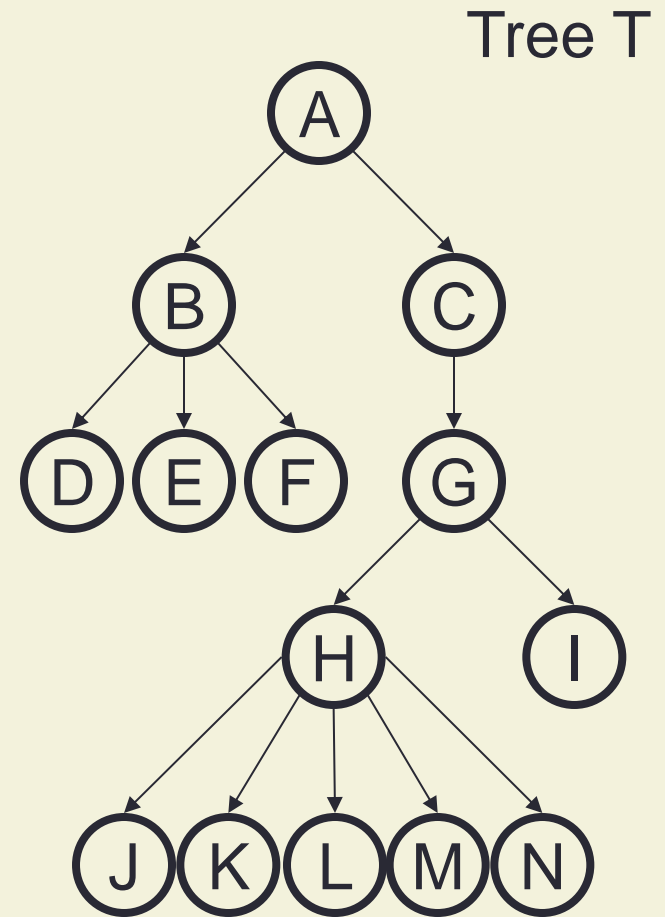
height(G):

height(T):

degree(B):

*branching
factor(T):*

n-ary tree:



Binary Heap Properties

A binary heap is a binary tree with two important properties that make it a good choice for priority queues:

1. **Completeness**
2. **Heap Order**

Note: we will sometimes refer to a binary heap as simply a “heap”.

Completeness Property

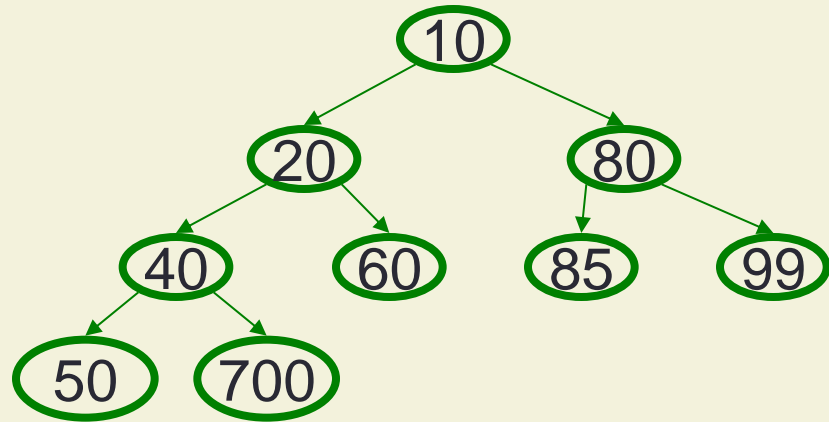
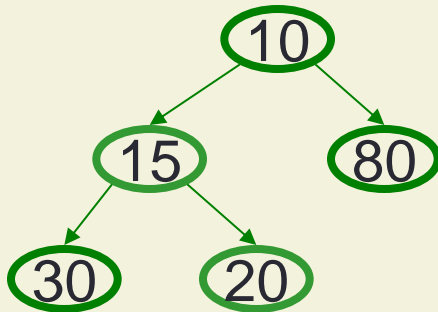
- A binary heap is a **complete** binary tree:
 - a binary tree with all levels full, except possibly the bottom level, which is filled left to right

Examples:

Height of a **complete** binary tree
with n nodes?

Heap Order Property

Heap order property: For every non-root node X , the value in the parent of X is less than (or equal to) the value in X .



