

Hannah Tang and Brian Tjaden Summer Quarter 2002

Today's Outline

- · Review of probability
- · Motivation for randomization
- Two randomized data structures – Treaps
 - Randomized Skip Lists
- Two randomized algorithms
 - Primality checking
 - Graph searching
 - Again?!

The Problem with Deterministic Data Structures

We've seen many data structures with good average case performance on random inputs, but bad behavior on particular inputs

We define the *worst case* runtime over all possible inputs *I* of size *n* as: Worst-case $T(n) = \max T(I)$

We define the *average case* runtime over all possible inputs *I* of size *n* as:

Average-case $T(n) = (S_{I} T(I)) / numPossInputs$

The Motivation for Randomization

Instead of randomizing the input (since we cannot!), consider randomizing the data structure

- No bad inputs, just unlucky random numbers
- Expected case good behavior on any input

Expectant Cases

Definition:

 A worst-case expected time analysis is a weighted sum of all possible outcomes over some probability distribution

Thus, the *expected* runtime of a *randomized* data structure on some input *I* is:

Expected T(I) = $S_{c}(Pr(S) * T(I, S))$

And the *worst-case expected* runtime of a *randomized* data structure* is:

Expected T(n) = max (S(Pr(S) * T(I, S)))

* Randomized data structure = = a data structure whose behaviour is dependant on a sequence of random numbers

What's the Difference?

· Randomized with good expected time

- Once in a while you will have an expensive operation, but no inputs can make this happen all the time
- Deterministic with good average time
 - If your application happens to always use the "bad" case, you are in big trouble!
- Expected time is kind of like an insurance policy for your algorithm!















Treap Summary

Implements Dictionary ADT

- Insert in *expected* O(log n) time
- Delete in *expected* O(log n) time
- Find in *expected* O(log n) time
- But worst case O(n)

Memory use

- O(1) per node
- About the cost of AVL trees
- Very simple to implement, little overhead
 - Less than AVL trees

Perfect Binary Skip List

- Sorted linked list
- # of links of a node is its *height*
- The height *i* link of each node (that has one) links to the next node of height *i* or greater



Find() in a Perfect Binary Skip List

- Start *i* at the maximum height
- Until the node is found, or *i* =1 and the next node is too large:
 - If the next node along the *i* link is less than the target, traverse to the next node
 - Otherwise, decrease *i* by one

Runtime?



Randomized Skip List Intuition

- It's far too hard to insert into a perfect skip list
- But is perfection necessary?
- What matters in a skip list?
 - We want way fewer tall nodes than short ones
 - Make good progress through the list with each high traverse

Randomized Skip List

- · Sorted linked list
- # of links of a node is its height
- The height i link of each node (that has one) links to the next node of height i or greater
- There should be *about 1/2 as many* height i+1



Find() in a RSL

- Start *i* at the maximum height
- Until the node is found or *i* is one and the next node is too large:
 - If the next node along the *i* link is less than the target, traverse to the next node
 - Otherwise, decrease *i* by one

Same as for a perfect skip list!

Runtime?

Insert() in a RSL

- Flip a coin until it comes up heads – This will take i flips. Make the new node's height i.
- Do a find, remembering nodes where we moved down one link
- Add the new node at the spot where the find ends
- Point all the nodes where we moved down (up to the new node's height) at the new node
- Point the new node's links where those redirected pointers were pointing





Randomized Skip List Summary

- Implements Dictionary ADT
 - Insert in *expected* O(log n)
 - Find in *expected* O(log n)
 - But worst case O(n)
- Memory use
 - O(1) memory per node
 - About double a linked list
- Less overhead than search trees for iteration over range queries

Intermission: Efficiently Calculating Powers

- How would you implement a function/method pow(x, n) which returns the number xⁿ?
- How could you do that *efficiently*?



• Given a number *P*, can we determine whether or not *P* is prime?

Date: Wed, 7 Aug 2002 11:00:43 -0700 (PDT) Newsgroups: uw-cs.ugrads.openforum Subject: Primes in P??

