# CSE 331 Software Design & Implementation

Autumn 2024 Section 8 – Trees and ADTs

#### Administrivia

- HW 8 written released tonight at 4:30 pm, due Thursday 11/21 at 11 pm
  - It is only 1 problem, try to get it done by Wednesday night
- HW 8 code released Wed 11/20 at 4:30 pm, due Monday 11/25 at 11 pm
  - Longer code section than recent weeks, so start doing it early and come to office hours

## Proof By Calculation (Review)

- The goal of proof by calculation is to show that an assertion is true given facts that you already know
- You should start the proof with the left side of the assertion and end the proof with the right side of the assertion. Each symbol (=, >, <, etc.) connecting each line of the proof is that line's relationship to the previous line on the proof</li>
- Only modify one side

#### **Example:**

Suppose we have the facts: x = 3, y = 4, z > 5 and we want to use proof by calculation to prove  $x^2 + y^2 < z^2$ . Our proof by calculation would look like this:

$$x^{2} + y^{2} = 3^{2} + y^{2}$$
 since  $x = 3$   
=  $3^{2} + 4^{2}$  since  $y = 4$   
=  $25$   
=  $5^{2}$   
<  $z^{2}$  since  $z > 5$ 

note that each line shows the relationship to the previous line ONLY

start with left side of assertion

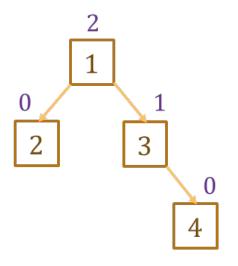
end with right side of assertion

#### **Trees**

- Trees are inductive data types with a constructor that has 2+ recursive arguments
- These come up all the time...
  - no constructors with recursive arguments = "generalized enums"
  - constructor with 1 recursive arguments = "generalized lists"
  - constructor with 2+ recursive arguments = "generalized trees"

## Height of a tree

- Binary Tree: a tree in which each node has at most
   2 children
  - Not to be confused with Binary Search Tree, which also has the ordering property that (nodes in L) < x and (nodes in R) > x
- type Tree := empty | node(x: ℤ, L: Tree, R: Tree)



Mathematical definition of height

height : Tree  $\rightarrow \mathbb{Z}$ 

height(empty) := -1

height(node(x, L, R)) := 1 + max(height(L), height(R))

## Using Definitions in Calculations (example)

```
height : Tree \rightarrow \mathbb{Z}
height(empty) := -1
height(node(x, L, R)) := 1 + max(height(L), height(R))
•Suppose "T = node(1, empty, node(2, empty, empty))"
•Prove that height(T) = 1
    height(T) = height(node(1, empty, node(2, empty, empty)) since T = ...
     = 1 + max(height(empty), height(node(2, empty, empty))) def of
    height
     = 1 + max(-1, height(node(2, empty, empty))) def of height
     = 1 + max(-1, 1+ max(height(empty), height(empty))) def of height
     = 1 + max(-1, 1 + max(-1, -1)) def of height (x 2)
     = 1 + max(-1, 1+ -1) def of max
     = 1 + max(-1, 0)
     = 1 + 0 def of max
```

## Task 1: One, Two, Tree...

The problem makes use of the following inductive type, representing a left-leaning binary tree

```
type Tree := empty  | \quad \mathsf{node}(\mathsf{val} : \mathbb{Z}, \ \mathsf{left} : \mathsf{Tree}, \ \mathsf{right} : \mathsf{Tree}) \quad \mathsf{with} \ \mathsf{height}(\mathsf{left}) \geqslant \mathsf{height}(\mathsf{right})
```

The "with" condition is an invariant of the node. Every node that is created must have this property,

```
\begin{array}{ll} \mathbf{func} \ \mathsf{height}(\mathsf{empty}) & := & -1 \\ \ \mathsf{height}(\mathsf{node}(x,S,T)) & := & 1 + \mathsf{height}(S) \quad \mathsf{for \ any} \ x : \mathbb{Z} \ \mathsf{and} \ S, T : \mathsf{Tree} \\ \ \mathsf{Since \ height}(\mathsf{S}) > = & \mathsf{height}(\mathsf{T}) \\ \ \mathsf{size} : \mathsf{Tree} \to \mathbb{N} \end{array}
```

```
\begin{aligned} & \mathsf{size}(\mathsf{empty}) & := & 0 \\ & \mathsf{size}(\mathsf{node}(x,S,T)) & := & 1 + \mathsf{size}(S) + \mathsf{size}(T) & \text{ for any } x : \mathbb{Z} \text{ and } S,T : \mathsf{Tree} \end{aligned}
```

Prove by structural induction that, for any left-leaning tree T we have

$$size(T) \leq 2^{height(T)+1} - 1$$

### Task 2: How do I Love Tree

a Path tells you how to get to a particular node where each step along the path (item in the list) would be a direction pointing you to keep going down the LEFT or RIGHT branch of the tree.

(a) Define a function "find $(p : \mathsf{Path}, \, T : \mathsf{BST})$ " that returns the node (a BST) at the path from the root of T or undefined if there is no such node.

(b) Define a function "remove(p: Path, T: BST)" that returns T except with the node at the given path replaced by empty.

