

# CSE 326: Data Structures Lecture #21 Multidimensional Search Trees

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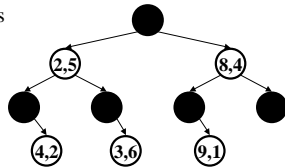
## Today's Outline

- Multidimensional search trees
- Range Queries
- $k$ -D Trees
- Quad Trees

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## Multi-D Search ADT

- Dictionary operations
  - create
  - destroy
  - find
  - insert
  - delete
  - range queries
- Each item has  $k$  keys for a  $k$ -dimensional search tree
- Searches can be performed on one, some, or all the keys or on ranges of the keys



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## Applications of Multi-D Search

- Astronomy (simulation of galaxies) - 3 dimensions
- Protein folding in molecular biology - 3 dimensions
- Lossy data compression - 4 to 64 dimensions
- Image processing - 2 dimensions
- Graphics - 2 or 3 dimensions
- Animation - 3 to 4 dimensions
- Geographical databases - 2 or 3 dimensions
- Web searching - 200 or more dimensions

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## Range Query

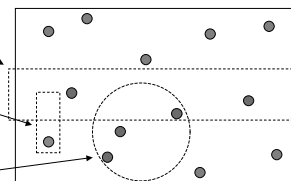
A *range query* is a search in a dictionary in which the exact key may not be entirely specified.

Range queries are the primary interface with multi-D data structures.

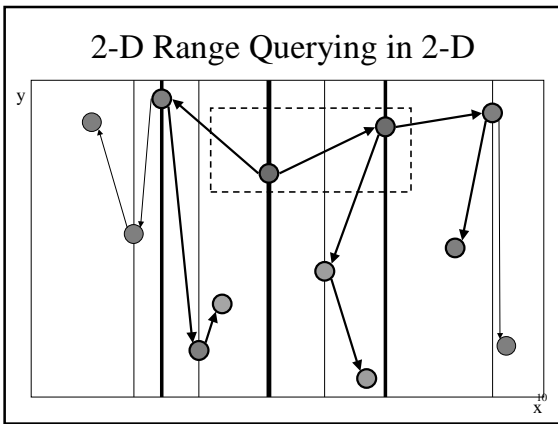
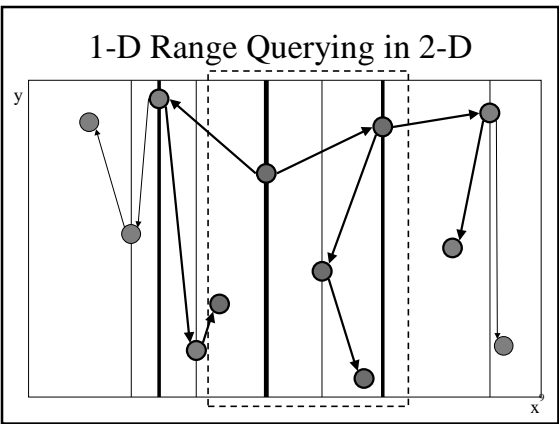
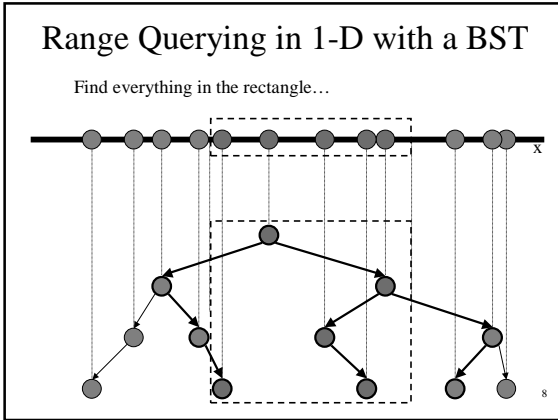
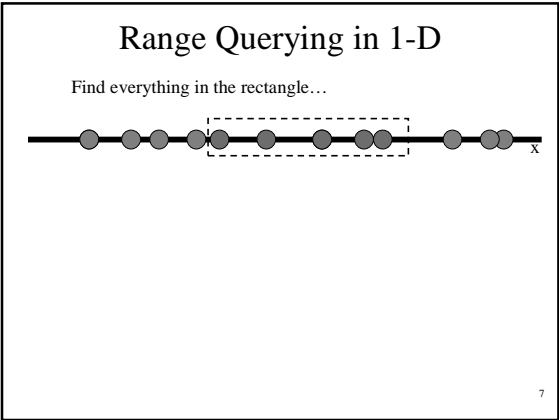
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## Range Query Examples: Two Dimensions

