



CSE332: Data Abstractions

Lecture 11: More Hashing

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Winter 2011

Announcements

- **Homework 3** – due NOW!
- **Project 2** – Phase A due next Wed Feb 2nd at 11pm
- (No homework due next Friday)
- **Midterm** – Monday Feb 7th during lecture
- **Homework 4** – not due until Friday Feb 11th at the BEGINNING of lecture

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Today

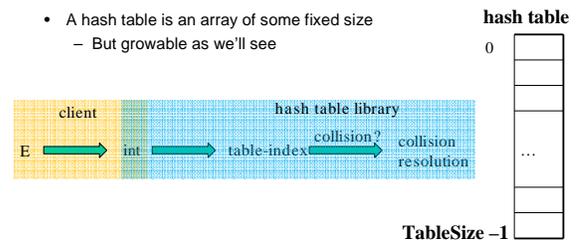
- Dictionaries
 - Hashing

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Hash Tables: Review

- Aim for constant-time (i.e., $O(1)$) **find**, **insert**, and **delete**
 - “On average” under some reasonable **assumptions**
- A hash table is an array of some fixed size
 - But growable as we’ll see



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Hashing Choices

1. Choose a Hash function
 2. Choose TableSize
 3. Choose a Collision Resolution Strategy from these:
 - Separate Chaining
 - Open Addressing
 - Linear Probing
 - Quadratic Probing
 - Double Hashing
- Other issues to consider:
 - Deletion?
 - What to do when the hash table gets “too full”?

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An Alternative to Separate Chaining: Open Addressing

- Why not use up the empty space in the table?
- Store directly in the array cell (no linked list)
- How to deal with collisions?
- If $h(\text{key})$ is already full,
 - try $h(\text{key}) + 1 \ \% \ \text{TableSize}$. If full,
 - try $h(\text{key}) + 2 \ \% \ \text{TableSize}$. If full,
 - try $h(\text{key}) + 3 \ \% \ \text{TableSize}$. If full...
- Example: insert 38, 19, 8, 109, 10

0	/
1	/
2	/
3	/
4	/
5	/
6	/
7	/
8	38
9	/

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An Alternative to Separate Chaining: Open Addressing

- Another simple idea: If $h(\text{key})$ is already full,
 - try $(h(\text{key}) + 1) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 2) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 3) \% \text{TableSize}$. If full...

- Example: insert 38, 19, 8, 109, 10

0	/
1	/
2	/
3	/
4	/
5	/
6	/
7	/
8	38
9	19

An Alternative to Separate Chaining: Open Addressing

- Another simple idea: If $h(\text{key})$ is already full,
 - try $(h(\text{key}) + 1) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 2) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 3) \% \text{TableSize}$. If full...

- Example: insert 38, 19, 8, 109, 10

0	8
1	/
2	/
3	/
4	/
5	/
6	/
7	/
8	38
9	19

An Alternative to Separate Chaining: Open Addressing

- Another simple idea: If $h(\text{key})$ is already full,
 - try $(h(\text{key}) + 1) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 2) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 3) \% \text{TableSize}$. If full...

- Example: insert 38, 19, 8, 109, 10

0	8
1	109
2	/
3	/
4	/
5	/
6	/
7	/
8	38
9	19

An Alternative to Separate Chaining: Open Addressing

- Another simple idea: If $h(\text{key})$ is already full,
 - try $(h(\text{key}) + 1) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 2) \% \text{TableSize}$. If full,
 - try $(h(\text{key}) + 3) \% \text{TableSize}$. If full...