So, a paper published yeterday alleges they have found a deterministic polynomial algorithm to determine primality.

http://www.cse.iitk.ac.in/primality.pdf

Two Properties of Primes

P is a prime 0 < A < P and 0 < X < P

Then:

 $\mathbb{A}^{\mathbb{P}-1} = 1 \pmod{\mathbb{P}}$

And, the only solutions to $X^2 = 1 \pmod{P}$ are: X = 1 and X = P - 1





"And, the *only* solutions to $X^2 = 1 \pmod{P}$ are: X = 1 and X = P - 1"







If the randomized algorithm reports failure, then P really isn't prime.

If the randomized algorithm reports success, then P*might be* prime. – P is prime with probability > ¾ – Each new A has independent probability of false positive

• Solution:

- Run the randomized algorithm several times

Evaluating Randomized Primality Testing

- Your probability of being struck by lightning this year: 0.00004%
- Your probability that a number that tests prime 11 times in a row is actually not prime: 0.00003%
- Your probability of winning a lottery of 1 million people five times in a row: 1 in 2^{100}
- Your probability that a number that tests prime 50 times in a row is actually not prime: 1 in 2^{100}



Implicitly Generated Graphs

- A huge graph may be implicitly specified by rules for generating it on-the-fly
- Blocks world:
 - vertex = relative positions of all blocks
 - edge = robot arm stacks one block



The Blocks World Problem: A Large Branching Factor

- Source = initial state of the blocks
- Goal = desired state of the blocks
- Path source to goal = sequence of actions (program) for robot arm!
- n blocks ≈ nⁿ vertices
- 10 blocks ≈ 10 billion vertices!
- We cannot search such huge graphs exhaustively!
 - Breadth-first search: If out-degree of each node is 10, potentially visits 10^d vertices
 - Dijkstra's algorithm is basically breadth-first search (modified to handle edge weights)

Review: Heuristic-Based Searching

• The Manhattan distance $(\Delta x + \Delta y)$ is an estimate of the distance to the goal

- A heuristic value

- · Best-First Search
 - Select nodes to *minimize estimated distance to the goal*; if a promising set of nodes doesn't pan out, *backtrack*
- Hill-climbing
 - Select nodes to *minimize estimated distance to the goal*
 - Says nothing about backtracking. In fact, we don't even keep track of our previous path!

"Hill Climbing": What's in a Name?

- Let's assume we're trying to *maximize* our heuristic
- If we view our graph as a terrain, and the heuristic values as elevations, then graph searching becomes a problem of finding the tallest hill
- But ...
 - What are some problems with hill climbing?

Solution: Hill Climbing with Random Restarts*

- Once you can't go any farther, randomly choose a node in the graph, and try again.
- Once you have several possible solutions, pick the one with the highest heuristic value
- A common variation is *simulated annealing*, which may pick a random move instead of the best move. As the algorithm progresses, we choose the random move less and less often

Example: N-Queens Problem

- Place N queens on an N by N chessboard so that no two queens can attack each other
- Graph search formulation:

 Each way of placing from 0 to N queens on the chessboard is a vertex
 Edge between vertices that differ by
- adding or removing one queen
 Start vertex: empty board
- Goal vertex: any one with N nonattacking queens (there are many such goals)



Hill Climbing with Random Restarts - Complexity?

- Can often prove that if you run long enough will reach a goal state but may take exponential time
- In some cases can prove that a hill-climbing or random walk algorithm will find a goal in polynomial time with high probability

 e.g., 2-SAT, Papadimitriou 1997
- Widely used for real-world problems where actual complexity is unknown scheduling, optimization
 - N-Queens probably polynomial, but no one has tried to prove formal bound

Other Real-World Applications

- Routing finding computer networks, airline route planning
- VLSI layout cell layout and channel routing
- Production planning "just in time" optimization
- · Protein sequence alignment
- Travelling Salesman
- · Many other "NP -Hard" problems
 - A class of problems for which no exact polynomial time algorithms exist – so heuristic search is the best we can hope for

Other Randomized Algorithms/Data Structures

- Data Structures
 Other Dictionary ADT's
- Algorithms
 - Find a minimum spanning tree in O(E) time
 - Max flow problems in O(V² log V) time
 In CSE 421, you'll see a deterministic algorithm works in O(V E²) time
 - Many others!