

CSE 326: Data Structures

Binary Search Trees

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Announcements (4/18/08)

- HW #3 will be assigned this afternoon, due at beginning of class next Friday.
- Project 2A due next Wed. night.

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Outline

- Dictionary ADT / Search ADT
- Quick Tree Review
- Binary Search Trees

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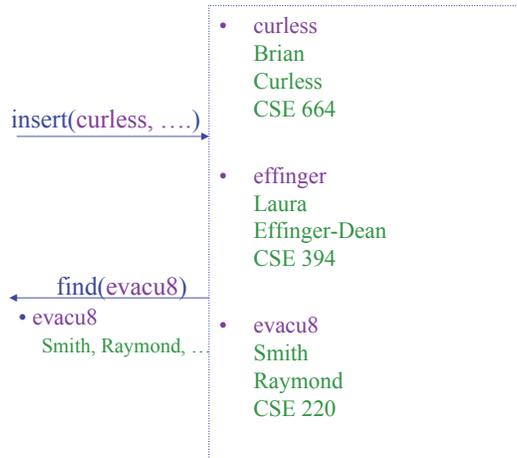
ADTs Seen So Far

- Stack
 - Push
 - Pop
 - Queue
 - Enqueue
 - Dequeue
 - Priority Queue
 - Insert
 - DeleteMin
- Then there is decreaseKey...

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The Dictionary ADT

- Data:
 - a set of (key, value) pairs
- Operations:
 - Insert (key, value)
 - Find (key)
 - Remove (key)



The Dictionary ADT is also called the "Map ADT"

A Modest Few Uses

- Sets
- Dictionaries
- Networks : Router tables
- Operating systems : Page tables
- Compilers : Symbol tables

Probably the most widely used ADT!

Implementations

insert find delete

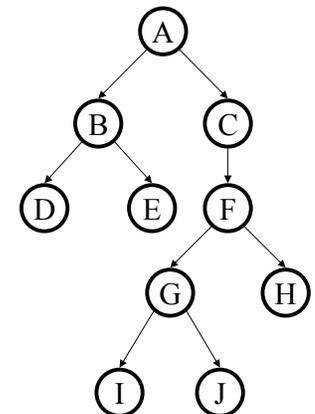
- Unsorted Linked-list
- Unsorted array
- Sorted array

Binary Trees

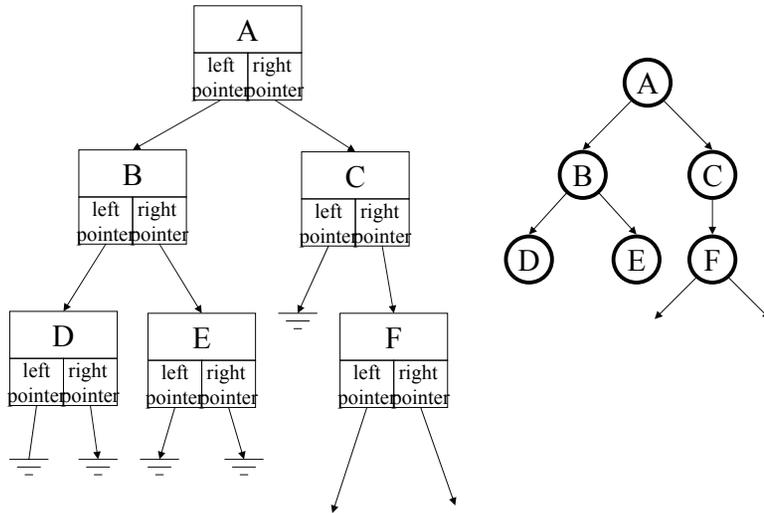
- Binary tree is
 - a root
 - left subtree (*maybe empty*)
 - right subtree (*maybe empty*)

- Representation:

Data	
left pointer	right pointer



Binary Tree: Representation



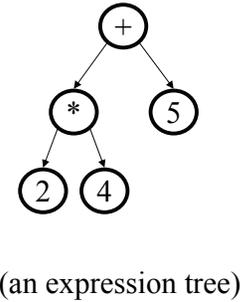
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Tree Traversals

A *traversal* is an order for visiting all the nodes of a tree

Three types:

- Pre-order: Root, left subtree, right subtree
- In-order: Left subtree, root, right subtree
- Post-order: Left subtree, right subtree, root



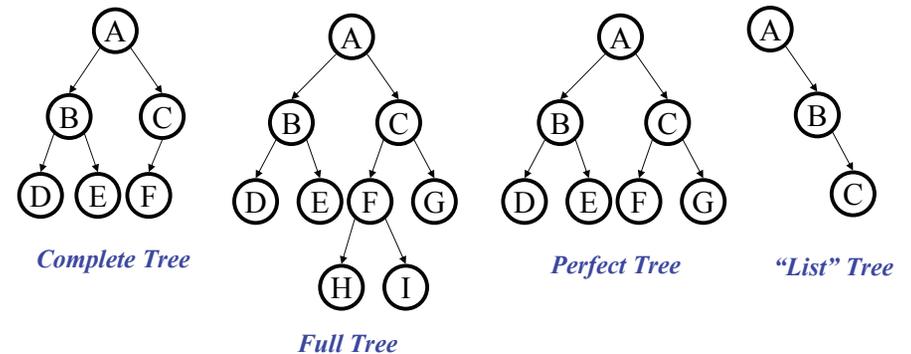
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Inorder Traversal

```
void traverse(BNode t){
    if (t != NULL)
        traverse (t.left);
        process t.element;
        traverse (t.right);
    }
}
```

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Binary Tree: Special Cases



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Binary Tree: Some Numbers...