- Search for items based on *just one key*
- Search for items based on *ranges for all keys*
- Search for items based on a function of several keys: e.g., a *circular range query*



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### k-D Trees

- Split on the next dimension at each succeeding level
- If building in batch, choose the median along the current dimension at each level
  - guarantees logarithmic height and balanced tree
- In general, add as in a BST

keys	value
dimension	
left	right

← The dimension that this node splits on

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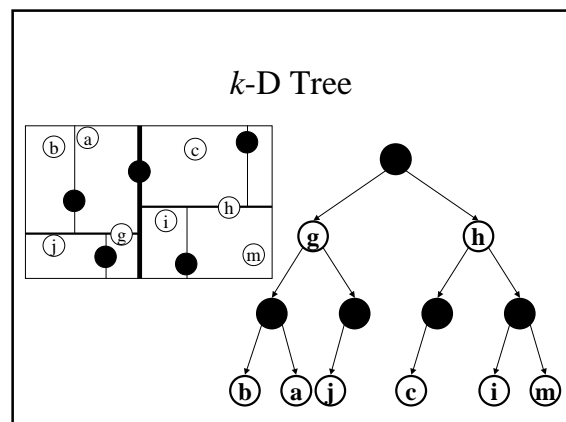
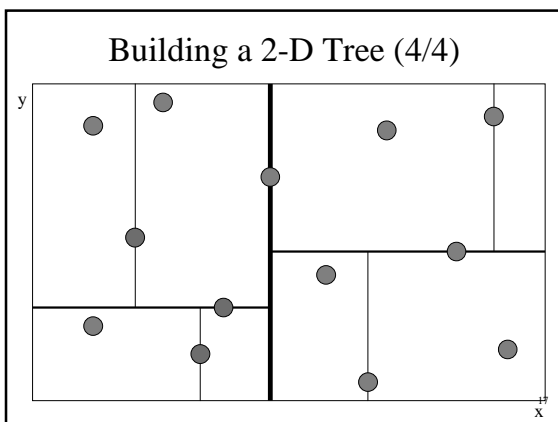
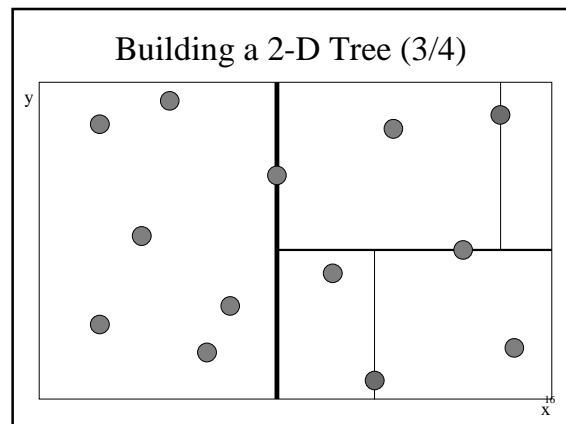
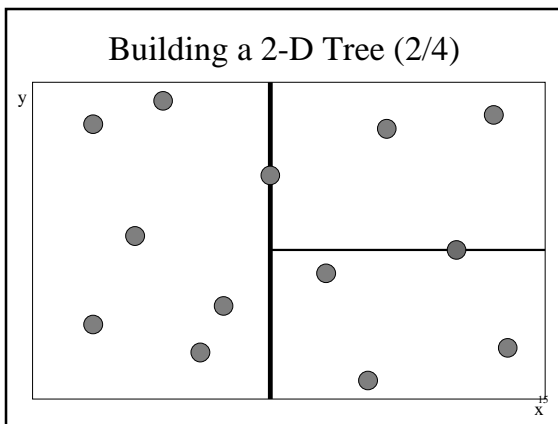
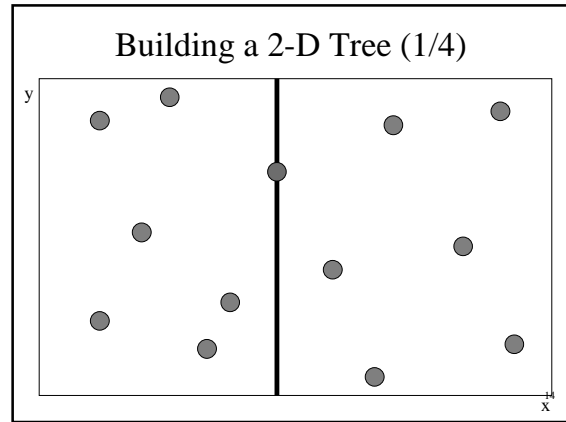
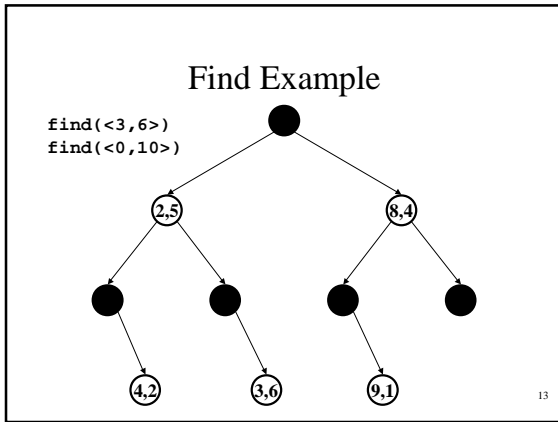
### Find in a k-D Tree

