

# CSE 332: Graphs

Richard Anderson, Steve Seitz  
Winter 2014

# Announcements (2/12/14)

- Exams
  - Return at end of class
  - Mean 62.5, Median 63, sd 7.2
  - HW 5 available
  - Project 2B due Thursday night
- Reading for this week: Chapter 9.1, 9.2, 9.3

# Graphs

- A formalism for representing relationships between objects

Graph  $G = (V, E)$

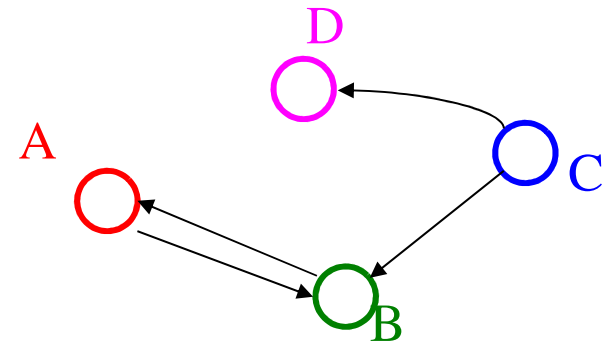
–Set of *vertices*:

$$V = \{v_1, v_2, \dots, v_n\}$$

–Set of *edges*:

$$E = \{e_1, e_2, \dots, e_m\}$$

where each  $e_i$  connects one vertex to another  $(v_j, v_k)$



$$V = \{A, B, C, D\}$$

$$E = \{(C, B), (A, B), (B, A), (C, D)\}$$

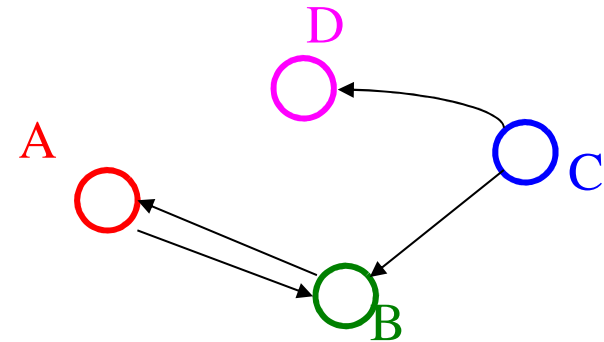
For *directed edges*,  $(v_j, v_k)$  and  $(v_k, v_j)$  are distinct.  
(More on this later...)

# Graphs

## Notation

$|\mathbf{V}|$  = number of vertices

$|\mathbf{E}|$  = number of edges



$\mathbf{V} = \{ \mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D} \}$

$\mathbf{E} = \{ (\mathbf{C}, \mathbf{B}),$   
 $(\mathbf{A}, \mathbf{B}),$   
 $(\mathbf{B}, \mathbf{A})$   
 $(\mathbf{C}, \mathbf{D}) \}$

- $\mathbf{v}$  is *adjacent* to  $\mathbf{u}$  if  $(\mathbf{u}, \mathbf{v}) \in \mathbf{E}$ 
  - *neighbor* of = adjacent to
  - Order matters for directed edges
- It is possible to have an edge  $(\mathbf{v}, \mathbf{v})$ , called a *loop*.
  - We will assume graphs without loops.

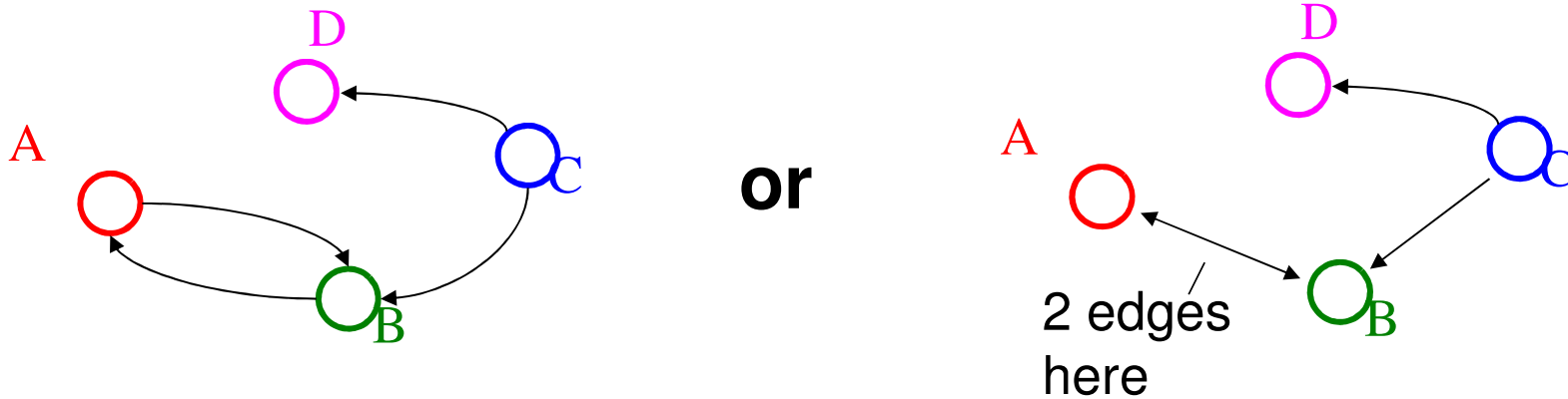
# Examples of Graphs

For each, what are the **vertices** and **edges**?

- The web
- Facebook
- Highway map
- Airline routes
- Call graph of a program
- ...

# Directed Graphs

In *directed* graphs (a.k.a., *digraphs*), edges have a direction:



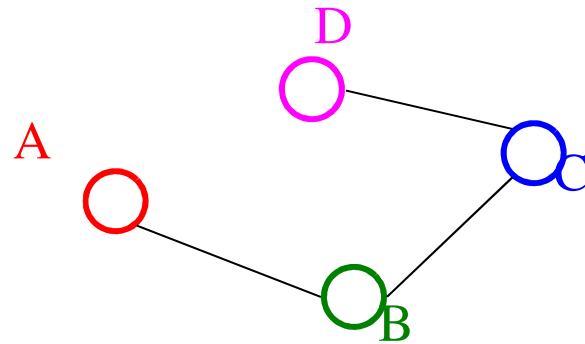
Thus,  $(\mathbf{u}, \mathbf{v}) \in \mathbf{E}$  does *not* imply  $(\mathbf{v}, \mathbf{u}) \in \mathbf{E}$ .  
I.e.,  $\mathbf{v}$  adjacent to  $\mathbf{u}$  does *not* imply  $\mathbf{u}$  adjacent to  $\mathbf{v}$ .

*In-degree* of a vertex: number of inbound edges.

*Out-degree* of a vertex : number of outbound edges.

