

**CSE 331** 

**Abstract Data Types (ADTs)** 

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## Recall: Properties of High-Quality Code

- Professionals are expected to write high-quality code
- Correctness is the most important part of quality
  - users hate products that do not work properly
- Also includes the following
  - easy to change
  - easy to understand
  - modular

abstraction provides all three properties

#### **Recall: Procedural Abstraction**

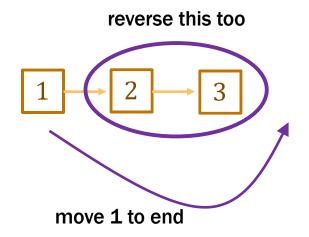
- Hide the details of the function from the caller
  - caller only needs to read the specification
  - ("procedure" means function)
- Caller promises to pass valid inputs
  - no promises on invalid inputs
- Implementer then promises to return correct outputs
  - does not matter how

#### **Definition of List Reversal**

Mathematical definition of rev(S)

$$\begin{array}{ll} \text{rev(nil)} & := \text{ nil} & \text{included in the reference sheet} \\ \text{rev}(x :: L) & := \text{rev}(L) \# [x] & \text{posted on the Topics page} \\ \end{array}$$

– note that rev uses concat (#) as a helper function



#### **Definition of List Reversal**

Mathematical definition of rev(S)

```
rev(nil) := nil
rev(x:: L) := rev(L) # [x]
```

- note that rev uses concat (#) as a helper function
- **ex**: rev(1 :: 2 :: 3 :: nil) = 3 :: 2 :: 1 :: nil

#### what other tests should we do?

## **Procedural Abstraction Example**

Specification of rev is imperative:

```
// @return same numbers but in reverse order, i.e.
// rev(nil) := nil
// rev(x :: L) := rev(L) ++ [x]
public static List rev(List L) {
   return rev_acc(L, nil); // faster way
}
```

- code implements a different function
- second version is O(n) instead of  $O(n^2)$
- need to use reasoning to check that these two match
   can prove that rev\_acc(L, nil) = rev(L) for all L by structural induction

## **Performance Improvements**

- Faster algorithm, rev-acc, for reversing a list
  - rare to see this
- Most perf improvements change data structures
  - different kind of abstraction barrier for data
- Let's see an example...

#### **Last Element of a List**

```
 last(x :: nil) := x 
 last(x :: y :: L) := last(y :: L) 
 last is undefined on nil
```

- Runs in  $\theta(n)$  time
  - walks down to the end of the list
  - no faster way to do this on a list
- How could we change data to make this faster?
  - we could cache the last element!
     analogous idea: store references to front and back nodes
  - can declare this in math as:

```
type FastLastList := {last: Z, list: List}
```

can do this in Java as well...

```
class FastLastList {
  private final int last;
 private final List list;
 FastLastList(List list) {
    this.list = list;
    this.last = last(list);
  public int getLast() {
    return this.last:
 public List getList() {
    return this.list;
```

lots of real-world performance improvements look like this

in what way is this worse than just using List?

— less memory efficient

```
class FastLastList {
  private final int last;
  private final List list;

public int getLast() { ... }

public List getList() { ... }
}
```

- How do we switch to this type?
  - change every List into FastLastList
  - not truly hiding data structure changes yet...

```
class FastLastList {
  private final int last;
  private final List list;

  public int getLast() { ... }

  public List getList() { ... }
}
```

- What if we also want the second-to-last element?
  - this is  $\Theta(n)$  to retrieve it
  - could cache the second to last element also
- What if we just want the items at the end of the list?
  - store it in reverse order!

