

# CSE 332: Data Structures

## Priority Queues – Binary Heaps

Richard Anderson, Steve Seitz

Winter 2014

# Administrative

- P1A due tonight (Monday) by 11:59pm
  - via catalyst
- HW1 due beginning of class Wednesday
- Reading for this week: Chapter 6.1-6.5

# Recall Queues

- FIFO: First-In, First-Out
  - Print jobs
  - File serving
  - Phone calls and operators
  - Lines at the Department of Licensing...

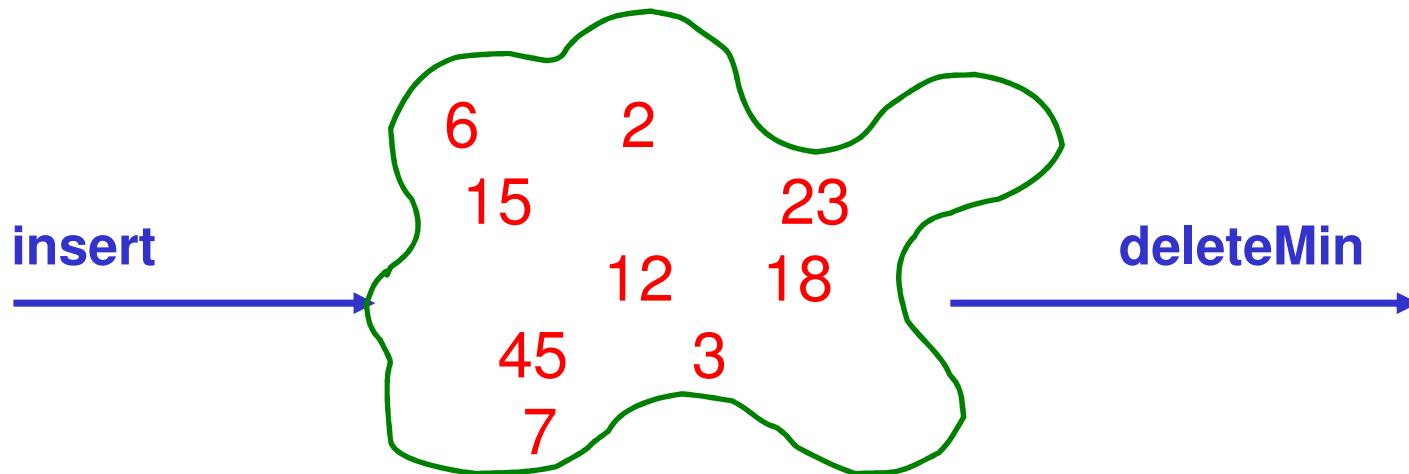
# Priority Queues

Prioritize who goes first – a **priority queue**:

- treat ER patients in order of **severity**
- route network packets in order of **urgency**
- operating system can favor jobs of shorter **duration** or those tagged as having higher **importance**
- Greedy optimization: “**best first**” problem solving

# Priority Queue ADT

- Need a new ADT
- Operations: Insert an Item,  
Remove the “Best” Item



# Priority Queue ADT

1. **PQueue data** : collection of data with **priority**

2. **PQueue operations**

– insert

– deleteMin

(also: create, destroy, is\_empty)

3. **PQueue property**: if  $x$  has **lower** **priority** than  $y$ ,  $x$  will be deleted before  $y$

# Potential implementations

	insert	deleteMin
Unsorted list (Array)	$O(1)$ or $O(n)$ if full	$O(n)$
Unsorted list (Linked-List)	$O(1)$	$O(n)$
Sorted list (Array)	$O(\log n)$ to find $O(n)$ to shift $\Rightarrow O(n)$	$O(1)$ to find no shift if reversed
Sorted list (Linked-List)	<del><math>O(\log n)</math></del> $O(n)$	$O(1)$
Binary Search Tree (BST)	$O(n)$	<del><math>O(\log n)</math></del> $O(n)$

B

# Binary Heap data structure

- **binary heap** (a kind of binary tree) for priority queues:
  - $O(\log n)$  **worst case** for both insert and deleteMin
  - $O(1)$  **average** insert
- It's optimized for priority queues. Lousy for other types of operations (e.g., searching, sorting)