# Undirected Graphs

In *undirected* graphs, edges have no specific direction (edges are always two-way):

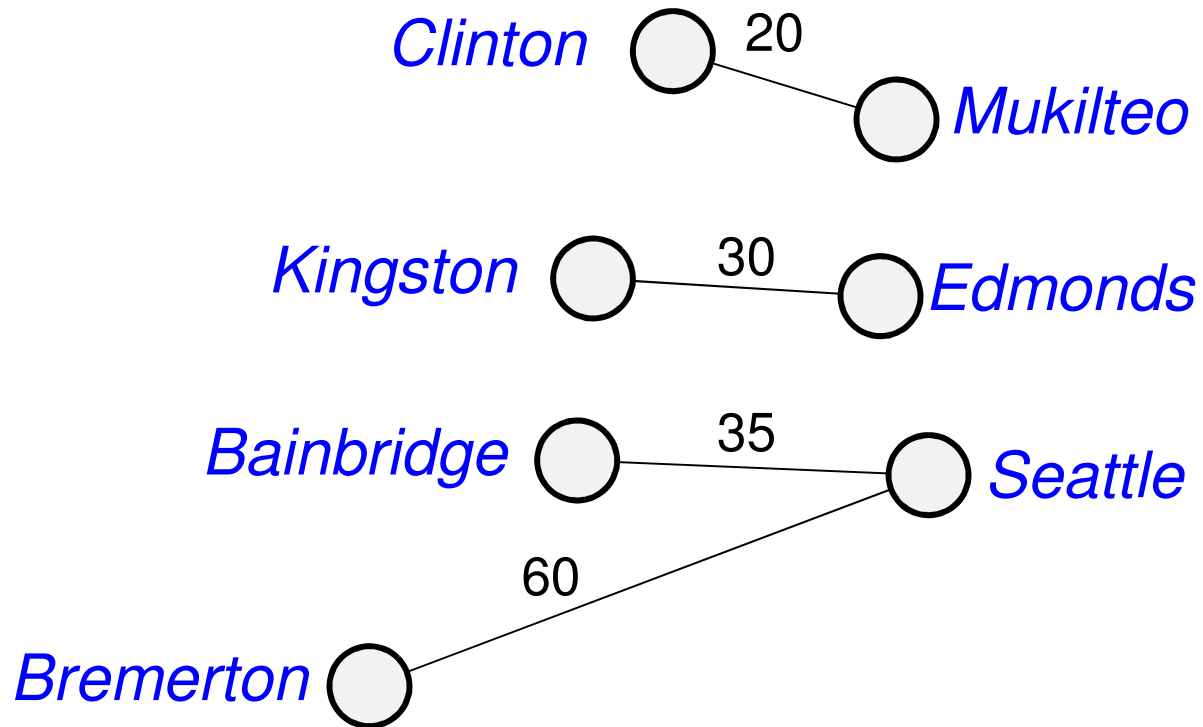


Thus,  $(\mathbf{u}, \mathbf{v}) \in \mathbf{E}$  *does* imply  $(\mathbf{v}, \mathbf{u}) \in \mathbf{E}$ . Only one of these edges needs to be in the set; the other is implicit.

*Degree* of a vertex: number of edges containing that vertex. (Same as number of adjacent vertices.)

# Weighted Graphs

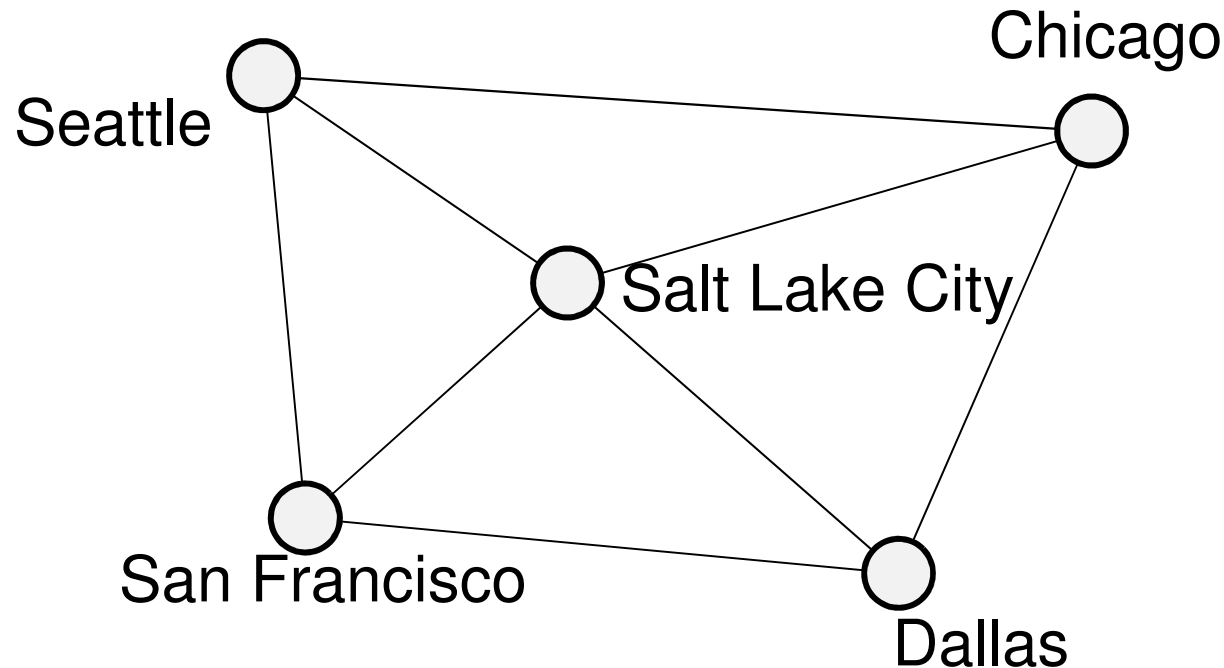
Each edge has an associated weight or cost.