Heap Operations

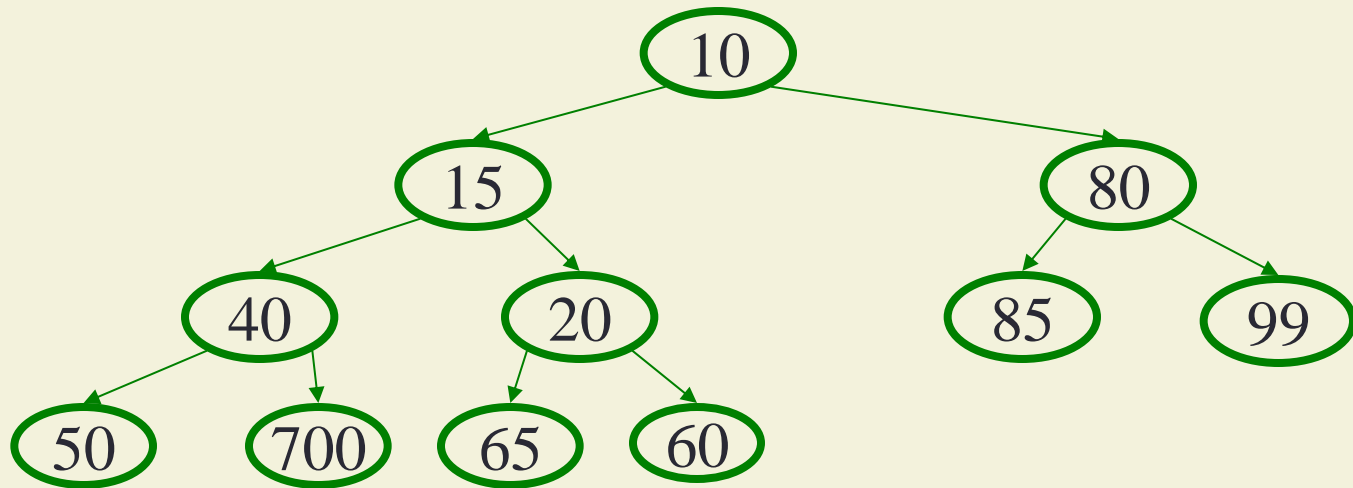
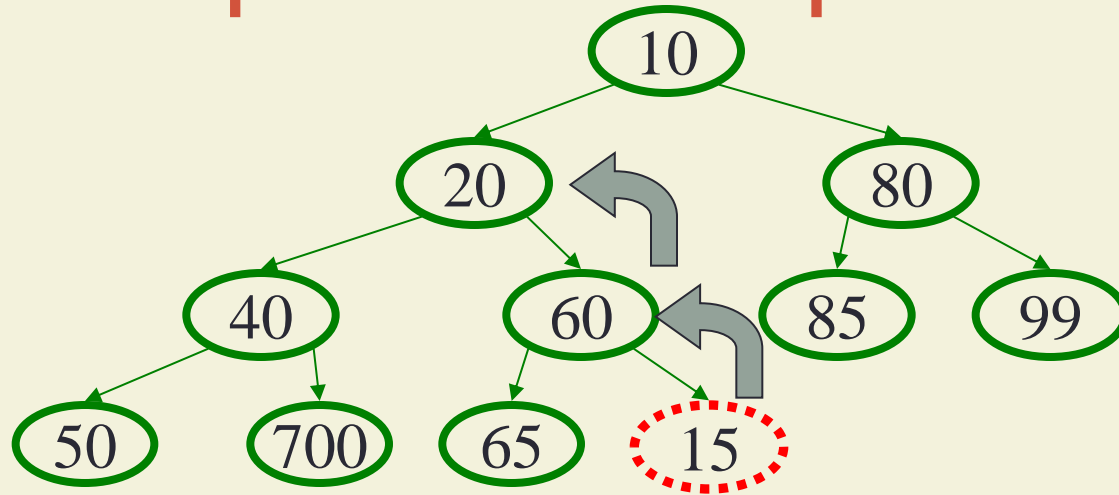
- Main ops: insert, deleteMin
- Key is to maintain
 - Completeness
 - Heap Order
- Basic idea is to propagate changes up/down the tree, fixing order as we go

Heap – insert(val)

Basic Idea:

1. Put val at last leaf position
2. Percolate up by repeatedly exchanging node with parent as long as needed

Insert: percolate up

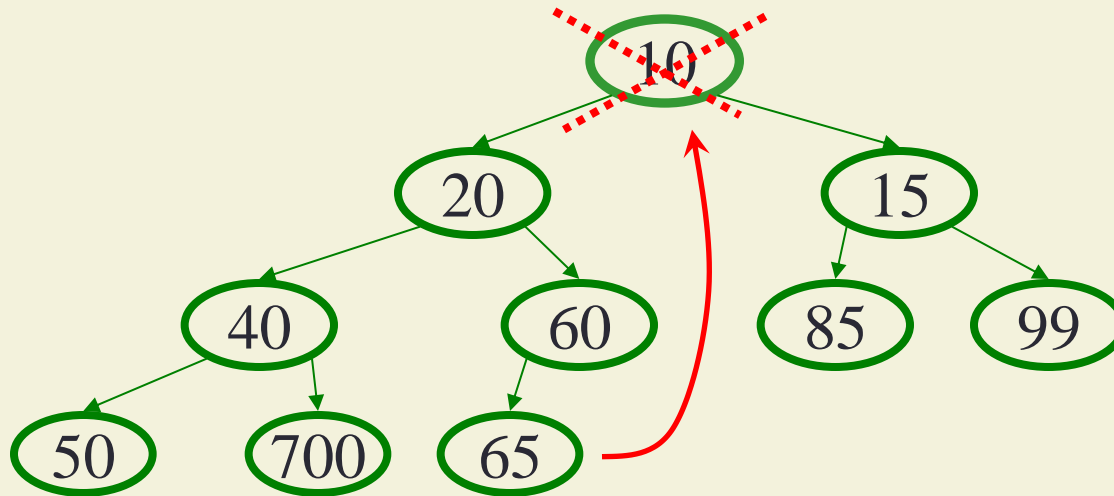


Heap – deleteMin

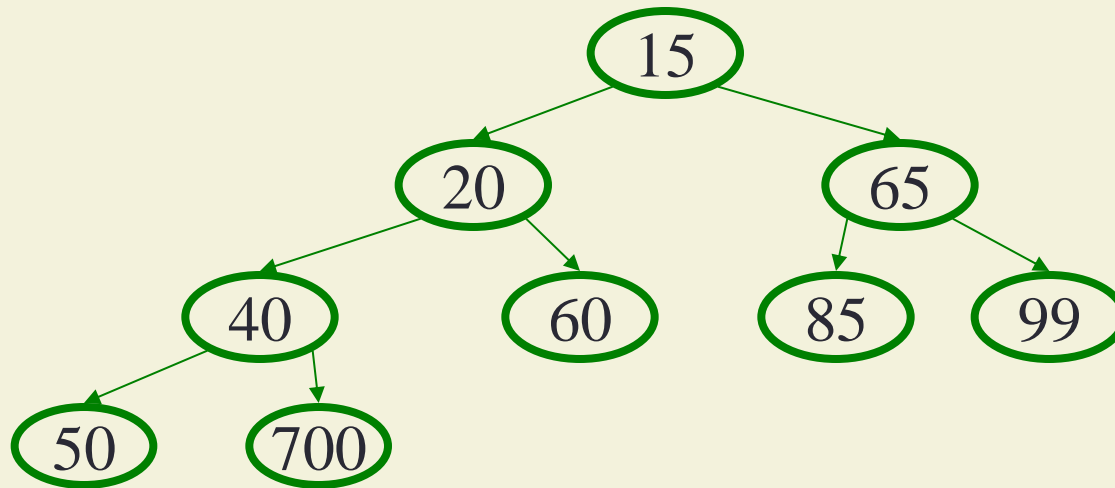
Basic Idea:

1. Remove min element
2. Put “last” leaf node value at root
3. Find smallest child of node
4. Swap node with its smallest child if needed.
5. Repeat steps 3 & 4 until no swaps needed.