# Tree Review

*root(T):* A

*leaves(T):* D-F, I-N

*children(B):* D-F

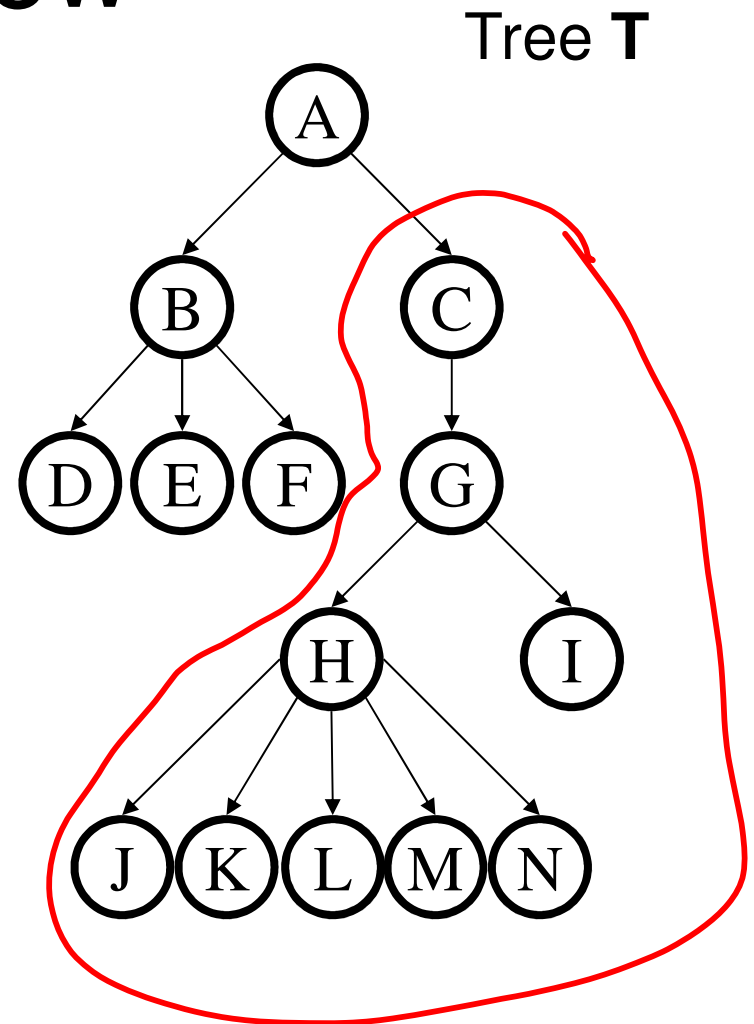
*parent(H):* G

*siblings(E):* D,F

*ancestors(F):* B, A

*descendants(G):* H-N

*subtree(C):*



# More Tree Terminology

$depth(B)$ : 1  
#edges on path from root to self

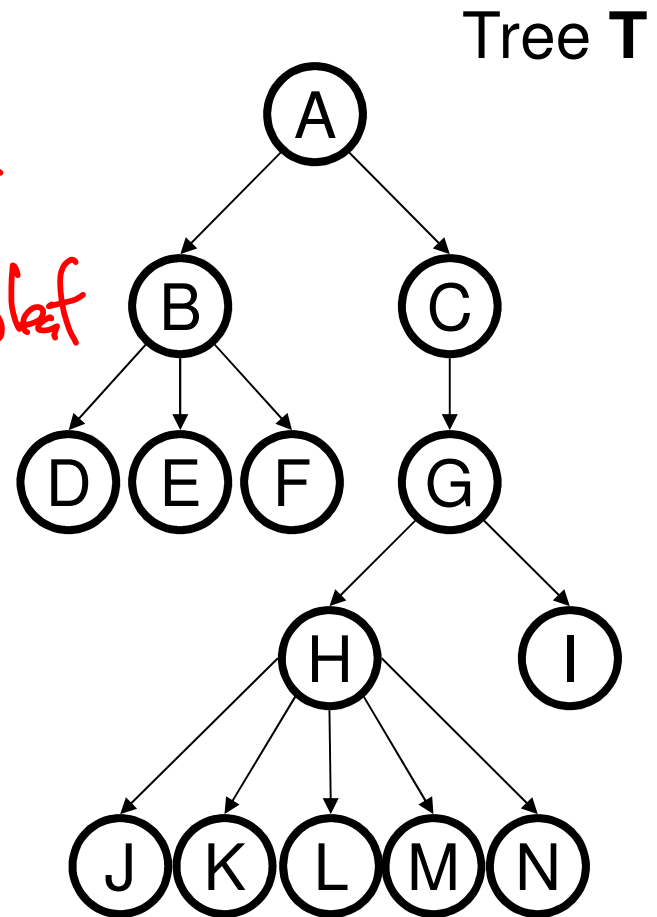
$height(G)$ : 2  
#edges on the longest path from self to leaf

$height(T)$ : 4  
=  $height(A)$

$degree(B)$ : 3  
#children

branching factor(T): 5  
max degree of any node

$n$ -ary tree:  
tree with branching factor  $n$



# Binary Heap Properties

A binary heap is a binary tree with two important properties that make it a good choice for priority queues:

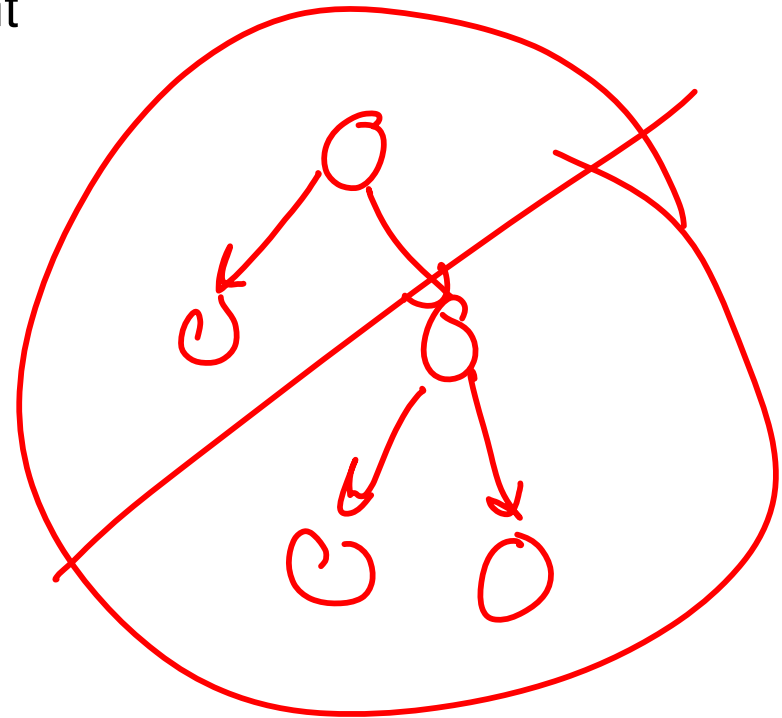
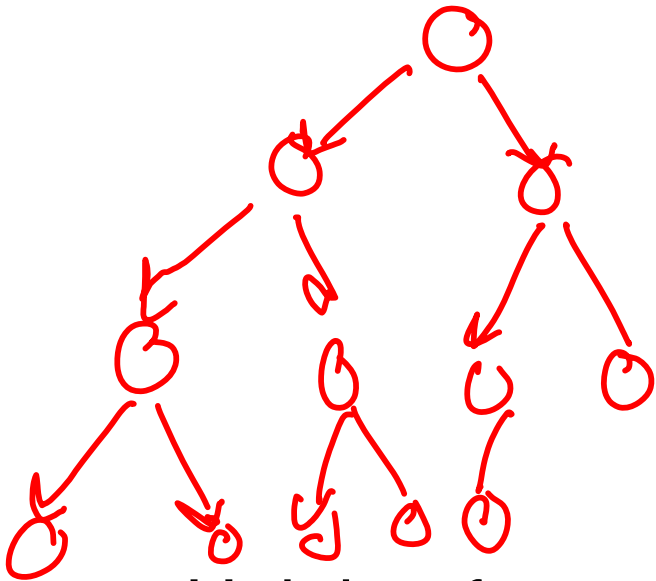
1. **Completeness** (Structure Prop)
2. **Heap Order**

**Note:** we will sometimes refer to a binary heap as simply a “heap”.

# Completeness Property

- A binary heap is a **complete** binary tree:
  - a binary tree with all levels full, except possibly the bottom level, which is filled left to right

## Examples:

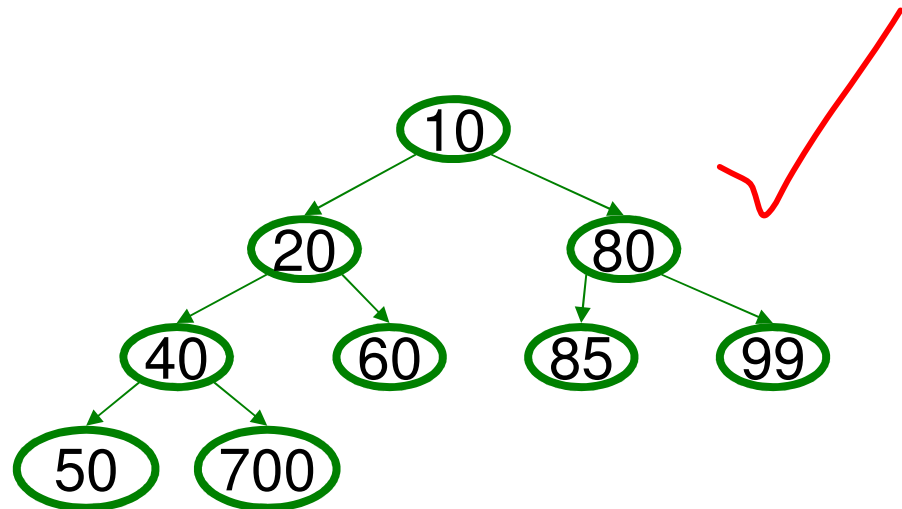
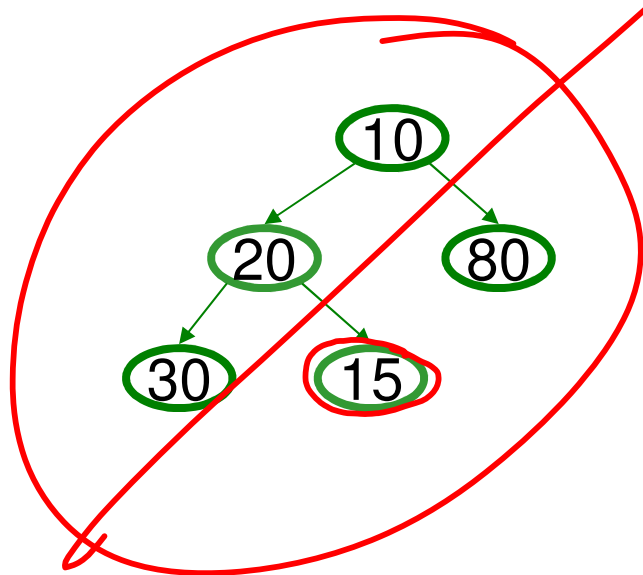


Height of a **complete** binary tree with  $n$  nodes?

$$\lceil \log_2 n \rceil$$

# Heap Order Property

**Heap order property**: For every non-root node  $X$ , the value in the parent of  $X$  is less than (or equal to) the value in  $X$ .



which of these is a heap?

