



CSE332: Data Abstractions

Lecture 6: Dictionaries; Binary Search Trees

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Where we are

Studying the absolutely essential ADTs of computer science and classic data structures for implementing them

ADTs so far:

1. Stack: `push, pop, isEmpty, ...`
2. Queue: `enqueue, dequeue, isEmpty, ...`
3. Priority queue: `insert, deleteMin, ...`

Next:

4. Dictionary (a.k.a. Map): associate keys with values
 - probably the most common, way more than priority queue

The Dictionary (a.k.a. Map) ADT

- Data:
 - set of (key, value) pairs
 - keys must be comparable
- Operations:
 - `insert(key, value)`
 - `find(key)`
 - `delete(key)`
 - ...



Will tend to emphasize the keys,
don't forget about the stored values

Comparison: The Set ADT

The Set ADT is like a Dictionary without any values

- A key is *present* or not (no repeats)

For `find`, `insert`, `delete`, there is little difference

- In dictionary, values are "just along for the ride"
- So *same data-structure ideas* work for dictionaries and sets

But if your Set ADT has other important operations this may not hold

- `union`, `intersection`, `is_subset`
- notice these are binary operators on sets

Dictionary data structures

Will spend the next 1.5-2 weeks implementing dictionaries with three different data structures

1. AVL trees
 - Binary search trees with *guaranteed balancing*
2. B-Trees
 - Also always balanced, but different and shallower
3. Hashtables
 - Not tree-like at all

Skipping: Other balanced trees (red-black, splay)

But first some applications and less efficient implementations...

A Modest Few Uses

Any time you want to store information according to some key and be able to retrieve it efficiently

– Lots of programs do that!

- Networks: router tables
- Operating systems: page tables
- Compilers: symbol tables
- Databases: dictionaries with other nice properties
- Search: inverted indexes, phone directories, ...
- Biology: genome maps
- ...

Simple implementations

For dictionary with n key/value pairs

insert find delete

- Unsorted linked-list
- Unsorted array
- Sorted linked list
- Sorted array

We'll see a Binary Search Tree (BST) probably does better, but not in the worst case unless we keep it balanced

Simple implementations

For dictionary with n key/value pairs

insert find delete

- Unsorted linked-list $O(1)$ $O(n)$ $O(n)$
- Unsorted array $O(1)$ $O(n)$ $O(n)$
- Sorted linked list $O(n)$ $O(n)$ $O(n)$
- Sorted array $O(n)$ $O(\log n)$ $O(n)$

We'll see a Binary Search Tree (BST) probably does better, but not in the worst case unless we keep it balanced

Lazy Deletion

10	12	24	30	41	42	44	45	50
✓	✗	✓	✓	✓	✓	✗	✓	✓

A *general technique* for making `delete` as fast as `find`:

- Instead of actually removing the item just mark it deleted

Plusses:

- Simpler
- Can do removals later in batches
- If re-added soon thereafter, just unmark the deletion

Minuses:

- Extra *space* for the “is-it-deleted” flag
- Data structure full of deleted nodes wastes *space*
- `find` $O(\log m)$ time where m is data-structure size (okay)
- May complicate other operations

Some tree terms (mostly review)

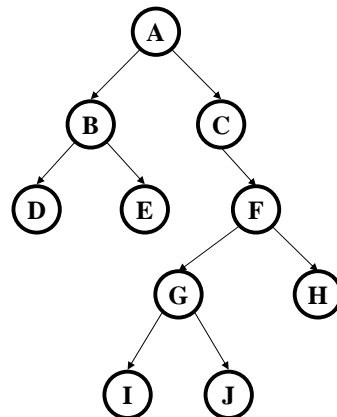
- There are many kinds of trees
 - Every binary tree is a tree
 - Every list is kind of a tree (think of “next” as the one child)
- There are many kinds of binary trees
 - Every binary min heap is a binary tree
 - Every binary search tree is a binary tree
- A tree can be balanced or not
 - A balanced tree with n nodes has a height of $O(\log n)$
 - Different tree data structures have different “balance conditions” to achieve this

Binary Trees

- Binary tree is empty or
 - a root (*with data*)
 - a left subtree (*maybe empty*)
 - a right subtree (*maybe empty*)
- Representation:

Data	
left pointer	right pointer

- For a dictionary, data will include a key and a value



Binary Tree: Some Numbers

Recall: height of a tree = longest path from root to leaf (count edges)

For binary tree of height h :

- max # of leaves:
- max # of nodes:
- min # of leaves:
- min # of nodes:

Binary Trees: Some Numbers

Recall: height of a tree = longest path from root to leaf (count edges)

For binary tree of height h :

- max # of leaves: 2^h
- max # of nodes: $2^{(h+1)} - 1$
- min # of leaves: 1
- min # of nodes: $h + 1$