# Paths and Cycles

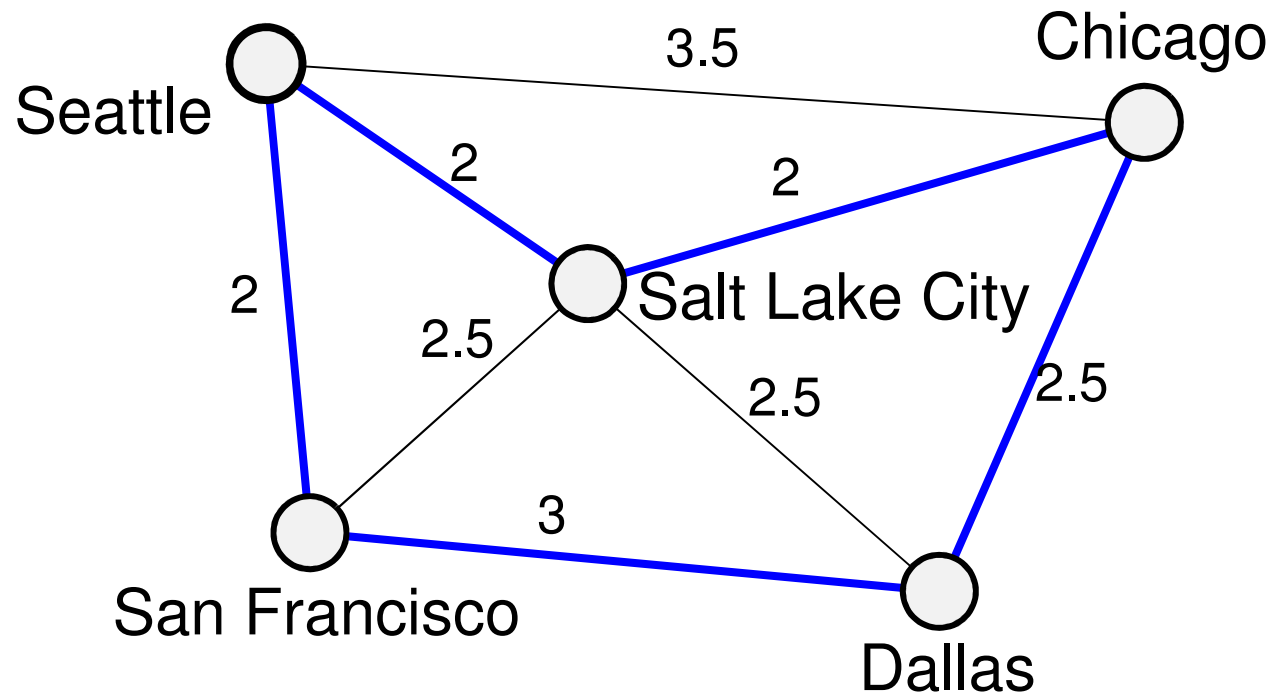
- A *path* is a list of vertices  $\{w_1, w_2, \dots, w_q\}$  such that  $(w_i, w_{i+1}) \in E$  for all  $1 \leq i < q$
- A *cycle* is a path that begins and ends at the same node



$P = \{\text{Seattle, Salt Lake City, Chicago, Dallas, San Francisco, Seattle}\}$

# Path Length and Cost

- *Path length*: the number of edges in the path
- *Path cost*: the sum of the costs of each edge



For path  $P$ :  
 $\text{length}(P) = 5$   
 $\text{cost}(P) = 11.5$

How would you ensure that  $\text{length}(p) = \text{cost}(p)$  for all  $p$ ?

# Simple Paths and Cycles

A *simple path* repeats no vertices (except that the first can also be the last):

$P = \{\text{Seattle, Salt Lake City, San Francisco, Dallas}\}$

$P = \{\text{Seattle, Salt Lake City, Dallas, San Francisco, Seattle}\}$

A *cycle* is a path that starts and ends at the same node:

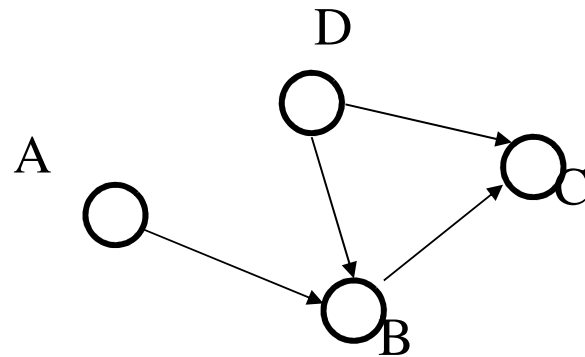
$P = \{\text{Seattle, Salt Lake City, Dallas, San Francisco, Seattle}\}$

$P = \{\text{Seattle, Salt Lake City, Seattle, San Francisco, Seattle}\}$

A *simple cycle* is a cycle that is also a simple path (in undirected graphs, no edge can be repeated).

# Paths/Cycles in Directed Graphs

Consider this directed graph:

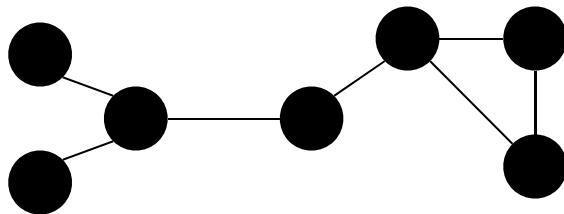


Is there a path from A to D?

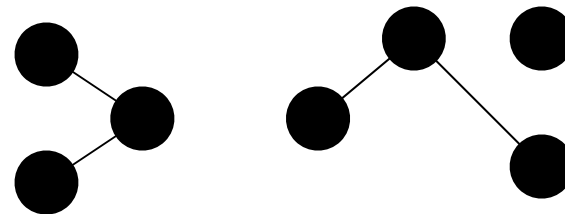
Does the graph contain any cycles?

# Undirected Graph Connectivity

Undirected graphs are *connected* if there is a path between any two vertices:

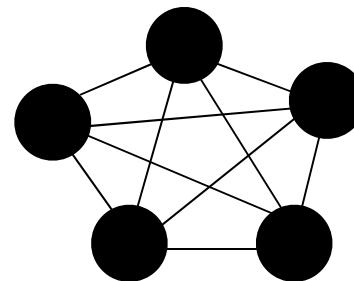


Connected graph



Disconnected graph

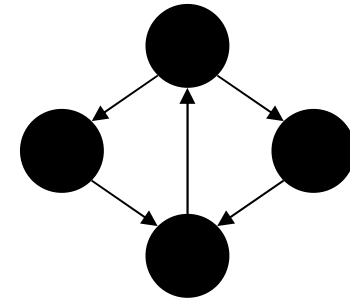
A *complete undirected* graph has an edge between every pair of vertices:



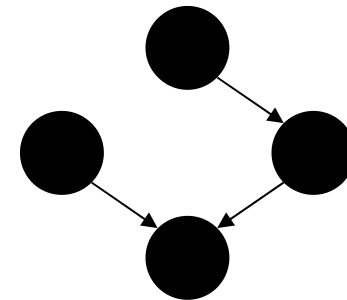
(Complete = *fully connected*)

# Directed Graph Connectivity

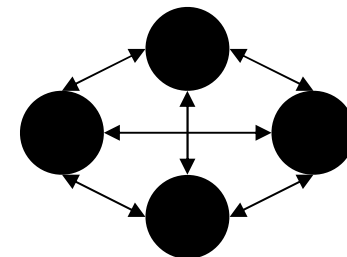
Directed graphs are *strongly connected* if there is a path from any one vertex to any other.



Directed graphs are *weakly connected* if there is a path between any two vertices, *ignoring direction*.



A *complete directed* graph has a directed edge between every pair of vertices. (Again, complete = *fully connected*.)