#### **Reversed List**

```
private List L; // regular order
private List R; // reversed

/** @param L a list. Must be in *reverse* order */
public static void f(List L) { ... }
```

- Why is this a <u>terrible</u> idea?
  - the type checker will not catch mistakes

humans make mistakes. count on it

- will unit tests catch this?
   might only show up in integration tests
- what will the debugging be like?

```
class FastBackList {
  private final List revList;

public int getLast() {
    return this.revList.hd;
  }

public List getList() {
    return rev(this.revList);

    How could we avoid having a linear-time getList?
    - keep list and revList
    - time / space tradeoff
```

- How do we switch to this type?
  - change every FastLastList into FastBackList
  - not good that every data structure change is a code change

```
class FastLastList {
  private final int last;
  private final List list;
  ...
}

class FastBackList {
  private final Last revList;
  ...
}
```

- How can we make data structure changes without having to change all the clients every time?
  - use a Java interface

#### **Fast List**

```
interface FastList {
  int getLast();
  List getList();
class FastLastList implements FastList {
 private final int last;
 private final List list;
class FastBackList implements FastList {
 private final List revList;
```

#### **Fast List**

```
interface FastList {
  int getLast();
  List getList();
}

Interfaces contain only
operations (methods)
not data structures
```

- Clients should use only FastList in declarations
  - only usen FastLastList after "new"
- Standard style in Java
  - e.g., create an ArrayList but store it as List

## **Example 1: Fast List**

```
interface FastList {
  int getLast();
  List getList();
}
```

Interfaces contain only operations (methods) not data structures

- Interface provides an abstraction barrier
  - hides the details of data structures from the client







#### **Data Abstraction**

- Give clients only operations, not data
  - operations are the spec, data is hidden
- We call this an Abstract Data Type (ADT)
  - invented by Barbara Liskov in the 1970s
     won the Turing award in 2008
  - fundamental concept in computer science
     built into Java's public and private
  - data abstraction via procedural abstraction



See recent interview with Computing History Museum

## **Example 2: Point in 2D Space**

```
// Represents an (x, y) point in 2D space.
class Point {
 private double x;
 private double y;
  public double getX() { return this.x; }
  public double getY() { return this.y; }
  public double getR() {
    return Math.sqrt(x*x + y*y);
                                  What if these are too slow?
  public double getTheta() {
                                   — store polar coordinates
    return Math.atan2(y, x);
                                   — time / space tradeoff
```

How do we write this as an ADT?

## **Example 2: Point in 2D Space**

```
// Represents an (x, y) point in 2D space.
interface Point {
  double getX();
                            What if we want to use PolarPoint.
  double getY();
                            for users with lots of memory and
  double getR();
                            SimplePoint for users with little?
  double getTheta();

    need code to decide which to make

class SimplePoint implements Point {
  private double x, y;
class PolarPoint implements Point {
  private double x, y;
  private double r, theta;
```

## **Example 2: Point in 2D Space**

```
/** Creates a point at the given coordinates. */
public static Point makePoint(double x, double y) {
   if (Runtime.getRuntime().totalMemory() > MIN_MEM) {
      return new PolarPoint(x, y);
   } else {
      return new SimplePoint(x, y);
   }
}
```

- This is a "factory function"
  - an example of a design pattern

more on these later...

– Java SDK includes many, e.g., Arrays.asList(...)

## **Types of Operations**

```
interface Point {
  public double getX();
  public double getY();
  public double getR();
  public double getTheta();
  ...
}
```

- Operations usually fall into a few classes:
  - observers: return properties of an object
  - mutators: change properties of the object
  - producers: create new objects from an existing one

#### **Observers on Point**

```
public double getX();
public double getR();
public double getTheta();

/** Return distance from this point to given one. */
public double distTo(Point p);
```

- Observers return information about the object, but do not change it in any way
  - also called "getters"

#### **Mutators on Point**

```
/** Move the point by dx in x coord and dy in y */
public void shift(double dx, double dy);
/** Move by rotating about the origin by theta. */
public void rotate(double theta);
```

- Mutators change the properties of the object, but usually do not return anything important
  - also called "setters"

#### **Producers on Point**

```
/** Move the point by dx in x coord and dy in y */
public Point shift(double dx, double dy);
/** Move by rotating about the origin by theta. */
public Point rotate(double theta);
```

- Producers create new objects
  - new object is returned
  - they do not change the existing object

#### Mutable vs Immutable ADTs

- Sensible to pick one or the other
  - would be dangerous to provide both
     will see why later on
- We will stick to immutable ADTs for now
  - mutation makes reasoning & debugging harder
  - EJ 17: minimize mutability in classes

#### **Recall: Fast List**

```
interface FastList {
  int getLast();
  List getList();
}
```

- What kind of operations are these?
  - both are observers
- What would be examples of useful producers?