`find(<x1, x2, ..., xk>, root)` finds the node which has the given set of keys in it or returns **null** if there is no such node

```

Node *amp find(const keyVector & keys,
               Node *amp root) {
    int dim = root->dimension;
    if (root == NULL)
        return root;
    else if (root->keys == keys)
        return root;
    else if (keys[dim] < root->keys[dim])
        return find(keys, root->left);
    else
        return find(keys, root->right);
}
runtime:
  
```

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### 2-D Range Querying in 2-D Trees

Search every partition that intersects the rectangle.  
Check whether each node (including leaves) falls into the range.

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### Range Query in a 2-D Tree

```

print_range(int xlow, xhigh, ylow, yhigh, Node * root) {
    if (root == NULL) return;
    if ( xlow <= root.x && root.x <= xhigh &&
        ylow <= root.y && root.y <= yhigh ){
        print(root);
    }
    if (root.dim == "x" && xlow <= root.x ) ||
        (root.dim == "y" && ylow <= root.y ) )
        print_range(root.left);
    if (root.dim == "x" && root.x <= xhigh) ||
        (root.dim == "y" && root.y <= yhigh)
        print_range(root.right);
}

```

runtime:  $O(\text{depth of tree})$

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### Range Query in a $k$ -D Tree

```

print_range(int low[MAXD], high[MAXD], Node * root) {
    if (root == NULL) return;
    inrange = true;
    for (i=0; i<MAXD;i++){
        if ( root.coord[i] < low[i] ) inrange = false;
        if ( high[i] < root.coord[i] ) inrange = false; }
    if (inrange) print(root);
    if ((low[root.dim] <= root.coord[root.dim] )
        print_range(root.left);
    if (root.coord[root.dim] <= high[root.dim])
        print_range(root.right);
}

```

runtime:  $O(N)$

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### Other Shapes for Range Querying

Search every partition that intersects the shape (circle).  
Check whether each node (including leaves) falls into the shape.