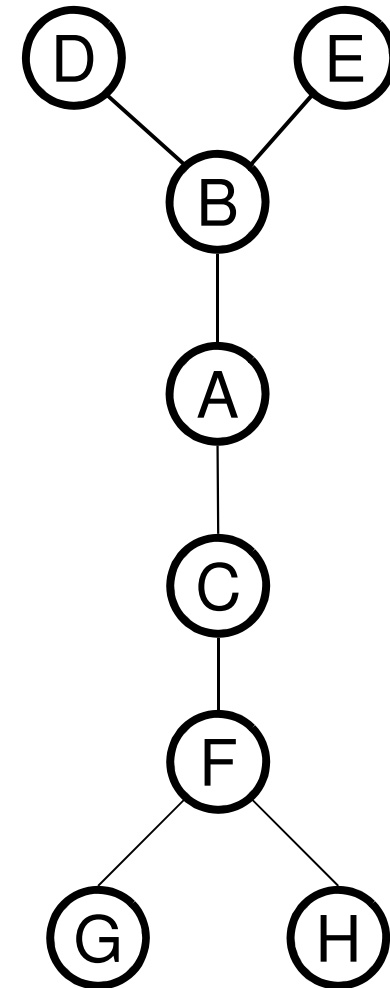


# Trees as Graphs

A tree is a graph that is:

- *undirected*
- *acyclic*
- *connected*

Hey, that doesn't look like a tree!

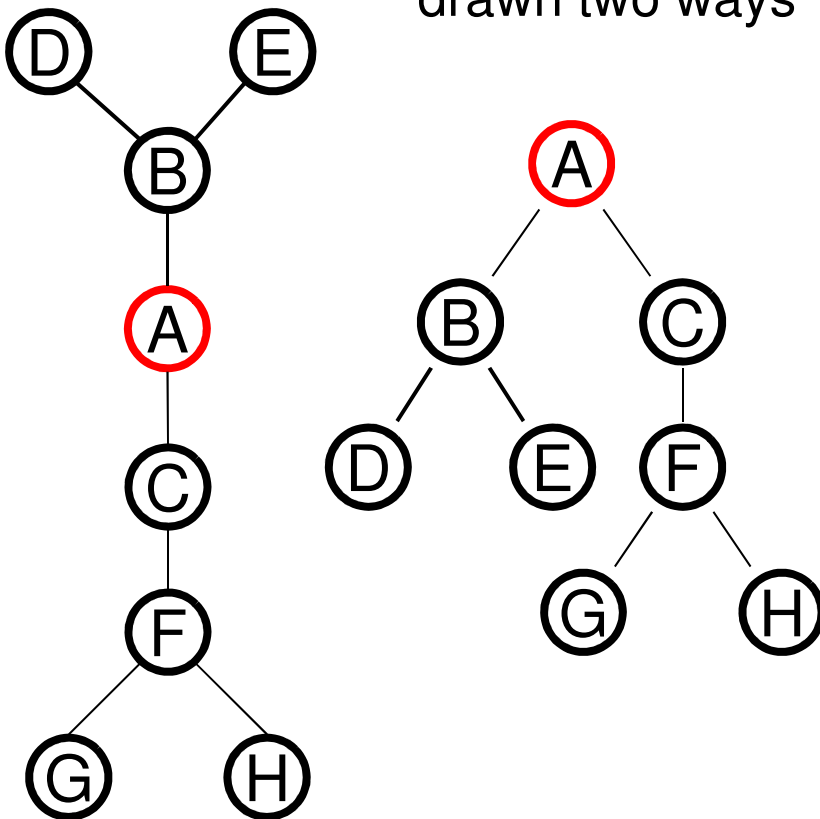


# Rooted Trees

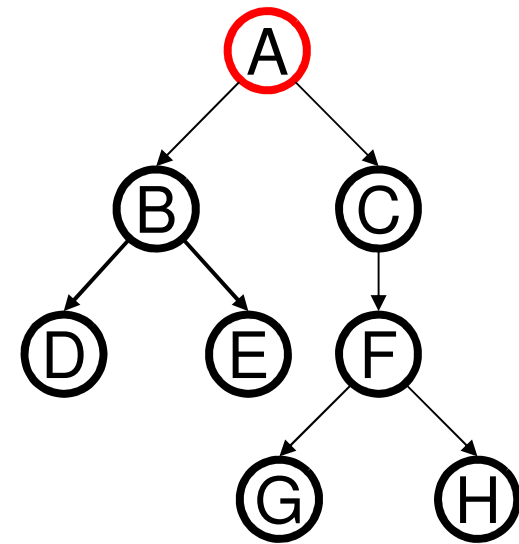
We are more accustomed to:

- Rooted trees (a tree node that is “special”)
- Directed edges from parents to children (parent closer to root).

A rooted tree (root indicated in red)  
drawn two ways



Rooted tree with directed  
edges from parents to children.



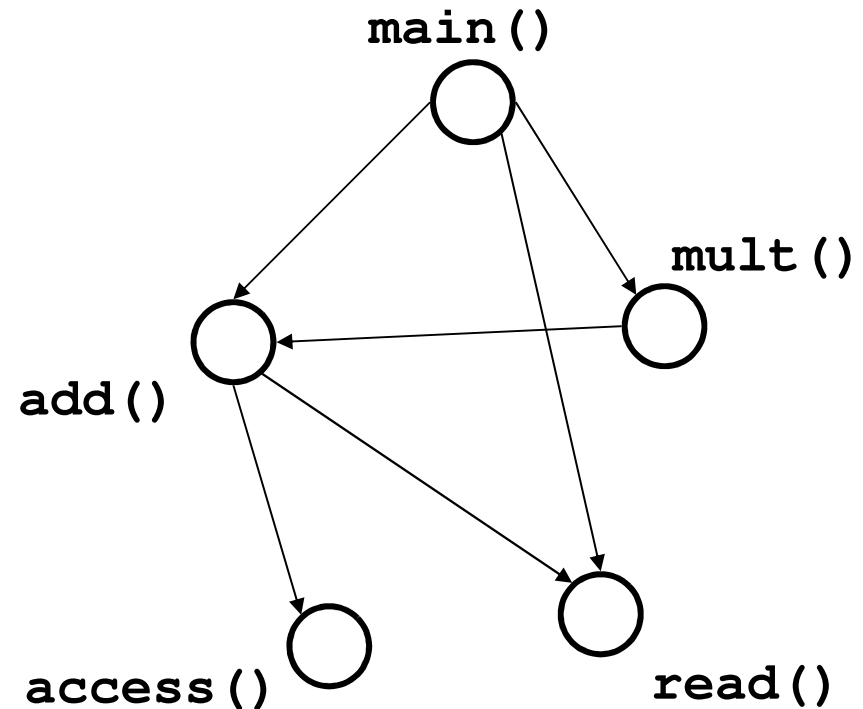
Characteristics of this one?



# Directed Acyclic Graphs (DAGs)

**DAGs** are directed graphs with no (directed) cycles.

*Aside: If program call-graph is a DAG, then all procedure calls can be in-lined*



# $|E|$ and $|V|$

How many edges  $|E|$  in a graph with  $|V|$  vertices?

What if the graph is directed?