#### **Producers on FastList**

```
/** Returns the list with x added at the front. */
public FastList cons(int x);
```

- What factory functions should we provide?
  - what is the minimum we could get away with?

### **Creator of FastLists**

```
/** @return nil. */
public static FastList emptyList() {
   return new FastBackList(null);
}
```

- How could we make this more memory efficient?
  - no need to create a new object every time

#### **Creator of FastLists**

```
public static FastList EMPTY_LIST =
    new FastBackList(null);

/** @return nil. */
public static FastList emptyList() {
    return EMPTY_LIST;
}
```

- This is the "singleton" design pattern
  - note: this is only possible since FastList is immutable! we will see why later on...

#### **Producers on FastList**

```
/** Returns the list with x added at the front. */
public FastList cons(int x);

/**
    * Returns the list containing the elements of
    * this list followed by those of R.
    */
public FastList concat(FastList R);
```

- How do we formalize this?
  - everything above is English

there is possibility for confusion

# **Specifications for ADTs**

## **Specifications for ADTs**

- Run into problems when we try to write specs
  - for example, what goes after @return?

```
don't want to say returns the .list field
we want to hide those details from clients

interface FastList {
    /**
    * Returns the last element of the list.
    * @return ??
    */
    int getLast();
};
```

Need some terminology to clear up confusion

## **ADT Terminology**

#### New terminology for specifying ADTs

#### **Concrete State / Representation**

actual fields of the record and the data stored in them

Last example: int last, List list

#### **Abstract State / Representation**

how clients should think about the object

Last example: List (i.e., nil or cons)

- We've had different abstract and concrete types all along...
  - in our math, List is an inductive type (abstract)
  - in our code, List is a record (concrete)

## **ADT Terminology**

#### New terminology for specifying ADTs

#### **Concrete State / Representation**

actual fields of the record and the data stored in them

Last example: int last, List list

#### **Abstract State / Representation**

how clients should think about the object

Last example: List (i.e., nil or cons)

- Term "object" (or "obj") will refer to abstract state
  - "object" means mathematical object
  - "obj" is the mathematical value that the record represents

## **Specifying FastList**

```
/**
  * A list of integers that can retrieve the last
  * element in O(1) time.
  */
interface FastList {
    /**
    * Returns the last element of the list (O(1) time)
    * @requires obj /= nil
    * @return last(obj)
    */
int getLast();
```

- "obj" refers to the abstract state (the list, in this case)
  - actual state will be a record with fields last and list

```
/**
  * A list of integers that can retrieve the last
  * element in O(1) time.
  */
interface FastList {
    ...
    /**
    * Returns a new list with x in front of this list.
    * @return x :: obj
    */
    FastList cons(int x);
```

- Producer method: makes a new list for you
  - "obj" above is a list, so x :: obj makes sense in math

```
/**
  * A list of integers that can retrieve the last
  * element in O(1) time.
  */
interface FastList {
    ...
    /**
    * Returns a new list with x in front of this list.
    * @return x :: obj
    */
    FastList cons(int x);
```

- Specification does not talk about fields, just "obj"
  - fields are *hidden* from clients

```
/**
  * A list of integers that can retrieve the last
  * element in O(1) time.
  */
interface FastList {
    ...
    /**
    * Returns the object as a regular list of items.
    * @return ??
    */
    List getList();
```