For n nodes, we cannot do better than $O(\log n)$ height, and we want to avoid $O(n)$ height

Calculating height

What is the height of a tree with root r ?

```
int treeHeight(Node root) {  
    ???  
}
```

Calculating height

What is the height of a tree with root r ?

```
int treeHeight(Node root) {  
    if (root == null)  
        return -1;  
    return 1 + max(treeHeight(root.left),  
                  treeHeight(root.right));  
}
```

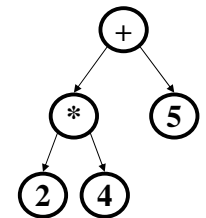
Running time for tree with n nodes: $O(n)$ – single pass over tree

Note: non-recursive is painful – need your own stack of pending nodes; much easier to use recursion's call stack

Tree Traversals

A *traversal* is an order for visiting all the nodes of a tree

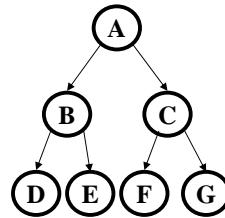
- *Pre-order*: root, left subtree, right subtree
- *In-order*: left subtree, root, right subtree
- *Post-order*: left subtree, right subtree, root



(an expression tree)

More on traversals

```
void inOrdertraversal(Node t){
  if(t != null) {
    traverse(t.left);
    process(t.element);
    traverse(t.right);
  }
}
```



A
B
D
E
C
F
G

Sometimes order doesn't matter

- Example: sum all elements

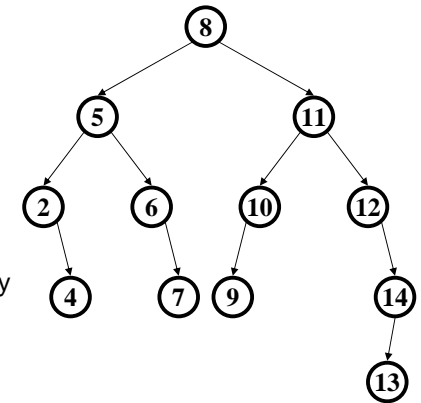
Sometimes order matters

- Example: print tree with parent above indented children (pre-order)
- Example: evaluate an expression tree (post-order)

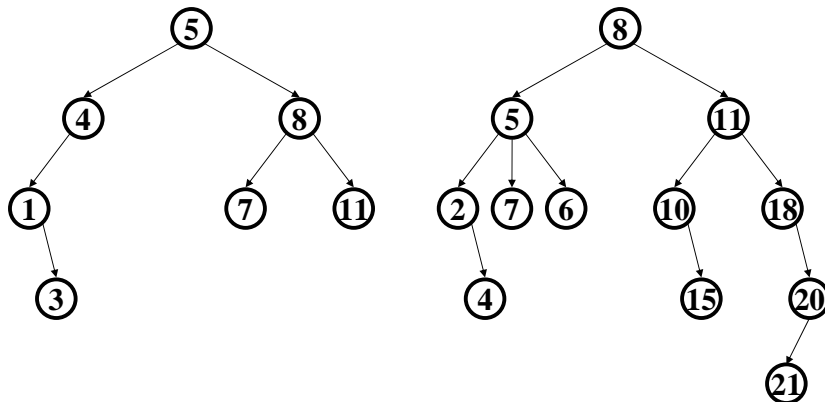
Binary Search Tree

- Structural property ("binary")
 - each node has ≤ 2 children
 - result: keeps operations simple

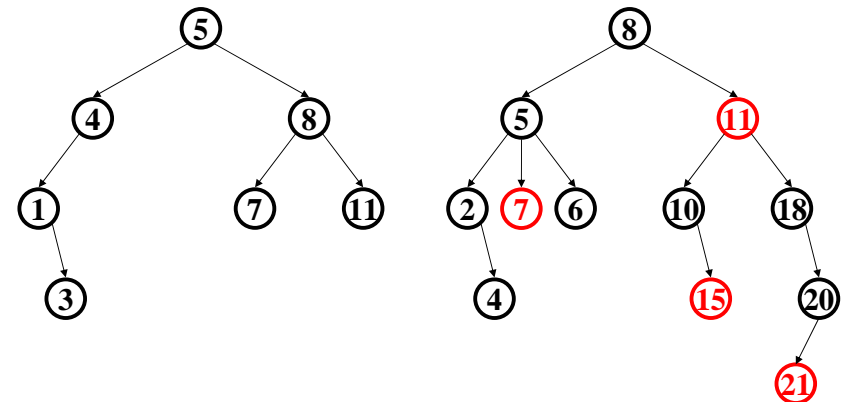
- Order property
 - all keys in left subtree smaller than node's key
 - all keys in right subtree larger than node's key
 - result: easy to find any given key



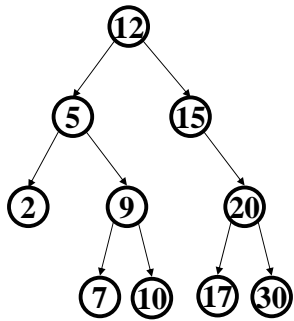
Are these BSTs?