What if it is undirected and connected?

Can the following bounds be simplified?

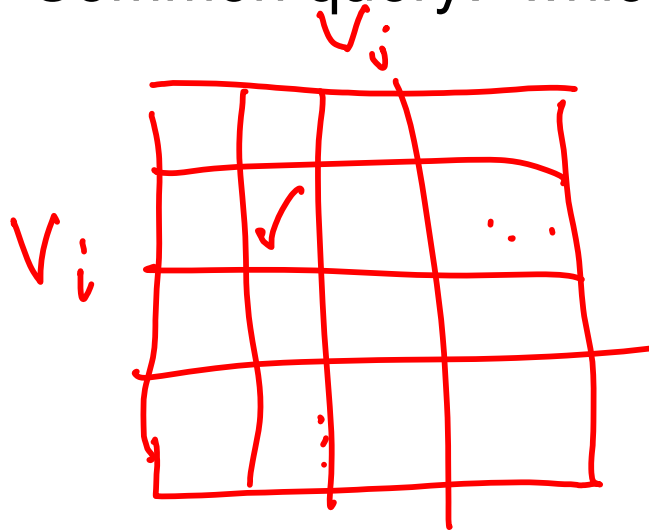
- Arbitrary graph:  $O(|E| + |V|)$
- Arbitrary graph:  $O(|E| + |V|^2)$
- Undirected, connected:  $O(|E| \log|V| + |V| \log|V|)$

Some (semi-standard) terminology:

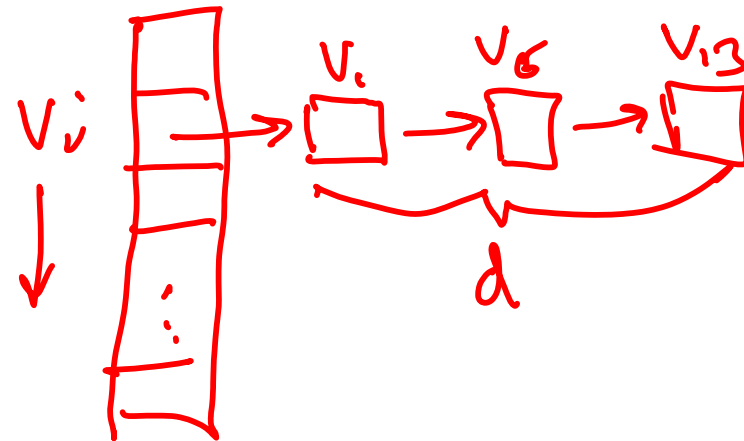
- A graph is *sparse* if it has  $O(|V|)$  edges (upper bound).
- A graph is *dense* if it has  $\Theta(|V|^2)$  edges.

# What's the data structure?

- Common query: which edges are adjacent to a vertex



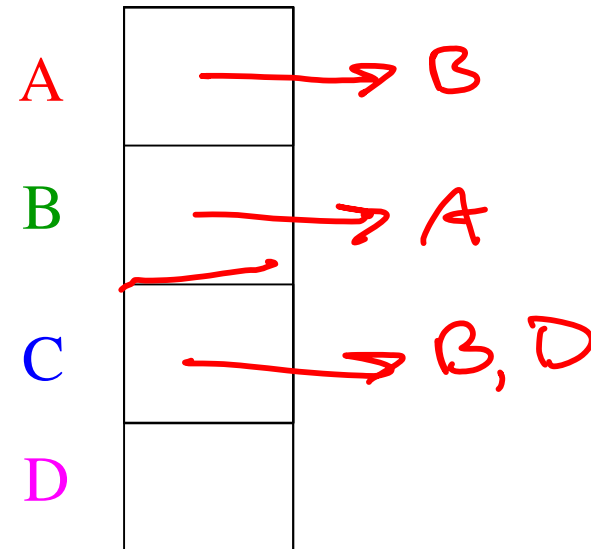
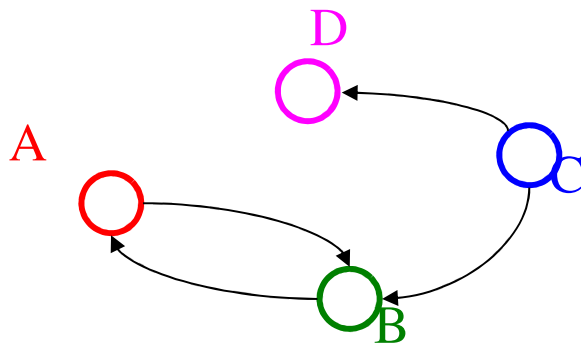
$$O(|V|)$$



$$O(|d|)$$

# Representation 2: Adjacency List

A list (array) of length  $|V|$  in which each entry stores a list (linked list) of all adjacent vertices



*Runtimes:*

*Iterate over vertices?*  $O(|V|)$

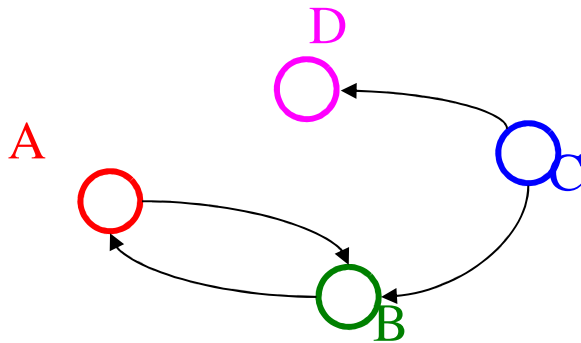
*Iterate over edges?*  $O(|V| + |E|)$  *Space requirements?*  $|V| + |E|$

*Iterate edges adj. to vertex?*  $O(d)$  *Best for what kinds of graphs?*

*Existence of edge?*  $O(d)$   $\uparrow$  length of linked list

# Representation 1: Adjacency Matrix

A  $|V| \times |V|$  matrix  $M$  in which an element  $M[u, v]$  is true if and only if there is an edge from  $u$  to  $v$