How do we specify this?

```
/**
  * A list of integers that can retrieve the last
  * element in O(1) time.
  */
interface FastList {
    ...
    /**
    * Returns the object as a regular list of items.
    * @return obj
    */
    List getList();
```

- In math, this function does nothing ("@return obj")
  - two different concrete representations of the same idea
  - details of the representations are hidden from clients

# **Specifying Point**

```
/** Represents an (x, y) point in 2D space. */
interface Point {
   /** @return x */
   double getX();

   /** @return y */
   double getY();
```

- Abstract state is a pair (x, y)
  - i.e., we have (x, y) := obj
  - so, we can refer to "x" and "y"

# **Specifying Point**

```
/** Represents an (x, y) point in 2D space. */
interface Point {
   /** @return (x^2 + y^2)^(1/2) */
   double getR();
   /** @return arctan(y/x) */
   double getTheta();
```

#### Imperative specifications

- code may or may not actually do these calculations
- PolarPoint just returns the value in a field

# **Specifying Point**

```
/** Represents an (x, y) point in 2D space. */
interface Point {

   /** @return (x + dx, y + dy) */
   Point shiftBy(double dx, double dy);
```

- Describe the abstract state of what is returned
  - actual value returned is a Point of some variety

#### **Recall: ADTs**

- Abstraction over data
  - hide the details of the data representation
  - only give users a set of operations (the interface)
     data abstraction via procedural abstraction
- Interface can make clever data structures possible
- Some commonly used ADTs:
  - stack: add & remove from one end
  - queue: add to one end, remove from other
  - set: add, remove, & check if contained in list
  - map: add, remove, & get value for (key, value) pair

#### **Immutable Queue**

- A queue is a list that can only be changed two ways:
  - add elements to the front
  - remove elements from the back

```
// List that only supports adding to the front and
          // removing from the end
          interface NumberOueue {
            // @return len(obj)
observer
            int size();
                                              class DequeueParts {
                                                public final List Q;
            // @return [x] ++ obj
producer
                                                public final int x;
            NumberQueue enqueue (int x);
            // @requires len(obj) > 0
producer
            // @return (x, Q) with obj = Q ++ [x]
            DequeueParts dequeue();
```

```
/**
    * Represents a polynomial with int coefficients. An
    * example int polynomial would be 3x + 5x^2 + 8.
    */
    interface IntPoly {
        /** @return obj(x) */
        int eval(int x);

        /** @return obj + p */
        IntPoly add(IntPoly p);
```

- Simple specs if the reader knows polynomials already
  - not typical for classes we write to be well-known math ideas
  - how would we do this with math we covered?

```
/**
* Represents a polynomial with int coefficients.
* This is a list of pairs (c, n), where each "c" is
* called a coefficient and "n" an exponent.
 *
* A polynomial can be thought of as a function whose
* value at a given x is calculated as follows:
 *
 *
     value(nil, x) := 0
     value((c, n) :: L, x) := c * x^n + value(L, x)
 *
 *
* For example, (3, 1) :: (5, 2) :: (8, 0) :: nil has
* the value 3x + 5x^2 + 8 at a given x.
*/
interface IntPoly {
```

```
/**
* Represents a polynomial with int coefficients.
* This is a list of pairs (c, n), where each "c" is
* called a coefficient and "n" an exponent.
*
* A polynomial can be thought of as a function whose
* value at a given x is calculated as follows:
 *
 *
     value(nil, x) := 0
     value((c, n) :: L, x) := c * x^n + value(L, x)
*
*/
interface IntPoly {
 /** @return value(obj, x) */
 int eval(int x);
```

```
/**
 * Represents a polynomial with int coefficients.
 * This is a list of pairs (c, n), ...
 */
interface IntPoly {
   /** @return ?? */
   IntPoly add(IntPoly p);
```

How do we specify add?

```
/**
 * Represents a polynomial with int coefficients.
 * This is a list of pairs (c, n), ...
 */
interface IntPoly {
   /** @return obj ++ p */
   IntPoly add(IntPoly p);
```