Recall: height of a tree = longest path from root to leaf.

For binary tree of height h :

- max # of leaves:
- max # of nodes:
- min # of leaves:
- min # of nodes:

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Binary Tree: Some Numbers...

Recall: depth of a node = path length from node to root.

Consider the space (forest) of all possible binary trees of N nodes.

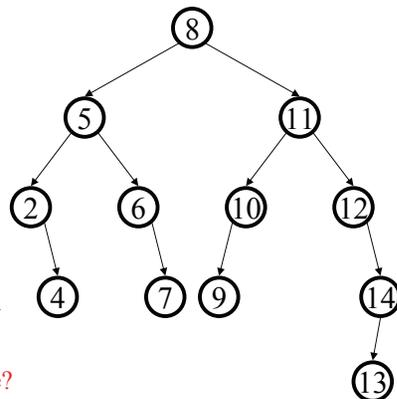
- Sum up the depths of every node in that forest and divide by the number of nodes.
- This is the average depth over all nodes over all binary trees of size N . How big is it?

What would the average depth be for a well-balanced tree?

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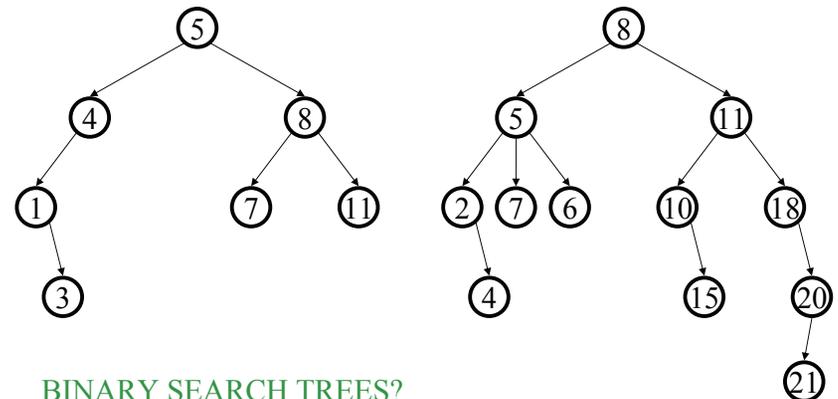
Binary Search Tree Data Structure

- Structural property
 - each node has ≤ 2 children
 - result:
 - storage is small
 - operations are simple
- Order property
 - all keys in left subtree smaller than root's key
 - all keys in right subtree larger than root's key
 - result: easy to find any given key
- What must I know about what I store?



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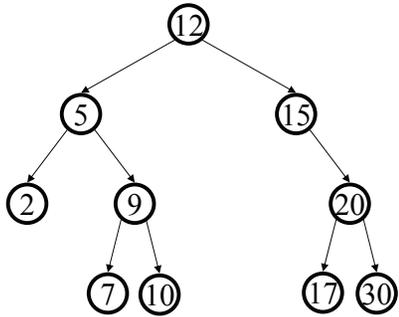
Example and Counter-Example



BINARY SEARCH TREES?

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Find in BST, Recursive



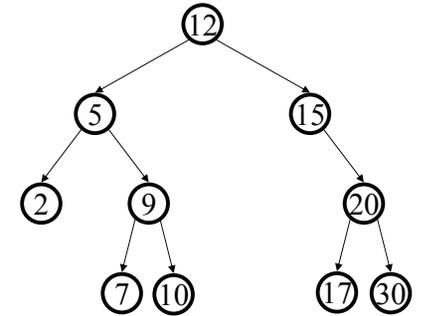
Runtime:

```
Node Find(Object key,
           Node root) {
    if (root == NULL)
        return NULL;

    if (key < root.key)
        return Find(key,
                    root.left);
    else if (key > root.key)
        return Find(key,
                    root.right);
    else
        return root;
}
```

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Find in BST, Iterative



Runtime:

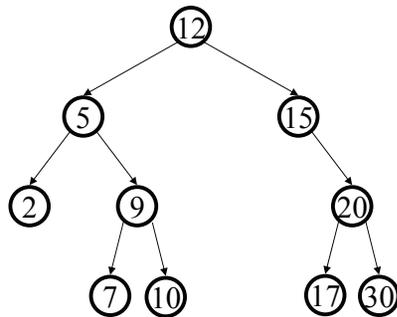
```
Node Find(Object key,
           Node root) {
    while (root != NULL &&
           root.key != key) {
        if (key < root.key)
            root = root.left;
        else
            root = root.right;
    }

    return root;
}
```

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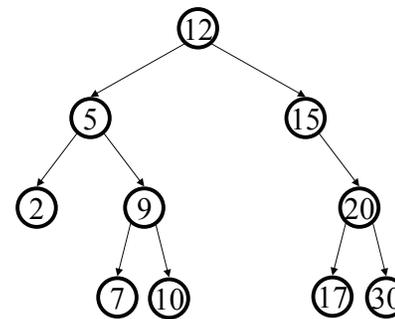
Bonus: FindMin/FindMax

- Find minimum
- Find maximum



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Insert in BST



Insert(13)
Insert(8)
Insert(31)

Insertions happen only
at the leaves – easy!

