Quiz Section 8: Trees – Solutions

Task 1 – One, Two, Tree...

The problem makes use of the following inductive type, representing a left-leaning binary tree

```
type Tree := empty  | \quad \mathsf{node}(\mathsf{val} : \mathbb{Z}, \; \mathsf{left} : \mathsf{Tree}, \; \mathsf{right} : \mathsf{Tree}) \quad \mathsf{with} \; \mathsf{height}(\mathsf{left}) \geqslant \mathsf{height}(\mathsf{right})
```

The "with" condition is an *invariant* of the node. Every node that is created must have this property, and we are allowed to use the fact that it holds in our reasoning.

The height of a tree is defined recursively by

$$\begin{array}{lll} \operatorname{height}: \mathsf{Tree} \to \mathbb{Z} \\ \\ \operatorname{height}(\mathsf{empty}) &:= & -1 \\ \\ \operatorname{height}(\mathsf{node}(x,S,R)) &:= & 1 + \operatorname{height}(S) \\ \end{array}$$

In a general binary tree, the height of a non-empty tree is the length of the *longest* path to a leaf. With a left-leaning tree, we know the longest path is the one that always travels toward the left child.

We can define the size of a tree, the number of values stored in it, as follows:

$$\begin{aligned} & \text{size}: \mathsf{Tree} \to \mathbb{N} \\ & \mathsf{size}(\mathsf{empty}) & := & 0 \\ & \mathsf{size}(\mathsf{node}(x,S,R)) & := & 1 + \mathsf{size}(S) + \mathsf{size}(R) \end{aligned}$$

Prove by structural induction that, for any left-leaning tree T, we have

$$size(T) \leq 2^{height(T)+1} - 1$$

Define P(T) to be the claim that $\operatorname{size}(T) \leqslant 2^{\operatorname{height}(T)+1} - 1$. We will prove this by structural induction.

Base Case (empty). In this case, we can see that

$$\begin{aligned} &\text{size}(\text{empty}) \\ &= 0 & \text{Def of size} \\ &= 1-1 \\ &= 2^0-1 \\ &= 2^{-1+1}-1 \\ &= 2^{\text{height}(\text{empty})+1}-1 & \text{Def of height} \end{aligned}$$

Inductive Hypothesis. Suppose that P holds for trees S and R.

Inductive Step. We need to show $P(\mathsf{node}(x, S, R))$ for any integer x.

Let x be any integer. Then, we can see that

$$\begin{split} \operatorname{size}(\operatorname{node}(x,S,R)) &= 1 + \operatorname{size}(S) + \operatorname{size}(R)) & \operatorname{Def of size} \\ &\leqslant 1 + 2^{\operatorname{height}(S)+1} - 1 + 2^{\operatorname{height}(R)+1} - 1 & \operatorname{Inductive Hypothesis} \\ &= 2^{\operatorname{height}(S)+1} + 2^{\operatorname{height}(R)+1} - 1 & \operatorname{since height}(S) \geqslant \operatorname{height}(R) \\ &\leqslant 2 \cdot 2^{\operatorname{height}(S)+1} - 1 & \operatorname{since height}(S) \geqslant \operatorname{height}(R) \\ &= 2 \cdot 2^{\operatorname{height}(\operatorname{node}(x,S,R)} - 1 & \operatorname{Def of height} \\ &= 2^{\operatorname{height}(\operatorname{node}(x,S,R)+1} - 1 \end{split}$$

Conclusion. P(T) holds for any left-leaning tree T by structural induction.

Task 2 – How Do I Love Tree, Let Me Count the Ways

The following is the definition of a binary search tree:

```
\label{eq:type_BST} \begin{split} \mathsf{type} \ \mathsf{BST} := & \ \mathsf{empty} \\ & | \ \mathsf{node}(x : \mathbb{Z}, \ S : \mathsf{BST}, \ R : \mathsf{BST}) \end{split}
```

Suppose that we wanted to have a way to refer to a specific node in a BST. One way to do so would be to give directions from the root to that node. If we define these types:

```
type Dir := LEFT \mid RIGHT
type Path := List\langle Dir \rangle
```

then a Path tells you how to get to a particular node where each step along the path (item in the list) would be a direction pointing you to keep going down the LEFT or RIGHT branch of the tree.

For example, LEFT :: RIGHT :: nil says to select the "LEFT" child of the parent and then the "RIGHT" child of that node, giving us a grand-child of the root node.

(a) Define a function "find(p: Path, T: BST)" that returns the node (a BST) at the path from the root of T or undefined if there is no such node.

```
\begin{split} & \text{find}: (\mathsf{Path}, \ \mathsf{BST}) \to \mathsf{BST} \\ & \text{find}(\mathsf{nil}, T) & := \ T \\ & \text{find}(d:: L, \mathsf{empty}) & := \ \mathsf{undefined} \\ & \text{find}(\mathsf{LEFT}:: L, \mathsf{node}(x, S, R)) & := \ \mathsf{find}(L, S) \\ & \text{find}(\mathsf{RIGHT}:: L, \mathsf{node}(x, S, R)) & := \ \mathsf{find}(L, R) \end{split}
```

(b) Define a function "remove(p: Path, T: BST)" that returns T except with the node at the given path replaced by empty.

```
\begin{aligned} \mathsf{remove} : (\mathsf{Path}, \ \mathsf{BST}) \to \mathsf{BST} \\ \mathbf{func} \ \mathsf{remove}(\mathsf{nil}, T) & := \ \mathsf{empty} \\ \mathsf{remove}(d :: L, \mathsf{empty}) & := \ \mathsf{undefined} \\ \mathsf{remove}(\mathsf{LEFT} :: L, \mathsf{node}(x, S, R)) & := \ \mathsf{node}(x, \mathsf{remove}(L, S), R) \\ \mathsf{remove}(\mathsf{RIGHT} :: L, \mathsf{node}(x, S, R)) & := \ \mathsf{node}(x, S, \mathsf{remove}(L, R)) \end{aligned}
```

Suppose we had the following interface for a Point class that represents a point in 2D space:

```
/** Represents a point with coordinates in (x,y) space. */
interface Point {
    /** @returns the x coordinate of the point */
    getX: () => number;

    /** @returns the y coordinate of the point */
    getY: () => number;

    /**
     * Returns the distance of this point to the origin.
     * @returns Math.sqrt(obj.x*obj.x + obj.y*obj.y)
     */
     distToOrigin: () => number;
}
```

The following is an implementation of the Point interface:

```
class SimplePoint implements Point {
    // RI: <TODO>
    // AF: <TODO>
    readonly x: number;
   readonly y: number;
    readonly r: number;
   // Creates a point with the given coordinates
    constructor(x: number, y: number) {
    this.x = x;
    this.y = y;
    this.r = Math.sqrt(x*x + y*y);
    }
    getX = (): number => this.x;
    getY = (): number => this.y;
    distToOrigin = (): number => this.r;
}
```

(a) Define the representation invariant (RI) and abstraction function (AF) for the SimplePoint class.

```
RI: r = Math.sqrt(this.x * this.x + this.y * this.y)
AF: obj = (this.x, this.y)
```

(b) Use the RI or AF to prove that the distToOrigin method of the SimplePoint class is correct.

We can see that:

```
Math.sqrt(obj.x*obj.x + obj.y*obj.y)
= Math.sqrt(this.x*this.x + this.y*this.y) by AF
= this.r by RI
```

Our function returns this.r, so we know that it is correct.

(c) The following problem will make use of this math definition that rotates a point around the origin (x, y) by an angle θ :

```
\begin{aligned} \operatorname{rotate}: \left( \mathsf{Point}, \ \mathbb{R} \right) &\to \mathsf{Point} \\ \operatorname{rotate}((x,y),\theta) &= (x \cdot \cos(\theta) - y \cdot \sin(\theta), \ x \cdot \sin(\theta) + y \cdot \cos(\theta) ) \end{aligned}
```

Suppose we have the following implementation of the rotate method:

```
/** @returns rotate(obj, θ) */
    rotate = (theta: number): Point => {
        const newX = this.x * Math.cos(theta) - this.y * Math.sin(theta);
        const newY = this.x * Math.sin(theta) + this.y * Math.cos(theta);
        return new SimplePoint(newX, newY);
}
```

Prove that the rotate method is correct using the RI or AF.

We can see that:

```
\begin{split} \operatorname{rotate}(obj,\theta) &= \operatorname{rotate}((\operatorname{this.x,\,this.y}),\theta) &= \operatorname{by\,AF} \\ &= (\operatorname{this.x} \cdot \cos(\theta) - \operatorname{this.y} \cdot \sin(\theta), \operatorname{this.x} \cdot \sin(\theta) + \operatorname{this.y} \cdot \cos(\theta)) & \text{def of rotate} \\ &= (\operatorname{newX}, \operatorname{this.x} \cdot \sin(\theta) + \operatorname{this.y} \cdot \cos(\theta)) & \text{def of newX} \\ &= (\operatorname{newX}, \operatorname{newY}) & \text{def of newY} \end{split}
```

Our function returns new SimplePoint(newX, newY), so we know that it is correct.

Task 4 – Going Back and Length

The following problem will make use of the following functions that operate on lists:

```
\begin{aligned} & \mathsf{len} : \mathsf{List} \to \mathbb{N} \\ & \mathsf{len}(\mathsf{nil}) & := & 0 \\ & \mathsf{len}(x :: L) & := & 1 + \mathsf{len}(L) \\ & \mathsf{rev} : \mathsf{List} \to \mathsf{List} \end{aligned}
```

$$\begin{array}{lll} \operatorname{rev}(\operatorname{nil}) & := & \operatorname{nil} \\ \operatorname{rev}(x::L) & := & \operatorname{rev}(L) + + \lceil x \rceil \end{array}$$

Suppose we also have the fact Lemma 1: $\operatorname{len}(\operatorname{rev}(L) + +[x]) = \operatorname{len}(\operatorname{rev}(L)) + \operatorname{len}(x :: nil)$ for any list L and element x.

Prove by Structural Induction that len(rev(L)) = len(L) for any list L. You may find that you need to use Lemma 1 in your proof.

Define P(L) to be the claim that len(rev(L)) = len(L). We will prove this by structural induction.

Base Case (nil). In this case, we can see that

$$\begin{aligned} & \mathsf{len}(\mathsf{rev}(\mathsf{nil})) \\ &= \mathsf{len}(\mathsf{nil}) & \mathsf{Def} \; \mathsf{of} \; \mathsf{rev} \\ &= 0 & \mathsf{Def} \; \mathsf{of} \; \mathsf{len} \\ &= \mathsf{len}(\mathsf{nil}) & \mathsf{Def} \; \mathsf{of} \; \mathsf{len} \end{aligned}$$

Inductive Hypothesis. Suppose that P holds for list L.

Inductive Step. We need to show P(x::L) for any element x and list L.

Let x be any element. Then, we can see that

$$\begin{split} & \operatorname{len}(\operatorname{rev}(x::L)) \\ &= \operatorname{len}(\operatorname{rev}(L) + + [x]) & \operatorname{Def of rev} \\ &= \operatorname{len}(\operatorname{rev}(L)) + \operatorname{len}(x::\operatorname{nil}) & \operatorname{Lemma 1} \\ &= \operatorname{len}(L) + \operatorname{len}(\operatorname{x::nil}) & \operatorname{Inductive Hypothesis} \\ &= \operatorname{len}(L) + 1 + \operatorname{len}(\operatorname{nil}) & \operatorname{Def of len} \\ &= \operatorname{len}(L) + 1 & \operatorname{Def of len} \\ &= \operatorname{len}(x::L) & \operatorname{Def of len} \end{split}$$

Conclusion. P(L) holds for any list L by structural induction.