- Does this match the other definition (obj + p)?
  - would need to show that:

```
value(obj + p, x) = value(obj, x) + value(p, x)
```

```
/**
 * Represents a polynomial with int coefficients.
 * This is a list of pairs (c, n), ...
 */
interface IntPoly {
   // Returns the coefficient with exponent "m"
   // @return ??
   int coeff(int m);
```

- How do we specify coeff?
  - what if there are multiple pairs with the same exponent?
  - what if there is no pair with that exponent?

```
// Returns the coefficient with exponent "m"
  // @return coeff(obj, m), where
  // coeff(nil, m) := 0
  // coeff((c, n) :: L, m) := c + coeff(L, m) if m = n
  // coeff((c, n) :: L, m) := coeff(L, m) if m /= n
  int coeff(int n);
Example: 3x + 5x^2 + 8
    coeff((3, 1) :: (5, 2) :: (8, 0) :: nil, 2)
     = coeff((5, 2) :: (8, 0) :: nil, 2)
                                            def of coeff (since 1 \neq 2)
     = 5 + coeff((8, 0) :: nil, 2)
                                            def of coeff (since 2 \neq 2)
     = 5 + coeff(nil, 2)
                                            def of coeff (since 0 \neq 2)
     =5
                                            def of coeff
```

```
/**
 * Represents a polynomial with int coefficients.
 * This is a list of pairs (c, n), ...
 */
interface IntPoly {

   // Returns the coefficient with exponent "m"

   // @return coeff(obj, m), where

   // coeff(nil, m) := 0

   // coeff((c, n) :: L, m) := c + coeff(L, m) if m = n

   // coeff((c, n) :: L, m) := coeff(L, m) if m /= n

int coeff(int n);
```

- Must add together all the coefficients with that exponent
- More than one option for missing exponents

```
/**
 * Represents a polynomial with int coefficients.
 * This is a list of pairs (c, n), ...
 */
interface IntPoly {

   // Returns the coefficient with exponent "m"

   // @return coeff(obj, m), where

   // coeff(nil, m) := 0

   // coeff((c, n) :: L, m) := c + coeff(L, m) if m = n

   // coeff((c, n) :: L, m) := coeff(L, m) if m /= n

int coeff(int n);
```

- What if we required all exponents to be distinct?
  - could stop at the first pair with that exponent...

```
/**
* Represents a polynomial with int coefficients.
* This is a list of pairs (c, n), ...
* All pairs are required to have distinct exponents.
*/
interface IntPoly {
 // Returns the coefficient with exponent "m"
 // @return coeff(obj, m), where
 // coeff(nil, m) := 0
 // coeff((c, n) :: L, m) := c if m = n
 // coeff((c, n) :: L, m) := coeff(L, m) if m /= n
 int coeff(int n);
```

Can stop at the first matching exponent now

```
/**
 * Represents a polynomial with int coefficients.
 * This is a list of pairs (c, n), ...
 * All pairs are required to have distinct exponents.
 */
interface IntPoly {
```

- Requiring distinct exponents is an "invariant"
  - extra assertion about a state that must always hold
  - we will see several types during this course
- An invariant of the abstract state is an "abstract invariant"

#### **Recall: Data Structures**

- ADTs hide the details of data structures
  - only give users a set of operations (the interface)
     data abstraction via procedural abstraction
- Interface can make clever data structures possible
- Some commonly used ADTs:
  - stack: add & remove from one end
  - queue: add to one end, remove from other
  - set: add, remove, & check if contained in list
  - map: add, remove, & get value for (key, value) pair