	A	B	C	D
A		X		
B	X			
C		X		X
D				

*Runtimes:*

*Iterate over vertices?*  $O(|V|)$

*Iterate over edges?*  $O(|V|^2)$

*Iterate edges adj. to vertex?*  $O(|V|)$

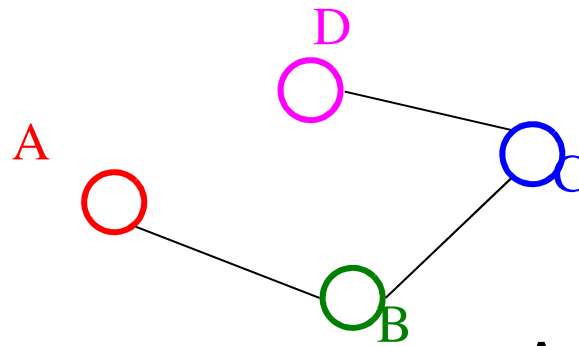
*Existence of edge?*  $O(1)$

*Space requirements?*  $|V|^2$

*Best for what kinds of graphs?* *dense*

# Representing Undirected Graphs

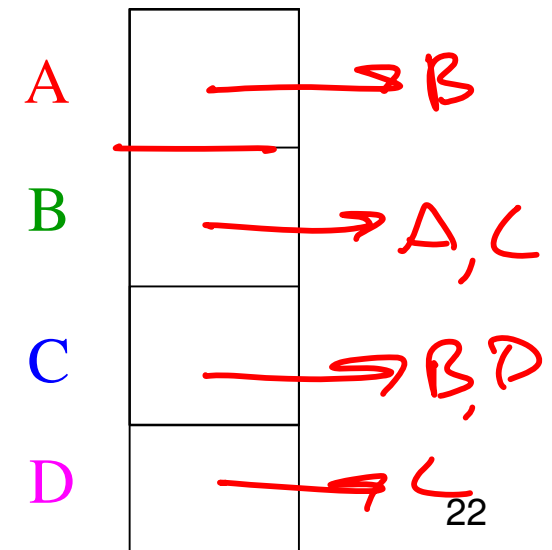
What do these reps look like for an undirected graph?



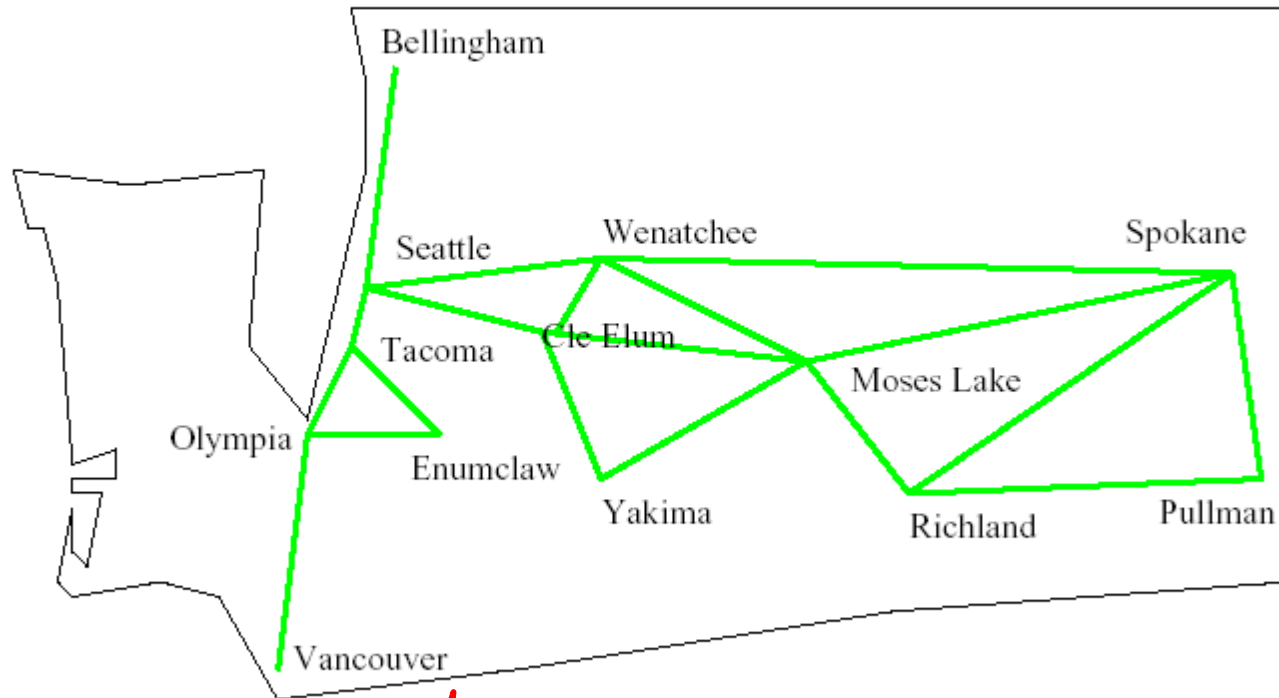
Adjacency matrix:

	A	B	C	D
A		X		
B	X		X	
C		X		X
D			X	

Adjacency list:



# Some Applications: Moving Around Washington



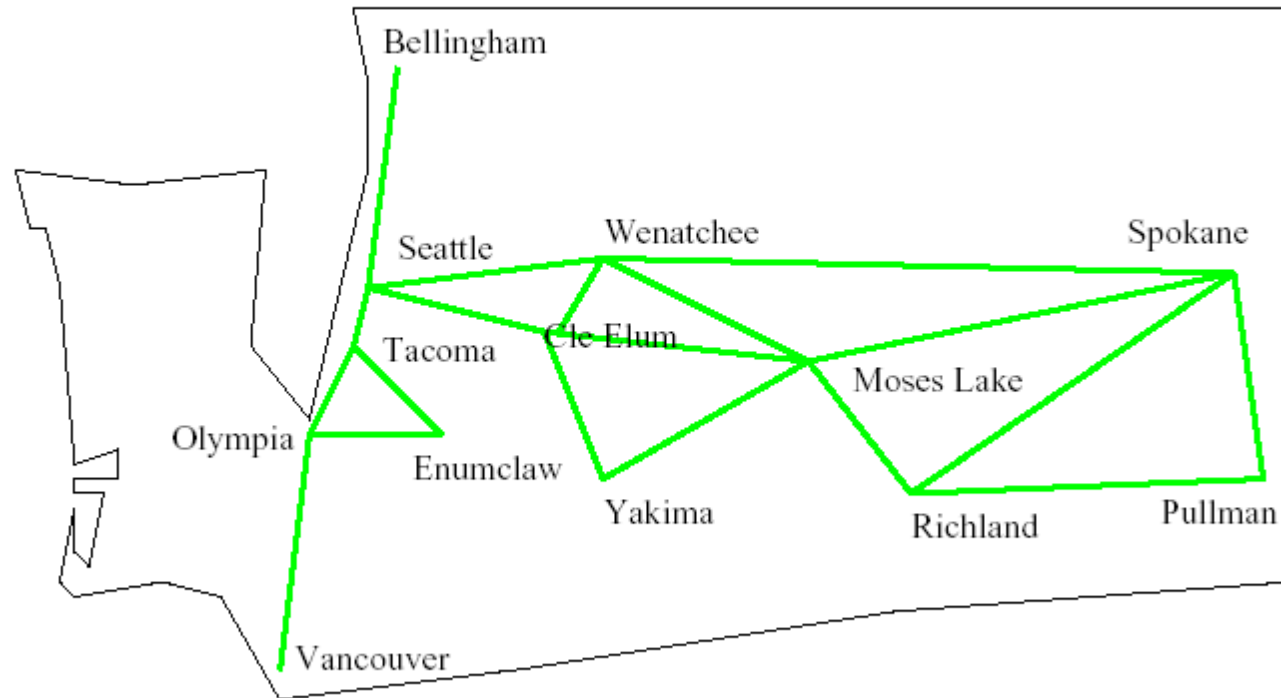
*distance*

What's the *shortest route* to from Seattle to Pullman?