# Heap Operations

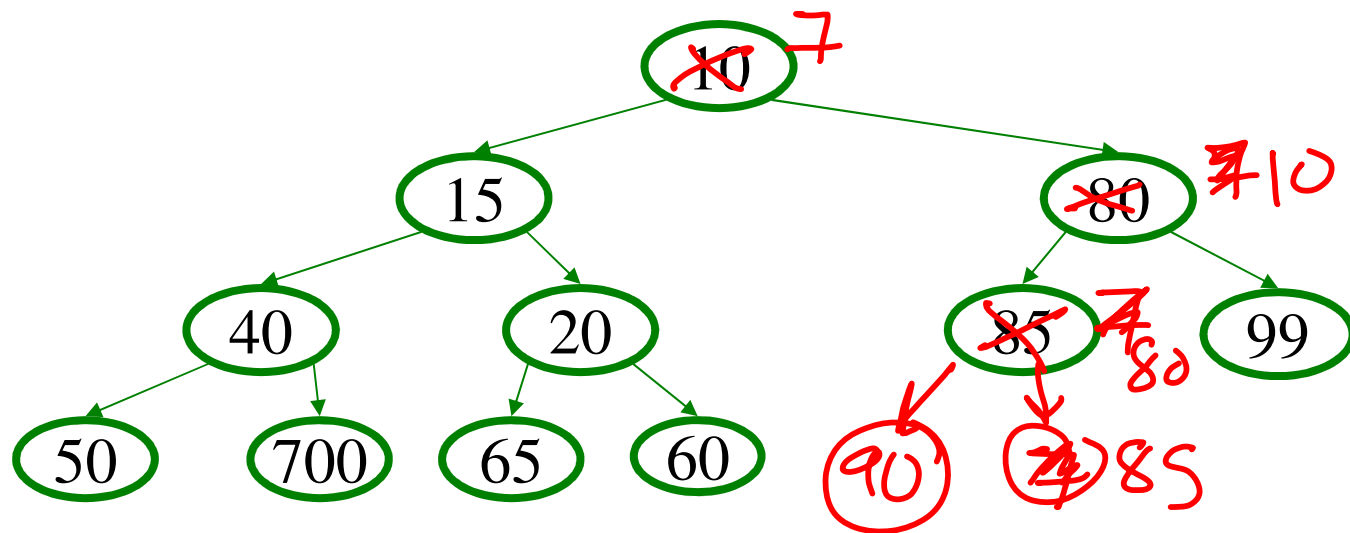
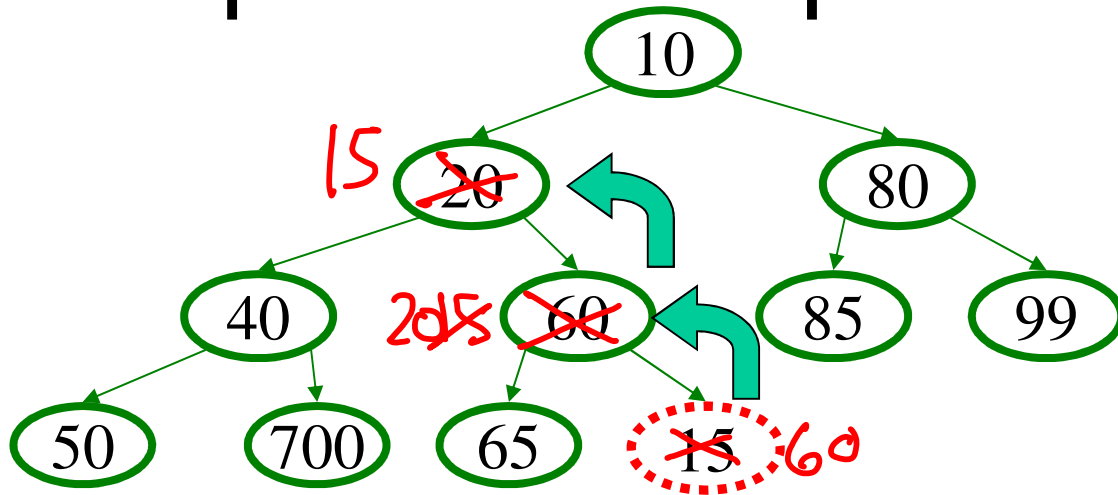
- Main ops: insert, deleteMin
- Key is to maintain
  - Completeness
  - Heap Order
- Basic idea is to propagate changes up/down the tree, fixing order as we go

# Heap – insert(val)

Basic Idea:

1. Put val at last leaf position
2. Percolate up by repeatedly exchanging node with parent as long as needed

# Insert: percolate up





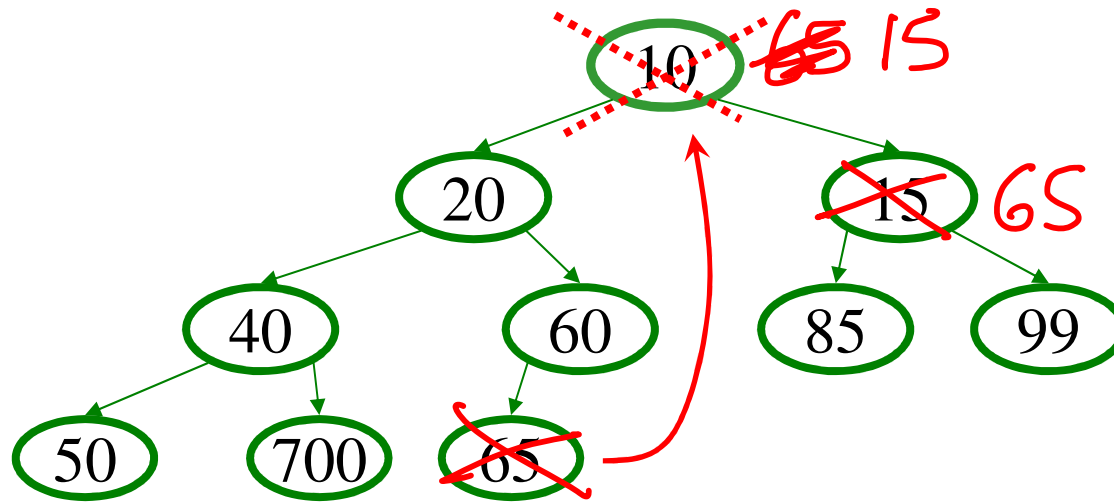
# Heap – deleteMin

Basic Idea:

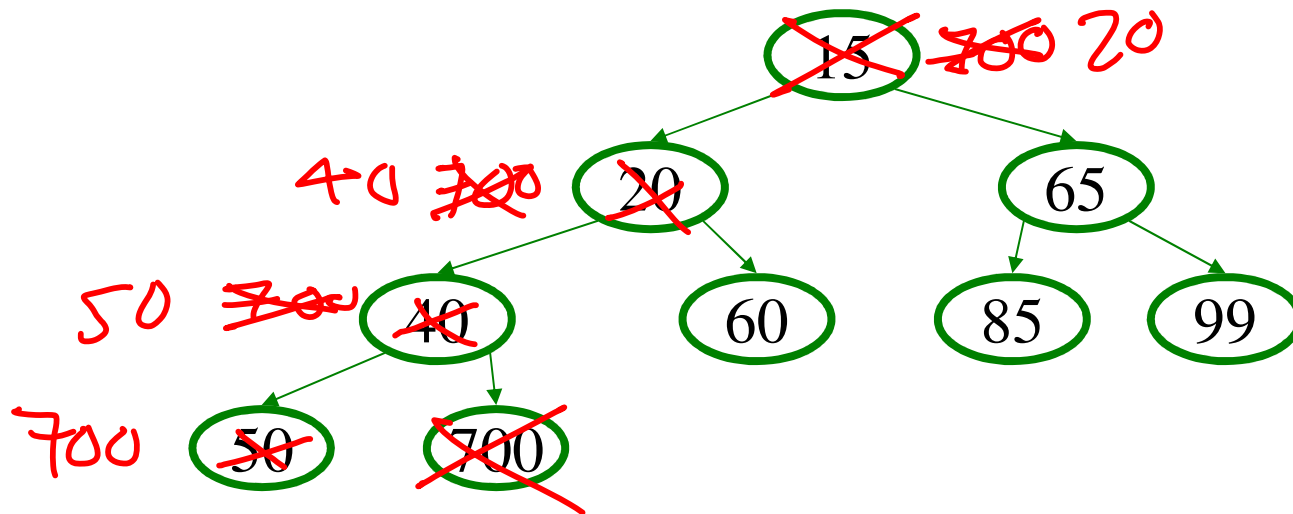
1. Remove min element
2. Put “last” leaf node value at root
3. Find smallest child of node
4. Swap node with its smallest child if needed.
5. Repeat steps 3 & 4 until no swaps needed.

$O(\log n)$

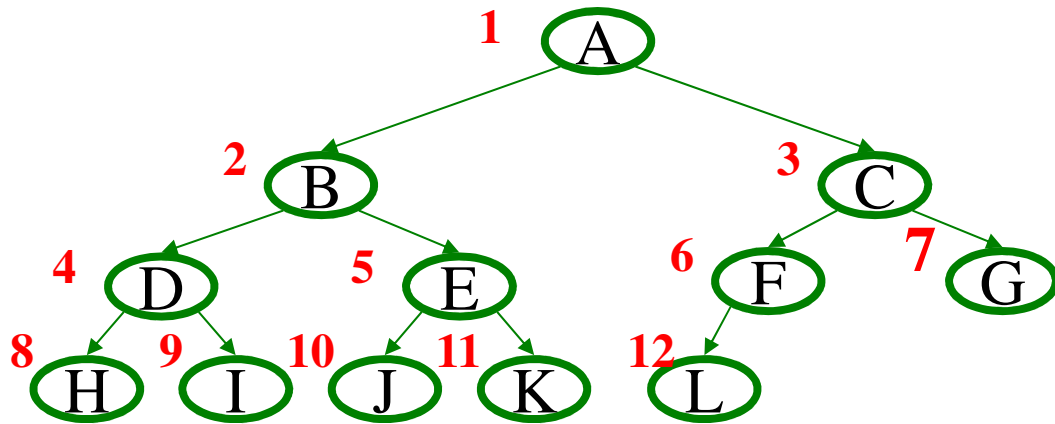
# DeleteMin: percolate down



# DeleteMin: percolate down



# Representing Complete Binary Trees in an Array



From node **i**:

left child:  $2i$   
right child:  $2i+1$   
parent:  $\lfloor i/2 \rfloor$

	A	B	C	D	E	F	G	H	I	J	K	L	
0	1	2	3	4	5	6	7	8	9	10	11	12	13

# Why use an array?

locality  
easy to access any element (leaves) <sup>end</sup>  
more memory efficient?