# **List Indexing**

```
at: (List, \mathbb{N}) \to \mathbb{Z}

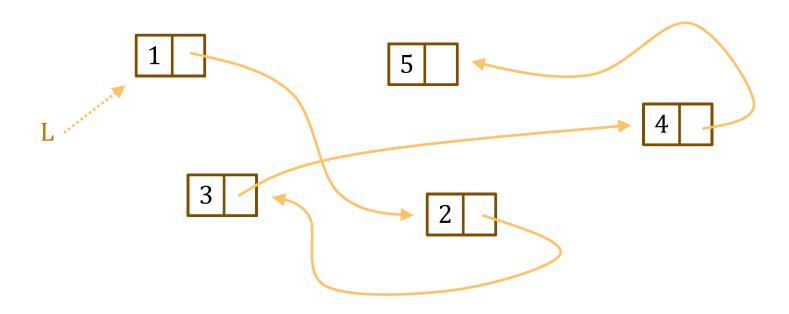
at(x:: L, 0) := x

at(x:: L, n+1) := at(L, n)
```

#### • Example:

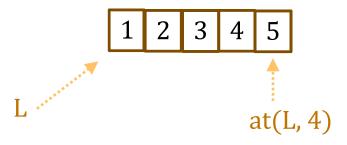
Not an especially efficient operation on linked lists...

#### **Linked Lists in Memory**



- Must follow the "next" pointers to find elements
  - at(L, n) is an O(n) operation
  - no faster way to do this on a linked list...
  - how can we do it faster?

#### **Faster Implementation of at**

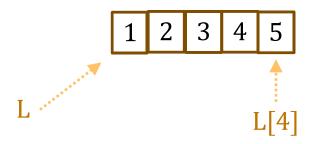


- Alternative: store the elements next to each other
  - can find the n-th entry by arithmetic:

```
location of L[4] = (location of L) + 4 * sizeof(int)
```

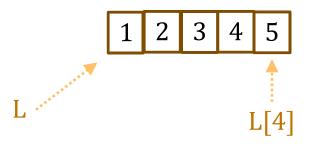
Resulting data structure is an array

#### **Faster Implementation of at**



- Resulting data structure is an array
- Efficient to read L[i]
- Inefficient to...
  - insert elements anywhere but the end
     trees can do everything in O(log n) time

#### **Arrays Are a Data Structure**



- One concrete representation of the List ADT
  - linked lists are another
  - trees can also implement the List ADT
- Mathematically, these are all List
  - a critical inductive data type

- Last lecture, we saw how to write an ADT spec
- Key idea is the "abstract state"
  - simple definition of the object (easier to think about)
  - clients use that to reason about calls to this code
- Write specifications in terms of the abstract state
  - describe the return value in terms of "obj"
- We also need to reason about ADT implementation
  - for this, we do want to talk about fields
  - fields are hidden from clients, but visible to implementers

- We also need to document the ADT implementation
  - for this, we need two new tools

#### **Abstraction Function**

defines what abstract state the field values currently represent

- Maps the field values to the object they represent
  - object is math, so this is a mathematical function
     there is no such function in the code just a tool for reasoning
  - will usually write this as an equation
     obj = ... right-hand side uses the fields

```
class FastLastList implements FastList {
    // AF: obj = this.list
    private final int last;
    private final List list;
    ...
}
```

- Abstraction Function (AF) gives the abstract state
  - obj = abstract state
  - this = concrete state (record with fields .last and .list)
  - AF relates abstract state to the current concrete state okay that "last" is not involved here
  - specifications only talk about "obj", not "this"
     "this" will appear in our reasoning

- We also need to document the ADT implementation
  - for this, we need two new tools

#### **Abstraction Function**

defines what abstract state the field values currently represent only needs to be defined when RI is true

#### **Representation Invariants (RI)**

facts about the field values that should always be true defines what field values are allowed

AF only needs to apply when RI is true

```
class FastLastList implements FastList {
    // RI: this.last = last(this.list)
    // AF: obj = this.list
    private final int last;
    private final List list;
    ...
}
```

- Representation Invariant (RI) holds info about this.last
  - fields cannot have just any number and list of numbers
  - they must fit together by satisfying RI

last must be the last number in the list stored

```
class FastBackList implements FastList {
   private final List revList;
   ...
}
```