Runtime:

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BuildTree for BST

- Suppose keys 1, 2, 3, 4, 5, 6, 7, 8, 9 are inserted into an initially empty BST.

If inserted in given order, what is the tree? What big-O runtime for this kind of sorted input?

If inserted in reverse order, what is the tree? What big-O runtime for this kind of sorted input?

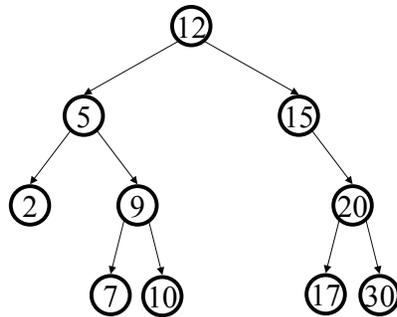
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BuildTree for BST

- Suppose keys 1, 2, 3, 4, 5, 6, 7, 8, 9 are inserted into an initially empty BST.
 - If inserted median first, then left median, right median, etc., what is the tree? What is the big-O runtime for this kind of sorted input?

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Deletion in BST



Why might deletion be harder than insertion?

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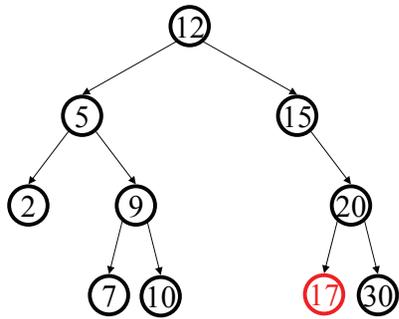
Deletion

- Removing an item disrupts the tree structure.
- Basic idea: **find** the node that is to be removed. Then “fix” the tree so that it is still a binary search tree.
- Three cases:
 - node has no children (leaf node)
 - node has one child
 - node has two children

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Deletion – The Leaf Case

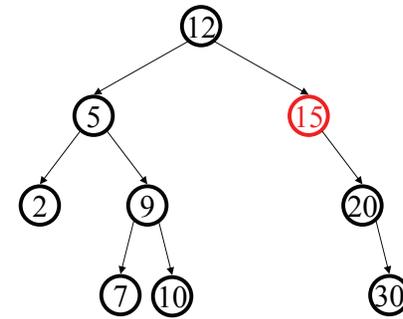
Delete(17)



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Deletion – The One Child Case

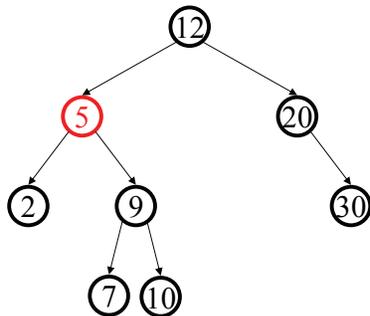
Delete(15)



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Deletion – The Two Child Case

Delete(5)



What can we replace 5 with?

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Deletion – The Two Child Case

Idea: Replace the deleted node with a value guaranteed to be between the two child subtrees

Options:

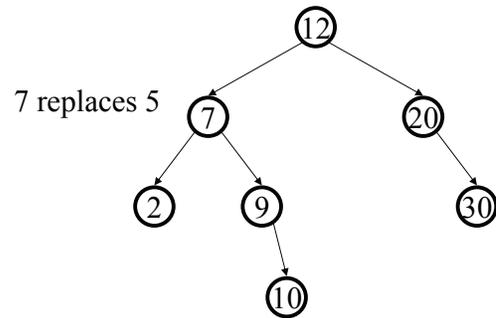
- *succ* from right subtree: $\text{findMin}(t.\text{right})$
- *pred* from left subtree : $\text{findMax}(t.\text{left})$

Now delete the original node containing *succ* or *pred*

- Leaf or one child case – easy!

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Finally...



Original node containing
7 gets deleted

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Balanced BST

Observations

- BST: the shallower the better!
- For a BST with n nodes
 - Average depth (averaged over all possible insertion orderings) is $O(\log n)$
 - Worst case maximum depth is $O(n)$
- Simple cases such as $\text{insert}(1, 2, 3, \dots, n)$ lead to the worst case scenario

Solution: Require a **Balance Condition** that

1. ensures depth is $O(\log n)$ – strong enough!
2. is easy to maintain – not too strong!

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