- Example: insert 38, 19, 8, 109, 10

0	8
1	109
2	10
3	/
4	/
5	/
6	/
7	/
8	38
9	19

Open addressing

This is *one example* of open addressing

- More generally, we just need to describe *where to check next when one attempt fails* (cell already in use)
- Each version of open addressing involves specifying a sequence of indices to try

Trying the next spot is called **probing**

- Our i^{th} probe was: $(h(\text{key}) + i) \% \text{TableSize}$
 - This is called **linear probing**
- In general have some **probe function f** and use:

$$(h(\text{key}) + f(i)) \% \text{TableSize}$$
 for the i^{th} probe (start at $i=0$)
 - For **linear probing**, $f(i)=i$

Open addressing does poorly with high load factor λ

- So want larger tables
- Too many probes means no more $O(1)$

Terminology

We and the book use the terms

- "chaining" or "separate chaining"
- "open addressing"

Very confusingly,

- "open hashing" is a synonym for "chaining"
- "closed hashing" is a synonym for "open addressing"

Open Addressing: Linear Probing

What about `find`? If value is in table? If not there? Worst case?

What about `delete`?

How does open addressing with linear probing compare to separate chaining?

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Other operations

Okay, so `insert` finds an open table position using a probe function

What about `find`?

- Must use same probe function to "retrace the trail" and find the data
- Unsuccessful search when reach empty position

What about `delete`?

- **Must** use "lazy" deletion. Why?
- But here just means "no data here, but don't stop probing"
- Note: `delete` with chaining is plain-old list-remove

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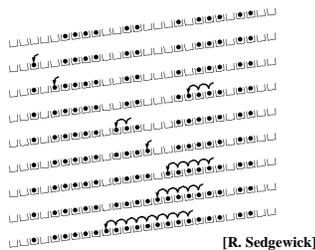
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(Primary) Clustering

It turns out linear probing is a *bad idea*, even though the probe function is quick to compute (a good thing)

Tends to produce *clusters*, which lead to long probing sequences

- Called **primary clustering**
- Saw this starting in our example



[R. Sedgewick]

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Analysis of Linear Probing

- Trivial fact: For any $\lambda < 1$, linear probing will find an empty slot
 - It is "safe" in this sense: no infinite loop unless table is full

- Non-trivial facts we won't prove:

Average # of probes given λ (in the limit as `TableSize` $\rightarrow \infty$)

- Unsuccessful search: $\frac{1}{2} \left(1 + \frac{1}{(1-\lambda)^2} \right)$

- Successful search: $\frac{1}{2} \left(1 + \frac{1}{(1-\lambda)} \right)$

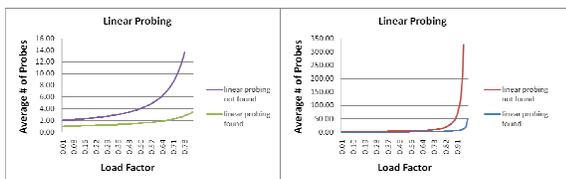
- This is pretty bad: need to leave sufficient empty space in the table to get decent performance (see chart)

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In a chart

- Linear-probing performance degrades rapidly as table gets full
 - (Formula assumes "large table" but point remains)
- By comparison, chaining performance is linear in λ and has no trouble with $\lambda > 1$



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Open Addressing: linear probing

$$(h(\text{key}) + f(i)) \% \text{TableSize}$$

- For linear probing:

$$f(i) = i$$

- So probe sequence is:

- 0th probe: $h(\text{key}) \% \text{TableSize}$
- 1st probe: $(h(\text{key}) + 1) \% \text{TableSize}$
- 2nd probe: $(h(\text{key}) + 2) \% \text{TableSize}$
- 3rd probe: $(h(\text{key}) + 3) \% \text{TableSize}$
- ...
- i^{th} probe: $(h(\text{key}) + i) \% \text{TableSize}$

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Open Addressing: Quadratic probing

- We can avoid primary clustering by changing the probe function...

$$(h(\text{key}) + f(i)) \% \text{TableSize}$$

- For quadratic probing:

$$f(i) = i^2$$

- So probe sequence is:

- 0th probe: $h(\text{key}) \% \text{TableSize}$
- 1st probe: $(h(\text{key}) + 1) \% \text{TableSize}$
- 2nd probe: $(h(\text{key}) + 4) \% \text{TableSize}$
- 3rd probe: $(h(\text{key}) + 9) \% \text{TableSize}$
- ...
- i^{th} probe: $(h(\text{key}) + i^2) \% \text{TableSize}$