# DeleteMin Code

```
Object deleteMin() {
    assert(!isEmpty());
    returnVal = Heap[1];
    size--;
    newPos =
        percolateDown(1,
            Heap[size + 1]);
    Heap[newPos] =
        Heap[size + 1];
    return returnVal;
}
```

*runtime:*

(Java code in book)

```
int percolateDown(int hole,
                  Object val) {
    while (2*hole <= size) {
        left = 2*hole;
        right = left + 1;
        if (right <= size &&
            Heap[right] < Heap[left])
            target = right;
        else
            target = left;

        if (Heap[target] < val) {
            Heap[hole] = Heap[target];
            hole = target;
        }
        else
            break;
    }
    return hole;
}
```

# Insert Code

```
void insert(Object o) {
    assert(!isFull());
    size++;
    newPos =
        percolateUp(size, o);
    Heap[newPos] = o;
}

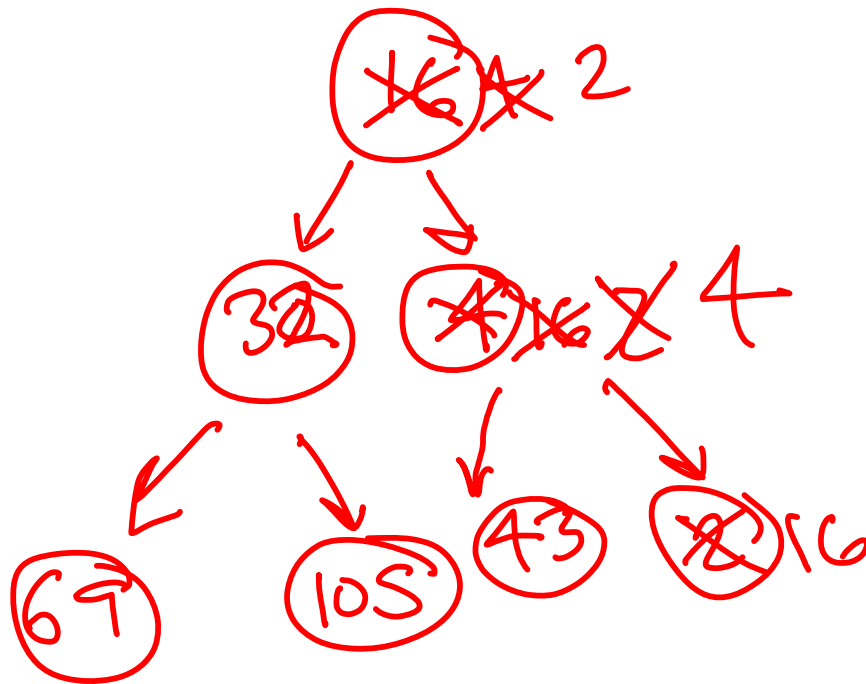
int percolateUp(int hole,
                Object val) {
    while (hole > 1 &&
           val < Heap[hole/2])
        Heap[hole] = Heap[hole/2];
        hole /= 2;
    }
    return hole;
}
```

*runtime:*  $O(\log n)$

(Java code in book)

Insert: 16, 32, 4, 69, 105, 43, 2

	2	32	4	69	105	43	16	
0	1	2	3	4	5	6	7	8





# More Priority Queue Operations

## **decreaseKey(nodePtr, amount):**

given a pointer to a node in the queue, reduce its priority

Binary heap: change priority of node and percolate up

## **increaseKey(nodePtr, amount):**

given a pointer to a node in the queue, increase its priority

Binary heap: change priority of node and percolate down

**Why do we need a *pointer*? Why not simply data value?**  
*search  $O(n)$*

**Worst case running times?**

*$O(\log n)$*

# More Priority Queue Operations

## **remove(objPtr):**

given a pointer to an object in the queue, remove it

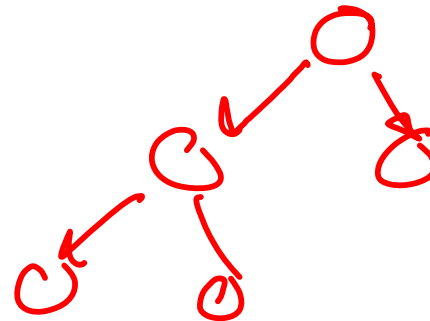
Binary heap: decrease (obj, Ptr,  $\infty$ ), delete min

## **findMax( ):**

Find the object with the highest value in the queue

Binary heap: largest leaf

**Worst case running times?**



# More Binary Heap Operations

## **expandHeap( ):**

If heap has used up array, copy to new, larger array.