- How can we specify this?
  - what is the AF and RI?

```
class FastBackList implements FastList {
    // AF: obj = rev(this.revList)
    private final List revList;
    ...
}
```

- No need for an RI
  - any value for revList is fine

```
class FastBackList implements FastList {
   private final List list;
   private final List revList;
   ...
}
```

- How can we specify this version?
  - what is the AF and RI?

```
class FastBackList implements FastList {
    // RI: this.revList = rev(this.list)
    // AF: obj = this.list
    private final List list;
    private final List revList;
    ...
}
```

Complexity moves from the AF to the RI

```
/** Represents an (x, y) point in 2D space. */
class PolarPoint implements FastList {
    private final double r, theta;
    ...
}
```

- How can we specify this version of Point?
  - what is the AF and RI?

```
/** Represents an (x, y) point in 2D space. */
class PolarPoint implements FastList {
   // RI: r >= 0
   // AF: (r cos(theta), r sin(theta))
   private final double r, theta;
   ...
}
```

- No constraints on theta
  - could restrict it by  $-\pi$  <  $\theta$  ≤  $\pi$  (for example)

```
/** Represents an (x, y) point in 2D space. */
class PolarPoint implements FastList {

   private final double x, y;
   private final double r, theta;
   ...
}
```

- How can we specify this version of Point?
  - what is the AF and RI?

```
/** Represents an (x, y) point in 2D space. */
class PolarPoint implements FastList {
   // RI: r = sqrt(x^2 + y^2) and theta = atan2(y, x)
   // AF: obj = (x, y)
   private final double x, y;
   private final double r, theta;
   ...
}
```

Complexity moves from AF to RI

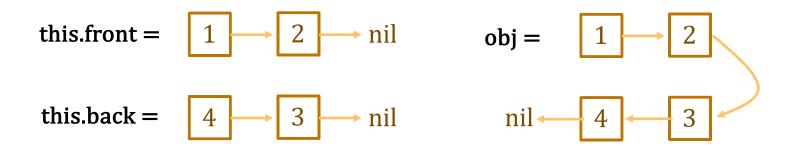
### Recall: Immutable Queue

- A queue is a list that can only be changed two ways:
  - add elements to the front
  - remove elements from the back

```
// Implements a queue using two lists.
class ListPairQueue implements NumberQueue {
    // AF: obj = this.front ++ rev(this.back)
    private final List front;
    private final List back; // in reverse order
```

- Back part stored in reverse order
  - head of front is the first element
  - head of back is the last element

this.front = 
$$\begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
 nil obj =  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$  this.back =  $\begin{bmatrix} 4 \\ 3 \end{bmatrix}$  nil nil  $\begin{bmatrix} 4 \\ 3 \end{bmatrix}$ 



- How do we enqueue (add at the front)?
  - remember that this is a producer
- How do we dequeue (remove from end)?
  - when is this not easy?
  - can we make this problem go away?

```
// Implements a queue using two lists.
class ListPairQueue implements NumberQueue {
    // AF: obj = this.front ++ rev(this.back)
    // RI: if this.back = nil, then this.front = nil
    private final List front;
    private final List back; // in reverse order
```

- If back is nil, then the queue is empty
  - if back = nil, then front = nil (by RI) and thus

```
obi =
```

```
// Implements a queue using two lists.
class ListPairQueue implements NumberQueue {
    // AF: obj = this.front ++ rev(this.back)
    // RI: if this.back = nil, then this.front = nil
    private final List front;
    private final List back;    // in reverse order
```

- If back is nil, then the queue is empty
  - if back = nil, then front = nil (by RI) and thus

```
obj = nil # rev(nil) by AF
= rev(nil) def of concat
= nil def of rev
```

if the queue is not empty, then back is not nil

```
(311 alert: this is the contrapositive)
```