- Intuition: Probes quickly "leave the neighborhood"

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$$i^{\text{th}} \text{ probe: } (h(\text{key}) + i^2) \% \text{TableSize}$$

Quadratic Probing Example

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

TableSize=10
 Insert:
 89
 18
 49
 58
 79

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Quadratic Probing Example

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	89

TableSize=10
 Insert:
 89
 18
 49
 58
 79

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Quadratic Probing Example

0	
1	
2	
3	
4	
5	
6	
7	
8	18
9	89

TableSize=10
 Insert:
 89
 18
 49
 58
 79

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Quadratic Probing Example

0	49
1	
2	
3	
4	
5	
6	
7	
8	18
9	89

TableSize=10
 Insert:
 89
 18
 49
 58
 79

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Quadratic Probing Example

0	49
1	
2	58
3	
4	
5	
6	
7	
8	18
9	89

TableSize=10
 Insert:
 89
 18
 49
 58
 79

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Quadratic Probing Example

0	49
1	
2	58
3	79
4	
5	
6	
7	
8	18
9	89

TableSize=10
Insert:
89
18
49
58
79

$$i\text{th probe: } (h(\text{key}) + i^2) \% \text{TableSize}$$

Another Quadratic Probing Example

0	
1	
2	
3	
4	
5	
6	

TableSize = 7
Insert:
76 (76 % 7 = 6)
40 (40 % 7 = 5)
48 (48 % 7 = 6)
5 (5 % 7 = 5)
55 (55 % 7 = 6)
47 (47 % 7 = 5)

Another Quadratic Probing Example

0	
1	
2	
3	
4	
5	
6	76

TableSize = 7
Insert:
76 (76 % 7 = 6)
40 (40 % 7 = 5)
48 (48 % 7 = 6)
5 (5 % 7 = 5)
55 (55 % 7 = 6)
47 (47 % 7 = 5)

Another Quadratic Probing Example

0	
1	
2	
3	
4	
5	40
6	76

TableSize = 7
Insert:
76 (76 % 7 = 6)
40 (40 % 7 = 5)
48 (48 % 7 = 6)
5 (5 % 7 = 5)
55 (55 % 7 = 6)
47 (47 % 7 = 5)

Another Quadratic Probing Example

0	48
1	
2	
3	
4	
5	40
6	76

TableSize = 7
Insert:
76 (76 % 7 = 6)
40 (40 % 7 = 5)
48 (48 % 7 = 6)
5 (5 % 7 = 5)
55 (55 % 7 = 6)
47 (47 % 7 = 5)

Another Quadratic Probing Example

0	48
1	
2	5
3	
4	
5	40
6	76

TableSize = 7
Insert:
76 (76 % 7 = 6)
40 (40 % 7 = 5)
48 (48 % 7 = 6)
5 (5 % 7 = 5)
55 (55 % 7 = 6)
47 (47 % 7 = 5)

i th probe: $(h(\text{key}) + i^2) \% \text{TableSize}$

Another Quadratic Probing Example

0	48
1	
2	5
3	55
4	
5	40
6	76

TableSize = 7

Insert:

76	$(76 \% 7 = 6)$
40	$(40 \% 7 = 5)$
48	$(48 \% 7 = 6)$
5	$(5 \% 7 = 5)$
55	$(55 \% 7 = 6)$
47	$(47 \% 7 = 5)$

Uh-oh: For all n , $(5 + (n*n)) \% 7$ is 0, 2, 5, or 6

• Proof uses induction and $(n^2+5) \% 7 = ((n-7)^2+5) \% 7$

• In fact, for all c and k , $(n^2+c) \% k = ((n-k)^2+c) \% k$

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i th probe: $(h(\text{key}) + i^2) \% \text{TableSize}$

Another Quadratic Probing Example

0	48
1	
2	5
3	55
4	
5	40
6	76

TableSize = 7

Insert:

76	$(76 \% 7 = 6)$
40	$(40 \% 7 = 5)$
48	$(48 \% 7 = 6)$
5	$(5 \% 7 = 5)$
55	$(55 \% 7 = 6)$
47	$(47 \% 7 = 5)$

Uh-oh: For all n , $(5 + (n*n)) \% 7$ is 0, 2, 5, or 6

• Proof uses induction and $(n^2+5) \% 7 = ((n-7)^2+5) \% 7$

• In fact, for all c and k , $(n^2+c) \% k = ((n-k)^2+c) \% k$

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From bad news to good news

- The bad news is: After TableSize quadratic probes, we will just cycle through the same indices
- The good news:
 - Assertion #1: If $T = \text{TableSize}$ is prime and $\lambda < 1/2$, then quadratic probing will find an empty slot in at most $T/2$ probes
 - Assertion #2: For prime T and $0 \leq i, j \leq T/2$ where $i \neq j$, $(h(\text{key}) + i^2) \% T \neq (h(\text{key}) + j^2) \% T$

That is, if T is prime, the first $T/2$ quadratic probes map to different locations

- Assertion #3: Assertion #2 is the "key fact" for proving Assertion #1

- So: If you keep $\lambda < 1/2$, no need to detect cycles

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Quadratic Probing: Success guarantee for $\lambda < 1/2$

- If size is prime and $\lambda < 1/2$, then quadratic probing will find an empty slot in size/2 probes or fewer.
 - show for all $0 \leq i, j \leq \text{size}/2$ and $i \neq j$

$$(h(x) + i^2) \bmod \text{size} \neq (h(x) + j^2) \bmod \text{size}$$
 - by contradiction: suppose that for some $i \neq j$:

$$(h(x) + i^2) \bmod \text{size} = (h(x) + j^2) \bmod \text{size}$$

$$\Rightarrow i^2 \bmod \text{size} = j^2 \bmod \text{size}$$

$$\Rightarrow (i^2 - j^2) \bmod \text{size} = 0$$

$$\Rightarrow [(i + j)(i - j)] \bmod \text{size} = 0$$
 BUT size does not divide $(i-j)$ or $(i+j)$

How can $i+j = 0$ or $i+j = \text{size}$ when:
 $i \neq j$ and $0 \leq i, j \leq \text{size}/2$?

Similarly how can $i-j = 0$ or $i-j = \text{size}$?

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Clustering reconsidered

- Quadratic probing does not suffer from primary clustering: quadratic nature quickly escapes the neighborhood
- But it's no help if keys initially hash to the same index
 - Called secondary clustering
 - Any 2 keys that hash to the same value will have the same series of moves after that
- Can avoid secondary clustering with a probe function that depends on the key: double hashing...

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Open Addressing: Double hashing

Idea: Given two good hash functions h and g , it is very unlikely that for some key, $h(\text{key}) = g(\text{key})$

$(h(\text{key}) + f(i)) \% \text{TableSize}$

- For double hashing:
 - $f(i) = i * g(\text{key})$
- So probe sequence is:
 - 0th probe: $h(\text{key}) \% \text{TableSize}$
 - 1st probe: $(h(\text{key}) + g(\text{key})) \% \text{TableSize}$
 - 2nd probe: $(h(\text{key}) + 2 * g(\text{key})) \% \text{TableSize}$
 - 3rd probe: $(h(\text{key}) + 3 * g(\text{key})) \% \text{TableSize}$
 - ...
 - i th probe: $(h(\text{key}) + i * g(\text{key})) \% \text{TableSize}$

- Detail: Make sure $g(\text{key})$ can't be 0

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Resolving Collisions with Double Hashing

0	
1	
2	
3	
4	
5	
6	
7	
8	
9	

T = 10 (TableSize)
Hash Functions:
 $h(\text{key}) = \text{key} \bmod T$
 $g(\text{key}) = 1 + ((\text{key}/T) \bmod (T-1))$

Insert these values into the hash table in this order. Resolve any collisions with double hashing:

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 28
 33
 147
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Double-hashing analysis

- Intuition: Since each probe is "jumping" by $g(\text{key})$ each time, we "leave the neighborhood" and "go different places from other initial collisions"
- But we could still have a problem like in quadratic probing where we are not "safe" (infinite loop despite room in table)
 - It is known that this cannot happen in at least one case:
 - $h(\text{key}) = \text{key} \% p$
 - $g(\text{key}) = q - (\text{key} \% q)$
 - $2 < q < p$
 - p and q are prime

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Yet another reason to use a prime TableSize

- So, for double hashing
 i^{th} probe: $(h(\text{key}) + i * g(\text{key})) \% \text{TableSize}$
- Say $g(\text{key})$ divides TableSize
 - That is, there is some integer x such that $x * g(\text{key}) = \text{TableSize}$
 - After x probes, we'll be back to trying the same indices as before
- Ex:
 - TableSize=50
 - $g(\text{key})=25$
 - Probing sequence:
 - $h(\text{key})$
 - $h(\text{key})+25$
 - $h(\text{key})+50=h(\text{key})$
 - $h(\text{key})+75=h(\text{key})+25$
- Only 1 & itself divide a prime

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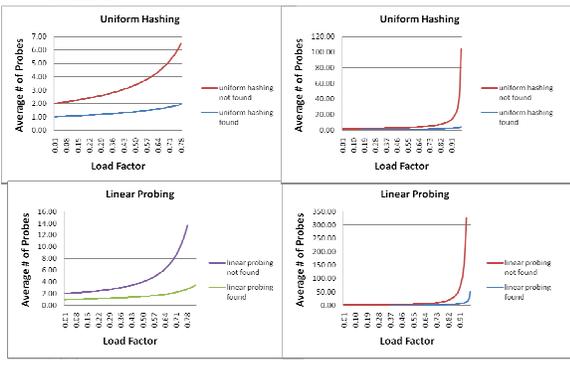
More double-hashing facts

- Assume "uniform hashing"
 - Means probability of $g(\text{key1}) \% p == g(\text{key2}) \% p$ is $1/p$
- Non-trivial facts we won't prove:
 Average # of probes given λ (in the limit as TableSize $\rightarrow \infty$)
 - Unsuccessful search (intuitive): $\frac{1}{1-\lambda}$
 - Successful search (less intuitive): $\frac{1}{\lambda} \log_e \left(\frac{1}{1-\lambda} \right)$
- Bottom line: unsuccessful bad (but not as bad as linear probing), but successful is not nearly as bad

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Charts



Where are we?

- **Separate Chaining** is easy
 - **insert, find, delete** proportion to load factor on average (**insert** can be constant if just push on front of list)
- **Open addressing** uses probe functions, has clustering issues as table gets full
 - Why use it:
 - Less memory allocation?
 - Some run-time overhead for allocating linked list (or whatever) nodes; open addressing could be faster
 - Easier data representation?
- Now:
 - Growing the table when it gets too full (aka "rehashing")
 - Relation between hashing/comparing and connection to Java

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Rehashing

- Like with array-based stacks/queues/lists, if table gets too full, create a bigger table and copy everything over
- Especially with chaining, we get to decide what "too full" means
 - Keep load factor reasonable (e.g., < 1)?
 - Consider average or max size of non-empty chains?
- For open addressing, half-full is a good rule of thumb
- New table size
 - Twice-as-big is a good idea, except, uhm, that won't be prime!
 - So go *about* twice-as-big
 - Can have a list of prime numbers in your code since you won't grow more than 20-30 times, and then calculate after that

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More on rehashing

- What if we copy all data to the same indices in the new table?
 - Not going to work; calculated index based on TableSize – we may not be able to find it later
- Go through current table, do standard insert for each into new table; run-time?
 - $O(n)$: Iterate through table
- But resize is an $O(n)$ operation, involving n calls to the hash function (1 for each insert in the new table)
 - Is there some way to avoid all those hash function calls again?
 - Space/time tradeoff: Could store $h(\text{key})$ with each data item, but since rehashing is rare, this is probably a poor use of space
 - And growing the table is still $O(n)$; only helps by a constant factor