- Running time:  $O(n)$

## **buildHeap(objList):**

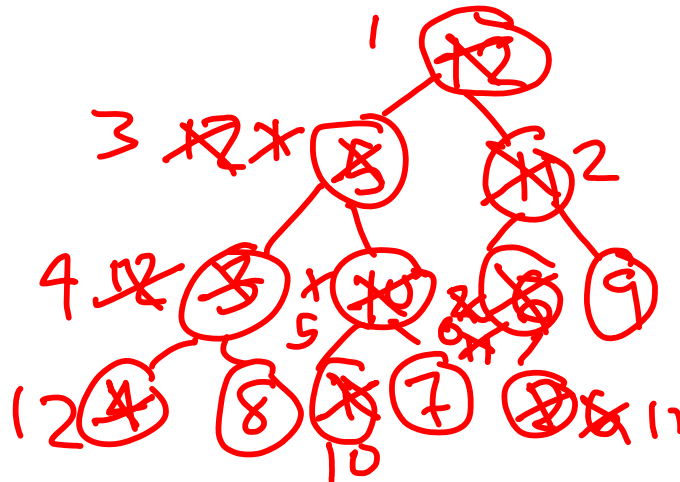
Given list of objects with priorities, fill the heap.

- Running time:  $O(n \log n)$

We do better with **buildHeap...**

# Building a Heap: ~~Take 1~~

12	5	11	3	10	6	9	4	8	1	7	2
----	---	----	---	----	---	---	---	---	---	---	---



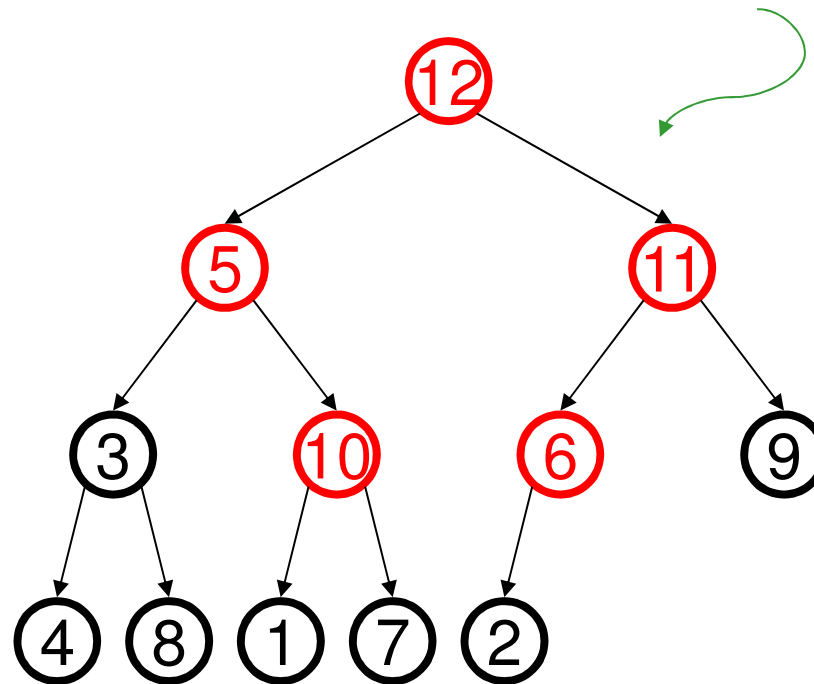
# BuildHeap: Floyd's Method

12	5	11	3	10	6	9	4	8	1	7	2
----	---	----	---	----	---	---	---	---	---	---	---

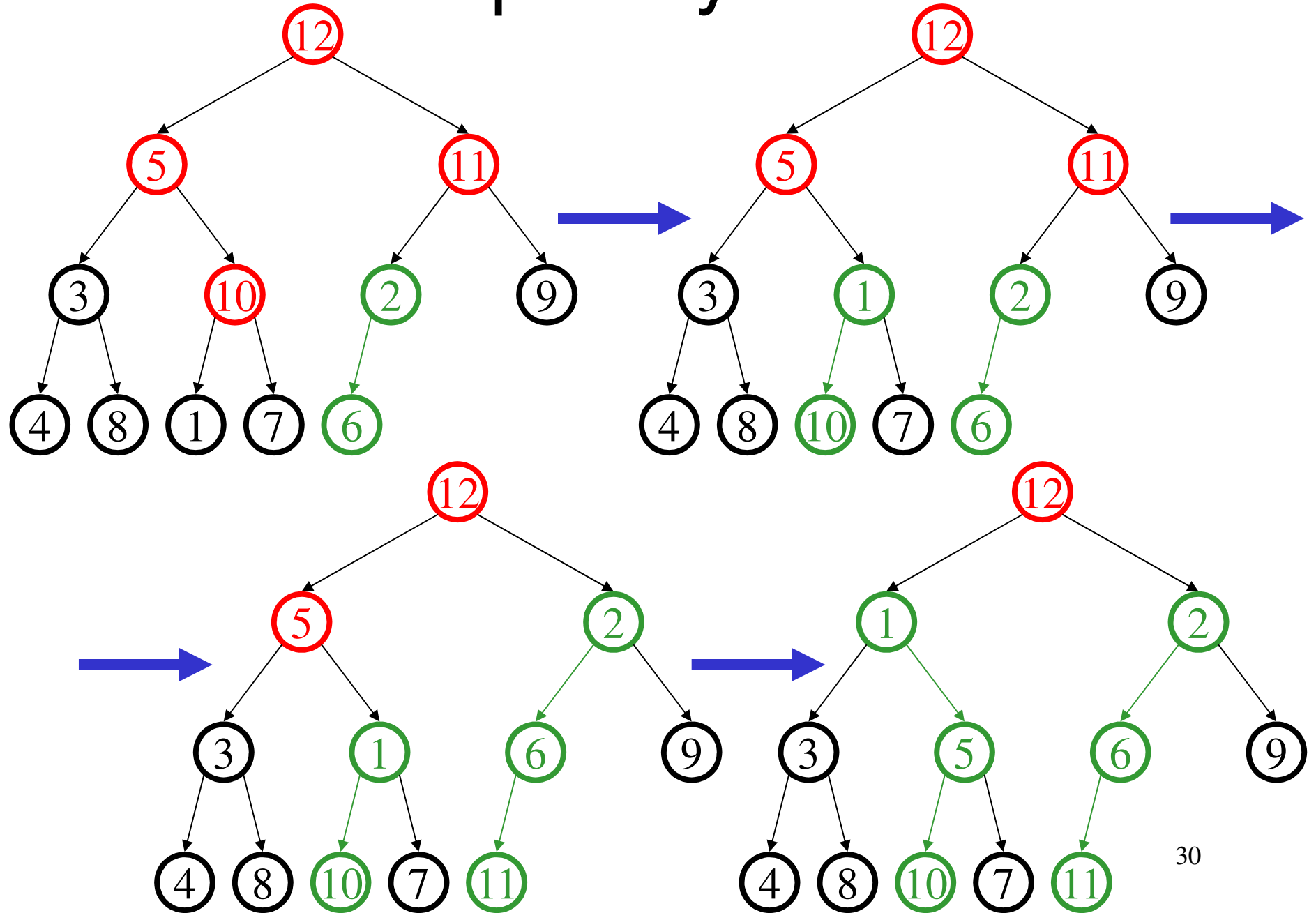
Add elements arbitrarily to form a complete tree.  
Pretend it's a heap and fix the heap-order property!