Edge labels: *distance*

*weights*  
*cost*

# Some Applications: Moving Around Washington

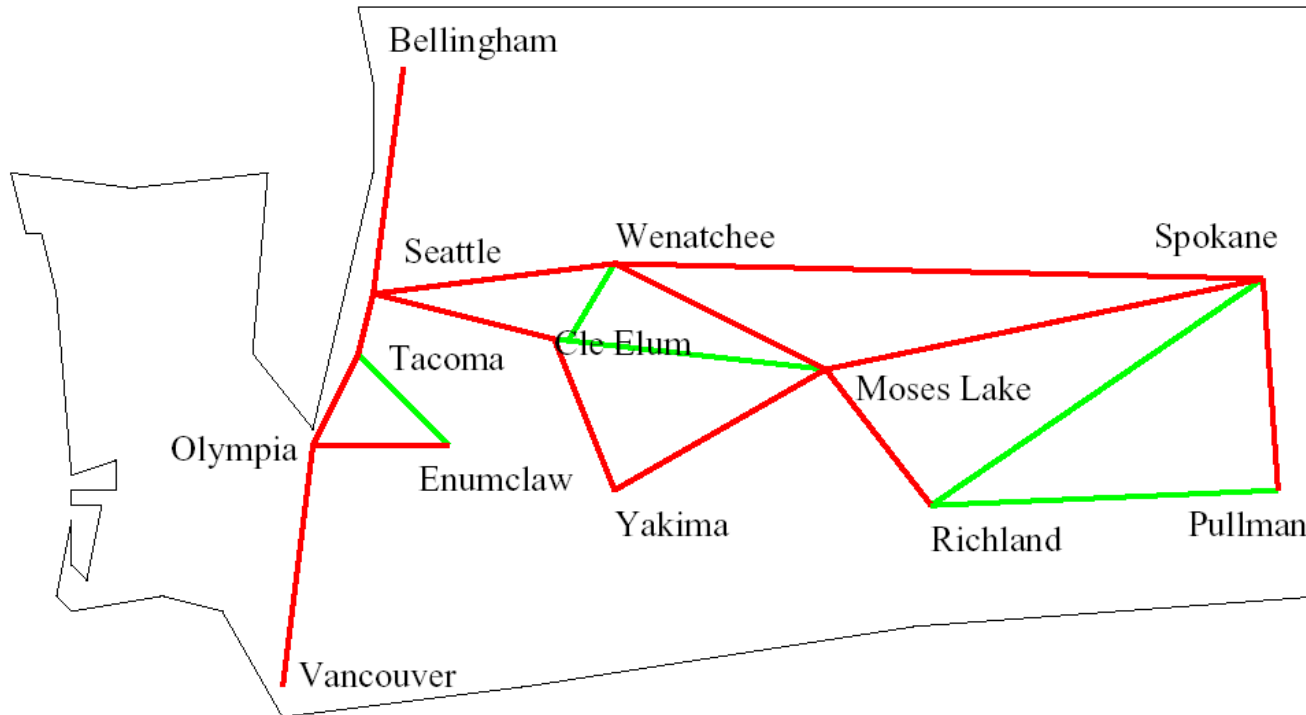


What's the *quickest* way to get from Seattle to Pullman?

Edge labels: *time*

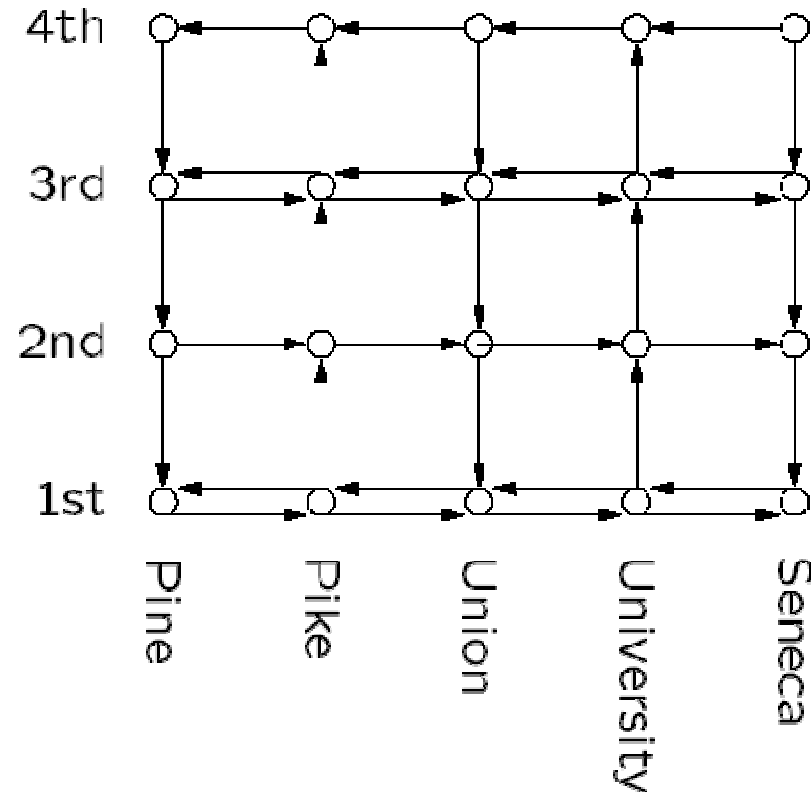


# Some Applications: Reliability of Communication



If Wenatchee's phone exchange *goes down*,  
can Seattle still talk to Pullman?