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Hashing and comparing

- For insert/find, as we go through the chain or keep probing, we have to *compare* each item we see to the key we're looking for
 - We need to have a comparator (or key's type needs to be comparable)
 - Don't actually need $<$ & $>$; just $=$
- So a hash table needs a hash function and a comparator
 - In Project 2, you'll use two function objects
 - The Java standard library uses a more OO approach where each object has an `equals` method and a `hashCode` method:

```
class Object {
    boolean equals(Object o) {...}
    int hashCode() {...}
    ...
}
```

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Equal objects must hash the same

- The Java library (and your project hash table) make a very important assumption that clients must satisfy...
- OO way of saying it:
 - If `a.equals(b)`, then we must require `a.hashCode() == b.hashCode()`
- Function object way of saying it:
 - If `c.compare(a,b) == 0`, then we must require `h.hash(a) == h.hash(b)`
- Why is this essential?

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Java bottom line

- Lots of Java libraries use hash tables, perhaps without your knowledge
- So: If you ever override `equals`, you need to override `hashCode` also in a consistent way
 - See CoreJava book, Chapter 5 for other "gotchas" with `equals`

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Bad Example

- Think about using a hash table holding points

```
class PolarPoint {
    double r = 0.0;
    double theta = 0.0;
    void addToAngle(double theta2) { theta+=theta2; }
    ...
    boolean equals(Object otherObject) {
        if(this==otherObject) return true;
        if(otherObject==null) return false;
        if(getClass()!=other.getClass()) return false;
        PolarPoint other = (PolarPoint)otherObject;
        double angleDiff =
            (theta - other.theta) % (2*Math.PI);
        double rDiff = r - other.r;
        return Math.abs(angleDiff) < 0.0001
            && Math.abs(rDiff) < 0.0001;
    }
    // wrong: must override hashCode!
}
```

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Aside: Comparable/Comparator have rules too

We didn't emphasize some important "rules" about comparison functions for:

- all our dictionaries
- sorting (next major topic)

Comparison must impose a consistent, total ordering:

For all a, b , and c ,

- If $\text{compare}(a,b) < 0$, then $\text{compare}(b,a) > 0$
- If $\text{compare}(a,b) == 0$, then $\text{compare}(b,a) == 0$
- If $\text{compare}(a,b) < 0$ and $\text{compare}(b,c) < 0$, then $\text{compare}(a,c) < 0$

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Some final arguments for a prime table size

If **TableSize** is 60 and...

- Lots of data items are multiples of 5, wasting 80% of table
- Lots of data items are multiples of 10, wasting 90% of table
- Lots of data items are multiples of 2, wasting 50% of table

If **TableSize** is 61...

- Collisions can still happen, but 5, 10, 15, 20, ... will fill table
- Collisions can still happen but 10, 20, 30, 40, ... will fill table
- Collisions can still happen but 2, 4, 6, 8, ... will fill table

In general, if x and y are "co-prime" (means $\text{gcd}(x,y)=1$), then

$$(a * x) \% y == (b * x) \% y \text{ if and only if } a \% y == b \% y$$

- So, given table size y and keys as multiples of x , we'll get a decent distribution if x & y are co-prime
- Good to have a **TableSize** that has no common factors with any "likely pattern" x

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Final word on hashing

- The hash table is one of the most important data structures
 - Supports only **find**, **insert**, and **delete** efficiently
 - **FindMin**, **FindMax**, **predecessor**, etc.: not so efficiently
 - Most likely data-structure to be asked about in interviews; many real-world applications
- Important to use a good hash function
 - Good distribution
 - Uses enough of key's values
- Important to keep hash table at a good size
 - Prime #
 - Preferable λ depends on type of table
- Side-comment: hash functions have uses beyond hash tables
 - Examples: Cryptography, check-sums

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