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### $k$ -D Trees Can Be Inefficient (but not when built in batch!)

```

insert(<5,0>)
insert(<6,9>)
insert(<9,3>)
insert(<6,5>)
insert(<7,7>)
insert(<8,6>)

```

suck factor:

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### $k$ -D Trees Can Be Inefficient (but not when built in batch!)

```

insert(<5,0>)
insert(<6,9>)
insert(<9,3>)
insert(<6,5>)
insert(<7,7>)
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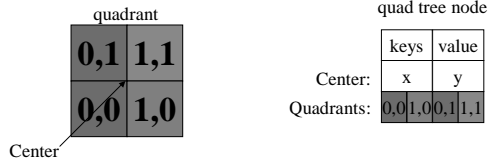
```

suck factor:  $O(n)$

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## Quad Trees

- Split on *all* (two) dimensions at each level
- Split key space into equal size partitions (quadrants)
- Add a new node by adding to a leaf, and, if the leaf is already occupied, split until only one node per leaf



## Find in a Quad Tree

`find(<x, y>, root)` finds the node which has the given pair of keys in it or returns quadrant where the point should be if there is no such node

```
Node *& find(Key x, Key y, Node *& root) {
    if (root == NULL)
        return NULL; // Empty tree
    if (root->isLeaf)
        return root; // Key may not actually be here
    int quad = getQuadrant(x, y, root);
    return find(x, y, root->quadrants[quad]);
}
```

Compares against center; always makes the same choice on ties.

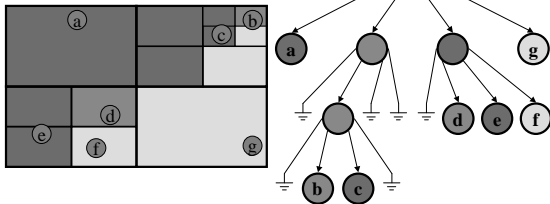
runtime: O(depth)

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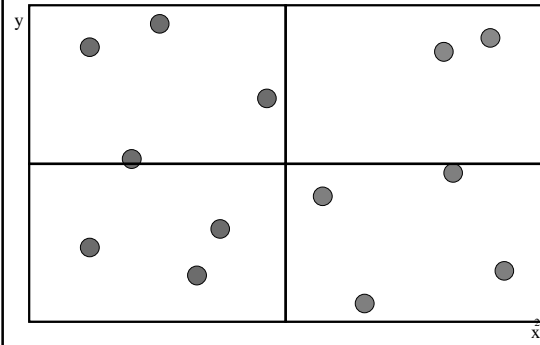
## Find Example

`find(<10,2>)` (i.e., c)

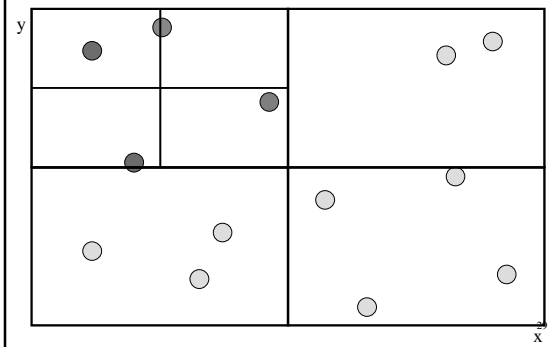
`find(<5,6>)` (i.e., d)



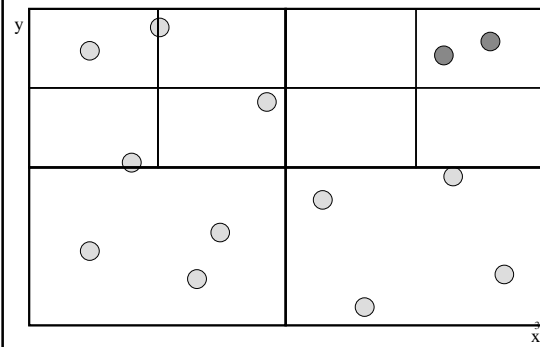
## Building a Quad Tree (1/5)