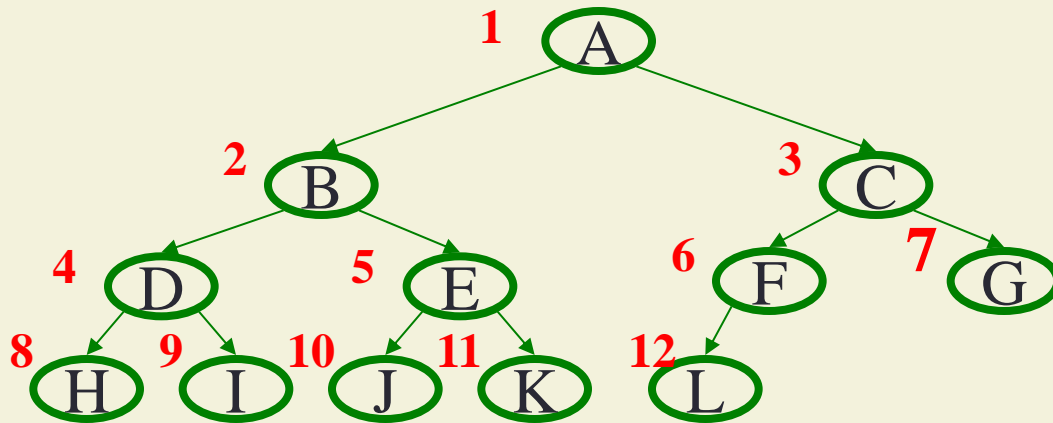
DeleteMin: percolate down



DeleteMin: percolate down



Representing Complete Binary Trees in an Array



From node **i**:

left child:

right child:

parent:

	A	B	C	D	E	F	G	H	I	J	K	L	
0	1	2	3	4	5	6	7	8	9	10	11	12	13

Why use an array?

DeleteMin Code

```
Object deleteMin() {
    assert(!isEmpty());
    returnVal = Heap[1];
    size--;
    newPos =
        percolateDown(1,
            Heap[size + 1]);
    Heap[newPos] =
        Heap[size + 1];
    return returnVal;
}
```

runtime:

(Java code in book)

```
int percolateDown(int hole,
                  Object val) {
    while (2*hole <= size) {
        left = 2*hole;
        right = left + 1;
        if (right <= size &&
            Heap[right] < Heap[left])
            target = right;
        else
            target = left;

        if (Heap[target] < val) {
            Heap[hole] = Heap[target];
            hole = target;
        }
        else
            break;
    }
    return hole;
}
```

Insert Code

```
void insert(Object o) {
    assert(!isFull());
    size++;
    newPos =
        percolateUp(size, o);
    Heap[newPos] = o;
}

int percolateUp(int hole,
                Object val) {
    while (hole > 1 &&
           val < Heap[hole/2])
        Heap[hole] = Heap[hole/2];
        hole /= 2;
    }
    return hole;
}
```

runtime:

(Java code in book)

Insert: 16, 32, 4, 69, 105, 43, 2

0	1	2	3	4	5	6	7	8

More Priority Queue Operations

decreaseKey(nodePtr, amount):

given a pointer to a node in the queue, reduce its priority

Binary heap: change priority of node and _____

increaseKey(nodePtr, amount):

given a pointer to a node in the queue, increase its priority

Binary heap: change priority of node and _____

Why do we need a *pointer*? Why not simply data value?

Worst case running times?

More Priority Queue Operations

remove(objPtr):

given a pointer to an object in the queue, remove it

Binary heap: _____

findMax():

Find the object with the highest value in the queue

Binary heap: _____

Worst case running times?

More Binary Heap Operations

expandHeap():

If heap has used up array, copy to new, larger array.

- Running time:

buildHeap(objList):

Given list of objects with priorities, fill the heap.

- Running time:

We do better with **buildHeap...**

Building a Heap: Take 1

12	5	11	3	10	6	9	4	8	1	7	2
----	---	----	---	----	---	---	---	---	---	---	---

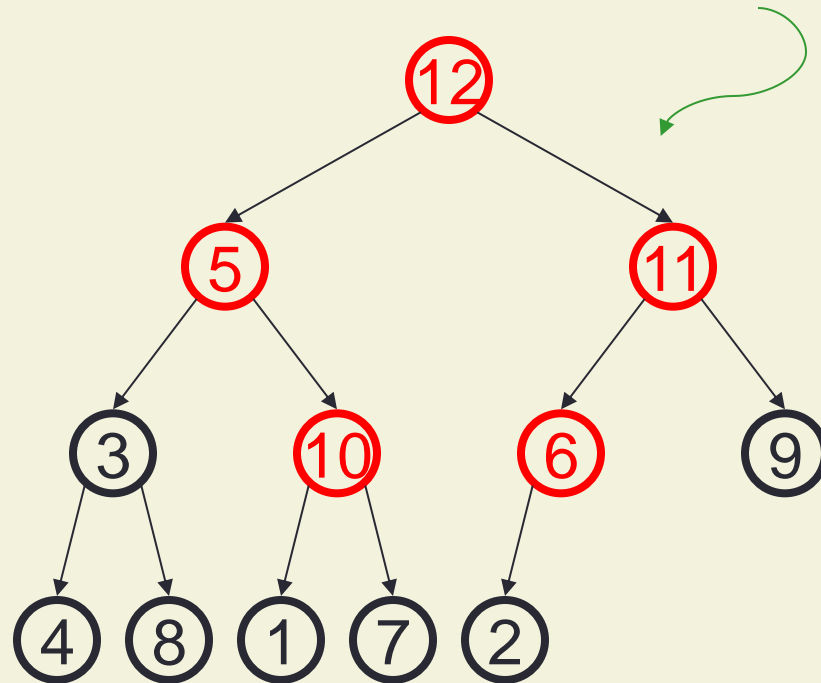
BuildHeap: Floyd's Method

12	5	11	3	10	6	9	4	8	1	7	2
----	---	----	---	----	---	---	---	---	---	---	---

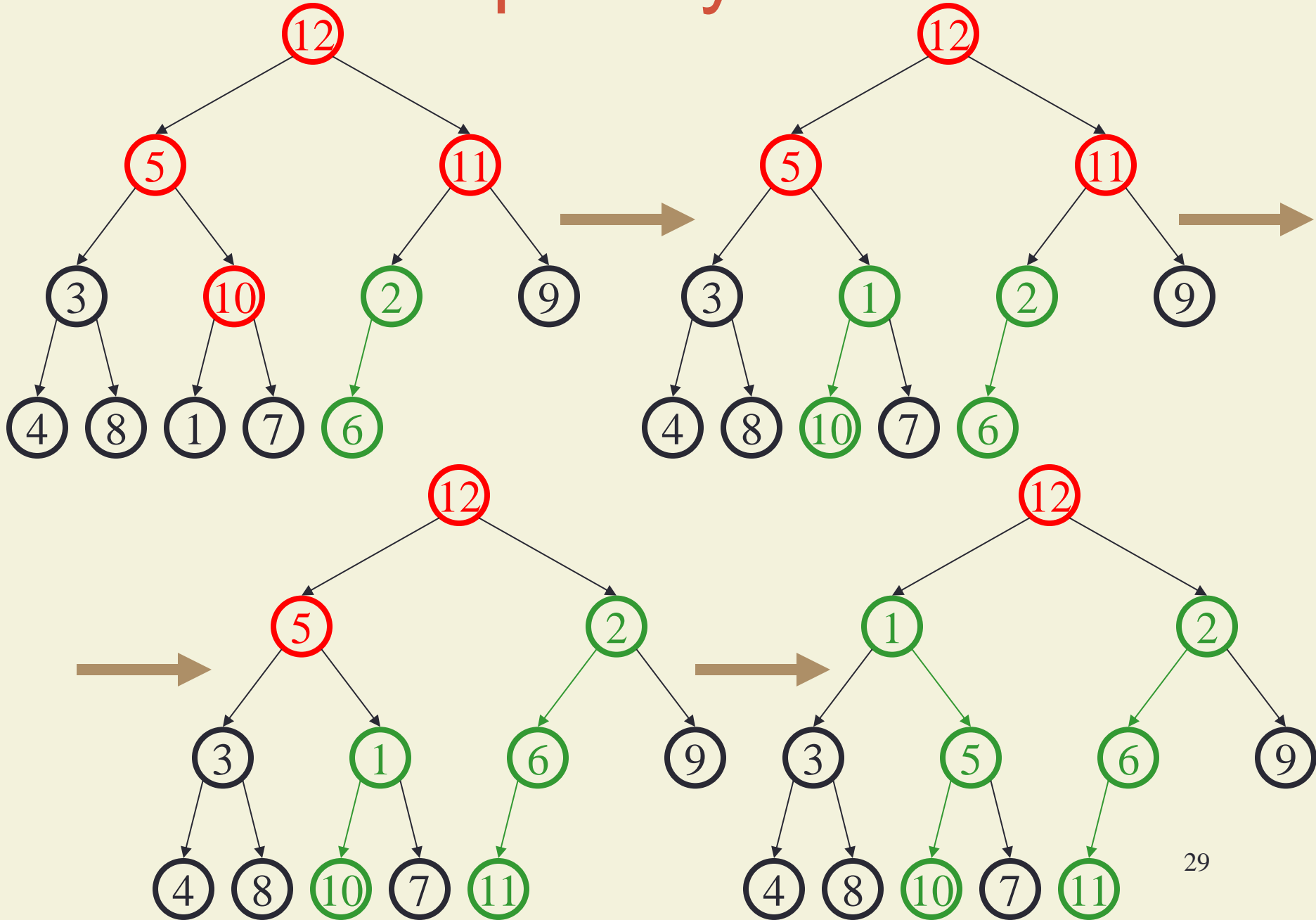
Add elements arbitrarily to form a complete tree.
Pretend it's a heap and fix the heap-order property!