## Specifications for ADTs – Review

- New Terminology for specifying ADTs:
  - Abstract State / Representation (Math)
    - How clients should understand the object
    - Ex: List(nil or cons)
  - Concrete State / Representation (Code)
    - Actual fields of the record and the data stored
    - Ex: { list: List, last: bigint | undefined }
- We've had different abstract and concrete types all along!
  - in our math, List is an inductive type (abstract)
  - in our code, List is a string or a record (concrete)
- Term "object" (or "obj") will refer to abstract state
  - "object" means mathematical object
  - "obj" is the mathematical value that the record represents

## Documenting ADTs – Review

**Abstract Function (AF)** – defines what abstract state the field values represent

- Maps field values → the object they represent
- Output is math, this is a mathematical function

Representation Invariants (RI) – facts about the field values that must always be true

- Constructor must always make sure RI is true at runtime
- Can assume RI is true when reasoning about methods
- AF only needs to make sense when RI holds
- Must ensure that RI always holds

## Documenting ADTs – Example

```
// A list of integers that can retrieve the last element in O(1)
export interface FastList {
                                           Talk about functions in
/**
 Returns the object as a regular list terms of the abstract state
                                           (obj)
* @returns obj 	
                                          Hide the representation
toList: () => List<bigint>
                                          details (i.e. real fields) from
                                          the client
class FastLastList implements FastList {
  // RI: this.last = last(this.list);
  // AF: obj = this.list;
  // @ returns last(obj)
 getLast = (): bigint | undefined => {
    return this.last;
```

#### Task 3: Let's Blow This Point

Suppose we had the following interface and implementation to represent a point in 2D space:

```
/** Represents a point with coordinates in (x,y) space. */ class SimplePoint implements Point {
interface Point {
                                                                // RI: <TODO>
    /** @returns the x coordinate of the point */
                                                                // AF: <TODO>
    getX: () => number;
                                                                readonly x: number;
                                                                readonly y: number;
    /** @returns the y coordinate of the point */
                                                                readonly r: number;
    getY: () => number;
                                                                // Creates a point with the given coordinates
    /**
                                                                constructor(x: number, y: number) {
     * Returns the distance of this point to the origin.
                                                                 this.x = x;
     * @returns Math.sqrt(obj.x*obj.x + obj.y*obj.y)
                                                                 this.y = y;
     */
                                                                 this.r = Math.sqrt(x*x + y*y);
    distToOrigin: () => number;
                                                                }
                                                                getX = (): number => this.x;
                                                                getY = (): number => this.y;
                                                                distToOrigin = (): number => this.r;
                                                            }
```

(a) Define the representation invariant (RI) and abstraction function (AF) for the SimplePoint class.

#### Task 3: Let's Blow This Point

```
/** Represents a point with coordinates in (x,y) space. */ class SimplePoint implements Point {
                                                             // RI: <TODO>
interface Point {
                                                             // AF: <TODO>
    /** Oreturns the x coordinate of the point */
                                                             readonly x: number;
   getX: () => number;
                                                             readonly y: number;
   /** @returns the y coordinate of the point */
                                                             readonly r: number;
   getY: () => number;
                                                             // Creates a point with the given coordinates
    /**
                                                             constructor(x: number, y: number) {
    * Returns the distance of this point to the origin.
                                                              this.x = x;
    * @returns Math.sqrt(obj.x*obj.x + obj.y*obj.y)
                                                              this.y = y;
    */
                                                              this.r = Math.sqrt(x*x + y*y);
    distToOrigin: () => number;
                                                             }
                                                             getX = (): number => this.x;
                                                             getY = (): number => this.y;
                                                             distToOrigin = (): number => this.r;
```

(b) Use the RI or AF to prove that the distToOrigin method of the SimplePoint class is correct.

#### Task 3: Let's Blow This Point

(c) The following problem will make use of this math definition that rotates a point around the origin (x, y) by an angle  $\theta$ :

Suppose we have the following implementation of the rotate method:

```
/** @returns rotate(obj, θ) */
    rotate = (theta: number): Point => {
        const newX = this.x * Math.cos(theta) - this.y * Math.sin(theta);
        const newY = this.x * Math.sin(theta) + this.y * Math.cos(theta);
        return new SimplePoint(newX, newY);
    }
```

Prove that the rotate method is correct using the RI or AF.

## Task 4: Going Back and Length

```
\begin{aligned} & \operatorname{len} : \operatorname{List} \to \mathbb{N} \\ & \operatorname{len}(\operatorname{nil}) & := & 0 \\ & \operatorname{len}(x :: L) & := & 1 + \operatorname{len}(L) \end{aligned}
```

```
\begin{array}{ccc} \operatorname{rev}:\operatorname{List} \to \operatorname{List} \\ \operatorname{rev}(\operatorname{nil}) & := & \operatorname{nil} \\ \operatorname{rev}(x::L) & := & \operatorname{rev}(L) + + [x] \end{array}
```

Lemma 1: len(rev(L) :: x) = len(rev(L)) + len(x::nil)for any list L and element x

4. Prove by Structural Induction that len(rev(L)) = len(L) for any list L. You may use Lemma 1 in your proof.

\*ok to work from top and bottom as long as only modifying right side!