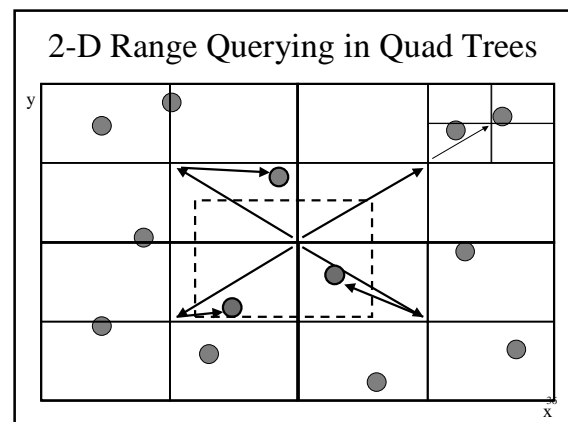
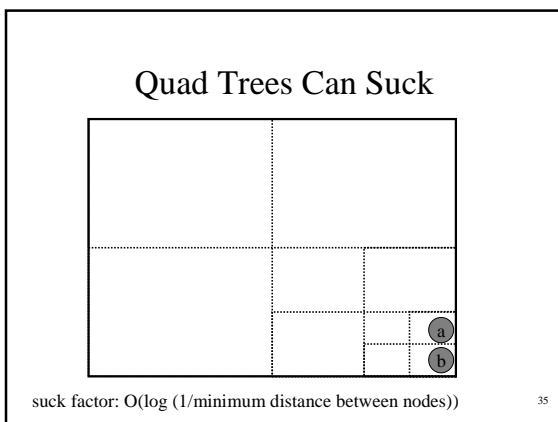
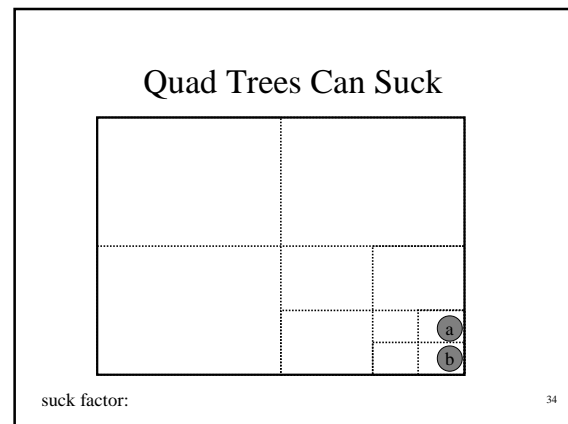
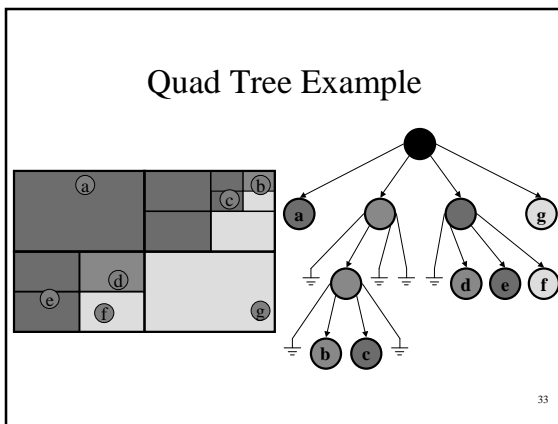
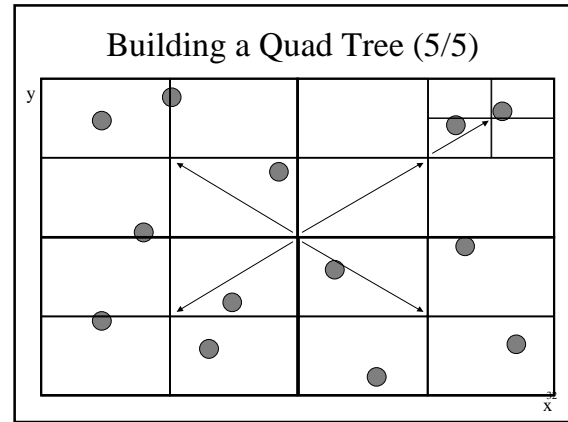
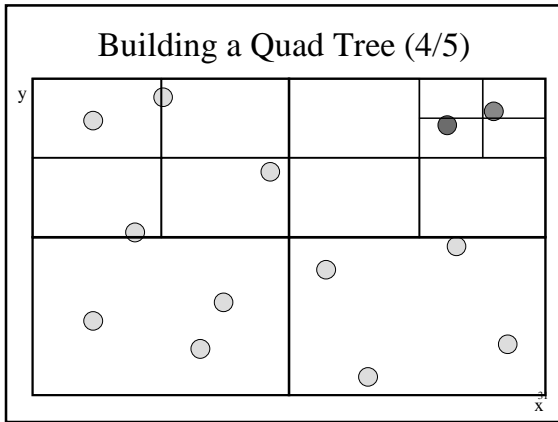