Red nodes need
to percolate
down

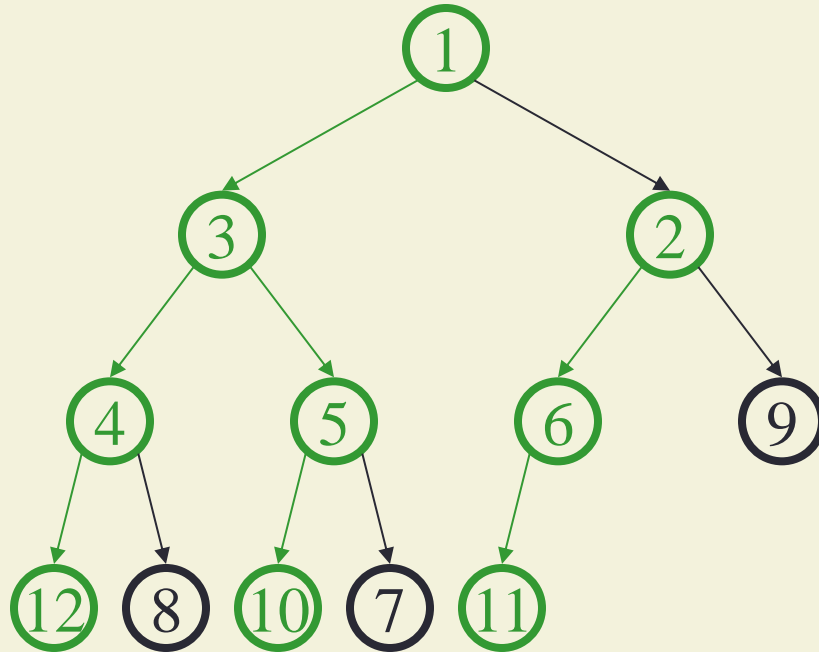
Key idea: fix red
nodes from
bottom-up



BuildHeap: Floyd's Method



Finally...



Buildheap pseudocode

```
private void buildHeap() {  
    for ( int i = currentSize/2; i > 0; i-- )  
        percolateDown( i );  
}
```

runtime:

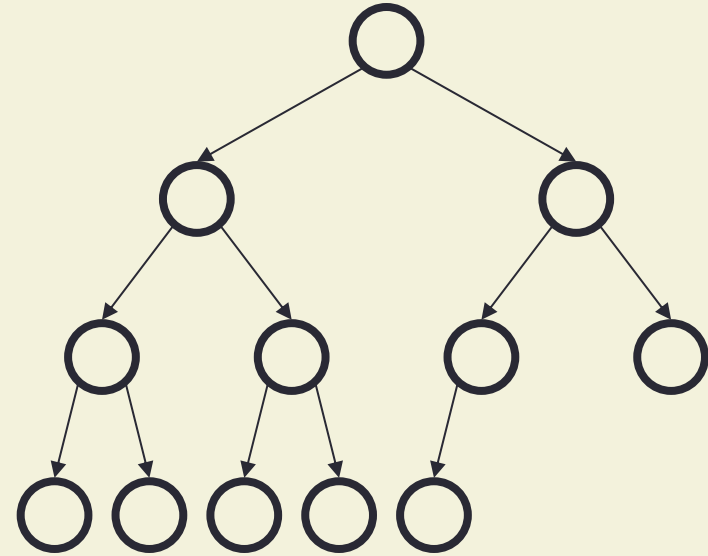
Buildheap Analysis

$n/4$ nodes percolate at most 1 level

$n/8$ percolate at most 2 levels

$n/16$ percolate at most 3 levels

...



runtime: