

CSE 332

Data Abstractions

Dictionaries & Trees



Outline

1 Dictionaries & Sets

2 Vanilla BSTs

ADT's So Far

1

Where We've Been So Far

- Stack (Get LIFO)
- Queue (Get FIFO)
- Priority Queue (Get By Priority)

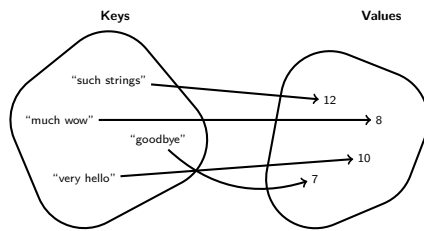
Today, we begin discussing **Maps**. This ADT is hugely important.

A New ADT: "Dictionaries" (Also called "Maps")

2

Dictionary ADT

Data	Set of Comparable (key, value) pairs
<code>insert(key, val)</code>	Places (key, val) in map (overwrites existing val entry)
<code>find(key)</code>	Returns the val currently associated to key
<code>delete(key)</code>	deletes any pair relating key from the map



`find("such strings") → 12`

Sets and Maps

3

Dictionaries are the **more general** structure, but, in terms of implementation, they're nearly identical.

In a Set, we store the key directly, but conceptually, there's nothing different in storing an **Entry**:

```
1 class Entry {
2     Data key;
3     Data value;
4 }
```

The Set ADT usually has our favorite operations: intersection, union, etc.

Notice that union, intersection, etc. **still make sense on maps!**

As always, depending on our usage, we might choose to add/delete things from our ADT.

Bottom Line: If we have a set implementation, we also have a valid dictionary implementation (and vice versa)!

Dictionary Implementations, Take # 1

4

It turns out dictionaries are super useful. They're a natural generalization of arrays. Instead of storing data at an index, we store data at **anything**.

- Networks: router tables
- Operating Systems: page tables
- Compilers: symbol tables
- Databases: dictionaries with other nice properties
- Search: inverted indexes, phone directories, ...
- Biology: genome maps

Dictionary Implementations, Take # 1

5

For each of the following potential implementations, what is the worst case runtime for insert, find, delete?

- Unsorted Array
 - Insert** by searching for existence and inserting which is $\mathcal{O}(n)$
 - Find** by linear search which is $\mathcal{O}(n)$
 - Delete** by linear search AND shift which is $\mathcal{O}(n)$
- Unsorted Linked List
 - Insert** by searching for existence and inserting which is $\mathcal{O}(n)$
 - Find** by linear search which is $\mathcal{O}(n)$
 - Delete** by linear search AND shift which is $\mathcal{O}(n)$
- Sorted Linked List
 - Insert** by searching for existence and inserting which is $\mathcal{O}(n)$
 - Find** by linear search which is $\mathcal{O}(n)$
 - Delete** by linear search AND shift which is $\mathcal{O}(n)$
- Sorted Array List
 - Insert** by binary search AND shift which is $\mathcal{O}(n)$
 - Find** by binary search which is $\mathcal{O}(\lg n)$
 - Delete** by binary search AND shift which is $\mathcal{O}(n)$

Dictionary Implementations, Take # ??

6

It turns out there are **many** different ways to do much better.

But they all have their own trade-offs!

So, we'll study many of them:

- "Vanilla BSTs" – today (vanilla because they're "plain")
- "Balanced BSTs" – there are many types: we'll study **AVL Trees**
- "B-Trees" – another strategy for **a lot of data**
- "Hashtables" – a completely different strategy (lack data ordering)
- We already saw another strategy: the amortized array dictionary

Where The Idea Comes From

7

Binary Search is great! It's the only thing that was even sort of fast in that table. But insert and delete are really bad into a sorted array. Store the data in a structure where **most of the data isn't accessed**.

Interestingly, this is **very similar** to what made heaps useful!

To put it another way, by storing the data in an **array**, we're paying for the constant-time access that we're never even using!

It's **okay** that it takes more time to access certain elements.

... as long as it's **never** too bad.

Definition (Vanilla BST)

A binary tree is a **BST** when an **in-order traversal of the tree** yields a sorted list.

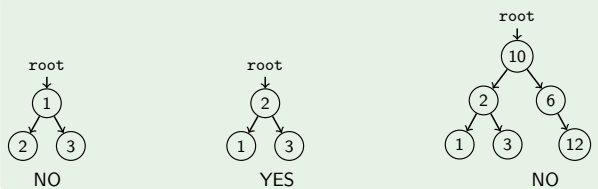
To put it another way, a binary tree is a **BST** when:

- All data "to the left of" a node is less than it
- All data "to the right of" a node is greater than it
- All sub-trees of the binary tree are also BSTs

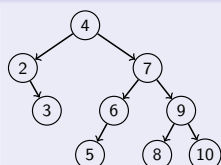
Am I A BST?

8

Example (Which of the following are BSTs?)



BST Properties



Structure Property:
0, 1, or 2 children

BST Property:
Keys in Left Subtree are smaller
Keys in Right Subtree are larger

Height of a Binary Tree

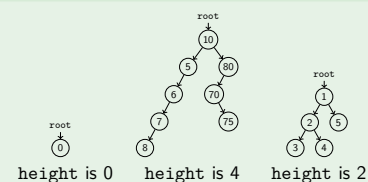
9

Definition (Height)

The **height** of a binary tree is the length of the longest **path** from the root to a leaf.

- Height of an empty tree? -1
- Height of ☹? 0

height



```
1 private int height(Node current) {
2     if (current == null) { return -1; }
3     return 1 + Math.max(height(current.left), height(current.right));
4 }
```

Height

```

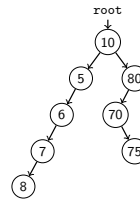
1 private int height(Node current) {
2   if (current == null) { return -1; }
3   return 1 + Math.max(height(current.left), height(current.right));
4 }
    
```

Given that a tree has height h ...

- What is the maximum number of **leaves**? 2^h
- What is the maximum number of **nodes**? $2^{h+1} - 1$
- What is the minimum number of **leaves**? 1
- What is the minimum number of **nodes**? $h + 1$

That's a big spread!

This confirms what we already know: height in a tree has a big impact on runtime.



Recursive find

```

1 Data find(Key key, Node curr) {
2   if (curr == null) { return null; }
3   if (key < curr.key) {
4     return find(key, curr.left);
5   }
6   if (key > curr.key) {
7     return find(key, curr.right);
8   }
9   return curr.data;
10 }
    
```

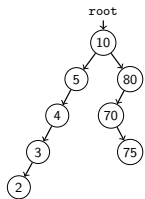
Iterative find

```

1 Data find(Key key) {
2   Node curr = root;
3   while (curr != null && curr.key != key) {
4     if (key < curr.key) {
5       curr = curr.left;
6     }
7     else (key > curr.key) {
8       curr = curr.right;
9     }
10  }
11  if (curr == null) { return null; }
12  return curr.data;
13 }
    
```

What about other finds?

- findMin?
- findMax?
- deleteMin?

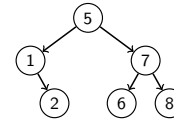


insert

- find
- create a new node

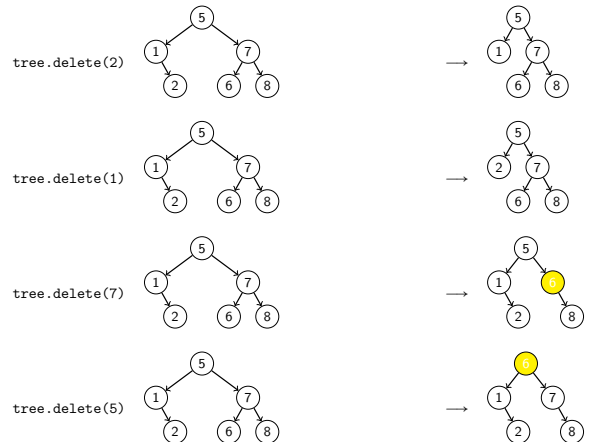
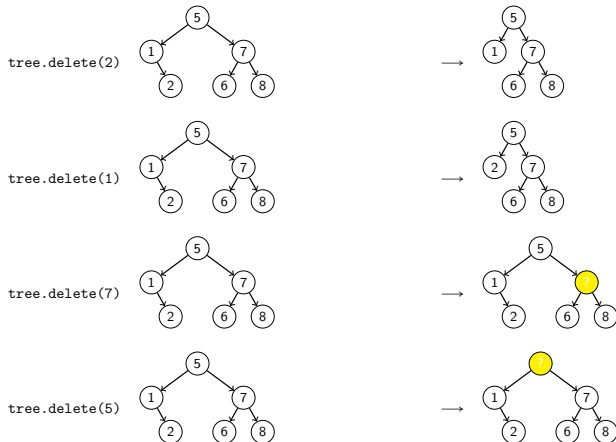
How about delete?

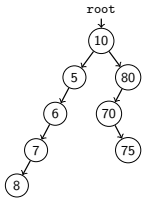
Consider the following tree:



Let's try the following removals:

- tree.delete(2)
- tree.delete(1)
- tree.delete(7)
- tree.delete(5)





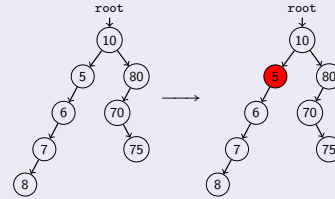
```
delete(x)
  Case 1: x is a leaf
    Just delete x
  Case 2: x has one child
    Replace x with its child
  Case 3: x has two children
    Replace x with the successor or predecessor of x
```

The tricky case is when x has two children. If we think of the BST in sorted array form, to get the successor, we `findMin(right subtree)` (or predecessor is `findMax(left subtree)`)

Instead of doing this complicated algorithm, here's an idea:

Mark the node as "deleted" instead of doing anything

```
lazyDelete(5)
```



Then, `insert` and `find` change slightly, but the whole thing is much simpler.

This "lazy deletion" is a very useful strategy!

Pseudocode

```
1 void buildTree(int[] input) {
2   for (int i = 0; i < input.length; i++) {
3     insert(input[i]);
4   }
5 }
```

What's the best case? The worst case?

The worst case is a sorted input which is $O(n^2)$. Ouch.

The Good News

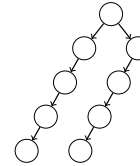
On average, we get $O(\lg n)$ height (see textbook for proof). But we want it to always be $O(\lg n)$ height...

The Solution

Add restrictions on the height of the tree. Somehow, the tree should "fix itself" so it never has too large a height. We call this condition a **Balance Condition**.

Ideas?

- Left and right subtrees of the root have the same number of nodes
- Left and right subtrees of the root have the same height

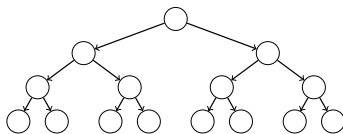


These ideas suffer from the same problem:

They're **local** conditions rather than **global** ones.

Ideas?

- Left and right subtrees ~~of the root~~ **recursively** have the same number of nodes
- Left and right subtrees ~~of the root~~ **recursively** have the same height



These ideas suffer from the same problem:

They're way too strong. Only **perfect** trees satisfy them.

Left and right subtrees **recursively** have heights differing by at most one.

Definition (balance)

$$\text{balance}(n) = \text{abs}(\text{height}(n.\text{left}) - \text{height}(n.\text{right}))$$

Definition (AVL Balance Property)

An AVL tree is balanced when:

$$\text{For every node } n, \text{balance}(n) \leq 1$$

- This ensures a small depth (we'll prove this next time)
- It's relatively easy to maintain (we'll see this next time)