Red nodes need  
to percolate  
down

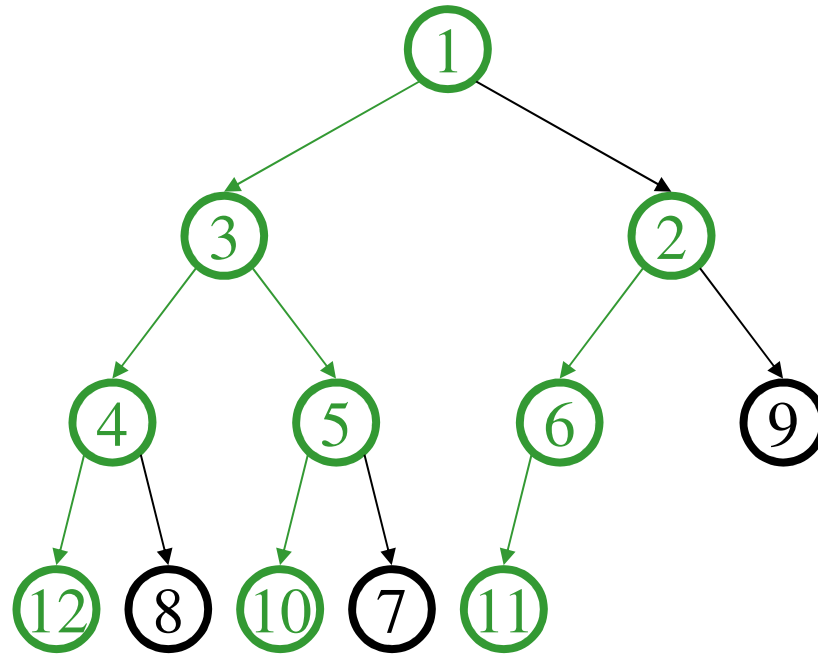
**Key idea:** fix red  
nodes from  
**bottom-up**



# BuildHeap: Floyd's Method



# Finally...



# Buildheap pseudocode

```
private void buildHeap() {  
    for ( int i = currentSize/2; i > 0; i-- )  
        percolateDown( i );  
}
```

*runtime:*



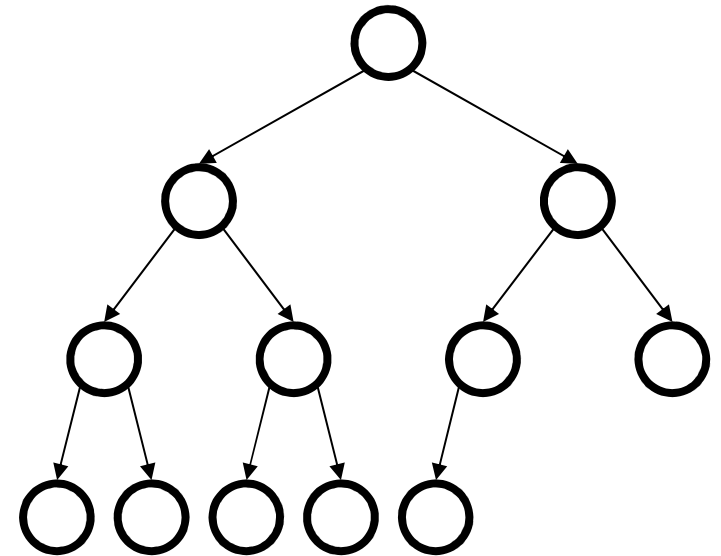
# Buildheap Analysis

$n/4$  nodes percolate at most 1 level

$n/8$  percolate at most 2 levels

$n/16$  percolate at most 3 levels

...



*runtime:*