### **Recall: Integer Polynomials**

```
/**
* Represents a polynomial with int coefficients.
* This is a list of pairs (c, n), ...
*/
interface IntPoly {
 // @return obj ++ p
 IntPoly add(IntPoly p);
 // Returns the coefficient with exponent "m"
 // @return coeff(obj, m), where
 // coeff(nil, m) := 0
 // coeff((c, n) :: L, m) := c + coeff(L, m) if m = n
 // coeff((c, n) :: L, m) := coeff(L, m) if m /= n
 int coeff(int n);
```

```
// Represents a list of pairs of the form (c, n),
// where c is coefficient and n is exponent
private static class MonoList {
   public final int coeff;
   public final int exponent;
   public final MonoList tl;
}
```

- Each pair stored in an instance of MonoList
  - empty list is represented by null

```
// Implements an IntPoly by storing the list.
class SimpleIntPoly implements IntPoly {
    // AF: obj = this.monos
    private final MonoList monos;

    private static class MonoList {
        public final int coeff;
        public final int exponent;
        public final MonoList tl;
    }
}
```

• Simple approach: concrete state = abstract state

```
// Implements an IntPoly by storing the list.
class SimpleIntPoly implements IntPoly {
    // RI: this.monos has no duplicate exponents
    // AF: obj = this.monos
    private final MonoList monos;

// @return obj ++ p
    public IntPoly add(IntPoly p) { ... }

// Returns the coefficient with exponent "m"
    // @return coeff(obj, m), where ...
    public int coeff(int n) { ... }
```

What changes if we disallow duplicates?

```
// Implements an IntPoly by storing the list.
class SimpleIntPoly implements IntPoly {
    // RI: this.monos has no duplicate exponents
    // AF: obj = this.monos
    private final MonoList monos;

    // @return obj ++ p
public IntPoly add(IntPoly p) { ... }

    // Returns the coefficient with exponent "m"
    // @return coeff(obj, m), where ...
public int coeff(int n) { ... }
```

- Easier to observer, but harder to produce
  - i.e., easier to read but harder to write

```
// Implements an IntPoly by storing the list.
class SimpleIntPoly implements IntPoly {
    // RI: this.monos has no duplicate exponents
    // AF: obj = this.monos
    private final MonoList monos;

// @return obj ++ p
    public IntPoly add(IntPoly p) { ... }

// Returns the coefficient with exponent "m"
    // @return coeff(obj, m), where ...
    public int coeff(int n) { ... }
```

 More restrictions (RI) usually makes reading easier but writing harder, but not always...

```
// Implements an IntPoly by storing the list.
class SimpleIntPoly implements IntPoly {
 // RI: this.monos has no duplicate exponents,
         this.monos is sorted by exponent
  // AF: obj = this.monos
 private final MonoList monos;
 // @return obj ++ p
 public IntPoly add(IntPoly p) { ... }
 // Returns the coefficient with exponent "m"
 // @return coeff(obj, m), where ...
 public int coeff(int n) { ... }
```

Sorting the monomials makes add easier!

#### **Definition of List Reversal**

Can add two sorted lists of monomials in O(n):

```
\begin{array}{lll} \text{poly-add(nil, R)} & := & R \\ \\ \text{poly-add(L, nil)} & := & L \\ \\ \text{poly-add((c, m) :: L, (d, n) :: R)} & := & (c, m) :: & \text{poly-add(L, (d, n) :: R)} \\ \\ & & \text{if } m < n \\ \\ \text{poly-add((c, m) :: L, (d, n) :: R)} & := & (d, n) :: & \text{poly-add((c, m) :: L, :: R)} \\ \\ & & \text{if } m > n \\ \\ \text{poly-add((c, m) :: L, (d, n) :: R)} & := & (c+d, m) :: & \text{poly-add(L, :: R)} \\ \\ & & \text{if } m = n \\ \end{array}
```

- if m < n, then R has no matching exponent</li>
- if n < m, then L has no matching exponent
- this is essentially merge-sort