Sorting Lower Bound Radix Sort

CSE 326
Data Structures
Lecture 16

Reading

- Reading
 - › Sections 7.8-7.11

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How fast can we sort?

- Heapsort, Mergesort, and Quicksort all run in O(N log N) best case running time
- · Can we do any better?
- No, if the basic action is a comparison.

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Sorting Model

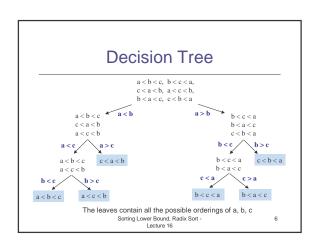
- Recall our basic assumption: we can <u>only</u> <u>compare two elements at a time</u>
 - we can only reduce the possible solution space by half each time we make a comparison
- Suppose you are given N elements
 - › Assume no duplicates
- · How many possible orderings can you get?
 - > Example: a, b, c (N = 3)

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Permutations

- · How many possible orderings can you get?
 - \rightarrow Example: a, b, c (N = 3)
 - \rightarrow (a b c), (a c b), (b a c), (b c a), (c a b), (c b a)
 - > 6 orderings = 3-2-1 = 3! (ie, "3 factorial")
 - › All the possible permutations of a set of 3 elements
- · For N elements
 - N choices for the first position, (N-1) choices for the second position, ..., (2) choices, 1 choice
 - \rightarrow N(N-1)(N-2)···(2)(1)= N! possible orderings

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Decision Trees

- A Decision Tree is a Binary Tree such that:
 - > Each node = a set of orderings
 - ie, the remaining solution space
 - > Each edge = 1 comparison
 - > Each leaf = 1 unique ordering
 - How many leaves for N distinct elements?
 - . N!, ie, a leaf for each possible ordering
- Only 1 leaf has the ordering that is the desired correctly sorted arrangement

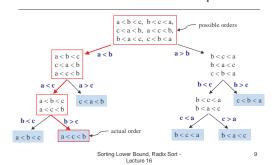
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Decision Trees and Sorting

- Every sorting algorithm corresponds to a decision tree
 - Finds correct leaf by choosing edges to follow
 ie, by making comparisons
 - Each decision reduces the possible solution space by one half
- Run time is ≥ maximum no. of comparisons
 - maximum number of comparisons is the length of the longest path in the decision tree, i.e. the height of the tree

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Decision Tree Example



How many leaves on a tree?

- Suppose you have a binary tree of height d. How many leaves can the tree have?
 - d = 1 à at most 2 leaves,
 - d = 2 à at most 4 leaves, etc.





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Lower bound on Height

- A binary tree of height d has at most 2d leaves
 - depth d = 1 à 2 leaves, d = 2 à 4 leaves, etc.
 - Can prove by induction
- Number of leaves, $L \le 2^d$
- Height d ≥ log₂ L
- · The decision tree has N! leaves
- So the decision tree has height d ≥ log₂(N!)

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log(N!) is $\Omega(MlogN)$

$$\begin{split} \log(N!) &= \log \left(N \cdot (N-1) \cdot (N-2) \cdots (2) \cdot (1) \right) \\ &= \log N + \log(N-1) + \log(N-2) + \cdots + \log 2 + \log 1 \\ &\geq \log N + \log(N-1) + \log(N-2) + \cdots + \log \frac{N}{2} \\ \\ &\Rightarrow \frac{N}{2} \log \frac{N}{2} \\ &\geq \frac{N}{2} (\log N - \log 2) = \frac{N}{2} \log N - \frac{N}{2} \\ &= \Omega(N \log N) \end{split}$$

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$\Omega(N \log N)$

- Run time of any comparison-based sorting algorithm is Ω(N log N)
- Can we do better if we don't use comparisons?

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Radix Sort: Sorting integers

- Historically goes back to the 1890 census.
- Radix sort = multi-pass bucket sort of integers in the range 0 to BP-1
- Bucket-sort from least significant to most significant "digit" (base B)
- Requires P(B+N) operations where P is the number of passes (the number of base B digits in the largest possible input number).
- If P and B are constants then O(N) time to sort!

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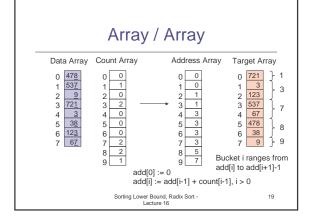
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Implementation Options

- List
 - › List of data, bucket array of lists.
 - › Concatenate lists for each pass.
- · Array / List
 - › Array of data, bucket array of lists.
- Array / Array
 - › Array of data, array for all buckets.
 - Requires counting.

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Array / Array

- Pass 1 (over A)
 - > Calculate counts and addresses for 1st "digit"
- Pass 2 (over T)
 - › Move data from A to T
 - > Calculate counts and addresses for 2nd "digit"
- Pass 3 (over A)
 - > Move data from T to A
 - > Calculate counts and addresses for 3nd "digit"
- .
- In the end an additional copy may be needed.

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Choosing Parameters for Radix Sort

- N number of integers given
- m bit numbers given
- · B number of buckets
 - \rightarrow B = 2^r calculations can be done by shifting.
 - N/B not too small, otherwise too many empty buckets.
 - P = m/r should be small.
- Example 1 million 64 bit numbers. Choose B = 2^{16} =65,536. 1 Million / B \approx 15 numbers per bucket. P = 64/16 = 4 passes.

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Properties of Radix Sort

- · Not in-place
 - › needs lots of auxiliary storage.
- Stable
 - equal keys always end up in same bucket in the same order.
- Fast
 - \rightarrow B = 2^r buckets on m bit numbers

 $O(\frac{m}{r}(n+2^r))$ time

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Internal versus External Sorting

- So far assumed that accessing A[i] is fast Array A is stored in internal memory (RAM)
 - › Algorithms so far are good for internal sorting
- What if A is so large that it doesn't fit in internal memory?
 - › Data on disk or tape
 - Delay in accessing A[i] e.g. need to spin disk and move head

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Internal versus External Sorting

- Need sorting algorithms that minimize disk/tape access time
 - > External sorting Basic Idea:
 - Load chunk of data into RAM, sort, store this "run" on disk/tape
 - Use the Merge routine from Mergesort to merge runs
 - Repeat until you have only one run (one sorted chunk)
 - Text gives some examples

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Summary of Sorting

- Sorting choices:
 - O(N²) Bubblesort, Insertion Sort
 - O(N log N) average case running time:
 - Heapsort: In-place, not stable (read about it).

 - Mergesort: O(N) extra space, stable.
 Quicksort: claimed fastest in practice but, O(N²) worst case. Needs extra storage for recursion. Not stable.
 - O(N) Radix Sort: fast and stable. Not comparison based. Not in-place.

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