Are these BSTs?

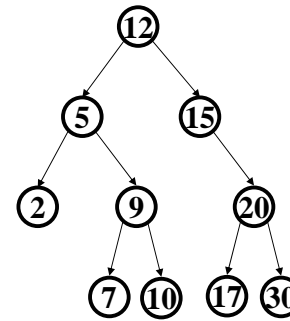


Find in BST, Recursive



```
Data find(Key key, Node root){
    if(root == null)
        return null;
    if(key < root.key)
        return find(key,root.left);
    if(key > root.key)
        return find(key,root.right);
    return root.data;
}
```

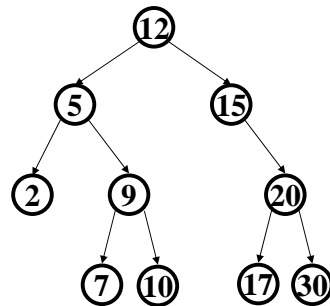
Find in BST, Iterative



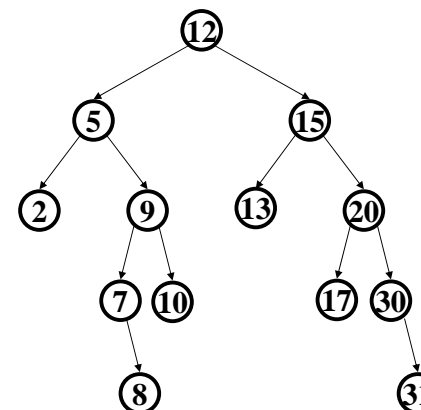
```
Data find(Key key, Node root){
    while(root != null
        && root.key != key) {
        if(key < root.key)
            root = root.left;
        else(key > root.key)
            root = root.right;
        }
    if(root == null)
        return null;
    return root.data;
}
```

Other “finding operations”

- Find *minimum* node
 - “the liberal algorithm”
- Find *maximum* node
 - “the conservative algorithm”
- Find *predecessor* of a non-leaf
- Find *successor* of a non-leaf
- Find *predecessor* of a leaf
- Find *successor* of a leaf



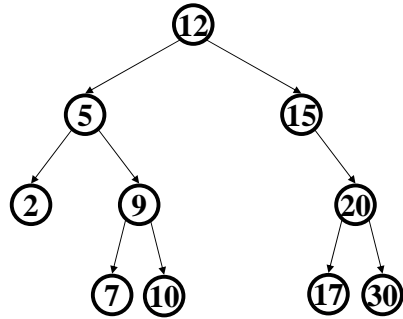
Insert in BST



```
insert(13)
insert(8)
insert(31)
```

(New) insertions happen only at leaves – easy!

Deletion in BST



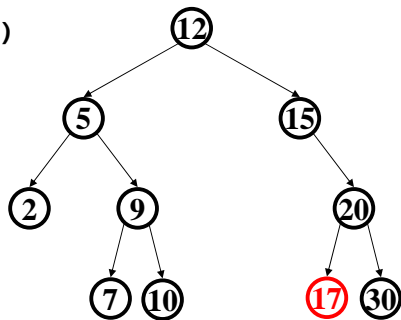
Why might deletion be harder than insertion?

Deletion

- Removing an item disrupts the tree structure
- Basic idea: **find** the node to be removed, then “fix” the tree so that it is still a binary search tree
- Three cases:
 - node has no children (leaf)
 - node has one child
 - node has two children

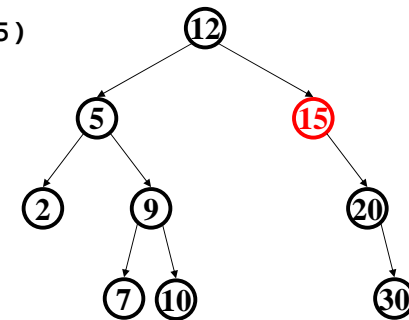
Deletion – The Leaf Case

`delete(17)`

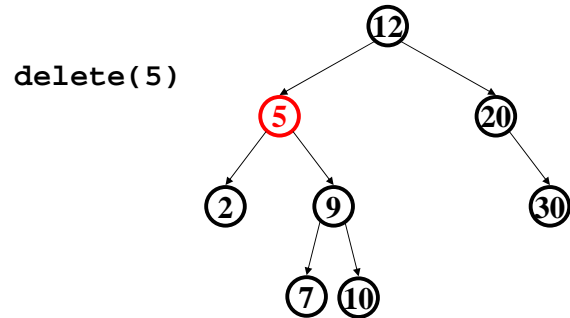


Deletion – The One Child Case

`delete(15)`



Deletion – The Two Child Case



What can we replace 5 with?

Deletion – The Two Child Case

Idea: Replace the deleted node with a value guaranteed to be between the two child subtrees

Options:

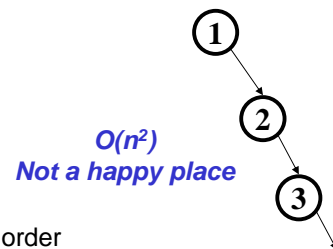
- *successor* from right subtree: `findMin(node.right)`
- *predecessor* from left subtree: `findMax(node.left)`
 - These are the easy cases of predecessor/successor

Now delete the original node containing *successor* or *predecessor*

- Leaf or one child case – easy cases of delete!

BuildTree for BST

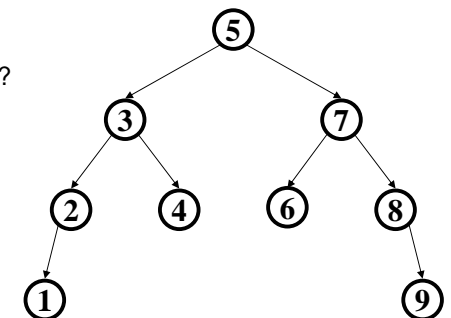
- We had `buildHeap`, so let's consider `buildTree`
- Insert keys 1, 2, 3, 4, 5, 6, 7, 8, 9 into an empty BST
 - If inserted in given order, what is the tree?
 - What big-O runtime for this kind of sorted input?
 - Is inserting in the reverse order any better?



BuildTree for BST

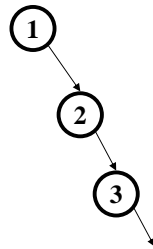
- Insert keys 1, 2, 3, 4, 5, 6, 7, 8, 9 into an empty BST
- What we if could somehow re-arrange them
 - median first, then left median, right median, etc.
 - 5, 3, 7, 2, 1, 4, 8, 6, 9
 - What tree does that give us?
 - What big-O runtime?

O(n log n), definitely better



Unbalanced BST

- Balancing a tree at build time is insufficient, as sequences of operations can eventually transform that carefully balanced tree into the dreaded list
- At that point, everything is $O(n)$ and nobody is happy
 - `find`
 - `insert`
 - `delete`



Balanced BST

Observation

- BST: the shallower the better!
- For a BST with n nodes inserted in arbitrary order
 - Average height is $O(\log n)$ – see text for proof
 - Worst case height is $O(n)$
- Simple cases such as inserting in key order lead to the worst-case scenario

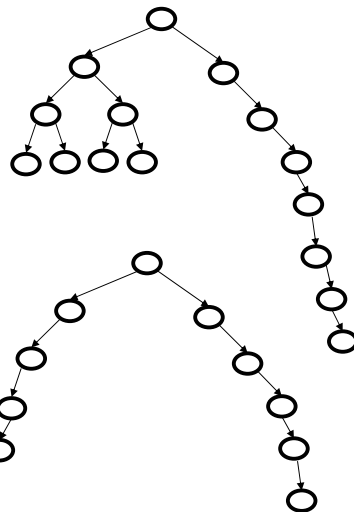
Solution: Require a **Balance Condition** that

- ensures depth is always $O(\log n)$ – strong enough!
- is easy to maintain – not too strong!

Potential Balance Conditions

- Left and right subtrees of the *root* have equal number of nodes

Too weak!
Height mismatch example:



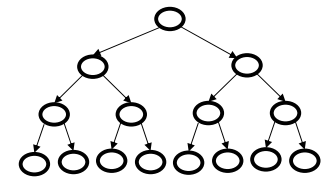
- Left and right subtrees of the *root* have equal *height*

Too weak!
Double chain example:

Potential Balance Conditions

- Left and right subtrees of every node have equal number of nodes

Too strong!
Only perfect trees ($2^n - 1$ nodes)



- Left and right subtrees of every node have equal *height*

Too strong!
Only perfect trees ($2^n - 1$ nodes)

The AVL Balance Condition

Left and right subtrees of every node
have heights **differing by at most 1**

Definition: **balance**(node) = height(node.left) – height(node.right)

AVL property: **for every node x , $-1 \leq \text{balance}(x) \leq 1$**

- Ensures small depth
 - Will prove this by showing that an AVL tree of height h must have a number of nodes *exponential* in h
- Easy (well, efficient) to maintain
 - Using single and double rotations