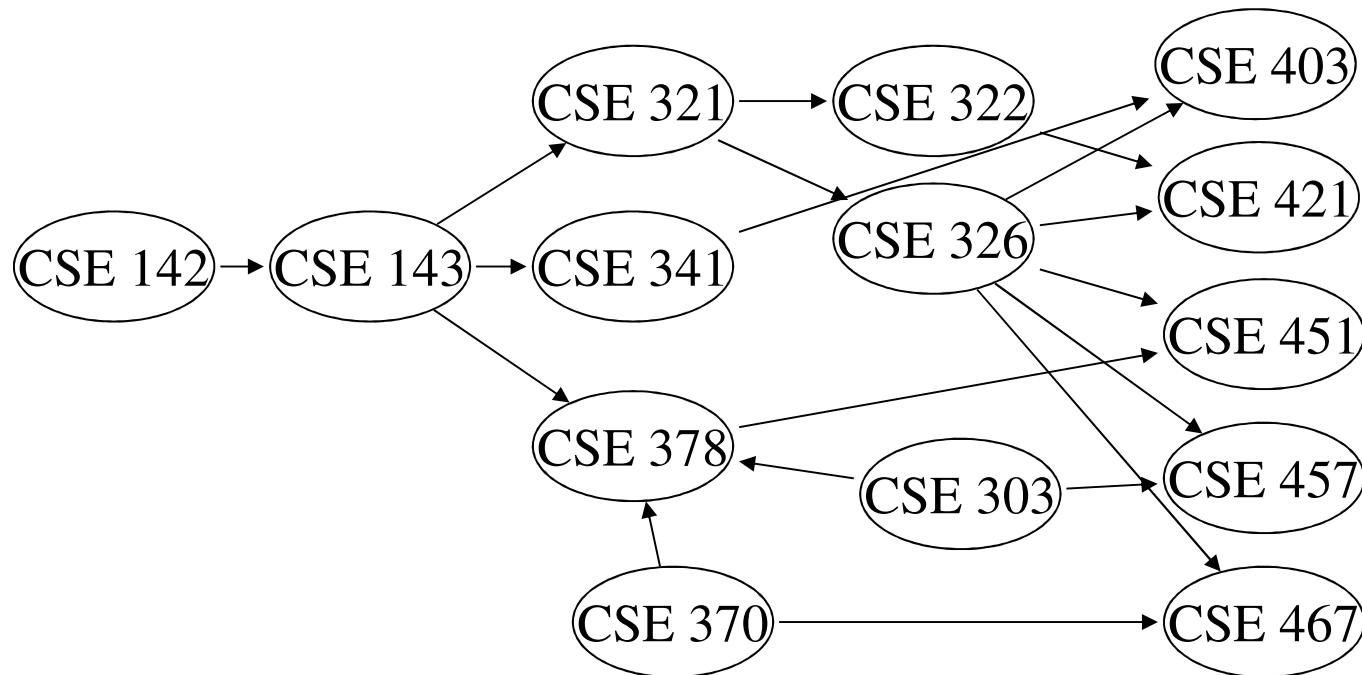
# Some Applications: Bus Routes in Downtown Seattle



If we're at 3<sup>rd</sup> and Pine, how can we get to  
1<sup>st</sup> and University using Metro?  
How about 4<sup>th</sup> and Seneca?

# Application: Topological Sort

Given a graph,  $G = (V, E)$ , output all the vertices in  $V$  sorted so that no vertex is output before any other vertex with an edge to it.



*What kind of input graph is allowed?* DAG

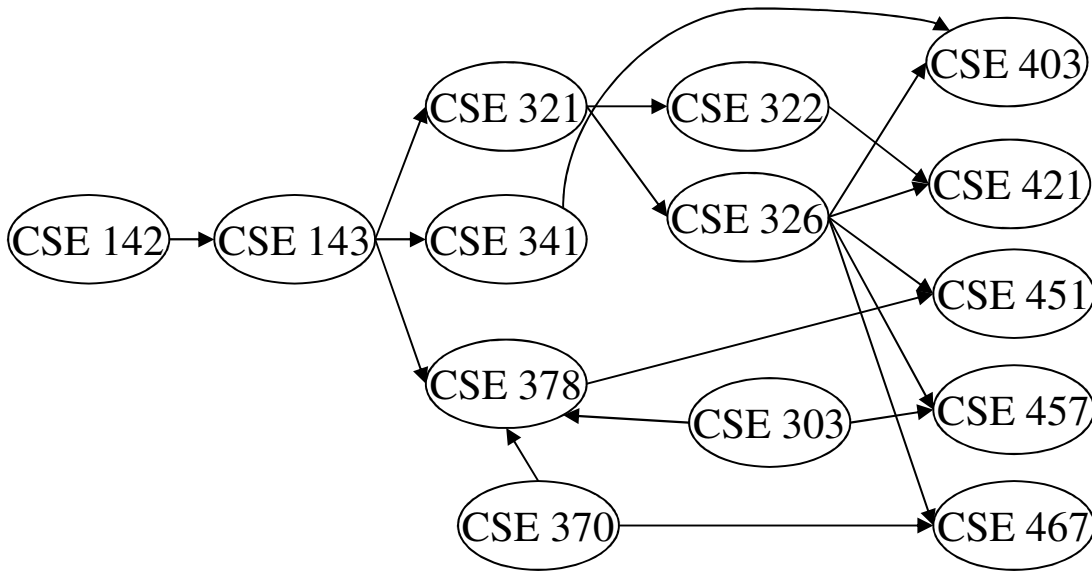
*Is the output unique?* No <sup>27</sup>



# Topological Sort: Take One

1. Label each vertex with its *in-degree* (# inbound edges)
2. **While** there are vertices remaining:
  - a. Choose a vertex  $v$  of *in-degree zero*; output  $v$
  - b. Reduce the in-degree of all vertices adjacent to  $v$
  - c. Remove  $v$  from the list of vertices

*Runtime:*



142, 143, 321, 341, 370, 322, 326,  
303, 370, 467, 457, 451, 421, 403

~~142 0~~  
~~143 10~~  
~~321 10~~  
~~341 10~~  
~~378 3210~~  
~~370 0~~  
~~322 10~~  
~~326 10~~  
~~303 0~~  
~~403 210~~  
~~421 210~~  
~~451 210~~  
~~457 210~~  
~~467 210~~

```
void Graph::topsort () {
```

```
    Vertex v, w;
```

```
    labelEachVertexWithItsInDegree ();
```

```
    for (int counter=0; counter < NUM_VERTICES; counter++) {
```

```
        v = findNewVertexOfDegreeZero ();
```

```
        v.topologicalNum = counter;
```

```
        for each w adjacent to v
```

```
            w.indegree--;
```

```
    }
```

```
}
```

$O(E) + O(V^2)$  ← AM

$O(V) + O(E)$  ← AL with incoming

$O(V^2)$   
over course of entire program

$O(|E|)$

total =  ~~$O(V^2)$~~   $O(V^2)$



# Topological Sort: Take Two

1. Label each vertex with its in-degree
2. Initialize a queue  $Q$  to contain all in-degree zero vertices
3. While  $Q$  not empty
  - a.  $v = Q.dequeue$ ; output  $v$
  - b. Reduce the in-degree of all vertices adjacent to  $v$
  - c. If new in-degree of any such vertex  $u$  is zero  
 $Q.enqueue(u)$

Note: could use a stack, list, set, box, ... instead of a queue

*Runtime:*

```
void Graph::topsort() {  
    Queue q(NUM_VERTICES);  
    int counter = 0;  
    Vertex v, w;  
    labelEachVertexWithItsIn-degree();
```

```
    q.makeEmpty();  
    for each vertex v  
        if (v.indegree == 0)  
            q.enqueue(v);
```

intialize the  
queue

```
    while (!q.isEmpty()) {  
        v = q.dequeue();  
        v.topologicalNum = ++counter;  
        for each w adjacent to v  
            if (--w.indegree == 0)  
                q.enqueue(w);  
    }  
}
```

get a vertex with  
indegree 0

insert new  
eligible  
vertices