## Building a Quad Tree (2/5)



## Building a Quad Tree (3/5)





## 2-D Range Query in a Quad Tree

```

print_range(int xlow, xhigh, ylow, yhigh, Node * root){
    if (root == NULL) return;
    if ( xlow <= root.x && root.x <= xhigh &&
        ylow <= root.y && root.y <= yhigh ){
        print(root);

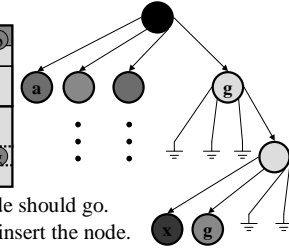
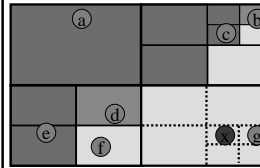
    if (xlow <= root.x && ylow <= root.y)
        print_range(root.lower_left);
    if (xlow <= root.x && root.y <= yhigh)
        print_range(root.upper_left);
    if (root.x <= x.high && ylow <= root.y)
        print_range(root.lower_right);
    if (root.x <= xhigh && root.y <= yhigh)
        print_range(root.upper_right);
}
    
```

runtime:  $O(N)$

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## Insert Example

`insert(<10,7>,x)`

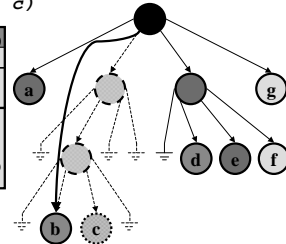


- Find the spot where the node should go.
- If the space is unoccupied, insert the node.
- If it is occupied, split until the existing node separates from the new one.

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## Delete Example

`delete(<10,2>)(i.e., c)`

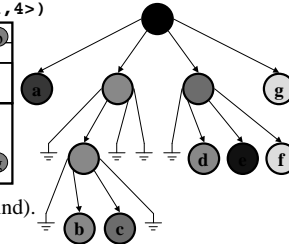
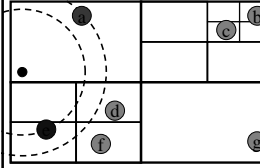


- Find and delete the node.
- If its parent has just one child, delete it.
- Propagate!

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## Nearest Neighbor Search

`getNearestNeighbor(<1,4>)`



- Find a nearby node (do a find).
- Do a circular range query.
- As you get results, tighten the circle.
- Continue until no closer node in query.

Works on <sup>40</sup>  
k-D Trees, too!

## Quad Trees vs. $k$ -D Trees

- $k$ -D Trees
  - Density balanced trees
  - Number of nodes is  $O(n)$  where  $n$  is the number of points
  - Height of the tree is  $O(\log n)$  with *batch insertion*
  - Supports insert, find, nearest neighbor, range queries
- Quad Trees
  - Number of nodes is  $O(n(1 + \log(\Delta/n)))$  where  $n$  is the number of points and  $\Delta$  is the ratio of the width (or height) of the key space and the smallest distance between two points
  - Height of the tree is  $O(\log n + \log \Delta)$
  - Supports insert, delete, find, nearest neighbor, range queries

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## To Do / Coming Attractions

- Read (a little) about  $k$ -D trees in Weiss 12.6
- (More) Heaps 'o fun
  - leftist heaps & binomial queues

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